ARE 213 PS 2a

S. Sung, H. Husain, T. Woolley, A. Watt

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Contents

| Packages | 1 |
|--|--|
| Problem 1 Part (a) | |
| Problem 2 Part (a) Part (b) Part (c) | 7 |
| Problem 3 Part (a) Part (b) Part (c) Part (d) Part (e) Part (f) Part (g) Part (h) Part (i) Part (j) | 12 13 13 13 13 14 14 14 |
| Packages | |

library(haven)
library(foreign)
library(tinytex)
library(stargazer)
library(plm)
library(lmtest)
library(sandwich)
library(tidyverse)

Problem 1

Question 10.3 from Wooldridge: For T=2 consider the standard unobserved effects model:

$$y_{it} = \alpha + x_{it}\beta + c_i + u_{it} \tag{1}$$

Let $\hat{\beta}_{FE}$ and $\hat{\beta}_{FD}$ represent the fixed effects and first differences estimators respectively.

Part (a)

Show that $\hat{\beta}_{FE}$ and $\hat{\beta}_{FD}$ are numerically identical. Hint: it may be easier to write $\hat{\beta}_{FE}$ as the "within estimator" rather than the fixed effects estimator.

Writing $\hat{\beta}_{FE}$ as the within estimator, $\hat{\beta}_{FE}$ and $\hat{\beta}_{FD}$ are given by

$$\hat{\beta}_{FD} = (\Delta X' \Delta X)^{-1} (\Delta X' \Delta y)$$
 and $\hat{\beta}_{FE} = (\ddot{X}' \ddot{X})^{-1} (\ddot{X}' \ddot{y})$

Expanding the inner products, we have

$$\hat{\beta}_{FD} = \left(\sum_{i} \sum_{t} \Delta X'_{it} \Delta X_{it}\right)^{-1} \left(\sum_{i} \sum_{t} \Delta X'_{it} \Delta y_{it}\right)$$

and

$$\hat{\beta}_{FE} = \left(\sum_{i} \sum_{t} \ddot{X}'_{it} \ddot{X}_{it}\right)^{-1} \left(\sum_{i} \sum_{t} \ddot{X}'_{it} \ddot{y}_{it}\right)$$

Since there are only two periods, $\hat{\beta}_{FD}$ simplifies to

$$\hat{\beta}_{FD} = \left(\sum_{i} \Delta X_{i}' \Delta X_{i}\right)^{-1} \left(\sum_{i} \Delta X_{i}' \Delta y_{i}\right)$$

where

$$\Delta X_i \equiv X_{i2} - X_{i1}$$
 and $\Delta y_i \equiv y_{i2} - y_{i1}$

Now we note that

$$\ddot{X}_{i1} = X_{i1} - \frac{1}{2}(X_{i1} + X_{i2}) = \frac{1}{2}(X_{i1} - X_{i2}) = -\frac{1}{2}\Delta X_i$$

and similarly

$$\ddot{X}_{i2} = \frac{1}{2}\Delta X_i, \quad \ddot{y}_{i1} = -\frac{1}{2}\Delta y_i \quad \ddot{y}_{i2} = \frac{1}{2}\Delta y_i$$

Then, $\hat{\beta}_{FE}$ becomes

$$\begin{split} \hat{\beta}_{FE} &= \left(\sum_{i} \sum_{t} \ddot{X}'_{it} \ddot{X}_{it}\right)^{-1} \left(\sum_{i} \sum_{t} \ddot{X}'_{it} \ddot{y}_{it}\right) \\ &= \left(\sum_{i} \frac{1}{4} \Delta X'_{i} \Delta X_{i} + \frac{1}{4} \Delta X'_{i} \Delta X_{i}\right)^{-1} \left(\sum_{i} \frac{1}{4} \Delta X'_{i} \Delta y_{i} + \frac{1}{4} \Delta X'_{i} \Delta y_{i}\right) \\ &= \left(\frac{1}{2} \sum_{i} \Delta X'_{i} \Delta X_{i}\right)^{-1} \left(\frac{1}{2} \sum_{i} \Delta X'_{i} \Delta y_{i}\right) \\ &= \left(\sum_{i} \Delta X'_{i} \Delta X_{i}\right)^{-1} \left(\sum_{i} \Delta X'_{i} \Delta y_{i}\right) \\ &= \hat{\beta}_{FD} \end{split}$$

So $\hat{\beta}_{FE}$ and $\hat{\beta}_{FD}$ are numerically identical.

