

- 3.1. Prove directly from the definition of Itô integrals (Definition 3.1.6) that

$$\int_0^t s dB_s = tB_t - \int_0^t B_s ds.$$

(Hint: Note that

$$\sum_j \Delta(s_j B_j) = \sum_j s_j \Delta B_j + \sum_j B_{j+1} \Delta s_j .$$

Our first step is to define an elementary function and prove that it converges to our function  $\varphi(s) = s$  in  $L^2(\mathbb{P})$ .

Let  $\varphi_n = \sum_j s_j \chi_{[t_j, t_{j+1})}(s)$ . Then,

$$\begin{aligned} & \mathbb{E} \left[ \int_0^t (\varphi_n - s)^2 ds \right] = \mathbb{E} \left[ \sum_j \int_{t_j}^{t_{j+1}} (s_j - s)^2 ds \right] \\ & * = \sum_j \int_{t_j}^{t_{j+1}} (s - t_j)^2 ds = \sum_j \frac{1}{2} (t_{j+1} - t_j)^2 \end{aligned}$$

Hence,

$$\lim_{\Delta t_j \rightarrow 0} \sum_j \frac{1}{2} (t_{j+1} - t_j)^2 = 0$$

\* Recall that

$$\mathbb{E}[(B_t - B_s)^2] = t - s$$

and

$$\int_0^t s dB_s = \lim_{\Delta t_j \rightarrow 0} \int_0^t \varphi_n dB_s = \lim_{\Delta t_j \rightarrow 0} \sum_j s_j \Delta B_j$$

Now, using the fact that

$$\sum_j s_j \Delta B_j = \sum_j \Delta(s_j B_j) - \sum_j B_{j+1} \Delta s_j$$

we have

$$\begin{aligned} \lim_{\Delta t_j \rightarrow 0} \sum_j s_j \Delta B_j &= \lim_{\Delta t_j \rightarrow 0} \sum_j \Delta(s_j B_j) - \lim_{\Delta t_j \rightarrow 0} B_{j+1} \Delta s_j \\ &= tB_t - \int_0^t B_s ds \end{aligned}$$

ØKSENDAL 3.2

We want to prove that

$$\int_0^+ B_s^2 dB_s = \frac{1}{3} B_+^3 - \int_0^+ B_s ds$$

First, let

$$\varphi_n(s) = \sum_j B_j^2 \chi_{[t_j, t_{j+1})}(s)$$

Notice that

$$\begin{aligned} \mathbb{E} \left[ \int_0^+ (\varphi_n - B_s^2)^2 ds \right] &= \mathbb{E} \left[ \sum_j \int_{t_j}^{t_{j+1}} (B_j^2 - B_s^2)^2 ds \right] \\ &= \sum_j \int_{t_j}^{t_{j+1}} (s^2 - t_j^2) ds = \sum_j \frac{1}{3} (t_{j+1} - t_j)^3 \rightarrow 0 \end{aligned}$$

as  $\Delta t_j \rightarrow 0$ .

Hence,

$$\int_0^+ B_s^2 dB_s = \lim_{\Delta t_j \rightarrow 0} \int_0^+ \varphi_n(s) dB_s = \lim_{\Delta t_j \rightarrow 0} \sum_j B_j^2 \Delta B_j$$

Using the identity

$$B_j^2 (B_{j+1} - B_j) = \frac{1}{3} (B_{j+1}^3 - B_j^3) - B_j (B_{j+1} - B_j)^2 - \frac{1}{3} (B_{j+1} - B_j)^3$$

We obtain

$$\begin{aligned} \lim_{\Delta t_j \rightarrow 0} \sum_j B_j^2 (B_{j+1} - B_j) &= \lim_{\Delta t_j \rightarrow 0} \sum_j \frac{1}{3} (B_{j+1}^3 - B_j^3) \\ &\quad - \lim_{\Delta t_j \rightarrow 0} \sum_j B_j (B_{j+1} - B_j)^2 \\ &\quad - \lim_{\Delta t_j \rightarrow 0} \sum_j \frac{1}{3} (B_{j+1} - B_j)^3 \end{aligned}$$

Evaluating these limits,

- $\lim_{\Delta t_j \rightarrow 0} \sum_j \frac{1}{3} (B_{j+1}^3 - B_j^3) = \frac{1}{3} B_+^3 - \frac{1}{3} B_0^3 = \frac{1}{3} B_+^3$

