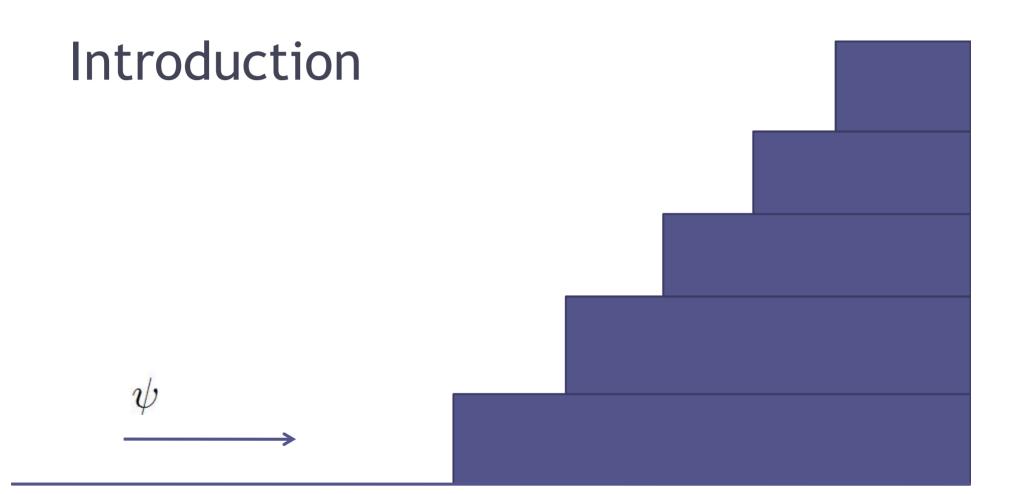
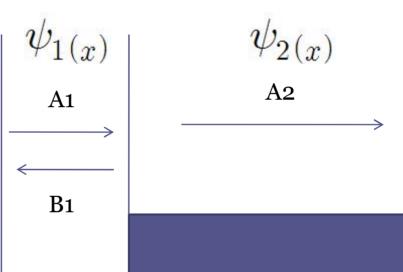
Transfer Matrix Approach for the 1-dim Schrödinger equation



Dividing Regions

$$\psi_{0(x)}$$
 Ao \longrightarrow Bo \leftarrow

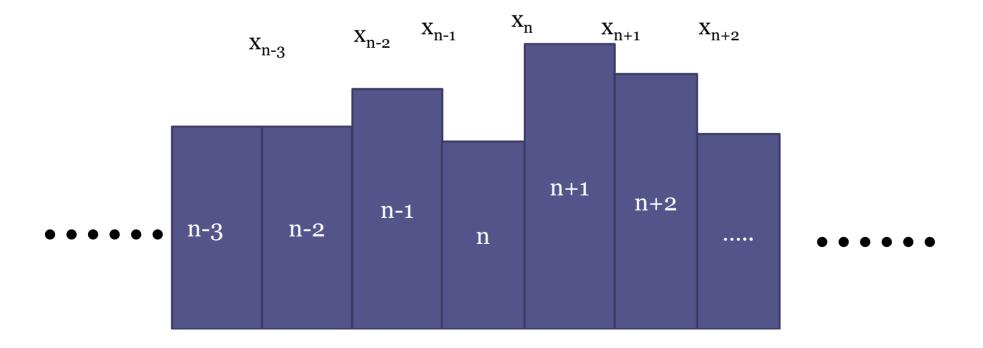


$$\begin{bmatrix} \psi_0(x_0) \\ \psi_0(x_0) \end{bmatrix} = \begin{bmatrix} \psi_1(x_0) \\ \psi_1(x_0) \end{bmatrix} \qquad \begin{bmatrix} \psi_1(x_1) \\ \psi_1(x_1) \end{bmatrix} = \begin{bmatrix} \psi_2(x_2) \\ \psi_2(x_2) \end{bmatrix}$$

 V_{1}

Boundary Condition

$$\begin{bmatrix} \psi_n(x_n) \\ \psi'_n(x_n) \end{bmatrix} = \begin{bmatrix} \psi_{n+1}(x_n) \\ \psi'_{n+1}(x_n) \end{bmatrix}$$



Time-Independent 1-dim Shcrödinger Equation

$$[\frac{\hat{p}^2}{2m} + V]\psi(x) = E\psi(x)$$
 (V is constant)
$$\psi(x) = Ae^{ikx} + Be^{-ikx}$$

$$\frac{d\psi(x)}{dx} = ikAe^{ikx} - ikBe^{-ikx}$$

$$k = \sqrt{E-V}$$

$$\begin{bmatrix} \psi(x) \\ \psi'(x) \end{bmatrix} = \begin{bmatrix} e^{ikx} & e^{-ikx} \\ ke^{ikx} - ke^{-ikx} \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix}$$

Transfer Matrix

$$\begin{bmatrix} \psi_n(x_n) \\ \psi'_n(x_n) \end{bmatrix} = \begin{bmatrix} \psi_{n+1}(x_n) \\ \psi'_{n+1}(x_n) \end{bmatrix}$$

