Message Passing Interface – Advanced Topics

Lecture 5

István Reguly

reguly.istvan@itk.ppke.hu



Groups and Communicators

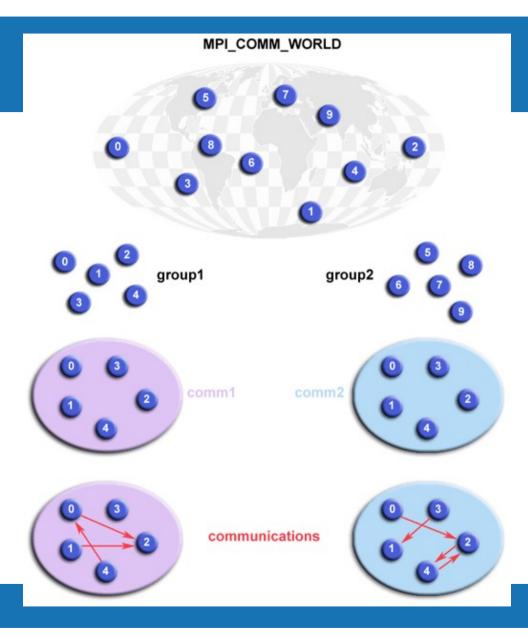
- So far we had MPI_COMM_WORLD, which included all the ranks
- An MPI group is an ordered set of processes.
 - Each process in a group is associated with a unique integer rank. Rank values start at zero and go to N-1, (N is the size of the group)
 - Always associated with a communicator
- An MPI communicator encompasses a group of processes that may communicate with each other
 - All MPI messages use one
 - From the programmer's perspective, no real difference



Purpose of MPI groups

- Allow you to organize tasks, based upon function, into task groups
- Enable collective communications operations over a subset of related tasks
- Provides basis for implementing user defined virtual topologies
- Safe communications
- Dynamic objects, can be created of freed at any time
- Processes may be in more than one group (they'll have a unique ID for each)





- Extract group handle from MPI_COMM_WORLD (MPI_Comm_group)
- 2. Create subset of global group with MPI_Group_incl
- 3. Create a new communicator for new group MPI_Comm_create
- 4. Determine new rank with MPI_Comm_rank
- 5. Do communications within the group
- 6. When done, deallocate MPI_Comm_free MPI_Group_free



Virtual topologies

- Describes a mapping/ordering of MPI processes into a geometric shape
- Two main kinds are Cartesian and Graph
- Virtual because there may be no relationship to the physical structure of the machine
 - Some implementations do try to optimize it, especially if communication to "far" nodes is more expensive
- Built upon MPI communicators and groups
- Useful in situations where the application-specific communication pattern matches the MPI topology structure



Cartesian topology

0	1	2	3
(0,0)	(0,1)	(0,2)	(0,3)
4	5	6	7
(1,0)	(1,1)	(1,2)	(1,3)
8	9	10	11
(2,0)	(2,1)	(2,2)	(2,3)
12	13	14	15
(3,0)	(3,1)	(3,2)	(3,3)

- MPI_Cart_create(incomm, numdims, dimsize, periodic, reorder, outcomm)
- MPI_Cart_coords(comm, serialrank, numdims, coords)
- MPI_Cart_shift(comm,dim,o ffset,&negidx,&posidx)



Cartesian topology

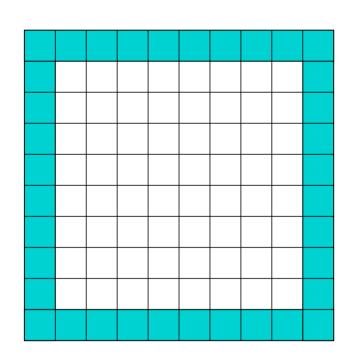
- MPI_Cart_create(incomm, numdims, dimsize, periodic, reorder, outcomm)
 - Creates a new communicator *outcomm*, representing a *numdims* dimensional space, with *dimsize[]* processes along each dimension. *periodic[]* specifies whether a rank at the end of a row is neighbours with the rank at the beginning
- MPI_Cart_coords(comm, serialrank, numdims, coords)
 - For a Cartesian communicator *comm*, puts the coordinates of process *rank* in *coords*
- MPI_Cart_shift(comm,dim,offset,&negidx,&posidx)
 - For a Cartesian communicator comm, returns the ranks of the neighbours of the current process in dimension dim that are offset away in the positive and the negative directions