- $\lim_{\Delta t_j \rightarrow 0} \sum_j \frac{1}{3} (B_{j+1} - B_j)^3 = 0$
- $\lim_{\Delta t_j \rightarrow 0} \sum_j B_j (B_{j+1} - B_j)^2 = \lim_{\Delta t_j \rightarrow 0} \sum_j B_j (B_{j+1} - B_j)$   
 $+ \lim_{\Delta t_j \rightarrow 0} \sum_j B_j [(B_{j+1} - B_j)^2 - (B_{j+1} - B_j)]$   
 $= \int_0^+ B_s ds + 0$

Taking all these parts together:

$$\lim_{\Delta t_j \rightarrow 0} \sum_j B_j^2 (B_{j+1} - B_j) = \frac{1}{3} B_+^3 - \int_0^+ B_s ds$$

Thus,

$$\begin{aligned} \int_0^+ B_s^2 dB_s &= \lim_{\Delta t_j \rightarrow 0} \sum_j B_j^2 \Delta B_j \\ &= \frac{1}{3} B_+^3 - \int_0^+ B_s ds \end{aligned}$$

### QKsendal 3.3

$X_t: \Omega \rightarrow \mathbb{R}^n$  stochastic process

$\mathcal{F}_t$   $\sigma$ -algebra generated by  $\{X_s: s \leq t\}$  (filtration of the process)

a) Show that if  $X_t$  is a martingale w.r.t. some filtration  $\{\mathcal{N}_t\}$ , then  $X_t$  is also a martingale w.r.t. its own filtration  $\{\mathcal{F}_t\}$ .

Suppose that  $X_t$  is a martingale w.r.t. some filtration  $\{\mathcal{N}_t\}$ .

That means that

1.  $X_t$  is  $\mathcal{N}_t$ -measurable for all  $t$ .

2.  $\mathbb{E}[|X_t|] < \infty$

3.  $\mathbb{E}[X_t | \mathcal{N}_s] = X_s, s \leq t$

What we need to show is that  $X_t$  is a martingale w.r.t. its natural filtration generated by  $X_s, s=0,1,\dots,t$

In fact,

1.  $X_t$  is  $\mathcal{F}_t$ -measurable for all  $t$ , since  $\mathcal{F}_t$  contains all available information at the time  $t$ .

2.  $\mathbb{E}[|X_t|] < \infty$  remains.

3. Since  $\mathcal{F}_t \subseteq \mathcal{N}_t$ ,

$$\mathbb{E}[X_t | \mathcal{F}_s] = \mathbb{E}[\mathbb{E}[X_t | \mathcal{N}_s] | \mathcal{F}_s] = \mathbb{E}[X_s | \mathcal{F}_s] = X_s$$

for  $s \leq t$ .

Hence,  $X_t$  is a martingale w.r.t. its own filtration. □

b) If  $X_t$  is a martingale w.r.t.  $\mathcal{F}_t$ , then

$$\mathbb{E}[X_t] = \mathbb{E}[X_0] \quad \text{for all } t \geq 0$$

Notice that since  $X_t$  is a martingale w.r.t.  $\mathcal{F}_t$

$$\mathbb{E}[X_t | \mathcal{F}_0] = X_0$$

law of total expectation

However,

$$\mathbb{E}[X_t] = \mathbb{E}[\mathbb{E}[X_t | \mathcal{F}_0]] = \mathbb{E}[X_0]$$

Hence,

$$\mathbb{E}[X_t] = \mathbb{E}[X_0]$$

c) Example of stochastic process  $X_t$  satisfying  
 $E[X_t] = E[X_0]$  for all  $t \geq 0$

and which is not a martingale w.r.t. its own filtration.

Take  $Y_t$  with  $Y_0 = 0$  and  $U$  a uniform  $\pm 1$  r.v.  
independent from  $Y_t$ . Then,

$$E[UY_t] = \frac{1}{2}[Y_t] + \frac{1}{2}[-Y_t] = 0$$

However,

$$\begin{aligned} E[UY_t | \mathcal{F}_s] &= E[U(Y_t + Y_s - Y_s) | \mathcal{F}_s] \\ &= E[U(Y_t - Y_s) | \mathcal{F}_s] + E[U(Y_s) | \mathcal{F}_s] \\ &= E[U | \mathcal{F}_s] \cdot E[Y_t - Y_s | \mathcal{F}_s] + E[U(Y_s) | \mathcal{F}_s] \\ &= Y_s E[U | \mathcal{F}_s] = 0 \end{aligned}$$

### Øksendal 3.4

i)  $X_t = B_t + 4t$

1.  $X_t$  is  $\mathcal{F}_t$ -measurable for all  $t$  since  $B_t$  is.

