

CPEN 305 – Reference Sheet

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Enable internal pull-ups on PORTB pins

---| RB0
---| RB1
---| RB2
---| RB3
---| RB4
---| RB5
---| RB6
---| RB7

```
INTCON2bits.RBPU = 0;
```

Classical (non-flag) way to handle push buttons

GND --- BTN -----| RB0
---| RB1
---| RB2
---| RB3
---| RB4
---| RB5
---| RB6
---| RB7

```
while(1) {  
    if(PORTBbits.RB0) {  
        ...  
        while(PORTBbits.RB0);  
    }  
}  
  
while(1) { //If BTN is pulled-up  
    if(!PORTBbits.RB0) {  
        ...  
        while(!PORTBbits.RB0);  
    }  
}
```

INTxIF - Pin Edge Flags

Affected pins

---| RB0, INT0IF
---| RB1, INT1IF
---| RB2, INT2IF

Flags referencing

INT0IF ==> INTCONbits.INT0IF
INT1IF ==> INTCON3bits.INT1IF
INT2IF ==> INTCON3bits.INT2IF

Configure pin edge flags to react on falling edge

1 -----
|
----- 0 INTEDGx = 0

```
INTCON2bits.INTEDG0 = 0;  
INTCON2bits.INTEDG1 = 0;  
INTCON2bits.INTEDG2 = 0;
```

Polling mode usage example

```
while(1) {  
    if(INTCONbits.INT0IF) {  
        INTCONbits.INT0IF = 0;  
        ...  
    }  
}
```

Configure pin edge flags to react on rising edge

----- 1
|
0 ----- INTEDGx = 1

```
INTCON2bits.INTEDG0 = 1;  
INTCON2bits.INTEDG1 = 1;  
INTCON2bits.INTEDG2 = 1;
```

Interrupt mode usage example

```
#pragma code ISR = 0x0008  
#pragma interrupt ISR  
  
void ISR(void)  
{  
    INTCONbits.INT0IF = 0;  
    ...  
}
```

Configure pin edge flags to run in interrupt mode

```
INTCONbits.GIE = 1;  
INTCONbits.INT0IE = 1;  
INTCON3bits.INT1IE = 1;  
INTCON3bits.INT2IE = 1;
```

RBIF - Pin Change Flag

Affected pins

---| RB4
---| RB5
---| RB6
---| RB7

Polling mode example

```
while(1) {  
    if(INTCONbits.RBIF) {  
        PORTB = PORTB;  
        INTCONbits.RBIF = 0;  
        ...  
    }  
}
```

Flag referencing

RBIF ==> INTCONbits.RBIF

Configure pin change flag to run in interrupt mode

```
INTCONbits.GIE = 1  
INTCONbits.RBIE = 1
```

Interrupt mode usage example

```
#pragma code ISR = 0x0008  
#pragma interrupt ISR  
  
void ISR(void)  
{  
    PORTB = PORTB;  
    INTCONbits.RBIF = 0;  
    ...  
}
```

Timer 0 Configuration register – T0CON

Register	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
T0CON	TMR0ON	T08BIT	T0CS	T0SE	PSA	TOPS2	TOPS1	TOPS0

Bit 7	TMR0ON: Timer0 On/Off Control bit 1 = Enables Timer0 0 = Stops Timer0
Bit 6	T08BIT: Timer0 8-Bit/16-Bit Control bit 1 = Timer0 is configured as an 8-bit timer/counter 0 = Timer0 is configured as a 16-bit timer/counter
Bit 5	T0CS: Timer0 Clock Source Select bit 1 = Transition on T0CKI pin 0 = Internal instruction cycle clock (CLKOUT)
Bit 4	T0SE: Timer0 Source Edge Select bit 1 = Increment on high-to-low transition on T0CKI pin 0 = Increment on low-to-high transition on T0CKI pin
Bit 3	PSA: Timer0 Prescaler Assignment bit 1 = Timer0 prescaler is not assigned. Timer0 clock input bypasses prescaler. 0 = Timer0 prescaler is assigned. Timer0 clock input comes from prescaler output.
Bit 2-0	T0PS<2:0>: Timer0 Prescaler Select bits 111 = 1:256 Prescale value 110 = 1:128 Prescale value 101 = 1:64 Prescale value 100 = 1:32 Prescale value 011 = 1:16 Prescale value 010 = 1:8 Prescale value 001 = 1:4 Prescale value 000 = 1:2 Prescale value

Polling mode usage example

```
while(1) {
    if(INTCONbits.TMR0IF) {
        INTCONbits.TMR0IF = 0;
        TMR0H = (65536 - n) / 256;
        TMR0L = (65536 - n) % 256;
        ...
    }
}
```

Interrupt mode usage example

```
#pragma code ISR = 0x0008
#pragma interrupt ISR

void ISR(void)
{
    INTCONbits.TMR0IF = 0;
    TMR0H = (65536 - n) / 256;
    TMR0L = (65536 - n) % 256;
    ...
}
```

Configure Timer 0 to run in interrupt mode

```
INTCONbits.GIE = 1;
INTCONbits.TMR0IE = 1;
```