Exercise

- Take a look at mpi_cart.cpp
- Modify it to work with any number of processes
 - Use MPI_Dims_create
 - Evaluate it for 1, 2, 4, 7, 8, 9
 - What sort of decomposition do you get?
- Modify it so each process send a message (its rank) to each of neighbours, receives a message (into inbuf) from each of its neighbours, and prints it



Cartesian grid & PDEs

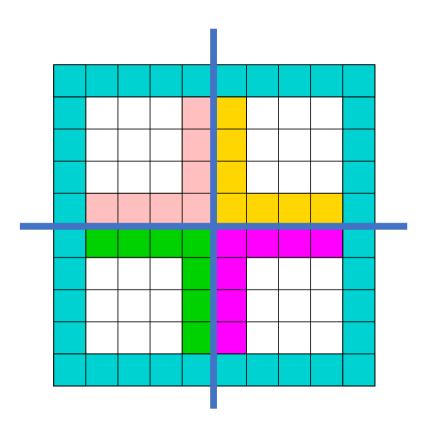


- Assume grid elements are updated using a 5-point finite-difference stencil
- Grid boundary in cyan
 - Typically constant
- Grid points in interior change in every step



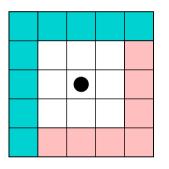
Partitioning the grid

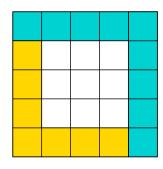
- Suppose we want to partition into four subdomains
- Could be done only vertically or only horizontally
- We do both

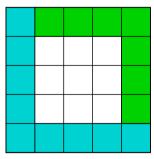


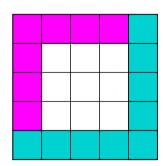


- To update the grid point marked, information is needed from the four neighbours
 - Homework's lbm_d2q9.cpp
 "Gather neighbour values" loop



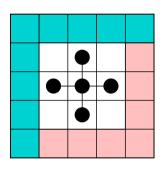


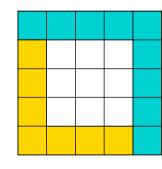


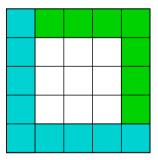


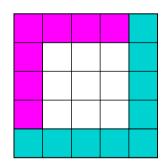


- To update the grid point marked, information is needed from the four neighbours
- The stencil shows the grid points needed for the update
- All accessed points are in the subdomain



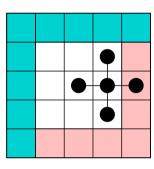


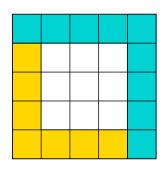


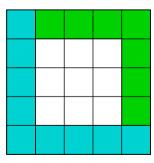


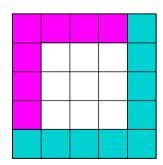


 To update an adjacent grid point, we are still okay



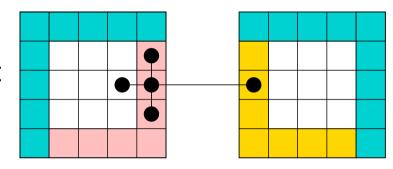


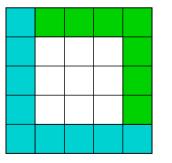


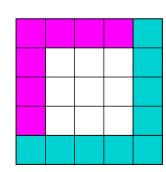




- To update an adjacent grid point, we are still okay
- But moving over one more, we now need information from the adjacent subdomain