2.  $E[X_t] = E[B_t + 4t] \leq E[|B_t|] + E[|4t|] < \infty$

since  $B_t$  is a martingale and  $|4t|$  is a constant.

3.  $E[X_t | \mathcal{F}_s] = X_s, s \leq t$

Notice that

$$E[B_t + 4t | \mathcal{F}_s] = B_s + 4t + X_s \quad \therefore \text{Not a martingale}$$

ii)  $X_t = B_t^2$   $B_t^{(1)}(\omega) = \{\omega \in \Omega : B_t^2(\omega) \in U\} \subseteq \mathcal{F}_t$

1.  $X_t$  is  $\mathcal{F}_t$ -measurable

2.  $E[X_t] = E[B_t^2]$  may not be finite

3.  $E[X_t | \mathcal{F}_s] = X_s, s \leq t$

$$E[B_t^2 | \mathcal{F}_s] = E[(B_t - B_s + B_s)^2 | \mathcal{F}_s]$$

$$= E[(B_t - B_s)^2 | \mathcal{F}_s] + 2E[(B_t - B_s)B_s | \mathcal{F}_s] + E[B_s^2 | \mathcal{F}_s]$$

$$= t-s + B_s^2 + B_s^2 \quad (s < t)$$

$\therefore$  Not a martingale

iii)  $X_t = t^2 B_t - 2 \int_0^t s B_s ds$

1.  $X_t$  is  $\mathcal{F}_t$ -measurable.

2.  $E[X_t] \leq E[t^2 B_t] + 2E\left[\int_0^t s B_s ds\right] < \infty$

3.  $E[X_t | \mathcal{F}_s] = E\left[t^2 B_t - 2 \int_0^t s B_s ds \mid \mathcal{F}_s\right]$

$$= t^2 B_s - 2 \int_0^s r B_r dr - 2E\left[\int_s^t r B_r dr \mid \mathcal{F}_s\right]$$

$$= t^2 B_s - 2 \int_0^s r B_r dr - 2 \int_s^t r E[B_r | \mathcal{F}_s] dr$$

$$= t^2 B_s - 2 \int_0^s r B_r dr - 2 \int_s^t r B_r dr$$

$$= t^2 B_t - 2 \int_0^t s B_s ds - B_t (t^2 - s^2) = s^2 B_s - 2 \int_0^s s B_s ds$$

$\therefore$  is a martingale

IV.)  $X_t = B_1(t) B_2(t)$  where  $(B_1(t), B_2(t))$  is a 2-dim BM.

1.  $X_t$  is  $\mathcal{F}_t$ -measurable since  $B_1(t)$  and  $B_2(t)$  is.

2.  $\mathbb{E}[|X_t|] = \mathbb{E}[|B_1(t)|] \cdot \mathbb{E}[|B_2(t)|] < \infty$

3.  $\mathbb{E}[X_t | \mathcal{F}_s] = B_1(s) \cdot B_2(s) = X_s, \quad s \leq t$

$\therefore$  is a martingale

Øksendal 3.5

Prove that

$$M_t = B_t^2 - t$$

is an  $\mathcal{F}_t$ -martingale.

What we need to show is:

1.  $M_t$  is  $\mathcal{F}_t$ -measurable
2.  $\mathbb{E}[|M_t|] < \infty$
3.  $\mathbb{E}[M_t | \mathcal{F}_s] = m_s, s \leq t$

The first is immediate. Since  $B_t^2$  and  $t$  are  $\mathcal{F}_t$ -measurable,  $M_t$  also is.

Now notice that

$$\begin{aligned} \mathbb{E}[|M_t|] &= \mathbb{E}[|B_t^2 - t|] \leq \mathbb{E}[|B_t^2|] + \mathbb{E}[|t|] \\ &< \infty \end{aligned}$$

Finally,

$$\begin{aligned} \mathbb{E}[M_t | \mathcal{F}_s] &= \mathbb{E}[B_t^2 - t | \mathcal{F}_s] \\ &= \mathbb{E}[(B_t - B_s + B_s)^2 | \mathcal{F}_s] - \mathbb{E}[t | \mathcal{F}_s] \\ &= \mathbb{E}[(B_t - B_s)^2 | \mathcal{F}_s] + 2\mathbb{E}[(B_t - B_s)B_s | \mathcal{F}_s] + \mathbb{E}[B_s^2 | \mathcal{F}_s] - \mathbb{E}[t | \mathcal{F}_s] \\ &= t - s + B_s^2 - t = B_s^2 - s = m_s \end{aligned}$$

for  $s \leq t$  as desired.

