```
import os
import numpy as np
import matplotlib.pyplot as plt
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
from tensorflow.keras.callbacks import ModelCheckpoint, EarlyStopping
```

- TensorFlow and Keras are imported for building neural networks
- NumPy for numerical operations
- Matplotlib for visualization
- Other standard libraries like os, urllib and zipfile

Part 1: Data Loading and Preprocessing

```
print("Loading and preprocessing data...")
```

→ Loading and preprocessing data...

Download the dataset if it doesn't exist

```
if not os.path.exists("jena_climate_2009_2016.csv"):
    print("Downloading dataset...")
    import urllib.request
    urllib.request.urlretrieve(
        "https://storage.googleapis.com/tensorflow/tf-keras-datasets/jena_climate_2
        "jena_climate_2009_2016.csv.zip")

import zipfile
with zipfile.ZipFile("jena_climate_2009_2016.csv.zip", 'r') as zip_ref:
        zip_ref.extractall()
```

- · Checks if the Jena climate dataset exists locally
- If not, downloads it from the TensorFlow storage
- Unzips the file using zipfile module

Load the data

```
fname = "jena_climate_2009_2016.csv"
with open(fname) as f:
    data = f.read()

lines = data.split("\n")
header = lines[0].split(",")
lines = lines[1:]
print(f"Number of data points: {len(lines)}")
```

Number of data points: 420551

- Opens the CSV file
- · Reads all lines from the file
- Extracts header information
- Prints the number of data points (420,551)

Parse the data

```
temperature = np.zeros((len(lines),))
raw_data = np.zeros((len(lines), len(header) - 1))
for i, line in enumerate(lines):
   values = [float(x) for x in line.split(",")[1:]]
   temperature[i] = values[1] # Temperature is the 2nd column
   raw_data[i, :] = values[:]
```

- Creates NumPy arrays to store temperature data and all features
- Iterates through each line of the CSV
- Converts values to floats
- Stores temperature in a separate array (column index 1)
- Stores all other values in the raw_data array

Split the data

```
num_train_samples = int(0.5 * len(raw_data))
num_val_samples = int(0.25 * len(raw_data))
num_test_samples = len(raw_data) - num_train_samples - num_val_samples
```

Training set: 50% of dataValidation set: 25% of data

• Test set: 25% of data

Normalize the data

```
mean = raw_data[:num_train_samples].mean(axis=0)
raw_data -= mean
std = raw_data[:num_train_samples].std(axis=0)
raw_data /= std
```

- Calculates mean and standard deviation from the training set only
- Subtracts mean from all data (centering)
- Divides by standard deviation (scaling)
- This standardization helps neural networks converge faster

Create datasets

```
sampling_rate = 6 \# One data point per hour (original data is 10min intervals) sequence_length = 120 \# Using 5 days of data to predict delay = sampling_rate * (sequence_length + 24 - 1) \# Predicting 24h into the futbatch_size = 256
```

- Sets sampling_rate = 6 (one data point per hour from original 10-minute intervals)
- Defines sequence_length = 120 (using 5 days of data to predict)
- Sets delay to predict 24 hours into the future
- Creates TensorFlow datasets for training, validation, and testing
- Each dataset includes input sequences and target temperatures

Create TensorFlow datasets

```
train_dataset = keras.utils.timeseries_dataset_from_array(
    raw_data[:-delay],
    targets=temperature[delay:],
    sampling_rate=sampling_rate,
    sequence_length=sequence_length,
    shuffle=True,
    batch_size=batch_size,
    start_index=0,
    end_index=num_train_samples
val_dataset = keras.utils.timeseries_dataset_from_array(
    raw_data[:-delay],
    targets=temperature[delay:],
    sampling_rate=sampling_rate,
    sequence_length=sequence_length,
    shuffle=True,
    batch_size=batch_size,
    start_index=num_train_samples,
    end_index=num_train_samples + num_val_samples
test_dataset = keras.utils.timeseries_dataset_from_array(
    raw_data[:-delay],
    targets=temperature[delay:],
    sampling_rate=sampling_rate,
    sequence_length=sequence_length,
    shuffle=True,
    batch_size=batch_size,
    start_index=num_train_samples + num_val_samples
)
```

Check dataset shapes

```
for samples, targets in train_dataset.take(1):
    print(f"Input shape: {samples.shape}")
    print(f"Target shape: {targets.shape}")
```