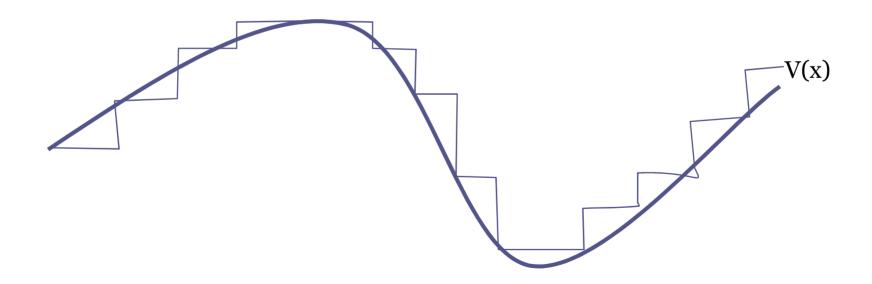
$$\begin{bmatrix} \psi(x_n) \\ \psi'(x_n) \end{bmatrix} = \begin{bmatrix} e^{ik_n x_n} & e^{-ik_n x_n} \\ k_n e^{ik_n x_n} - \mathrm{i}k_n e^{-ik_n x_n} \end{bmatrix} \begin{bmatrix} A_n \\ B_n \end{bmatrix} = \begin{bmatrix} e^{ik_{n+1} x_n} & e^{-ik_{n+1} x_n} \\ k_{n+1} e^{ik_{n+1} x_n} - \mathrm{i}k_{n+1} e^{-ik_{n+1} x_n} \end{bmatrix} \begin{bmatrix} A_{n+1} \\ B_{n+1} \end{bmatrix}$$

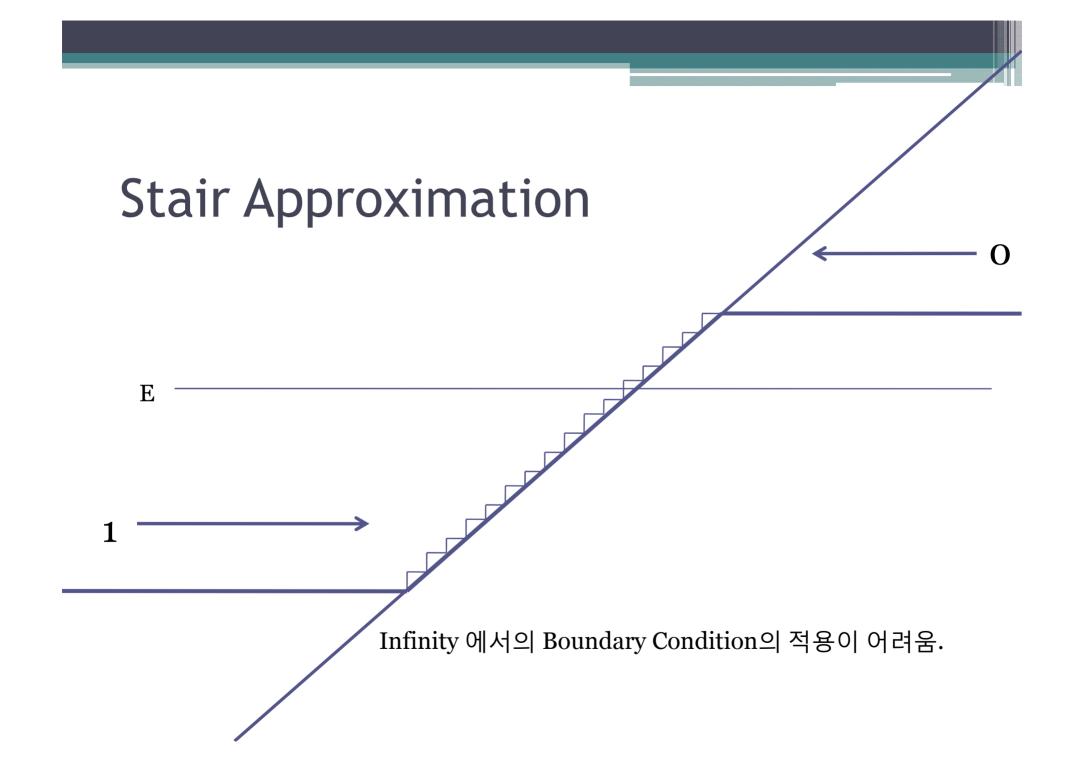
$$\begin{bmatrix} A_{n+1} \\ B_{n+1} \end{bmatrix} = \begin{bmatrix} \frac{k_{n+1} + k_n}{2k_{n+1}} e^{i(k_n - k_{n+1})x_n} \frac{k_{n+1} - k_n}{2k_{n+1}} e^{i(-k_n - k_{n+1})x_n} \\ \frac{k_{n+1} - k_n}{2k_{n+1}} e^{i(k_n + k_{n+1})x_n} \frac{k_{n+1} + k_n}{2k_{n+1}} e^{i(-k_n + k_{n+1})x_n} \end{bmatrix} \begin{bmatrix} A_n \\ B_n \end{bmatrix}$$

$$\begin{bmatrix} A_{n+1} \\ B_{n+1} \end{bmatrix} = M_{n+1,n} \begin{bmatrix} A_n \\ B_n \end{bmatrix}$$