Part (b)

Show that the standard errors of $\hat{\beta}_{FE}$ and $\hat{\beta}_{FD}$ are numerically identical. If you wish, you may assume that x_{it} is a scalar (i.e. there is only one regressor) and ignore any degree of freedom corrections. You are not clustering the standard errors in this problem.

The standard errors are estimates of the square root of the asymptotic variances of our estimators, so WLOG, we can compare the asymptotic variances. The asymptotic variances of our estimators are

$$\widehat{Avar(\hat{\beta}_{FE})} = \hat{\sigma}_{u,FE}^2 \left(\ddot{X}'\ddot{X}\right)^{-1}$$
 and $\widehat{Avar(\hat{\beta}_{FE})} = \hat{\sigma}_{u,FD}^2 \left(\Delta X'\Delta X\right)^{-1}$

where $\hat{\sigma}_{u,FE}^2$ and $\hat{\sigma}_{u,FD}^2$ are estimated from the residuals of the corresponding regressions and using the correct degrees of freedom:

$$\hat{\sigma}_{u,FE}^2 = \frac{\sum\limits_{i}\sum\limits_{t}\widehat{\vec{u}}_{it}^2}{N(T-1)-K} = \frac{\sum\limits_{i}\sum\limits_{t}\widehat{\vec{u}}_{it}^2}{N-K} \qquad \text{and} \qquad \hat{\sigma}_{u,FD}^2 = \frac{\sum\limits_{i}\widehat{\Delta u}_i^2}{N(T-1)-K} = \frac{\sum\limits_{i}\widehat{\Delta u}_i^2}{N-K}$$

Let $\hat{\beta} := \hat{\beta}_{FD} = \hat{\beta}_{FE}$. Then, from part (a), we can find the relationship between $\widehat{\Delta u}_i$ and \widehat{u}_{it} :

$$\begin{split} \widehat{\boldsymbol{u}}_{it}^2 &= (\ddot{y}_{it} - \ddot{X}_{it} \widehat{\boldsymbol{\beta}})^2 \\ &= \left((-1)^t \left(\frac{1}{2} \Delta y_i - \frac{1}{2} \Delta X_i \widehat{\boldsymbol{\beta}} \right) \right)^2 \\ &= \frac{1}{4} \left(\Delta y_i - \Delta X_i \widehat{\boldsymbol{\beta}} \right)^2 \\ &= \frac{1}{4} \widehat{\Delta u}_i^2 \end{split}$$

So the estimated error variances are related by

$$\begin{split} \hat{\sigma}_{u,FE}^2 &= \frac{\sum\limits_{i}\sum\limits_{t}\widehat{u}_{it}^2}{N-K} \\ &= \frac{\sum\limits_{i}\sum\limits_{t}\frac{1}{4}\widehat{\Delta u}_{i}^2}{N-K} \\ &= \frac{\sum\limits_{i}\frac{1}{2}\widehat{\Delta u}_{i}^2}{N-K} \\ &= \frac{1}{2}\frac{\sum\limits_{i}\widehat{\Delta u}_{i}^2}{N-K} \\ &= \frac{1}{2}\hat{\sigma}_{u,FD}^2 \end{split}$$

We know from part (a) that

$$\left(\sum_{i}\sum_{t}\ddot{X}'_{it}\ddot{X}_{it}\right)^{-1} = \left(\frac{1}{2}\sum_{i}\Delta X'_{i}\Delta X_{i}\right)^{-1}$$
$$= 2\left(\sum_{i}\Delta X'_{i}\Delta X_{i}\right)^{-1}$$

And putting all these together, we have

$$\begin{split} \widehat{Avar(\hat{\beta}_{FE})} &= \hat{\sigma}_{u,FE}^2 \left(\ddot{X}' \ddot{X} \right)^{-1} \\ &= \frac{1}{2} \hat{\sigma}_{u,FD}^2 2 \left(\sum_i \Delta X_i' \Delta X_i \right)^{-1} \\ &= \hat{\sigma}_{u,FD}^2 \left(\sum_i \Delta X_i' \Delta X_i \right)^{-1} \\ &= \widehat{Avar(\hat{\beta}_{FE})} \end{split}$$

Because the estimates of the asymptotic variances are equal, the standard errors (the square roots) will be equal.