→ Input shape: (256, 120, 14) Target shape: (256,)

• Confirms the input shape: (256, 120, 14) meaning:

o Batch size: 256

Sequence length: 120 time steps

Features: 14 weather measurements

• Target shape: (256,) - one temperature value per sequence

Part 2: Establish a baseline (non-ML method)

Baseline - Validation MAE: 2.44
Baseline - Test MAE: 2.62

Define Naive Baseline Method:

- Implements a simple prediction strategy: "future temperature = last observed temperature"
- Uses the temperature from the last time step in each sequence

Evaluate Baseline:

- Calculates Mean Absolute Error (MAE) on validation and test sets
- Validation MAE: 2.44
- Test MAE: 2.62
- This provides a reference point for ML model performance

Part 3: Model Building and Evaluation Functions

```
def build_and_train_model(model_type, units=32, num_layers=1, use_lstm=False,
                          use_cnn=False, dropout_rate=0, recurrent_dropout_rate=0
                          bidirectional=False, epochs=20):
    """Build and train different types of RNN models for time-series forecasting"
    inputs = keras.Input(shape=(sequence_length, raw_data.shape[-1]))
   x = inputs
   # Add CNN layers if specified
    if use_cnn:
        x = layers.Conv1D(filters=32, kernel_size=5, activation="relu", padding="
        x = layers.MaxPooling1D(pool_size=2)(x)
   # Add RNN layers
    for i in range(num_layers - 1):
        if use_lstm:
            rnn_layer = layers.LSTM(units, return_sequences=True,
                                    dropout=dropout_rate, recurrent_dropout=recur
        else:
            rnn_layer = layers.GRU(units, return_sequences=True,
                                  dropout=dropout rate, recurrent dropout=recurre
        if bidirectional:
            x = layers.Bidirectional(rnn_layer)(x)
        else:
            x = rnn_{layer}(x)
   # Final RNN layer
    if use lstm:
        rnn_layer = layers.LSTM(units, dropout=dropout_rate, recurrent_dropout=re
```

```
else:
        rnn_layer = layers.GRU(units, dropout=dropout_rate, recurrent_dropout=rec
    if bidirectional:
        x = layers.Bidirectional(rnn_layer)(x)
    else:
        x = rnn_{ayer}(x)
    if dropout_rate > 0:
        x = layers.Dropout(dropout_rate)(x)
    outputs = layers.Dense(1)(x)
    model = keras.Model(inputs, outputs)
    model_name = f"jena_{model_type}.keras"
    callbacks = [
        ModelCheckpoint(model_name, save_best_only=True),
        EarlyStopping(patience=5, restore_best_weights=True)
    1
    model.compile(optimizer="adam", loss="mse", metrics=["mae"])
    history = model.fit(
        train_dataset,
        epochs=epochs,
        validation_data=val_dataset,
        callbacks=callbacks
    )
    # Evaluate on test set
    test_mae = model.evaluate(test_dataset)[1]
    print(f"{model_type} - Test MAE: {test_mae:.2f}")
    return model, history, test_mae
def plot_history(history, title):
    """Plot training and validation MAE"""
    plt.figure(figsize=(10, 6))
    plt.plot(history.history["mae"], label="Training MAE")
    plt.plot(history.history["val_mae"], label="Validation MAE")
    plt.title(title)
    plt.xlabel("Epoch")
    plt.ylabel("MAE")
    plt.legend()
    plt.grid(True)
    plt.savefig(f"{title.replace(' ', '_').lower()}.png")
    plt.show()
```

Define Model Building Function:

- Creates a flexible function that can build various RNN architectures
- Parameters include:
 - o model_type: Name for the model
 - units: Number of recurrent units
 - num_layers: Number of recurrent layers
 - use_lstm: Boolean to choose between LSTM and GRU
 - use_cnn: Boolean to add convolutional layers
 - dropout_rate: Regularization parameter
 - recurrent_dropout_rate: Dropout specifically for recurrent connections
 - bidirectional: Boolean for bidirectional RNNs
 - epochs: Training duration

Model Architecture Components:

- CNN layers (optional): Conv1D + MaxPooling1D
- Stacked RNN layers (variable number)
- LSTM or GRU cells based on parameter
- Bidirectional wrapper (optional) Dropout layers (optional)
- · Dense output layer

Model Training Setup:

- Compiles model with Adam optimizer
- Uses MSE loss and MAE metric
- Adds callbacks:
 - ModelCheckpoint to save best model
 - EarlyStopping to prevent overfitting

Define Plotting Function:

- Creates function to visualize training history
- Plots training and validation MAE over epochs
- Saves the plot as an image file

Part 4: Experiment with Different Model Architectures

```
print("\nExperimenting with different model architectures...\n")
```

Experimenting with different model architectures...