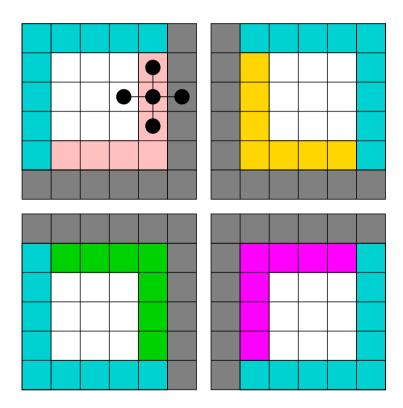






Communication

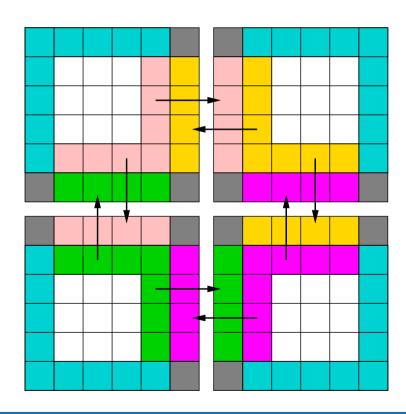
- Assuming message passing, we want to minimize communication
- We create additional grid locations to hold the copy of data from neighbours: Ghost cells
- Transfer can happen in blocks





Communication

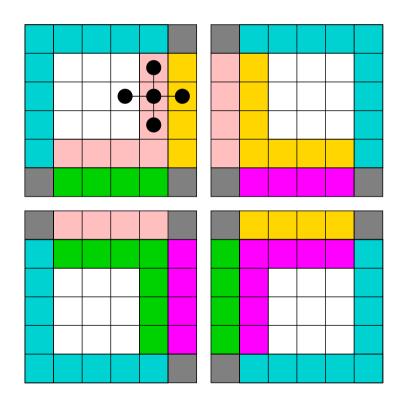
- Before each new set of updates...
- Interior boundary data is sent to processes working on adjacent subdomains





Computations

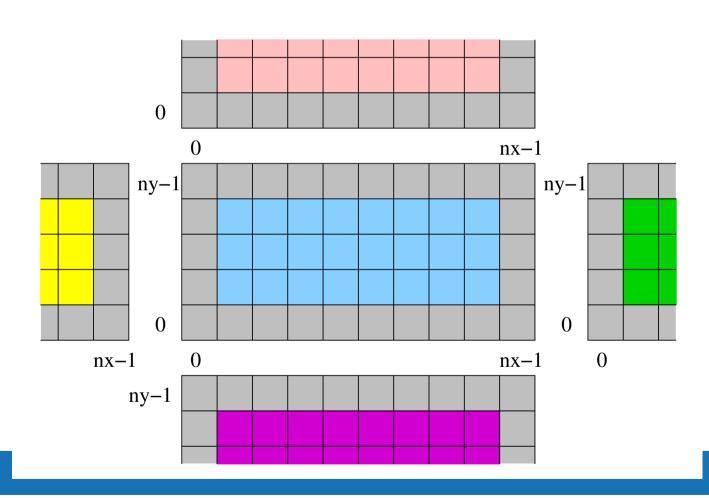
- Before each new set of updates...
- Interior boundary data is sent to processes working on adjacent subdomains
- Now accesses are once again limited to local subdomain

