

7.7. Let B_t be Brownian motion on \mathbf{R}^n starting at $x \in \mathbf{R}^n$ and let $D \subset \mathbf{R}^n$ be an open ball centered at x .

- a) Use Exercise 2.15 to prove that the harmonic measure μ_D^x of B_t is rotation invariant (about x) on the sphere ∂D . Conclude that μ_D^x coincides with normalized surface measure σ on ∂D .
 b) Let ϕ be a bounded measurable function on a bounded open set $W \subset \mathbf{R}^n$ and define

$$u(x) = E^x[\phi(B_{\tau_W})] \quad \text{for } x \in W.$$

Prove that u satisfies the classical mean value property:

$$u(x) = \int_{\partial D} u(y) d\sigma(y)$$

for all balls D centered at x with $\overline{D} \subset W$.

a) First we want to show that

Definition 6.2.6 (Harmonic Measure). The **harmonic measure** of X on ∂G , denoted by μ_G^x , is defined as
 $\mu_G^x(F) = Q^x[X_{\tau_G} \in F], \quad \text{for } F \subset \partial G, x \in G$

$$\mu_D^x(UF) = \mu_D^x(F)$$

where U is a rotation (i.e., orthogonal matrix on $\mathbb{R}^{n \times n}$).

By the exercise 2.15.,

2.15. Let B_t be n -dimensional Brownian motion starting at 0 and let $U \in \mathbf{R}^{n \times n}$ be a (constant) orthogonal matrix, i.e. $UU^T = I$. Prove that

$$\tilde{B}_t := UB_t$$

is also a Brownian motion.

it follows that

$$\begin{aligned} Q^x[B_{\tau_D} \in F] &= Q^x[UB_{\tau_D} \in UF] \\ &= Q^x[\tilde{B}_{\tau_D} \in UF] \\ &= Q^x[B_{\tau_D} \in UF] \end{aligned}$$

Hence, $\mu_D^x(UF) = \mu_D^x(F)$.

To show that $\mu_D^x = \sigma$ on ∂D , notice that

$$\begin{aligned}
 \int_{\partial D} f(x) d\sigma(x) &= \int_{SO(n)} \int_{\partial D} f(gx) d\sigma(x) d\nu(g) && \text{where } \nu \text{ is left-inv.} \\
 &&& \text{measure on } SO(n) \\
 &= \int_{\partial D} \int_{SO(n)} f(gx) d\nu(g) d\sigma(x) && \text{by Fubini's thm.} \\
 &= \int_{\partial D} \int_{\partial D} f(y) d\mu_D^x(y) d\sigma(x) && \text{since } \mu_D^x \text{ is} \\
 &&& \text{rot. invariant} \\
 &= \int_{\partial D} f(y) d\mu_D^x(y) && \text{since } \sigma \text{ is a} \\
 &&& \text{normalized surf. meas.}
 \end{aligned}$$

Since f is arbitrary, $\sigma = \mu_D^x$ on ∂D as desired.

b) We know that

$$\mathbb{E}^x[f(X_{\tau_H})] = \mathbb{E}^x[\mathbb{E}^{X_{\tau_0}}[f(X_{\tau_H})]] = \int_{\partial G} \mathbb{E}^y[f(X_{\tau_H})] Q^x[X_{\tau_0} \in dy]$$

for $x \in G$.

Plus the fact that $\sigma = \mu_D^x$ on ∂D , it follows that

$$\begin{aligned}
 u(x) &= \mathbb{E}^x[\varphi(B_{\tau_D})] = \int_{\partial D} \mathbb{E}^y[\varphi(B_{\tau_D})] \mu_D^x(dy) \\
 &= \int_{\partial D} u(y) d\mu_D^x(y) = \int_{\partial D} u(y) d\sigma(y)
 \end{aligned}$$

□