Problem 2

Question 21-3 from Cameron-Trivedi (enhanced): Consider the fixed effects, two-way error component panel data model:

$$y_{it} = \alpha + x_{it}\beta + \mu_i + \lambda_t + \epsilon_{it} \tag{2}$$

Part (a)

Show that the fixed effects estimator of β can be obtained by applying two within (one-way) transformations on this model. The first is the within transformation ignoring the time effects followed by the within transformation ignoring the individual effects. Assume the panel is balanced. (Hint: it may be easier to analyze the fixed effects regression using partitioned regression.)

We want to show that

$$\ddot{y}_{it} = \ddot{x}_{it}\beta + \ddot{e}_{it}$$

Ignoring time effects, we get

$$\ddot{y}_{it} = y_{it} - \overline{y_i} = y_{it} - \frac{1}{T} \sum_{t} y_{it}$$

$$\implies \ddot{y}_{it} = y_{it} - \frac{1}{T} \sum_{t} (\alpha + x_{it}\beta + \mu_i + \lambda_t + \epsilon_{it})$$

Applying the second within transformation, we get that

$$\begin{aligned} \ddot{y}_{it} &= \ddot{y}_{it} - \frac{\ddot{y}_{it}}{\ddot{y}_{it}} \\ &= \ddot{y}_{it} - \frac{1}{N} \sum_{i} \ddot{y}_{it} \\ &= y_{it} - \overline{y}_{i} - \overline{y}_{t} + \overline{y} \\ &= \alpha + X_{it}\beta + \mu_{i} + \lambda_{t} + \epsilon_{it} \\ -\left(\frac{1}{T} \sum_{t} (\alpha + X_{it}\beta + \mu_{i} + \lambda_{t} + \epsilon_{it})\right) \\ -\left(\frac{1}{N} \sum_{i} (\alpha + X_{it}\beta + \mu_{i} + \lambda_{t} + \epsilon_{it})\right) \\ +\left(\frac{1}{NT} \sum_{i} \sum_{t} (\alpha + X_{it}\beta + \mu_{i} + \lambda_{t} + \epsilon_{it})\right) \\ &= \beta \left(x_{it} - \overline{x}_{i} - \overline{x}_{t} + \overline{x}\right) + \epsilon_{it} - \overline{\epsilon}_{i} - \overline{\epsilon}_{t} + \overline{\epsilon}_{it} \end{aligned}$$

Since

$$\ddot{x}_{it} = x_{it} - \overline{x_i} - \overline{x_t} + \overline{x}$$

and

$$\ddot{e}_{it} = e_{it} - \overline{e_i} - \overline{e_t} + \overline{e}$$

We get that

$$\ddot{y}_{it} = \ddot{x}_{it}\beta + \ddot{e}_{it}$$

Part (b)

Show that the order of the transformations is unimportant. Give an intuitive explanation for why.

Reversing the order, we can show that we get the same result

Again, we want to show that

$$\ddot{y}_{it} = \ddot{x}_{it}\beta + \ddot{e}_{it}$$

Ignoring individual effects, we get

$$\ddot{y}_{it} = y_{it} - \overline{y_t} = y_{it} - \frac{1}{N} \sum_{i} y_{it}$$

$$\implies \ddot{y}_{it} = y_{it} - \frac{1}{N} \sum_{i} (\alpha + x_{it}\beta + \mu_i + \lambda_t + \epsilon_{it})$$

