

Integration Manual Vin

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1 Introduction

1.1 General

For a general introduction to the BAC4 Platform Modules please refer to [1].

This document only describes topics related to the SWT BAC4 Module.

This Integration Manual describes the basis functionality, API and the configuration of the BMW system function VIN.

1.2 Functional overview

The Vin module is used to request the VIN over the bus, set the qualifier and hand it over to application software components.

2 Acronyms and Abbreviations

A&S	Authentication and Signature (Grundschutzmechanismen)
AllgGB	Allgemeine Gültigkeitsbedingung
AN	Applikationsnummer
API	Application Programming Interface
AppGB	Applikationsspezifische Gültigkeitsbedingung
AUTOSAR	Automotive Open System Architecture
CA	Certification Authority
CAL	Cryptographic Abstraction Layer
CAS	Car Access System (Steuergerät)
CCC	Car Communication Computer
CKD	Completely Knocked Down. A BMW plant that is not connected to the central BMW IT.
CSM	Client Security Module
CRL	Certificate Revocation List
DEK	Data Encryption Key
DER	Distinguished Encoding Rules (As described by ASN.1)
DES	Data Encryption Standard
DN	Distinguished Name
DTC	Diagnostic Trouble Code -> Fehlercode des Fehlerspeichereintrages
ECU	Electronic Control Unit
FAT	Flash-Absicherungs-Tool
FSC	Freischaltcode
FSCS	Freischaltcode-Stelle
FZG	Fahrzeug
FZG-R	BMW Fahrzeug-Root-CA
GB	Gültigkeitsbedingung

GG	Gültigkeitsgruppe
GMT	Greenwich Mean Time
HO	Handelsorganisation (BMW)
HW	Hardware
M-FSCS	Master-Freischaltcodestelle
OS	Operating System
PKI	Public Key Infrastructure
RCn	Routine Control Option n / Exit Result n
RI	Routine Identifier
RSA	Asymmetric Cryptalgorithm by Rivest, Shamir und Adleman
RTE	Runtime Environment
SG	Steuergerät
SGID	Steuergeräte-ID, Diagnoseadresse, Steuergeräte-Adresse
SID	Service Identifier
SigS	SW-Signatur-Stelle
SW	Software
SW-C	Software Component
SWID	Software-ID consisting of application number and upgrade index
SWT	SWEEPING Technologies (SoftWare Enabled Electronic Platform for Innovative Next Generation Technologies)
UDS	Universal Diagnostic Services
UI	Upgrade Index
UTC	Coordinated Universal Time
VCM	Vehicle Configuration Management
VIN	Vehicle Identification Number
VIN7	The last 7 digits of the 17-digit VIN

All abbreviations used throughout this document -- except the ones listed here -- can be found in the official AUTOSAR glossary [6].

3 Related documentation

3.1 BMW Specifications

- [1] BAC4 General Concept for the Module Integration
BAC4_General_Concepts_for_the_Module_Integration.pdf
- [2] Specification of Module DataLogistic
ModuleSpecification_Dlog.pdf
- [3] Specification of Module FSCSM
ModuleSpecification_Fscsm.pdf
- [4] Integration Manual FSCSM
IntegrationManual_Fscsm.pdf
- [5] Specification of Module Vin
ModuleSpecification_Vin.pdf

3.2 AUTOSAR Specifications

- [6] Glossary
AUTOSAR_TR_Glossary
- [7] Specification of RTE Software
AUTOSAR_SWS_RTE
- [8] Specification of NVRAM Manager
AUTOSAR_SWS_NVRAMManager

4 Limitations

Autosar 4.2.1 or later is required.

5 Software Architecture

5.1 Dependencies on AUTOSAR modules

5.1.1 RTE

The module Vin is realized as a software component and is using RTE services [7] for client/server as well as sender/receiver communication to communicate with other SWCs.

5.1.2 NvM

The NVRAM Manager [8] is used to store the last VIN and the SSV state.

5.2 Dependencies on BMW modules

5.2.1 Dlog

The Dlog module [2] is used to get the internal VIN.

5.2.2 Fscsm

The Fscsm module [3] is needed for receiving the secure VIN.

6 Integration

6.1 Configuration of other Modules

The following modules shall be configured, before the module Vin is compiled and linked.

6.1.1 Communication Stack

The communication stack shall be configured to provide the Vehicle Identification Number (VIN) message from the corresponding bus.

For $i \in \{1, \dots, 7\}$ configure the signals

Shortname (according to BMW BNE):	NO_VECH_<i>
ComBitPosition:	$8(i - 1)$
ComBitSize:	8
ComSignalEndianness:	OPAQUE
ComSignalLength:	1
ComSignalType:	UINT8_N
ComTransferProperty:	TRIGGERED

Note: The Signals “NO_VECH_<i>” ($1 \leq i \leq 7$) have to be configured as a Signalgroup!