Dictionary to store results

```
results = {}
```

Experiment 1: Simple GRU (baseline)

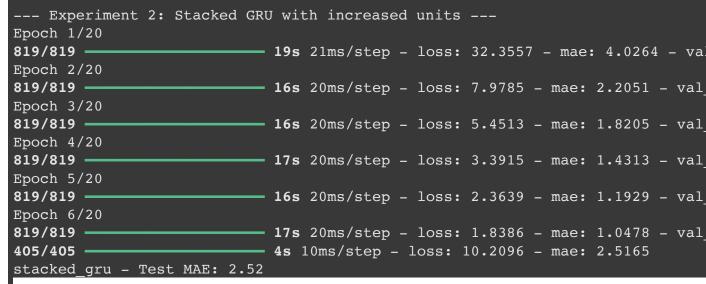
```
print("\n--- Experiment 1: Simple GRU (baseline) ---")
model_gru, history_gru, mae_gru = build_and_train_model(
    model_type="simple_gru",
    units=32,
    num_layers=1,
    use_lstm=False
)
results["Simple GRU"] = mae_gru
plot_history(history_gru, "Simple GRU Model")
```

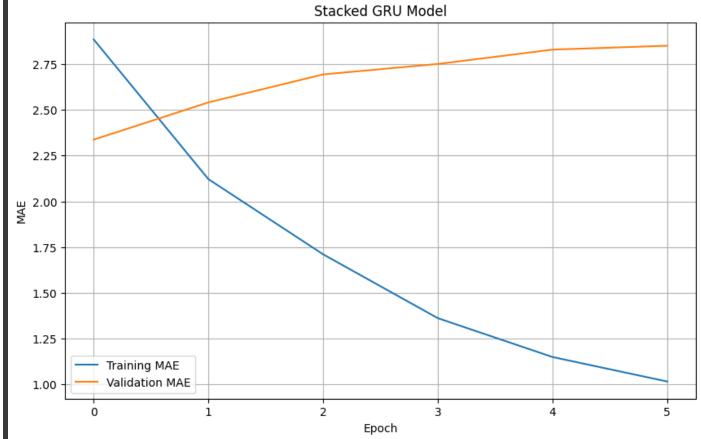
```
\overline{\Rightarrow}
    --- Experiment 1: Simple GRU (baseline) ---
    Epoch 1/20
    819/819
                                  14s 16ms/step - loss: 57.4103 - mae: 5.6132 - val
    Epoch 2/20
                                  13s 15ms/step - loss: 10.8389 - mae: 2.5505 - val
    819/819
    Epoch 3/20
    819/819
                                  13s 16ms/step - loss: 9.1029 - mae: 2.3505 - val
    Epoch 4/20
    819/819
                                  13s 16ms/step - loss: 8.2371 - mae: 2.2393 - val
    Epoch 5/20
                                  13s 15ms/step - loss: 7.5497 - mae: 2.1463 - val
    819/819
    Epoch 6/20
    819/819
                                  13s 16ms/step - loss: 7.0134 - mae: 2.0676 - val
    Epoch 7/20
    819/819
                                  13s 16ms/step - loss: 7.0679 - mae: 2.0563 - val
    Epoch 8/20
```

```
819/819 -
                               13s 16ms/step - loss: 6.9607 - mae: 2.0484 - val
Epoch 9/20
819/819 -
                              13s 15ms/step - loss: 6.5141 - mae: 1.9849 - val
Epoch 10/20
819/819
                              13s 16ms/step - loss: 6.1499 - mae: 1.9300 - val
Epoch 11/20
819/819 -
                              13s 15ms/step - loss: 5.8089 - mae: 1.8787 - val
Epoch 12/20
819/819
                              13s 15ms/step - loss: 5.5036 - mae: 1.8301 - val
405/405 -
                              4s 10ms/step - loss: 10.6655 - mae: 2.5657
simple gru - Test MAE: 2.57
                                    Simple GRU Model
                                                                      Training MAE
                                                                      Validation MAE
  3.5
  3.0
  2.5
  2.0
                                                                       10
                                              6
                                                           8
                                          Epoch
```

