## 1 Parabolic PDEs

## 1.1 diff\_adv\_2D.py

 ${\bf Calculates\ the\ solution\ to\ the\ two-dimensional\ diffusion-advection/heat-convection\ equation}$ 

$$\frac{\partial u}{\partial t} = D(x, y) \nabla^2 u - \hat{\mathbf{v}} \cdot \nabla u + q(x, y, t),$$

using cartesian coordinates on a uniform mesh, on the domain  $\Omega$  bound by  $x \in [0, L_x]$  and  $y \in [0, L_y]$ , where

$$\hat{\mathbf{v}} = v_x \hat{\imath} + v_y \hat{\jmath}$$

describes the direction of advection/convection, D(x,y) is the diffusivity/conductivity and q(x,y,t) is a source/sink term. The program assumes Robin boundary conditions

$$a\ u(x,y,t) + b\ \frac{\partial u}{\partial n} = g(x,y)$$

where a and b are real scalars, g(x,y) is an arbitrary function on the boundary and  $\partial n$  denotes differentiation in the direction of a normal to the boundary. The initial condition  $u_0(x,y) = u(x,y,0)$  can be any real valued function. The solution is calculated using the finite difference method.

## 1.2 mc\_stefan.py

Calculates the solution to the classical Stefan problem

$$\begin{split} \frac{\partial u}{\partial t} &= \alpha \; \frac{\partial^2 u}{\partial x^2}, \quad \ \, 0 < x < s(t), \ \, t > 0 \\ u(0,t) &= 1, \\ u(x,0) &= 0, \\ u(s(t),t) &= T_m \\ s(0) &= 0 \\ L \; \rho \; \frac{ds}{dt} &= k \; \frac{\partial u}{\partial x} \end{split}$$

using a monte carlo, where u(x,t) is the temperature, s(t) is the position of the moving boundary,  $\alpha$  is the thermal diffusivity,  $T_m$  is the melting temperature, L is the latent heat,  $\rho$  is the density and k is the thermal conductivity. The solution is calculated on the domain  $\Omega$  bound by  $x \in [0, L_x]$  and t > 0. The code models the free boundary using the method proposed by Stoor [stoor].

The answer is compared to the analytical solution derived by Neumann<sup>1</sup>

$$u(x,t) = 1 - \frac{\operatorname{erf}\left(\frac{x}{2\sqrt{t}}\right)}{\operatorname{erf}(\lambda)},$$
  
$$s(t) = 2\lambda\sqrt{t},$$

where  $\lambda$  satisfies

$$\beta \sqrt{\pi} \lambda e^{\lambda^2} \operatorname{erf}(\lambda) = 1, \tag{1}$$

where  $\beta$  is the Stefan number.

# 2 Hyperbolic PDEs

#### 2.1 wave\_2D.py

Calculates the solution to the two-dimensional acoustic wave equation

$$\frac{\partial^2 p}{\partial t^2} + \nu(x, y) \frac{\partial p}{\partial t} = c^2 \nabla^2 u + q(x, y, t),$$

using cartesian coordinates on a uniform mesh, on the domain  $\Omega$  bound by  $x \in [0, L_x]$  and  $y \in [0, L_y]$ , where  $\nu(x, y)$  is a damping term, c is the speed of sound and q(x, y, t) is a source/sink term. The program assumes Robin boundary conditions

$$a \ u(x, y, t) + b \ \frac{\partial u}{\partial n} = g(x, y),$$

where a and b are real scalars, g(x,y) is an arbitrary function on the boundary and  $\partial n$  denotes differentiation in the direction of a normal to the boundary. The initial pressure  $p_0(x,y) = p(x,y,0)$  can be any real valued function. The solution is calculated using the finite difference method.

### 2.2 wave\_2D\_PML.py

Calculates the solution to the two-dimensional acoustic wave equation

$$\begin{split} \frac{\partial \hat{\mathbf{v}}}{\partial t} &= -\frac{1}{\rho} \nabla p, \\ \frac{\partial p}{\partial t} + \nu(x,y) \; p &= -c^2 \rho \nabla \cdot \hat{\mathbf{v}} + q(x,y,t), \end{split}$$

where  $\hat{\mathbf{v}}(x,y,t)$  describes the velocity at each point in the mesh and p(x,y,t) describes the pressure at each point in the mesh. Solution is calcualted using cartesian coordinates and a uniform mesh, on the domain  $\Omega$  bound by  $x \in [0, L_x]$  and  $y \in [0, L_y]$ , where  $\nu(x, y)$  is a damping term, c is the speed of sound

 $<sup>^1\</sup>mathrm{A}$  similarity solution derived using the variable  $\xi = \frac{x}{\sqrt{t}}.$ 

and q(x,y,t) is a source/sink term. The program assumes Robin boundary conditions

$$a u(x, y, t) + b \frac{\partial u}{\partial n} = g(x, y),$$

where a and b are real scalars, g(x,y) is an arbitrary function on the boundary and  $\partial n$  denotes differentiation in the direction of a normal to the boundary. The initial pressure  $p_0(x,y)=p(x,y,0)$  can be any real valued function. The solution is calculated using the finite difference method. Absorbing boundary conditions can optionally be turned on or off to simulate far-field conditions. Absorbing boundary conditions are implemented by stretching the coordinates of the governing equations into the complex domain in Fourier-transform-space using the method proposed by Berenger [Berenger1994].

## 3 Elliptical PDEs

#### 3.1 helmholtz.py

Calculates the solution to the nonhomogenous Helmholtz equation

$$(\nabla^2 + k(x, y)^2) f(x, y, t) = \psi(x, y),$$

using cartesian coordinates on a uniform mesh, on the domain  $\Omega$  bound by  $x \in [0, L_x]$  and  $y \in [0, L_y]$ , where k(x, y) and  $\psi(x, y)$  are real valued functions. The program assumes Robin boundary conditions

$$a \ u(x, y, t) + b \ \frac{\partial u}{\partial n} = g(x, y),$$

where a and b are real scalars, g(x,y) is an arbitrary function on the boundary and  $\partial n$  denotes differentiation in the direction of a normal to the boundary. The solution is calculated using the finite difference method.

keywords: Laplace's equation, Poisson's equation.

#### 4 References