Applying the second within transformation, we get that

$$\begin{aligned} \overrightarrow{y}_{it} &= \overrightarrow{y}_{it} - \overline{\overrightarrow{y}_{it}} \\ &= \overrightarrow{y}_{it} - \frac{1}{T} \sum_{i} \overrightarrow{y}_{it} \\ &= y_{it} - \overline{y}_{t} - \overline{y}_{i} + \overline{y} \\ &= \alpha + X_{it}\beta + \mu_{i} + \lambda_{t} + \epsilon_{it} \\ -\left(\frac{1}{N} \sum_{i} (\alpha + X_{it}\beta + \mu_{i} + \lambda_{t} + \epsilon_{it})\right) \\ -\left(\frac{1}{T} \sum_{t} (\alpha + X_{it}\beta + \mu_{i} + \lambda_{t} + \epsilon_{it})\right) \\ +\left(\frac{1}{NT} \sum_{i} \sum_{t} (\alpha + X_{it}\beta + \mu_{i} + \lambda_{t} + \epsilon_{it})\right) \\ &= \beta \left(x_{it} - \overline{x}_{t} - \overline{x}_{i} + \overline{x}\right) + \epsilon_{it} - \overline{\epsilon}_{t} - \overline{\epsilon}_{i} + \overline{\epsilon} \end{aligned}$$

Since

$$\ddot{x}_{it} = x_{it} - \overline{x_t} - \overline{x_i} + \overline{x}$$

and

$$\ddot{e}_{it} = e_{it} - \overline{e_t} - \overline{e_i} + \overline{e}$$

We get that

$$\ddot{y}_{it} = \ddot{x}_{it}\beta + \ddot{e}_{it}$$

Intuitively, the order of the transformations is unimportant because in the end, were still manage to difference out the individual and time effects. There is nothing particular to individual or time effects that would warrant removal in any particular order.

Part (c)

Does your answer to part (a) change if the panel becomes unbalanced (i.e., contains different numbers of observations for each individual i). Why or why not?

Problem 3

We now begin with an actual analysis of the data. The goal here is to determine what effect, if any, primary belt laws have on the log of traffic fatalities per capita (we log the LHS variable because we believe the effect of safety belt laws should be proportional to the overall level of fatalities per capita).

```
data <- read_dta('traffic_safety2.dta')
df <- dplyr::filter(data, state != 99)</pre>
```

Part (a)

