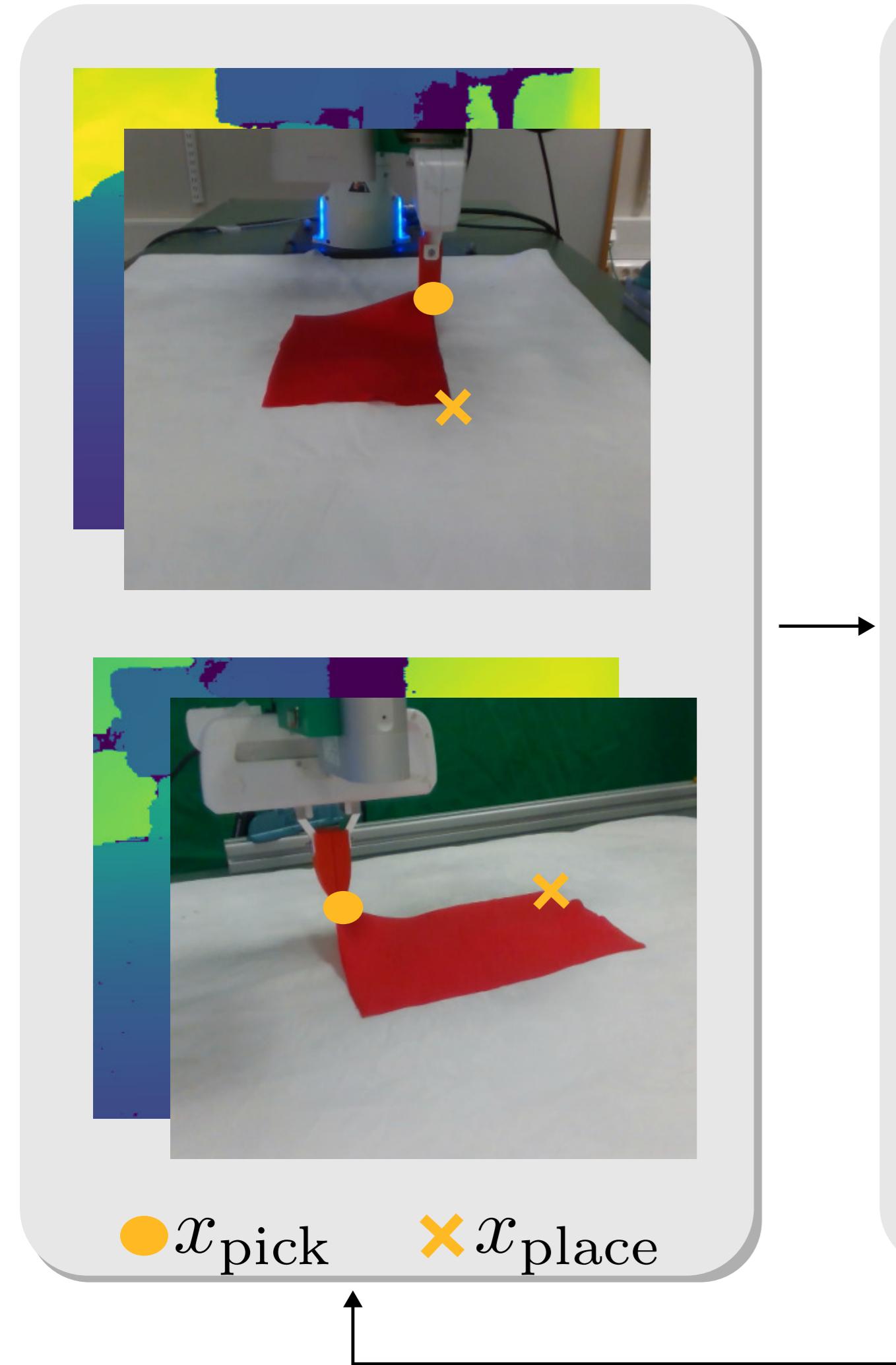
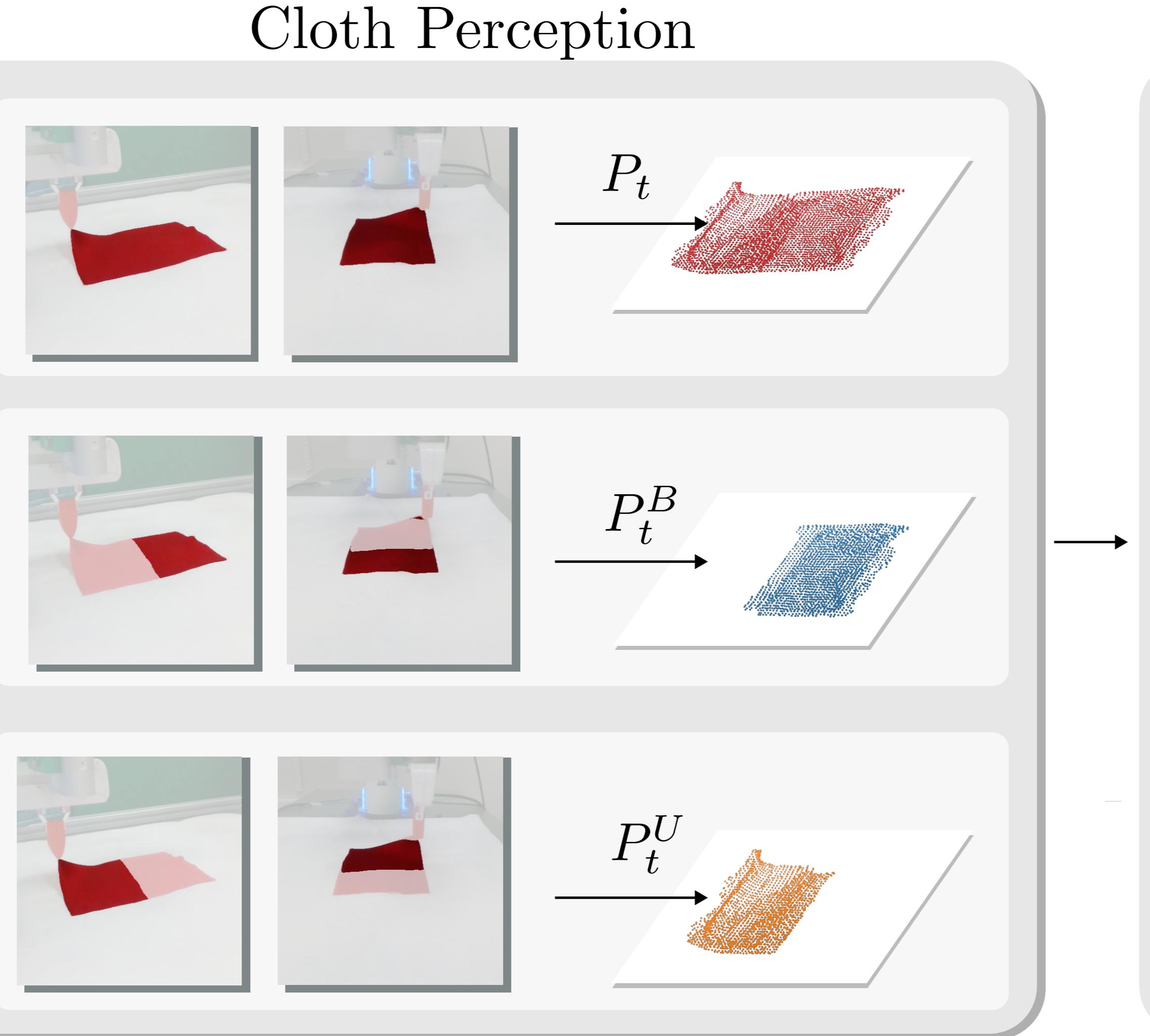