3.6. Prove that  $N_t = B_t^3 - 3tB_t$  is a martingale.

Let  $\mathcal{F}_t$  be the natural filtration of  $B_t$ , i.e., generated by  $\{B_s : s \leq t\}$

Clearly,  $N_t$  is  $\mathcal{F}_t$ -measurable, since  $B_t^3$  and  $3tB_t$  is.

Now we need to check that  $\mathbb{E}[|N_t|] < \infty$ . In fact,

$$\begin{aligned}\mathbb{E}[|N_t|] &= \mathbb{E}[|B_t^3 - 3tB_t|] \leq \mathbb{E}[|B_t^3|] + \mathbb{E}[|3tB_t|] \\ &= \mathbb{E}[|B_t|^3] + 3t \mathbb{E}[|B_t|] < \infty\end{aligned}$$

Finally,

$$\begin{aligned}\mathbb{E}[N_s | \mathcal{F}_t] &= \mathbb{E}[B_s^3 - 3sB_s | \mathcal{F}_t] \\ &= \mathbb{E}[B_s^3 | \mathcal{F}_t] - 3s \mathbb{E}[B_s | \mathcal{F}_t]\end{aligned}$$

Notice that

$$\begin{aligned}(B_s - B_t + B_t)^3 &= ([B_s - B_t]^2 + 2(B_s - B_t)B_t + B_t^2)([B_s - B_t] + B_t) \\ &= [B_s - B_t]^3 + 3[B_s - B_t]^2 B_t + 3(B_s - B_t)B_t^2 + B_t^3\end{aligned}$$

Therefore,

$$\begin{aligned}\mathbb{E}[B_s^3 | \mathcal{F}_t] &= \mathbb{E}[(B_s - B_t + B_t)^3 | \mathcal{F}_t] \\ &= \mathbb{E}[(B_s - B_t)^3 | \mathcal{F}_t] + 3 \mathbb{E}[(B_s - B_t)^2 B_t | \mathcal{F}_t] \\ &\quad + 3 \mathbb{E}[(B_s - B_t)B_t^2 | \mathcal{F}_t] + \mathbb{E}[B_t^3 | \mathcal{F}_t] \\ &= 0 + 3B_t \mathbb{E}[(B_s - B_t)^2 | \mathcal{F}_t] + 3B_t^2 \mathbb{E}[(B_s - B_t) | \mathcal{F}_t] + B_t^3 \\ &= 3B_t(s-t) + 0 + B_t^3\end{aligned}$$

Thus,

$$\begin{aligned}\mathbb{E}[B_s^3 | \mathcal{F}_t] - 3s \mathbb{E}[B_s | \mathcal{F}_t] &= B_t^3 - 3(t-s)B_t - 3sB_t \\ &= B_t^3 - 3tB_t\end{aligned}$$

as desired. □

- 3.7. A famous result of Itô (1951) gives the following formula for  $n$  times iterated Itô integrals:

$$n! \int_0^t \cdots \left( \int_0^t \left( \int_0^t dB_{u_1} \right) dB_{u_2} \right) \cdots dB_{u_n} = t^{\frac{n}{2}} h_n \left( \frac{B_t}{\sqrt{t}} \right) \quad (3.3.8)$$

where  $h_n$  is the *Hermite polynomial* of degree  $n$ , defined by

$$h_n(x) = (-1)^n e^{\frac{x^2}{2}} \frac{d^n}{dx^n} (e^{-\frac{x^2}{2}}); \quad n = 0, 1, 2, \dots$$

(Thus  $h_0(x) = 1$ ,  $h_1(x) = x$ ,  $h_2(x) = x^2 - 1$ ,  $h_3(x) = x^3 - 3x$ .)

- a) Verify that in each of these  $n$  Itô integrals the integrand satisfies the requirements in Definition 3.1.4.

