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COMP. MATH - L3
                                                    p' = Ap = A(p, e+p, j)
= Ap. i + Ap. j
= p, Ai + p. Aj
                          Ai = A(0) = a;, i.e. to first ool.

Aj = a:: i.e. the and only
                                                                                             P'= AP = P, a:1 + P2 a:2
                                  Shor comple A = (1)
                                          A y = \lambda y

A y = \lambda y

A y - \lambda y = 0

A y - \lambda y = 
                                                  e.j. A = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}
                                                    I want let (A- >I) =0
                                      0 = \left| \begin{pmatrix} 1 & 3 \\ 3 & 1 \end{pmatrix} - \lambda \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right|
                                                  = (3-2)2-1
                                                    = 9-62+22-1
                                                             = 22-62+8
                                                      = (2-4)(2-3)
        =) \lambda = 4 or \lambda = 2
>,=4: (A->,I)y = 0
                                          \Rightarrow \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} V_1 \\ V_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}
                                          \Rightarrow \begin{cases} -V_1 + V_L = 0 \\ V_1 - V_L = 0 \end{cases}
e \cdot J \quad Y = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{is } \underbrace{A}_{1} \cdot \underbrace{S_0}_{1} 
                                                             Y = (MR) is the normalized to
                                                                       Q, Y, + α, Y, + α, Y, = 0
                                                                                                                                    this happy does not a sola exto
                                                          (=) \qquad \underline{V}_{\nu} = \frac{1}{2} \left( (\times_{1} \times_{1} + (\times_{2} \times_{3})) \right)
                                                                                                                                    A = PAP-
                                                                                                                     \Leftrightarrow p^{\mathsf{T}} A p = p^{\mathsf{T}} p \Lambda p^{\mathsf{T}} p= I \Lambda J = \Lambda
                                                                                                                                    PAPT of. AbAAST
                                                                                                                 A = \begin{pmatrix} 3 & 1 \\ 1 & 7 \end{pmatrix} \qquad \lambda_1 = \theta \quad \chi_1 = \begin{pmatrix} 1/27 \\ 1/27 \end{pmatrix}
\lambda_1 = 1 \quad \chi_2 = \begin{pmatrix} 1/27 \\ 1/27 \end{pmatrix}
A = \begin{pmatrix} 1/27 & -1/47 \\ 1/27 & 1/27 \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1/27 & 1/27 \\ 1/27 & 1/27 \end{pmatrix}
A = \begin{pmatrix} 1/27 & -1/47 \\ 1/27 & 1/27 \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1/27 & 1/27 \\ 1/27 & 1/27 \end{pmatrix}
                                                                                                   S. ~ A P (=) PAPT P
                                                                                                                                                                    dx = f(+,>)
                                                                                                                                                                              dx = Ax
                                                                                                                                      Scalar das = ax
                                                                                                                                                            => x, (t) = C e **
                                                                                                                                Vector can \frac{dx}{dt} = Ax
                                                                                                                                                                  =) x = cxp(+A) =
                                                                                                                                    Above: A = PAPA
                                                                                                                   No. A = QAQT

No. A = QEV

Not the same note:
Not good to the good
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