## **CS4618: Artificial Intelligence I**

### **Deliberative Agents**

Derek Bridge School of Computer Science and Information Technology University College Cork

#### **Initialization**

#### In [3]:

```
%reload_ext autoreload
%autoreload 2
%matplotlib inline
```

#### In [4]:

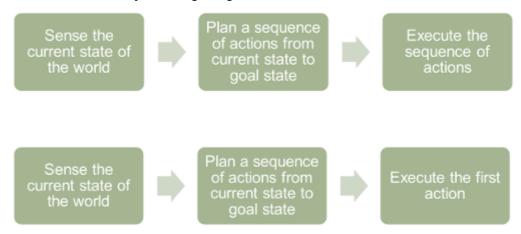
```
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
```

### Thinking ahead

- In the sense-plan-act cycle, the plan phase should generally be more deliberative
- Thinking ahead is a form of simulation
  - Trying out actions on a mental representation prior to executing the actions in the actual world
- Class exercise: Give precise reasons why thinking ahead is advantageous: what can go wrong if you don't think ahead?
- Class exercise: Are there times when thinking ahead is disadvantageous: what can go wrong if you do think ahead?

### **Planning sequences of actions**

- · Often, the agent will plan whole sequences of actions
- But, there are at least two ways of integrating this with execution:



 Class exercise: The second approach appears to be wasteful. But the first approach is suitable only for certain environments. What kinds of environments?

### **State space**

- · We implement deliberation (thinking ahead) as a form of search through a directed graph
- State space:
  - all states reachable by sequences of actions from some start state
- · Represented by a directed graph in which
  - nodes represent states of the world
  - edges represent actions (state transformations)
- The task is to find a path from the node labelled by the start state to one of the nodes labelled by goal states

#### **State space**

- In AI, the graph may be too large to specify and store explicitly
- Instead, specify it implicitly:
  - The start state
  - The set of operators for transforming states to other states
  - The goal condition that can detect whether a state is a goal state
- There can also be a path cost function, g

### The 8-puzzle

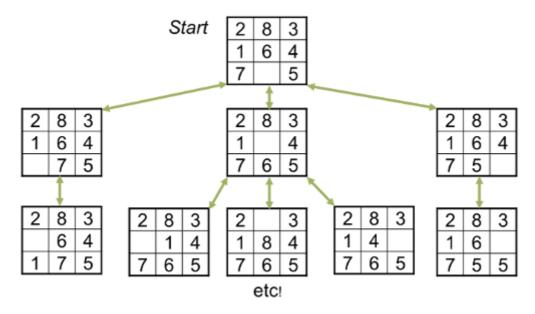
- Sliding 8 numbered tiles around a  $3 \times 3$  grid
- How to represent the states:
  - $3 \times 3$  array of integers
- Start state, e.g.:

2	8	3
1	6	4
7		5

- · Operators:
  - If blank is not leftmost, move it left by 1
  - If blank is not uppermost, move it up by 1
  - Etc.
- · Goal state, e.g.:



## 8-puzzle state space



• This state space has 9! = 362,800 states

### The water jugs problem

- A 4-gallon jug and 3-gallon jug with no measuring markers, and a tap
- · Must get exactly 2 gallons into the 4-gallon jug
- Representation of states
  - Pair of integers,  $\langle x, y \rangle$
  - x is the amount of water in the 4-gallon jug,  $x \in \{0, 1, 2, 3, 4\}$
  - y is the amount of water in the 3-gallon jug,  $y \in \{0, 1, 2, 3\}$
- Start state:  $\langle 0,0 \rangle$
- Goal state:  $\langle 2, n \rangle$

### The water jugs operators

```
1. If x < 4 then \langle 4, y \rangle
```

2. If 
$$y < 3$$
 then  $\langle x, 3 \rangle$ 

3. If 
$$x > 0$$
 then  $\langle 0, y \rangle$ 

4. If 
$$y > 0$$
 then  $\langle x, 0 \rangle$ 

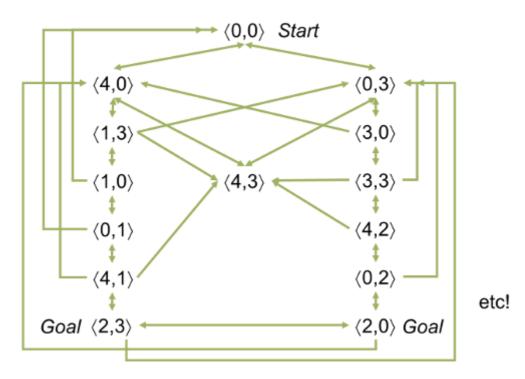
5. If 
$$x + y \ge 4$$
 then  $(4, y - (4 - x))$ 

6. If 
$$x + y \ge 3$$
 then  $(x - (3 - y), 3)$ 

7. If 
$$x + y \le 4 \land y > 0$$
 then  $\langle x + y, 0 \rangle$ 

8. If 
$$x + y \le 3 \land x > 0$$
 then  $\langle 0, x + y \rangle$ 

### The water jugs state space



# **Applications of state space search**

- Route planning
- Pathfinding in games
- Cargo loading
- Automatic assembly

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