Experiment 2: Stacked GRU with different unit sizes

```
print("\n--- Experiment 2: Stacked GRU with increased units ---")
model_stacked_gru, history_stacked_gru, mae_stacked_gru = build_and_train_model(
    model_type="stacked_gru",
    units=64, # Increased units
    num layers=2,
    use_lstm=False
)
results["Stacked GRU"] = mae_stacked_gru
plot_history(history_stacked_gru, "Stacked GRU Model")
\rightarrow
     -- Experiment 2: Stacked GRU with increased units ---
    Epoch 1/20
    819/819
                                 - 19s 21ms/step - loss: 32.3557 - mae: 4.0264 - val
    Epoch 2/20
    819/819 -
                                  16s 20ms/step - loss: 7.9785 - mae: 2.2051 - val
    Epoch 3/20
    819/819 -
                                 16s 20ms/step - loss: 5.4513 - mae: 1.8205 - val
```



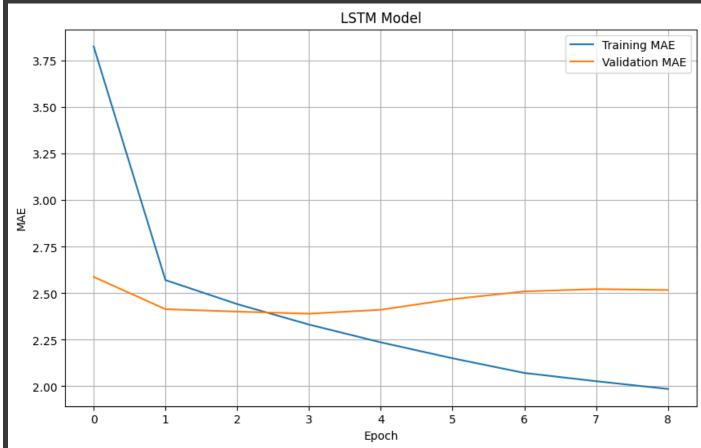


- Two GRU layers with 64 units each
- · Second layer increases model capacity
- Test MAE: 2.52 (improvement over single layer)
- Training history shows faster convergence

Experiment 3: Using LSTM instead of GRU

```
print("\n--- Experiment 3: LSTM instead of GRU ---")
model_lstm, history_lstm, mae_lstm = build_and_train_model(
    model_type="lstm",
    units=32,
    num_layers=1,
    use_lstm=True
)
results["LSTM"] = mae_lstm
plot_history(history_lstm, "LSTM Model")
```

```
--- Experiment 3: LSTM instead of GRU ---
Epoch 1/20
819/819
                            • 14s 16ms/step - loss: 55.6187 - mae: 5.4481 - val
Epoch 2/20
819/819
                             13s 15ms/step - loss: 11.3988 - mae: 2.6199 - val
Epoch 3/20
819/819 -
                            - 13s 16ms/step - loss: 9.9840 - mae: 2.4653 - val
Epoch 4/20
819/819
                            13s 16ms/step - loss: 9.1559 - mae: 2.3583 - val
Epoch 5/20
819/819
                            13s 15ms/step - loss: 8.3569 - mae: 2.2515 - val
Epoch 6/20
819/819
                            - 13s 15ms/step - loss: 7.7492 - mae: 2.1655 - val
Epoch 7/20
                            13s 15ms/step - loss: 7.1922 - mae: 2.0829 - val
819/819
Epoch 8/20
819/819 -
                            - 13s 16ms/step - loss: 6.9519 - mae: 2.0504 - val
Epoch 9/20
819/819
                            • 13s 15ms/step - loss: 6.7164 - mae: 2.0066 - val
405/405 -
                            4s 10ms/step - loss: 10.8891 - mae: 2.5908
lstm - Test MAE: 2.59
                                     LSTM Model
```