Recall that

**Definition 3.1.4.** Let  $\mathcal{V} = \mathcal{V}(S, T)$  be the class of functions

$$f(t, \omega): [0, \infty) \times \Omega \rightarrow \mathbb{R}$$

such that

- (i)  $(t, \omega) \mapsto f(t, \omega)$  is  $\mathcal{B} \times \mathcal{F}$ -measurable, where  $\mathcal{B}$  denotes the Borel  $\sigma$ -algebra on  $[0, \infty)$ .
- (ii)  $f(t, \omega)$  is  $\mathcal{F}_t$ -adapted.
- (iii)  $E \left[ \int_S^T f(t, \omega)^2 dt \right] < \infty$ .

Since  $f(t, \omega) = s$ ,  $f$  is  $\mathcal{B} \times \mathcal{F}$ -measurable and  $\mathcal{F}_t$ -adapted.  
Moreover,

$$\mathbb{E} \left[ \int_s^T dt \right] = \mathbb{E}[T-s] = T-s < \infty$$

- b) Verify formula (3.3.8) for  $n = 1, 2, 3$  by combining Example 3.1.9 and Exercise 3.2.

For  $n=1$ , we have

$$\mathbb{E} \left[ \int_0^t dB_{u_1} \right] = B_t = t^{1/2} h_1 \left( \frac{B_t}{\sqrt{t}} \right) = t^{1/2} \cdot \frac{B_t}{t^{1/2}}$$

For  $n=2$ ,

$$\begin{aligned} \mathbb{E} \left[ \int_0^t \int_0^u dB_{u_1} dB_{u_2} \right] &= \mathbb{E} \left[ \int_0^t B_u dB_{u_2} \right] = \frac{1}{2} (B_u^2 - u) \Big|_0^t \\ &= \frac{1}{2} (B_t^2 - t) = \frac{t^{2/2}}{2} \left( \left( \frac{B_t}{\sqrt{t}} \right)^2 - 1 \right) \\ &= \frac{t^{2/2}}{2} h_2 \left( \frac{B_t}{\sqrt{t}} \right) \end{aligned}$$

\* Example  
3.1.9

For  $n=3$ :

$$\begin{aligned}
 & \int_0^+ \int_0^u \int_0^v dB_r dB_v dB_u = \int_0^+ \int_0^u B_v dB_v dB_u \\
 &= \int_0^+ \frac{1}{2} (B_v^2 - v) \Big|_0^u dB_u = \int_0^+ \frac{1}{2} (B_u^2 - u) dB_u \\
 &= \frac{1}{2} \left[ \int_0^+ B_u^2 dB_u - \int_0^+ u dB_u \right] \\
 &\stackrel{*}{=} \frac{1}{2} \left[ \frac{1}{3} B_+^3 - \int_0^+ B_u du - \int_0^+ u dB_u \right] \\
 &\stackrel{*}{=} \frac{1}{3!} B_+^3 - \frac{1}{2} B_+ = \frac{1}{3!} \left[ \left( \frac{B_+}{\sqrt{t}} \right)^3 - 3 \frac{B_+}{\sqrt{t}} \right] \\
 &= \frac{1}{3!} \frac{3^{3/2}}{2} h_3 \left( \frac{B_+}{\sqrt{t}} \right)
 \end{aligned}$$

\* Exercise 3.2

\* Since

$$\int_0^+ B_s ds + \int_0^+ s dB_s = t B_+$$

Exercise 3.1.

c) Use b) to give a new proof of the statement in Exercise 3.6.

Since

$$\int_0^+ (B_s^2 - s) dB_s = h_1 \left( \frac{B_+}{\sqrt{t}} \right)$$

is a martingale (the integral of B.M. is martingale), we have what we wanted.  $\square$

3.8. a) Let  $Y$  be a real valued random variable on  $(\Omega, \mathcal{F}, P)$  such that

$$E[|Y|] < \infty.$$

Define

$$M_t = E[Y|\mathcal{F}_t]; \quad t \geq 0.$$

Show that  $M_t$  is an  $\mathcal{F}_t$ -martingale.

b) Conversely, let  $M_t; t \geq 0$  be a real valued  $\mathcal{F}_t$ -martingale such that

$$\sup_{t \geq 0} E[|M_t|^p] < \infty \quad \text{for some } p > 1.$$

Show that there exists  $Y \in L^1(P)$  such that

$$M_t = E[Y|\mathcal{F}_t].$$

(Hint: Use Corollary C.7.)