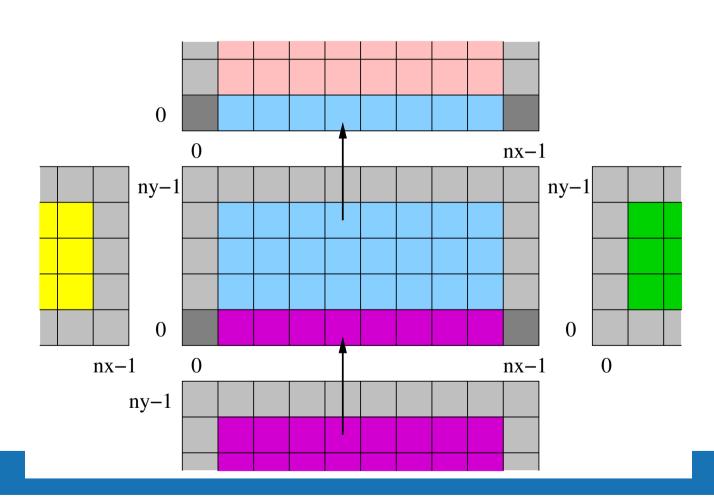


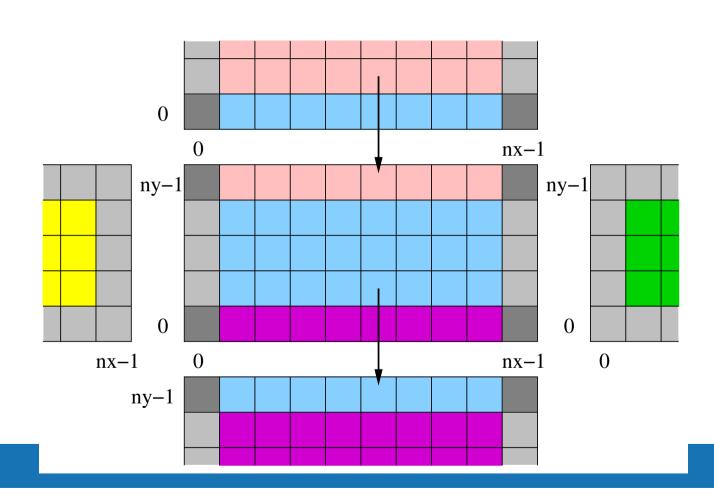


Typical Application

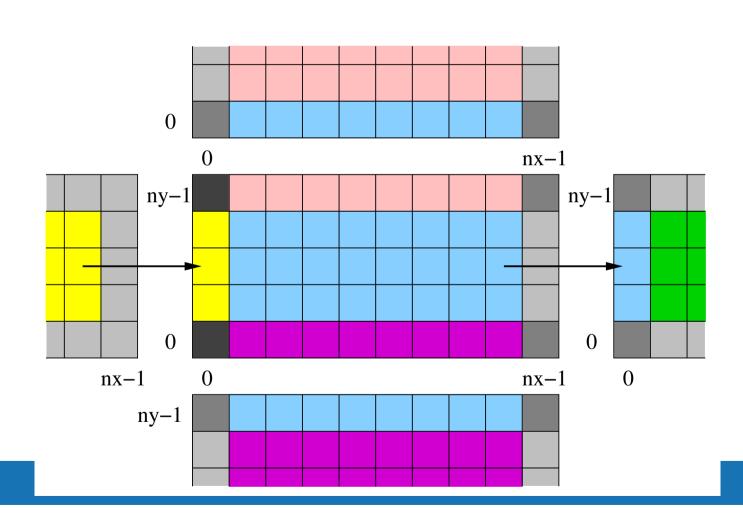
- An important class of applications that uses this data access patterns is the numerical solution of partial differential equations
- Programs are iterative and repeatedly update grid points with various "sweeps"
- Between each sweep, interior boundary data must be communicated
 - By dimension: first in x, then in y, etc...
 - Either non-blocking, or circular pattern of MPI Sendrecv



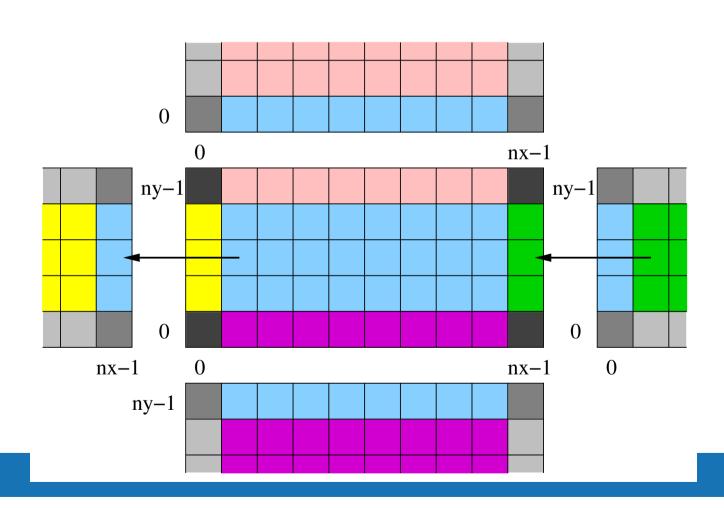










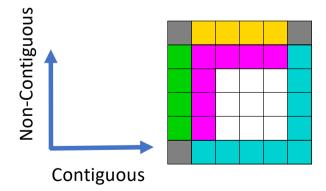




- Extends trivially to diagonal dependencies
- Extends trivially to periodic boundaries
- MPI_Sendrecv can be used with non-existent processes: MPI_PROC_NULL
 - If this is the destination, nothing is sent