Run pooled bivariate OLS. Interpret. Add year fixed effects. Interpret. Add all covariates that you believe are appropriate. Think carefully about which covariates should be log transformed and which should enter in levels. What happens when you add these covariates? Why?

```
df <- df %>%
       mutate(fat_pc = fatalities/population,
              ln_fat_pc = log(fat_pc),
              ln_tvmt_pc = log(totalvmt/population))
reg3a_1 <- lm(ln_fat_pc ~ primary, data = df)</pre>
summary(reg3a_1)
##
## Call:
## lm(formula = ln_fat_pc ~ primary, data = df)
##
## Residuals:
                     Median
##
       Min
                  1Q
                                    30
                                            Max
##
  -1.07553 -0.21571 0.03105 0.23493
##
## Coefficients:
              Estimate Std. Error t value Pr(>|t|)
##
## (Intercept) -1.70492
                          0.01098 -155.249 < 2e-16 ***
                                   -5.727 1.32e-08 ***
## primary
              -0.15490
                           0.02705
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 0.3335 on 1102 degrees of freedom
## Multiple R-squared: 0.0289, Adjusted R-squared: 0.02802
## F-statistic: 32.8 on 1 and 1102 DF, p-value: 1.317e-08
stargazer(reg3a_1, type = "text")
```

```
## ## Dependent variable:
## In_fat_pc
## ------
## primary -0.155***
## (0.027)
##
## Constant -1.705***
## (0.011)
```

```
##
## -----
                               1,104
## Observations
                               0.029
## R2
## Adjusted R2
                               0.028
## Residual Std. Error 0.333 (df = 1102)
## F Statistic 32.799*** (df = 1: 1102)
## Note:
                     *p<0.1; **p<0.05; ***p<0.01
reg3a_2 <- lm(ln_fat_pc ~ primary + factor(year), data = df)</pre>
stargazer(reg3a_2, type = "text", no.space = TRUE, omit.stat=c("f", "ser"))
##
##
                      Dependent variable:
##
##
                          ln_fat_pc
## primary
                          -0.091***
                            (0.028)
## factor(year)1982
                           -0.122*
                            (0.066)
## factor(year)1983
                           -0.158**
                           (0.066)
## factor(year)1984
                           -0.149**
                            (0.066)
## factor(year)1985
                           -0.165**
##
                            (0.066)
## factor(year)1986
                            -0.111*
##
                            (0.066)
## factor(year)1987
                            -0.111*
##
                            (0.066)
## factor(year)1988
                            -0.101
##
                            (0.066)
## factor(year)1989
                           -0.160**
##
                            (0.066)
## factor(year)1990
                           -0.182***
##
                           (0.066)
## factor(year)1991
                           -0.255***
                            (0.066)
## factor(year)1992
                           -0.313***
##
                           (0.066)
## factor(year)1993
                           -0.311***
##
                            (0.066)
## factor(year)1994
                           -0.317***
##
                           (0.066)
## factor(year)1995
                           -0.293***
                            (0.066)
## factor(year)1996
                          -0.304***
                           (0.066)
                           -0.291***
## factor(year)1997
                            (0.066)
## factor(year)1998
                           -0.308***
##
                           (0.066)
```

```
## factor(year)1999 -0.313***
##
                      (0.066)
## factor(year)2000
                     -0.333***
##
                      (0.067)
## factor(year)2001
                     -0.329***
##
                      (0.067)
## factor(year)2002
                     -0.318***
##
                      (0.067)
## factor(year)2003 -0.329***
##
                      (0.067)
## Constant
                     -1.486***
##
                      (0.047)
## Observations 1,104
## R2
                      0.107
## Adjusted R2 0.088
*p<0.1; **p<0.05; ***p<0.01
df.p <- pdata.frame(df, index = c("state", "year")) #declaring panel dataset</pre>
reg3a_2_p <- plm(ln_fat_pc ~ primary, data = df.p, effect = "time", model = "within") #checking reg3a_2
stargazer(reg3a_2_p, type = "text", no.space = TRUE, omit.stat=c("f", "ser"))
##
##
              Dependent variable:
##
                  ln_fat_pc
## -----
## primary
                  -0.091***
##
                  (0.028)
## Observations
                   1,104
## R2
                    0.010
## Adjusted R2 -0.011
## Note: *p<0.1; **p<0.05; ***p<0.01
reg3a_3 <- plm(ln_fat_pc ~ primary + secondary + college + beer + unemploy</pre>
           + ln_tvmt_pc + precip + snow32 + rural_speed + urban_speed,
           data = df.p, effect = "time", model = "within")
stargazer(reg3a_3, type = "text", no.space = TRUE, omit.stat=c("f", "ser"))
##
## ==============
              Dependent variable:
##
           -----
                  ln_fat_pc
## -----
## primary
                   0.033
##
                   (0.021)
## secondary
                  0.041**
##
                   (0.017)
                -2.246***
## college
##
                   (0.147)
```

```
## beer
                         0.199 ***
##
                          (0.024)
##
  unemploy
                         0.017***
##
                          (0.004)
## ln_tvmt_pc
                         1.161***
                          (0.041)
##
## precip
                          -0.006
##
                          (0.005)
## snow32
                         -0.174***
##
                          (0.014)
## rural_speed
                         0.011***
##
                          (0.002)
                          0.003*
## urban_speed
##
                          (0.001)
##
## Observations
                           1,104
## R2
                           0.741
## Adjusted R2
                           0.734
## ===============
                *p<0.1; **p<0.05; ***p<0.01
```

Including these covariates drastically changes our point estimate, including the sign, on the primary belt law variable. These covariates must be correlated with both the primary belt law as well as log traffic fatalities per capita. NEED TO EXPLAIN MORE HERE.

Part (b)

Ignore omitted variables bias issues for the moment. Do you think the standard errors from above are right? Compute the Huber-White heteroskedasticity robust standard errors (e.g., ", robust"). Do they change much? Compute the clustered standard errors that are robust to within-state correlation (e.g., ", cluster(state)"). Do this using both the "canned" command and manually using the formulas we learned in class. Do the standard errors change much? Are you surprised? Interpret.