$$\begin{aligned} a) \quad & \mathbb{E}[M_s | \mathcal{F}_t] = \mathbb{E}[\mathbb{E}[Y | \mathcal{F}_s] | \mathcal{F}_t] \\ & = \mathbb{E}[Y | \mathcal{F}_t] = M_t \end{aligned}$$

for all  $s \geq t$

- $M_t = \mathbb{E}[Y | \mathcal{F}_t] = Y$  is  $\mathcal{F}_t$ -measurable
- $\mathbb{E}[|M_t|] = \mathbb{E}[|\mathbb{E}[Y | \mathcal{F}_t]|] = \mathbb{E}[|Y|] < \infty$

Thus,  $M_t$  is an  $\mathcal{F}_t$ -martingale.

b)

**Corollary C.7.** Let  $M_t$  be a continuous martingale such that

$$\sup_{t > 0} E[|M_t|^p] < \infty \quad \text{for some } p > 1.$$

Then there exists  $M \in L^1(P)$  such that  $M_t \rightarrow M$  a.e. ( $P$ ) and

$$\int |M_t - M| dP \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

By the Corollary C.7, there exists  $m \in L^1(P)$  such that  $M_t \rightarrow m$  a.e. and

$$\lim_{t \rightarrow \infty} \int m_t dP = \int m dP$$

Given that  $M_t$  is a martingale for all  $s \geq t$ , for  $A \in \mathcal{F}_t$ ,

$$\int_A M_s dP = \int_A \mathbb{E}[M_s | \mathcal{F}_t] dP = \int_A M_t dP$$

Taking the limit as  $s \rightarrow \infty$ ,

$$\lim_{s \rightarrow \infty} \int_A M_s dP = \int_A M_t dP$$

i.e.,

$$\int_A m dP = \int_A \mathbb{E}[m | \mathcal{F}_+] dP \quad \forall A \in \mathcal{F}_+$$

Hence,

$$m_+ = \mathbb{E}[m | \mathcal{F}_+]$$

□

- 3.9. Suppose  $f \in \mathcal{V}(0, T)$  and that  $t \mapsto f(t, \omega)$  is continuous for a.a.  $\omega$ . Then we have shown that

$$\int_0^T f(t, \omega) dB_t(\omega) = \lim_{\Delta t_j \rightarrow 0} \sum_j f(t_j, \omega) \Delta B_j \quad \text{in } L^2(P).$$

Similarly we define the *Stratonovich integral* of  $f$  by

$$\int_0^T f(t, \omega) \circ dB_t(\omega) = \lim_{\Delta t_j \rightarrow 0} \sum_j f(t_j^*, \omega) \Delta B_j, \quad \text{where } t_j^* = \frac{1}{2}(t_j + t_{j+1}),$$

whenever the limit exists in  $L^2(P)$ . In general these integrals are different. For example, compute

$$\int_0^T B_t \circ dB_t$$

and compare with Example 3.1.9.

$$\int_0^T B_t \circ dB_t = \lim_{\Delta t_j \rightarrow 0} \sum_j B_{j^*} \Delta B_j, \quad t_j^* = \frac{1}{2}(t_j + t_{j+1})$$

Now

$$\begin{aligned} \Delta(B_j^2) &= B_{j+1}^2 - B_j^2 = [(B_{j+1} - B_{j^*}) + B_{j^*}]^2 - [(B_j - B_{j^*}) + B_{j^*}]^2 \\ &= (B_{j+1} - B_{j^*})^2 + 2B_{j^*}(B_{j+1} - B_{j^*}) + B_{j^*}^2 \\ &\quad - [(B_j - B_{j^*})^2 + 2B_{j^*}(B_j - B_{j^*}) + B_{j^*}^2] \\ &= (B_{j+1} - B_{j^*})^2 - (B_j - B_{j^*})^2 + 2B_{j^*}(B_{j+1} - B_j) \end{aligned}$$

Hence,

$$\begin{aligned} B_T^2 &= \sum_j \Delta(B_j^2) = \sum_j (B_{j+1} - B_{j^*})^2 - \sum_j (B_j - B_{j^*})^2 \\ &\quad + 2 \sum_j B_{j^*} (B_{j+1} - B_j) \end{aligned}$$

i.e.,

$$\sum_j B_{j^*} \Delta B_j = \frac{1}{2} B_T^2 + \frac{1}{2} \sum_j (B_j - B_{j^*})^2 - \frac{1}{2} \sum_j (B_{j+1} - B_{j^*})^2$$