Derived datatypes

- The MPI standard defines many built-in datatypes, mostly mirroring C/C++ and Fortran datatypes
- These are sufficient for sending single values or contiguous chunks
- Sometimes however we want to send non-contiguous data
 - E.g. 2D grid boundary





Derived Datatypes

- MPI provides ways of constructing datatypes to handle a wide variety of situations:
 - Contiguous
 - Vector, Hvector
 - Indexed, Hindexed
 - Indexed_block
 - Struct
- Routines marked with "H" differ from the others in that strides and block displacements are specified in bytes



Creating & using a new datatype

- Two steps are necessary to create and use a new datatype in MPI:
 - Create the type using one of MPI's type construction routines
 - Commit the type using MPI_Type_commit()
- Once a type has been committed, it may be used in send, receive and other buffer operations
- Can be released with MPI_Type_free()

Contiguous type

 The contiguous datatype allows for a single type to refer to multiple contiguous elements of an existing datatype

 Essentially an array of count elements having oldtype. The following two are equivalent:

```
MPI_Send(a, n, MPI_DOUBLE, dest, tag, MPI_COMM_WORLD);
MPI_Datatype rowtype;
MPI_Type_contiguous(n, MPI_DOUBLE, &rowtype);
MPI_Type_commit(&rowtype);
MPI_Send(a, 1, rowtype, dest, tag, MPI_COMM_WORLD);
```

Vector type

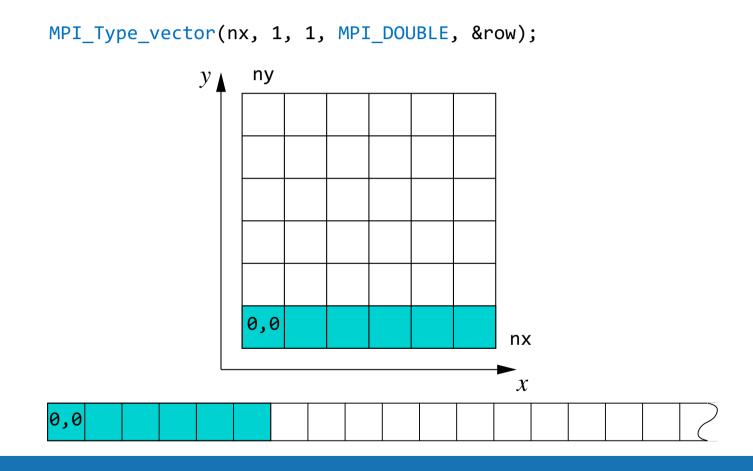
• Similar to the contiguous, but allows for a constant non-unit stride between

elements
 int MPI_Type_vector(

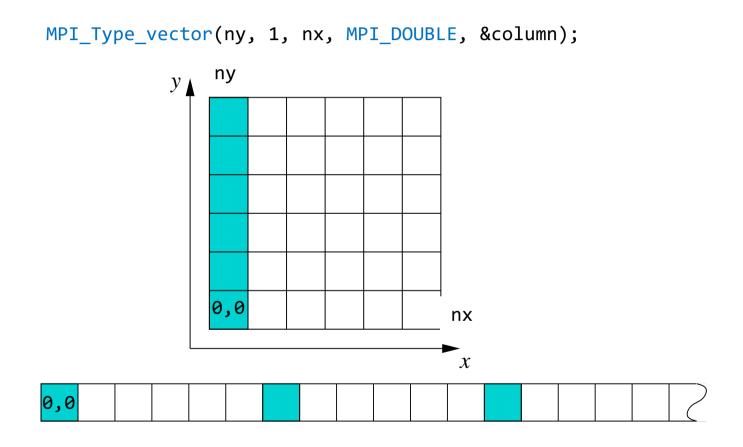
 For an nx * ny Cartesian grid is stored in a row-contiguous way, the we can define the following two:

```
MPI_Datatype row, column;
MPI_Type_vector(nx, 1, 1, MPI_DOUBLE, &row);
MPI_Type_vector(ny, 1, nx, MPI_DOUBLE, &column);
MPI_Type_commit(&row);
MPI_Type_commit(&column);
```