Note: In Ethernet, these signals are modeled as structure in the field `ChassisNumber` of the Service Interface `VehicleInformation`.

6.1.2 Nvm

Following NvM blocks shall be configured:

NVM_BLOCK_Vin	
NvMBlockCrcType	NVM_CRC16
NvMBlockHeaderInclude	Vin_NvM.h
NvMBlockManagementType	NVM_BLOCK_NATIVE
NvMBlockUseCrc	true
NvMBlockWriteProt	false
NvMExtraBlockChecks	true
NvMNvBlockLength	8 ¹
NvMNvBlockNum	1
NvMProvideRteServicePort	true
NvMRamBlockDataAddress	-
NvMResistantToChangedSw	true, if NvMDynamicConfiguration = true
NvMRomBlockDataAddress	&Vin_NVStateDefault
NvMRomBlockNum	0

¹block length might differ depending on the used compiler and compiler settings

NvMSelectBlockForReadAll	false
NvMSelectBlockForWriteAll	false
NvMWriteBlockOnce	False

Write Frequency: The block will be written every time a different VIN than the last VIN is received on the bus and once on switch to safe environment. In practice this means, it is written once in the plant and every time, the ECU is transferred into a different vehicle.

6.1.3 Fscsm

For the secure VIN, FscsmActivateVerifyMessage shall be enabled in Fscsm, see [3, 4] for details.

6.2 Configuration

For a detailed description of the configuration parameters, please consult the Vin Software Specification [5].

6.3 Configuration of the RTE

6.3.1 Assembly connectors

6.3.1.1 Always

- <BSW-Servicename>* shall be connected with its corresponding BSW port.
- <Modulename><Portname> shall be connected with its corresponding <Portname> of the module <Modulename>.

6.3.1.2 If SecureVin is configured

- SSVErrCode shall be connected to the DEM Environment Data for the FscsmError, see [3, 4] for details.
- RandomNumberGenerator shall be connected to the corresponding Port of the Fscsm module.

6.3.2 Event Mapping

All events must be mapped to the same or to non-preemptive tasks.

6.3.3 Data Mapping

6.3.3.1 If EnableSIAdapter=false

For the R-Port ComVin, the data elements Vin_ComVinType/Vin<*i*> shall be mapped to the signals NO_VECH_<*i*> for $i \in \{1, \dots, 7\}$.

For the P-Port VinRequest, the data element RequestMessageIdentifier shall be mapped to the signal ID_FN_INQY.

6.3.3.2 If SecureVin is configured with EnableSIAdapter=false

For the P-Port SSVChallengeToSSS, the data element Challenge shall be mapped to the PDU SECU_CHAL as follows:

SsvId	→ SSV_IDENT_CHAL
SSsId	→ SSS_IDENT_CHAL
Challenge	→ SECU_CHAL

For the R-Port SSVResponseFromSSS, the data element Response shall be mapped to the PDU SECU_RESP as follows:

SsvId	→ SSV_IDENT_RESP
CounterBase	→ COU_BS_RESP
Signature	→ STU_RESP

For the R-Port SSVWinMacFromSSS, the data element Mac shall be mapped to the signal STU_8_BYTE.

6.3.3.3 If EnableSIAdapter=true

The R-Port ComVin shall be connected to the corresponding P-Port of the VinSIAdapter SWC.

The P-Port VinRequest shall be connected to the corresponding R-Port of the VinSIAdapter SWC.

The R-Port ChassisNumberNotifier of the VinSIAdapter SWC shall be connected with the notifier of the Field ChassisNumber of the Service Interface VehicleInformation.

The R-Port ChassisNumber of the VinSIAdapter SWC shall be connected with the getter of the Field ChassisNumber of the Service Interface VehicleInformation.

6.3.3.4 If SecureVin is configured with EnableSIAdapter=true

The P-Port SSVChallengeToSSS and the R-Ports SSVResponseFromSSS, SSVWinMacFromSSS shall be connected to the corresponding ports of the VinSIAdapter SWC.

The R-Port ChassisNumberAuthentication of the VinSIAdapter SWC shall be connected with the Service Interface ChassisNumberAuthentication.

6.3.4 Exclusive Areas

The exclusive area VinState shall be configured.

6.4 Software Integration

6.4.1 Startup/Initialisation

The INITIALIZED mode shall be requested.

6.4.2 Normal Operation

When the LifeCycle mode is in INITIALIZED, the RUNNING mode shall be requested.

6.4.3 Shutdown/Deactivation

The STOPPED mode shall be requested.