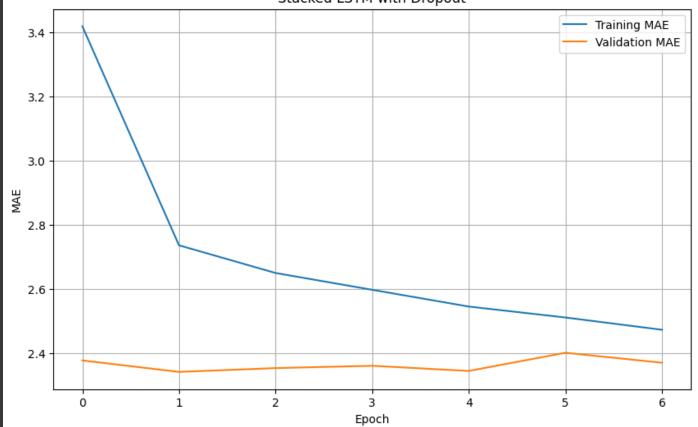
- Single LSTM layer with 32 units
- Tests if LSTM gates provide advantage over GRU
- Test MAE: 2.59 (slightly worse than GRU)
- · Training history shows similar pattern to GRU

Experiment 4: Stacked LSTM with dropout

```
print("\n--- Experiment 4: Stacked LSTM with dropout ---")
model_stacked_lstm, history_stacked_lstm, mae_stacked_lstm = build_and_train_mode
    model_type="stacked_lstm_dropout",
    units=64,
    num_layers=2,
    use_lstm=True,
    dropout_rate=0.3,
    recurrent_dropout_rate=0.3
)
results["Stacked LSTM with Dropout"] = mae_stacked_lstm
plot_history(history_stacked_lstm, "Stacked LSTM with Dropout")
```

```
--- Experiment 4: Stacked LSTM with dropout ---
Epoch 1/20
819/819 -
                            - 490s 590ms/step - loss: 37.4233 - mae: 4.4695 - v
Epoch 2/20
819/819
                             480s 586ms/step - loss: 12.4784 - mae: 2.7624 - v
Epoch 3/20
                            - 483s 590ms/step - loss: 11.5766 - mae: 2.6596 - v
819/819 -
Epoch 4/20
819/819 -
                             • 481s 587ms/step - loss: 11.0710 - mae: 2.6046 - v
Epoch 5/20
819/819
                             • 481s 588ms/step - loss: 10.6913 - mae: 2.5582 - v
Epoch 6/20
819/819
                             • 477s 582ms/step - loss: 10.3268 - mae: 2.5150 - v
Epoch 7/20
819/819 -
                             • 478s 584ms/step - loss: 10.0125 - mae: 2.4795 - v
405/405 -
                            - 50s 124ms/step - loss: 10.0558 - mae: 2.4708
stacked 1stm dropout - Test MAE: 2.48
```

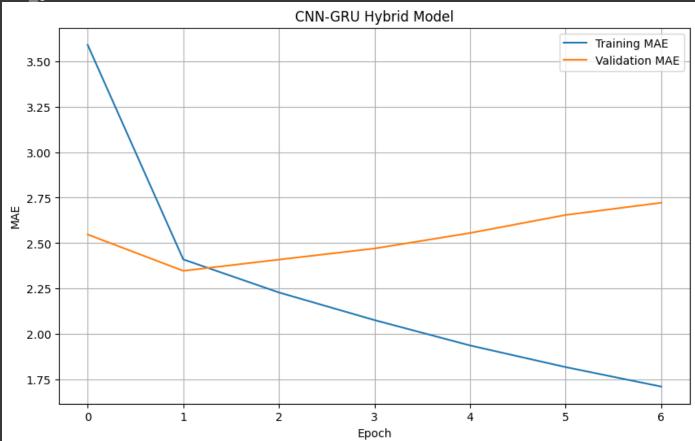
Stacked LSTM with Dropout



- Two LSTM layers with 64 units
- Dropout rate of 0.3 (regularization) 8 Recurrent dropout of 0.3 (internal state regularization)
- Test MAE: 2.48 (best performing model)
- Training is significantly slower due to dropout computation