Vector type



Vector type



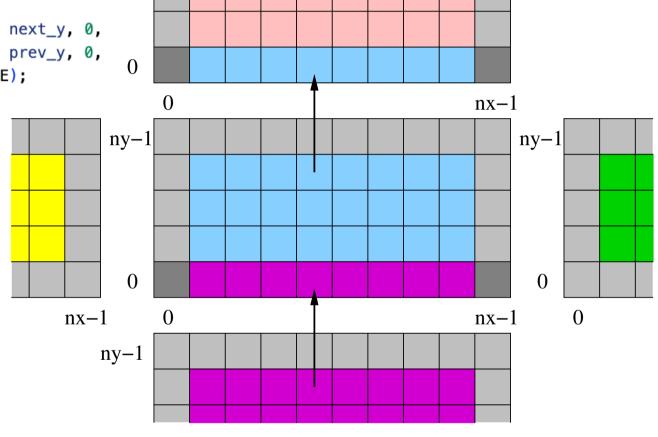
Indexed & Struct type

Indexed datatype provides for varying strides between elements

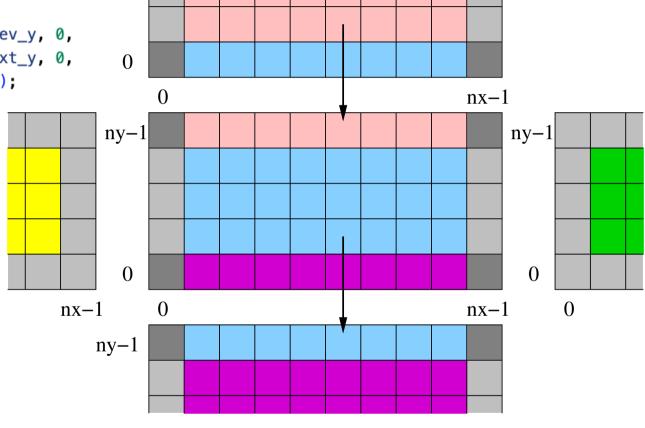
 Most general constructor allows for the creation of types representing general C/C++ structs/classes



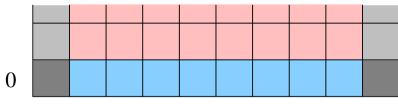
Send last-1 row up Receive into first row



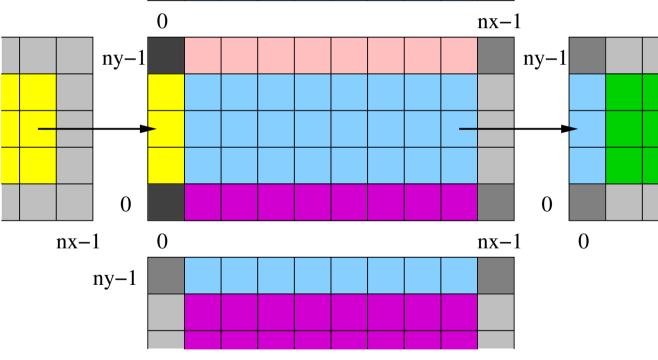
Send first row down Receive into last row



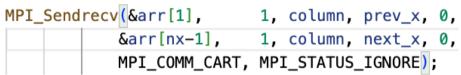




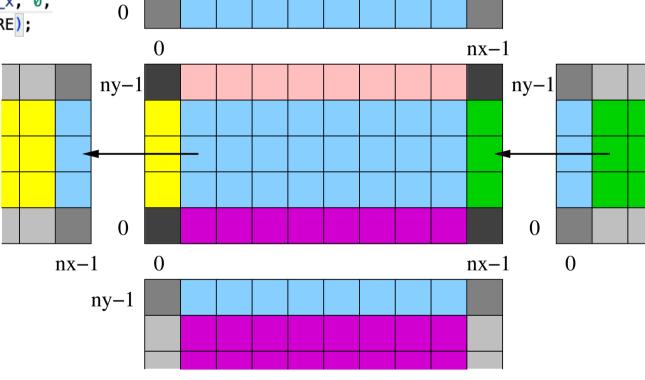
Send last-1 column right Receive into first column







