$$t_{1} = \mathcal{M}_{1} P_{1} t = \begin{pmatrix} \frac{1}{10} & 0 & 0 \\ \frac{1}{10} & 1 & 0 \\ \frac{1}{10} & 1 & 0 \\ \frac{1}{10} & 0 & 1 \end{pmatrix} \begin{pmatrix} 10 & 0 & 3 \\ 3 & -1 & 0 \\ -2 & 1 & 1 \end{pmatrix} \begin{pmatrix} 7 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0.3 \\ 0 & -1 & -0.9 \\ 0 & 9 & 1.6 \end{pmatrix} \begin{pmatrix} 0.7 \\ -0.1 \\ 2.7 \end{pmatrix}$$

$$P_{2} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}; P_{2} t_{1} = \begin{pmatrix} 1 & 0 & 0.3 & 0.4 \\ 0 & 1 & 1.5 & 2.4 \\ 0 & -1 & -0.9 & -0.1 \end{pmatrix}$$

$$\mathcal{M}_{2} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{4} & 0 \\ 0 & \frac{1}{4} & 1 \end{pmatrix} \qquad \qquad \\ \mathcal{L}_{3} = \mathcal{M}_{2} \mathcal{P}_{3} \mathcal{L}_{4} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{4} & 0 \\ 0 & \frac{1}{4} & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0.3 & 0.3 & 0.3 \\ 0 & 1 & 0.3 & 0.6 \\ 0 & -0.5 & 0.6 \end{pmatrix}$$

$$M_3 = \begin{pmatrix} 10 & 6 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$
; $P_3 = E_j$

$$M_3 = \begin{pmatrix} 10 & 6 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$
; $P_3 = E_3$ $A_4 = M_3 P_3 A_3 = \begin{pmatrix} 1 & 0 & 0.3 \\ 0 & 1 & 0.4 \\ 0 & 0 & 1 \end{pmatrix}$

$$X_{3} = -7$$

$$X_{7} = 0.6 - (-1) \cdot 0.4 = 1$$

$$X_{7} = 1$$

2)
$$E_2 = M_2 \cdot P_2 \cdot M_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{7} & 0 \\ 0 & +\frac{1}{4} & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{70} & 0 & 0 \\ +\frac{1}{70} & 0 & 1 \\ -\frac{3}{40} & 1 & 0 \end{pmatrix} = \begin{pmatrix} 21 & 0 & 0 \\ \frac{1}{20} & 0 & \frac{1}{4} \\ -\frac{1}{4} & 1 & \frac{1}{4} \end{pmatrix}$$

3)
$$E_{3} = M_{3} \cdot P_{3} \cdot E_{2} = \begin{pmatrix} 10 & 6 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 21 & 0 & 0 \\ \frac{1}{20} & 0 & \frac{1}{4} \\ \frac{1}{2} & \frac{1}{4} & \frac{1}{4} \end{pmatrix} = \begin{pmatrix} 0.1 & 0 & 0 \\ \frac{1}{20} & 0 & \frac{1}{4} \\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \end{pmatrix} = \widetilde{E}.$$

$$A_{-1} = X = \{x_i\}$$

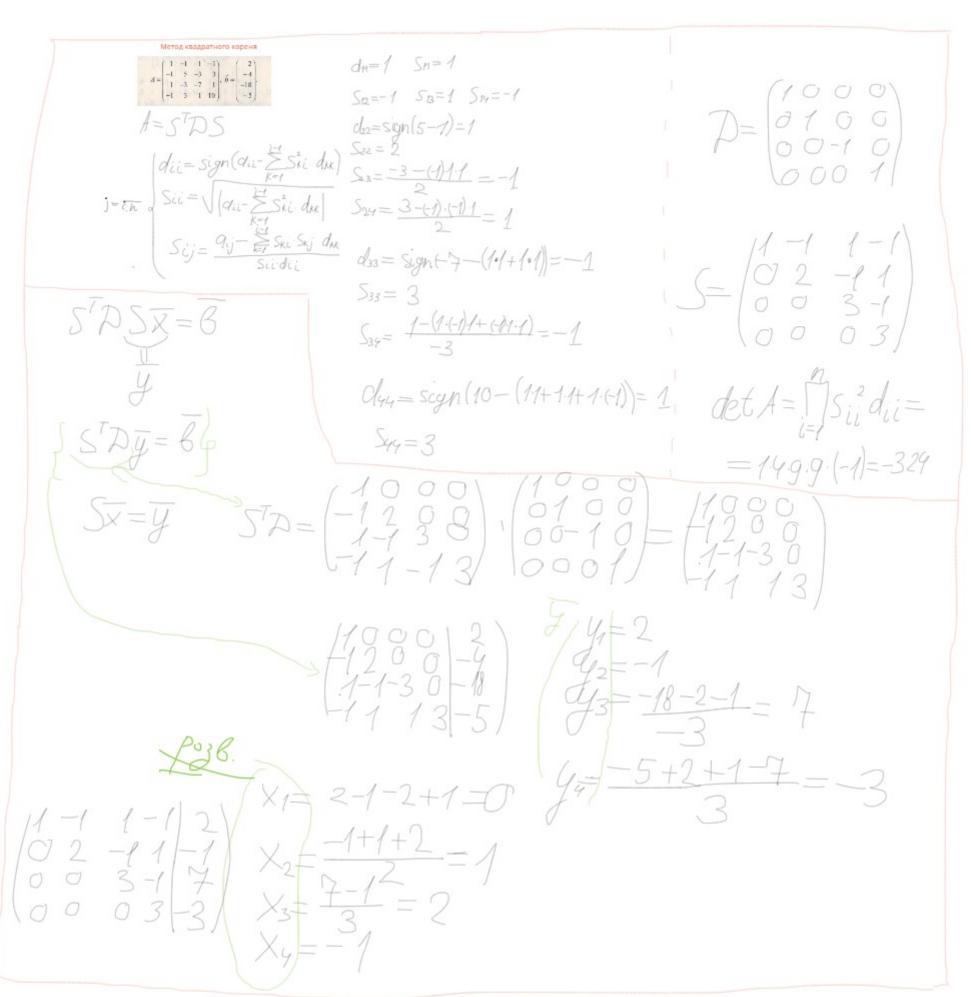
$$A^{-1} = X = \{x_i\}$$

$$A_{ij} = \{x_i\}$$

$$\widetilde{E} = \{\widehat{e}_{\delta}\}_{\delta=1}^{3}$$

$$A = \delta N$$

miro



$$S^{T}D \cdot S \cdot X_{j} = \overline{e_{j}}$$

$$\frac{11}{y_{j}}$$

$$S^{T}D \cdot y_{j} = \overline{e_{j}}$$

$$Sx_{j} = \overline{y_{j}}$$

$$A^{-1} = \{x_{j}\}_{j=1}^{n}$$

$$n = 3$$