Experiment 5: CNN-GRU hybrid

```
--- Experiment 5: CNN-GRU hybrid ---
Epoch 1/20
819/819
                            • 16s 16ms/step - loss: 46.7453 - mae: 4.9723 - val
Epoch 2/20
819/819
                             12s 15ms/step - loss: 10.2419 - mae: 2.4719 - val
Epoch 3/20
819/819 -
                            12s 15ms/step - loss: 8.5170 - mae: 2.2719 - val
Epoch 4/20
819/819
                             12s 15ms/step - loss: 7.3945 - mae: 2.1129 - val
Epoch 5/20
819/819
                            13s 15ms/step - loss: 6.4479 - mae: 1.9709 - val
Epoch 6/20
819/819
                            12s 15ms/step - loss: 5.6881 - mae: 1.8503 - val
Epoch 7/20
819/819
                            12s 15ms/step - loss: 5.0211 - mae: 1.7388 - val
405/405 -
                            • 4s 10ms/step - loss: 11.0326 - mae: 2.5865
cnn gru - Test MAE: 2.59
```

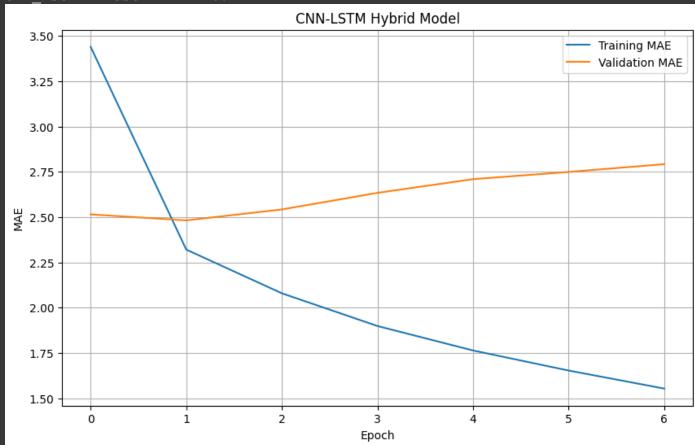


- CNN layers for feature extraction
- GRU layer for sequence processing
- Test MAF: 2:59
- Shows CNN preprocessing doesn't help in this case

Experiment 6: CNN-LSTM hybrid

```
print("\n--- Experiment 6: CNN-LSTM hybrid ---")
model_cnn_lstm, history_cnn_lstm, mae_cnn_lstm = build_and_train_model(
    model_type="cnn_lstm",
    units=32,
    num_layers=1,
    use_lstm=True,
    use_cnn=True
)
results["CNN-LSTM Hybrid"] = mae_cnn_lstm
plot_history(history_cnn_lstm, "CNN-LSTM Hybrid Model")
```

```
--- Experiment 6: CNN-LSTM hybrid ---
Epoch 1/20
819/819
                            • 14s 16ms/step - loss: 42.9937 - mae: 4.7298 - val
Epoch 2/20
819/819
                             12s 15ms/step - loss: 9.6751 - mae: 2.4005 - val
Epoch 3/20
819/819 -
                            12s 15ms/step - loss: 7.5411 - mae: 2.1225 - val
Epoch 4/20
819/819
                             12s 15ms/step - loss: 6.3483 - mae: 1.9378 - val
Epoch 5/20
819/819
                            12s 15ms/step - loss: 5.4482 - mae: 1.7868 - val
Epoch 6/20
819/819
                             12s 15ms/step - loss: 4.7968 - mae: 1.6753 - val
Epoch 7/20
819/819
                            12s 15ms/step - loss: 4.2490 - mae: 1.5749 - val
405/405 -
                            • 4s 9ms/step - loss: 11.6006 - mae: 2.6719
cnn lstm - Test MAE: 2.67
```

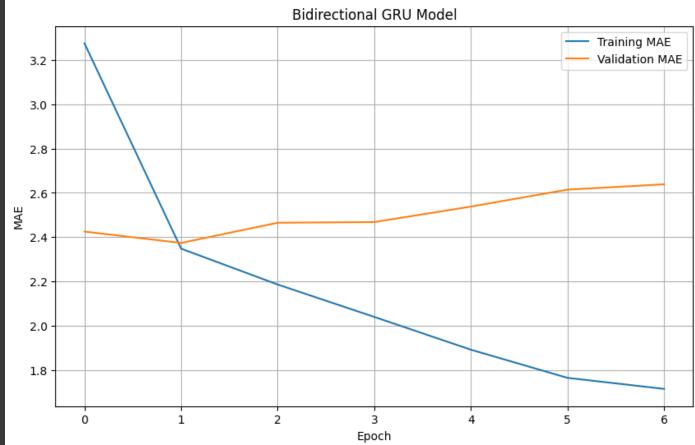


- CNN layers followed by LSTM
- Test MAE: 2.67 (worst performing model)
- Confirms CNN isn't beneficial for this dataset