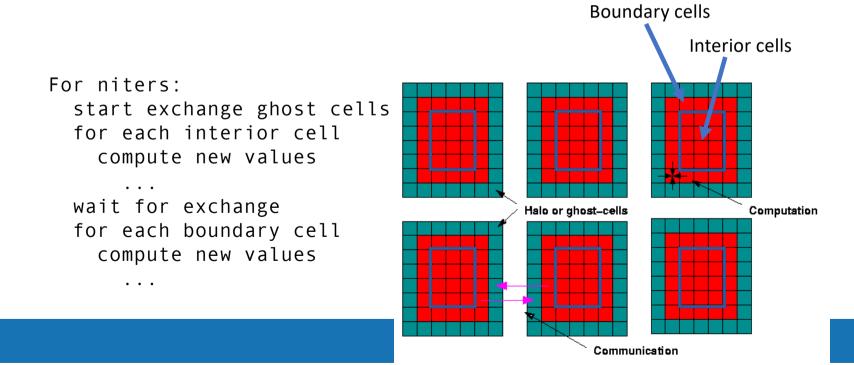
Send second column left Receive into last column





Non-blocking operations

• Some interior cells do not need the presence of updated ghost cells – let's use them to hide the latency of communications





Outlook – MPI 2 and 3

• MPI 2 standard

- Dynamic processes can remove and create new processes at runtime
- One-sided communications one-directional comms
- More collectives
- Parallel I/O

MPI 3 standard

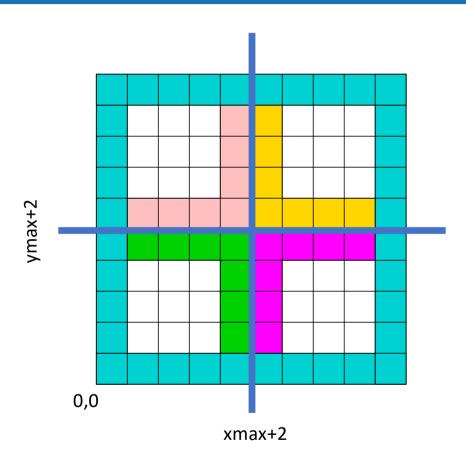
- Non-blocking collective operations
- More one-sided communications
- Neighbourhood collectives (for Cartesian and graph topologies)
- MPIT Tool Interface for profiling



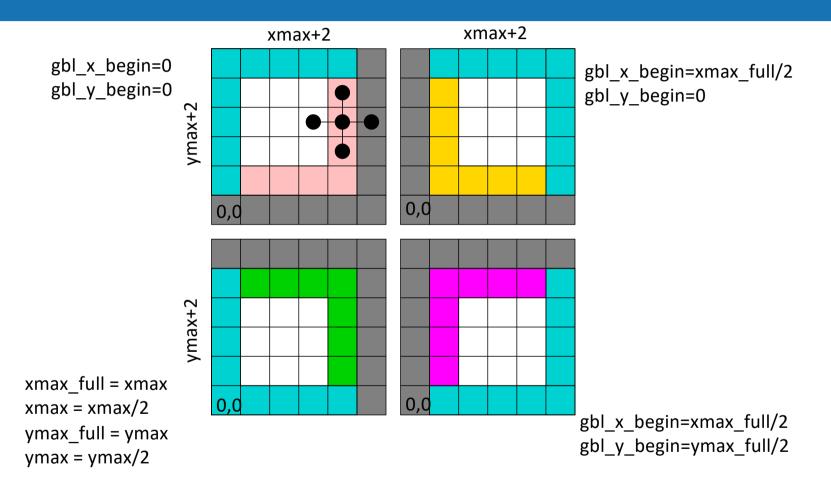
Exercise

- Laplace 2D convert the laplace.cpp example to use MPI, with any arbitrary number of processes
 - Use the mpi_laplace.h and mpi_laplace.cpp files to perform MPI initialization and communications

Exercise - solution



Exercise - solution





Homework – due apr 14 midnight

- Modify your homework to support MPI
 - Use lbm_d2q9.cpp from previous homework, commit to this lecture's repo
- Re-use our mpi_laplace.cpp and mpi_laplace.h
- Push results to assignment-5 repo!
- Things to keep in mind
 - Only need to work for square number of processes
 - See which loops require ghost cells, add the call to exchange right before
 - We use periodic boundaries here (rightmost process' right neighbour is the leftmost one)
 - Reduction...