Standard errors from specifications in part (a) is likely incorrect given we have potential correlation across observations from same state.

```
##
  Regression with Robust SE
##
##
                                            Log(Fatality per Population)
##
##
                    Biv
                             Biv (Robust)
                                             Yr FE
                                                      Yr FE (Robust) Ctr/Yr FE Ctr/Yr FE (Robust)
                                              (3)
##
                    (1)
                                 (2)
                                                            (4)
                                                                          (5)
                                                                                          (6)
```

| ## | | | | | | | | |
|----|-------------------------------------|------------|------------|------------|------------|------------|---|--|
| ## | primary | -0.1549*** | -0.1549*** | -0.0906*** | 0.0331* | 0.0331 | 0.0331* | |
| ## | | (0.0270) | (0.0283) | (0.0275) | (0.0192) | (0.0205) | (0.0192) | |
| ## | secondary | | | | 0.0407** | 0.0407** | 0.0407** | |
| ## | | | | | (0.0159) | (0.0172) | (0.0159) | |
| ## | college | | | | -2.2462*** | -2.2462*** | -2.2462*** | |
| ## | | | | | (0.1400) | (0.1474) | (0.1400) | |
| ## | beer | | | | 0.1987*** | 0.1987*** | 0.1987*** | |
| ## | | | | | (0.0240) | (0.0244) | (0.0240) | |
| ## | unemploy | | | | 0.0170*** | 0.0170*** | 0.0170*** | |
| ## | | | | | (0.0036) | (0.0036) | (0.0036) | |
| ## | ln_tvmt_pc | | | | 1.1607*** | 1.1607*** | 1.1607*** | |
| ## | | | | | (0.0452) | (0.0413) | (0.0452) | |
| ## | precip | | | | -0.0058 | -0.0058 | -0.0058 | |
| ## | | | | | (0.0047) | (0.0048) | (0.0047) | |
| ## | snow32 | | | | -0.1744*** | -0.1744*** | -0.1744*** | |
| ## | | | | | (0.0141) | (0.0140) | (0.0141) | |
| ## | rural_speed | | | | 0.0115*** | 0.0115*** | 0.0115*** | |
| ## | | | | | (0.0019) | (0.0020) | (0.0019) | |
| ## | urban_speed | | | | 0.0026* | 0.0026* | 0.0026* | |
| ## | | | | | (0.0014) | (0.0015) | (0.0014) | |
| ## | Constant | -1.7049*** | -1.7049*** | | | | | |
| ## | | (0.0110) | (0.0108) | | | | | |
| ## | | | | | | | | |
| ## | ${\tt Observations}$ | 1,104 | | 1,104 | | 1,104 | | |
| ## | R2 | 0.0289 | | 0.0099 | | 0.7413 | | |
| ## | Adjusted R2 | 0.0280 | | -0.0111 | | 0.7336 | | |
| | ========= | | ======== | ======== | ========= | ======== | ======================================= | |
| ## | # Note: *p<0.1; **p<0.05; ***p<0.01 | | | | | | | |

Above table demonstrates that

Part (c)

Compute the between estimator, both with and without covariates. Under what conditions will this give an unbiased estimate of the effect of primary seat belt laws on fatalities per capita? Do you believe those conditions are met? Are you concerned about the standard errors in this case?

Part (d)

Compute the Random Effects estimator (including covariates). Under what conditions will this give an unbiased estimate of the effect of primary seat belt laws on fatalities per capita? What are its advantages or disadvantages as compared to pooled OLS?

Part (e)

Do you think the standard errors from RE are right? Compute the clustered standard errors. Are they substantially different? If so, why? (i.e., what assumption(s) are being violated?)

Part (f)

Compute the FE estimator using only primary and year fixed effects as the covariates. Compute the normal standard errors and the clustered standard errors. If they are different, why?

Part (g)

Add the same range of covariates to the FE estimator that you did to the OLS estimator. Are the FE estimates more or less stable than the OLS estimates? Why?

Part (h)

Estimate a first-differences estimator, a 5-year differences estimator, and a long differences estimator, including year fixed effects (when feasible) and the appropriate covariates in each case. Briefly describe the pattern that emerges from the three differencing estimates. Where does the FE estimate fall in this pattern? Are you surprised?

Part (i)

Make the case that the first-differences estimate is superior to the 5-year or long differences estimates.

Part (j)

Make the case that the 5-year or long differences estimates are superior to the first-differences estimate.