Experiment 7: Bidirectional GRU

```
print("\n--- Experiment 7: Bidirectional GRU ---")
model_bidirectional_gru, history_bidirectional_gru, mae_bidirectional_gru = build_
    model_type="bidirectional_gru",
    units=32,
    num_layers=1,
    use_lstm=False,
    bidirectional=True
)
results["Bidirectional GRU"] = mae_bidirectional_gru
plot_history(history_bidirectional_gru, "Bidirectional GRU Model")
```

```
--- Experiment 7: Bidirectional GRU ---
Epoch 1/20
819/819
                            - 19s 20ms/step - loss: 43.3996 - mae: 4.7619 - val
Epoch 2/20
819/819 -
                             16s 19ms/step - loss: 9.4375 - mae: 2.3972 - val
Epoch 3/20
819/819 -
                            - 16s 19ms/step - loss: 8.0995 - mae: 2.2209 - val
Epoch 4/20
819/819 -
                             16s 20ms/step - loss: 7.0379 - mae: 2.0737 - val
Epoch 5/20
819/819
                            16s 19ms/step - loss: 6.0359 - mae: 1.9229 - val
Epoch 6/20
819/819
                            16s 19ms/step - loss: 5.2560 - mae: 1.7902 - val
Epoch 7/20
819/819 -
                            16s 19ms/step - loss: 4.7682 - mae: 1.7016 - val
405/405 -
                            - 4s 10ms/step - loss: 10.0268 - mae: 2.4718
bidirectional gru - Test MAE: 2.48
```

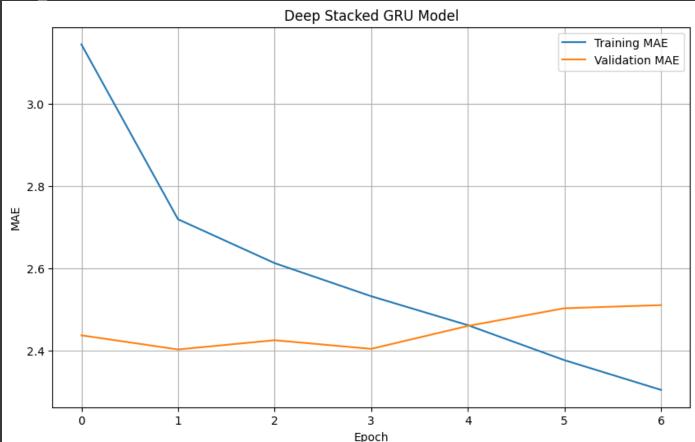


- GRU that processes sequence in both directions
- Can capture dependencies regardless of position
- Test MAE: 2.48 (ties for best performance)
- · Shows bidirectional processing is valuable

Experiment 8: Deep Stacked GRU with higher capacity

```
print("\n--- Experiment 8: Deep Stacked GRU with higher capacity ---")
model_deep_gru, history_deep_gru, mae_deep_gru = build_and_train_model(
    model_type="deep_gru",
    units=128,
    num_layers=3,
    use_lstm=False,
    dropout_rate=0.4,
    recurrent_dropout_rate=0.2
)
results["Deep GRU"] = mae_deep_gru
plot_history(history_deep_gru, "Deep Stacked GRU Model")
```