Application

$$\begin{bmatrix} A_n \\ B_n \end{bmatrix} = M_{n,n-1} M_{n-1,n-2} \dots M_{4,3} M_{3,2} M_{2,1} M_{1,0} \begin{bmatrix} A_0 \\ B_0 \end{bmatrix}$$





Note that, $M_{n+1,n}^{-1} = M_{n,n+1}$

$$\begin{bmatrix} A_n \\ B_n \end{bmatrix} = M_{n,n-1} M_{n-1,n-2} M_{4,3} M_{3,2} M_{2,1} M_{1,0} \begin{bmatrix} A_0 \\ B_0 \end{bmatrix}$$

E가 V(x) 보다 작아지기 시작하는 점에서는

$$k = \sqrt{E - V} = i\kappa$$

$$\psi(x) = Ae^{-\kappa x} + Be^{+\kappa x}$$

발산하는 두번째 항은 nonphysical, zero

이때가 n=N일 때라 하면

$$\begin{bmatrix} A_N \\ B_N \end{bmatrix} = M_{N,N-1} M_{N-1,N-2} \dots M_{4,3} M_{3,2} M_{2,1} M_{1,0} \begin{bmatrix} A_0 \\ B_0 \end{bmatrix}$$

$$\begin{bmatrix} A_N \\ B_N \end{bmatrix} = \begin{bmatrix} q_{11} \ q_{12} \\ q_{21} \ q_{22} \end{bmatrix} \begin{bmatrix} A_0 \\ B_0 \end{bmatrix}$$

 $egin{array}{c|c} A_N \ B_N \ \end{array} = egin{array}{c|c} q_{11} \, q_{12} \ q_{23} \, q_{23} \ \end{array} egin{array}{c|c} A_0 \ R_0 \ \end{array}$ 왼쪽에서 오른쪽으로 지속적으로 펄스가 공급되는 경우를

Infinity 에서의 Boundary Condition으로 정하면

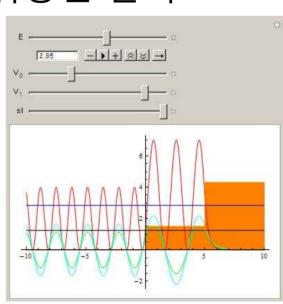
$$\begin{bmatrix} T \\ 0 \end{bmatrix} = \begin{bmatrix} q_{11} & q_{12} \\ q_{21} & q_{22} \end{bmatrix} \begin{bmatrix} 1 \\ R \end{bmatrix} \qquad R = -\frac{q_{21}}{q_{22}} \qquad T = q_{11} - q_{12} \frac{q_{21}}{q_{22}}$$

$$\begin{bmatrix} A_n \\ B_n \end{bmatrix} = M_{n,n-1} M_{n-1,n-2} \dots M_{4,3} M_{3,2} M_{2,1} M_{1,0} \begin{bmatrix} 1 \\ -\frac{q_{21}}{q_{22}} \end{bmatrix}$$

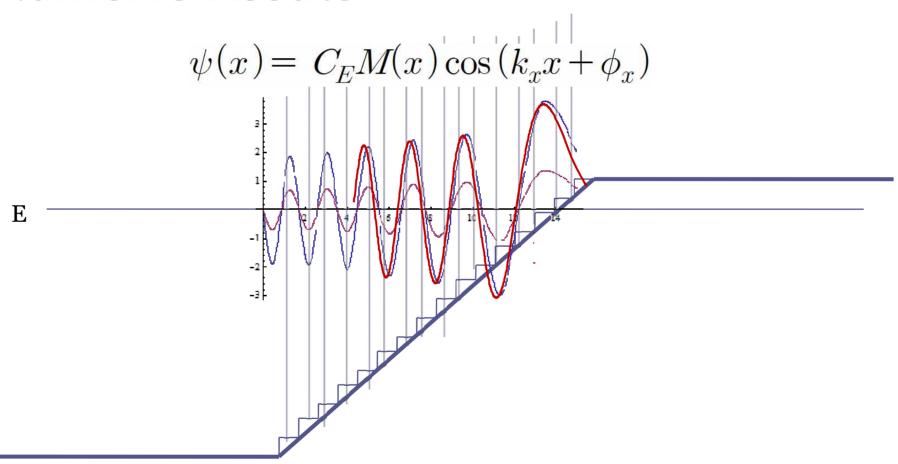
두 개의 step이 있는 경우

- 윗계단에서의 amplitude가 아랫계단에서의 amplitude보다 항상 크거나 같다.
- 실수부와 허수부의 진폭은 다르나 위상은 같다.
 - -> Standing Wave

$$(a+bi)\cos(kx+\phi)$$



Numeric Result



Not suitable cases

급격하게 변화하는 포탠셜

- -> 단위 barrier의 폭을 무한소로 보낼 필요
- -> 무한번의 연산이 필요
- -> 기계적 오차 누적, 증가

Time-Dependent solution

• Eigenfunction : standing wave, Time-independent solution 에서 진폭만 변한다.