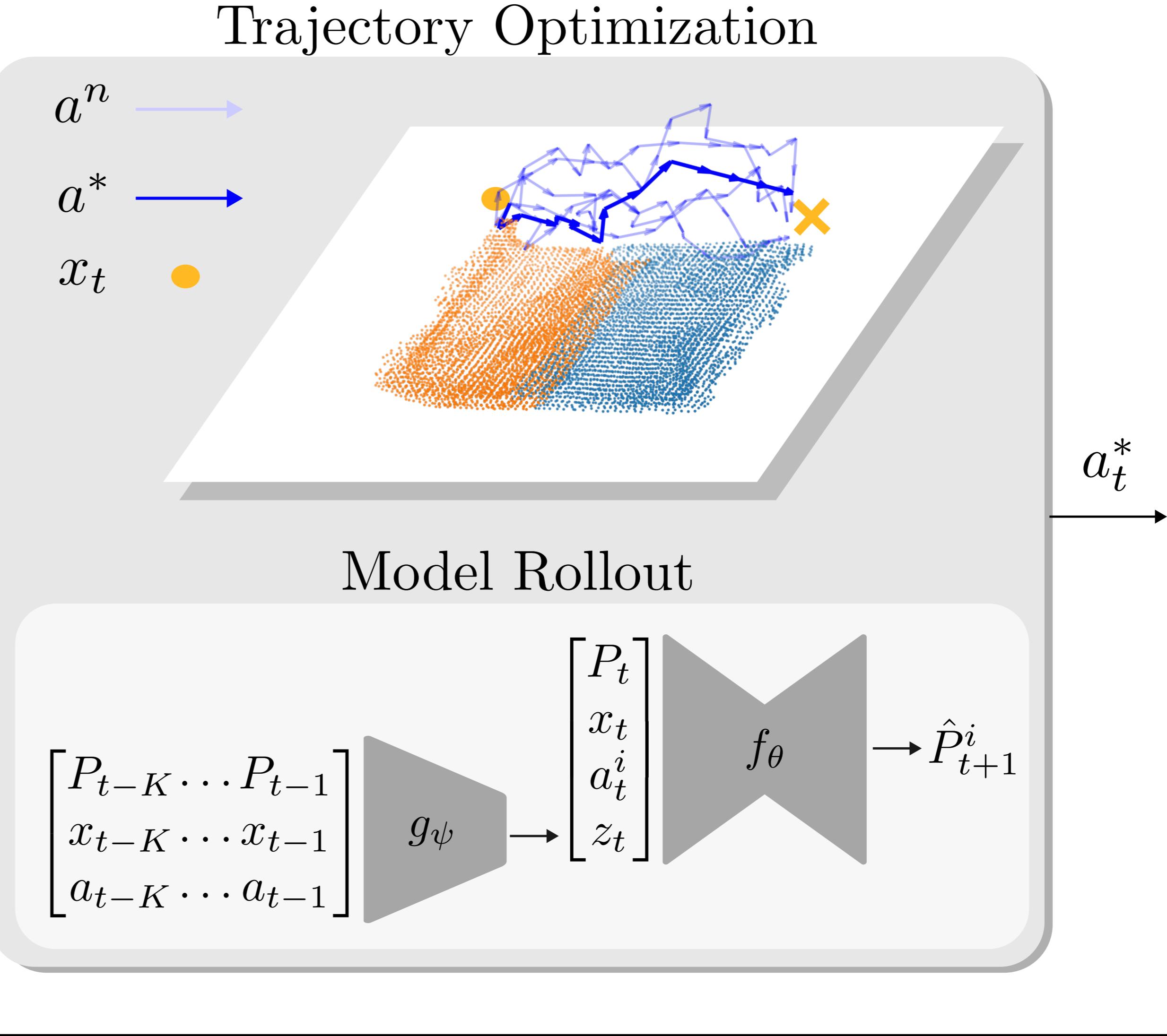
Back Camera Front Camera



RGB-D Observations



Cloth Perception



Trajectory Optimization