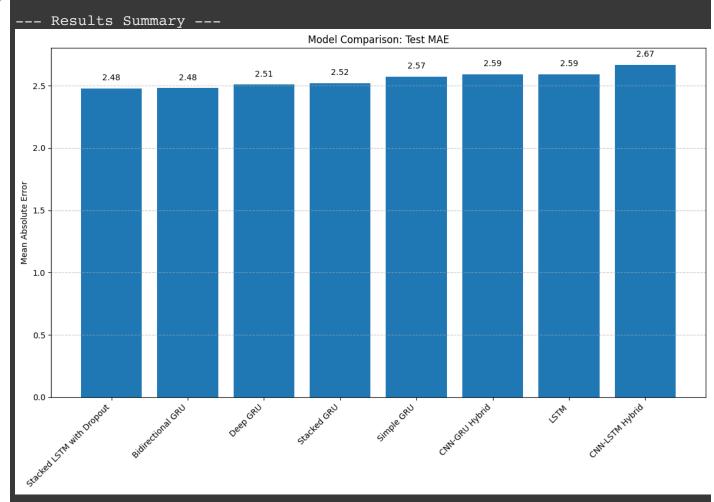
```
--- Experiment 8: Deep Stacked GRU with higher capacity ---
Epoch 1/20
819/819
                            • 692s 835ms/step - loss: 27.1839 - mae: 3.8400 - v
Epoch 2/20
819/819
                             673s 822ms/step - loss: 12.2681 - mae: 2.7462 - v
Epoch 3/20
819/819 -
                            - 670s 818ms/step - loss: 11.2819 - mae: 2.6305 - v
Epoch 4/20
819/819
                             666s 813ms/step - loss: 10.5555 - mae: 2.5478 - v
Epoch 5/20
819/819
                             667s 815ms/step - loss: 9.9671 - mae: 2.4751 - va
Epoch 6/20
819/819
                             664s 811ms/step - loss: 9.2700 - mae: 2.3860 - va
Epoch 7/20
                            • 663s 810ms/step - loss: 8.7941 - mae: 2.3212 - va
819/819
405/405 -
                            - 71s 175ms/step - loss: 10.1598 - mae: 2.5019
deep gru - Test MAE: 2.51
```



- Three GRU layers with 128 units
- Higher capacity with more regularization
- Test MAF: 2 51
- Shows diminishing returns with more complexity

Part 5: Results Summary and Visualization

```
print("\n--- Results Summary ---")
results_sorted = sorted(results.items(), key=lambda x: x[1])
# Create a bar chart
plt.figure(figsize=(12, 8))
models = [r[0] for r in results_sorted]
maes = [r[1] for r in results sorted]
bars = plt.bar(models, maes)
plt.xticks(rotation=45, ha='right')
plt.title('Model Comparison: Test MAE')
plt.ylabel('Mean Absolute Error')
plt.grid(axis='y', linestyle='--', alpha=0.7)
# Add value labels on top of bars
for bar in bars:
    height = bar.get_height()
    plt.text(bar.get_x() + bar.get_width()/2., height + 0.05,
            f'{height:.2f}', ha='center', va='bottom')
plt.tight_layout()
plt.savefig("model_comparison.png")
plt.show()
```



A bar chart is created to compare the performance of all models

Print results in table format

```
print("\nModel Performance Summary (Test MAE):")
print("-" * 50)
print(f"{'Model Type':<30} {'Test MAE':<10}")
print("-" * 50)
for model, mae in results_sorted:
    print(f"{model:<30} {mae:<10.2f}")
print("-" * 50)</pre>
```

 $\overline{\Rightarrow}$

Model Performance Summary (Test MAE):

Model Type Tes	st MAE
Stacked LSTM with Dropout Bidirectional GRU Deep GRU Stacked GRU Simple GRU CNN-GRU Hybrid LSTM CNN-LSTM Hybrid 2.6	48 51 52 57 59

Shows all models ranked by performance

Find best model

```
best_model_name, best_mae = results_sorted[0]
print(f"\nBest performing model: {best_model_name} with MAE of {best_mae:.2f}")
```



Best performing model: Stacked LSTM with Dropout with MAE of 2.48

- Records the top-performing model
- "Stacked LSTM with Dropout" with MAE of 2.48

Print improvement percentage over baseline

```
baseline_mae = evaluate_naive_method(test_dataset)
improvement = ((baseline_mae - best_mae) / baseline_mae) * 100
print(f"Improvement over baseline: {improvement:.2f}%")
```

- → Improvement over baseline: 5.39%
 - Compares best model to baseline
 - 5.39% improvement over naive approach

Overall Process Flow:

- The code first establishes the problem: predicting temperature 24 hours in advance using
 days of historical weather data
- 2. It implements a simple baseline to benchmark against
- 3. It systematically tests different RNN architectures (GRU vs LSTM, stacked vs single layer, etc.)
- 4. It applies regularization techniques like dropout to prevent overfitting
- 5. It compares all models and identifies the best performers
- 6. It quantifies improvement over the baseline approach

The results show that while neural networks provide improvement, the benefit is modest (5.39%), suggesting that temperature prediction is inherently challenging with this approach or that there might be room for further optimization