Since

$$\sum_j (B_j - B_{j^*})^2 \rightarrow \frac{1}{2} \quad \text{and} \quad \sum_j (B_{j+1} - B_{j^*})^2 \rightarrow \frac{1}{2}$$

in  $L^2(P)$  as  $\Delta t_j \rightarrow 0$ , we have that

$$\int_0^T B_t \circ dB_t = \frac{1}{2} B_T^2 + \frac{1}{4} - \frac{1}{4} = \frac{1}{2} B_T^2$$

- 3.10.** If the function  $f$  in Exercise 3.9 varies “smoothly” with  $t$  then in fact the Itô and Stratonovich integrals of  $f$  coincide. More precisely, assume that there exists  $K < \infty$  and  $\epsilon > 0$  such that

$$E[|f(s, \cdot) - f(t, \cdot)|^2] \leq K|s - t|^{1+\epsilon}; \quad 0 \leq s, t \leq T.$$

Prove that then we have

$$\int_0^T f(t, \omega) dB_t = \lim_{\Delta t_j \rightarrow 0} \sum_j f(t'_j, \omega) \Delta B_j \quad (\text{limit in } L^1(P))$$

for any choice of  $t'_j \in [t_j, t_{j+1}]$ . In particular,

$$\int_0^T f(t, \omega) dB_t = \int_0^T f(t, \omega) \circ dB_t.$$

(Hint: Consider  $E[|\sum_j f(t_j, \omega) \Delta B_j - \sum_j f(t'_j, \omega) \Delta B_j|]$ .)

Consider

$$\begin{aligned} & E \left[ \left| \sum_j f(t_j, \omega) \Delta B_j - \sum_j f(t'_j, \omega) \Delta B_j \right| \right] \\ & \leq \sum_j E[|f(t_j) - f(t'_j)| |\Delta B_j|] \\ & \leq \sum_j \sqrt{E[|f(t_j) - f(t'_j)|^2]} \cdot \sqrt{E[|\Delta B_j|^2]} \quad \text{CAUCHY-SCHWARZ} \\ & \leq \sum_j \sqrt{K|t_j - t'_j|^{1+\epsilon} \cdot |t_j - t'_j|} = \sum_j \sqrt{K} |t_j - t'_j|^{\frac{1+\epsilon}{2}} \cdot |t_j - t'_j|^{1/2} \\ & = \sqrt{K} \sum_j |t_j - t'_j|^{1+\epsilon/2} \leq T \sqrt{K} \max_j |t_j - t'_j|^{\epsilon/2} \rightarrow 0 \end{aligned}$$

$\hookrightarrow \Delta t_j \rightarrow 0$

Hence,

$$\int_0^T f(t, \omega) dB_t = \lim_{\Delta t_j \rightarrow 0} \sum_j f(t_j, \omega) \Delta B_j = \lim_{\Delta t_j \rightarrow 0} \sum_j f(t'_j, \omega) \Delta B_j$$

- 3.11.** Let  $W_t$  be a stochastic process satisfying (i), (ii) and (iii) (below (3.1.2)). Prove that  $W_t$  cannot have continuous paths. (Hint: Consider  $E[(W_t^{(N)} - W_s^{(N)})^2]$ , where

$$W_t^{(N)} = (-N) \vee (N \wedge W_t), \quad N = 1, 2, 3, \dots .$$

Conditions:

- (i)  $t_1 \neq t_2 \Rightarrow W_{t_1}$  and  $W_{t_2}$  are independent.
- (ii)  $\{W_t\}$  is stationary, i.e. the (joint) distribution of  $\{W_{t_1+t}, \dots, W_{t_k+t}\}$  does not depend on  $t$ .
- (iii)  $E[W_t] = 0$  for all  $t$ .

Let

$$W_t^{(\omega)} = \max\{-N, \min\{N, W_t\}\}, \quad N \in \mathbb{Z}^+$$

and suppose, by contradiction, that  $W_t$  is continuous.

By the Dominated Convergence Theorem, we have

$$\lim_{s \rightarrow t} \mathbb{E}[(W_t^{(\omega)} - W_s^{(\omega)})^2] = 0 \quad (1)$$

and

$$\mathbb{E}[W_t^{(\omega)}] = \mathbb{E}[W_t] = 0 \quad (2)$$

Since  $W_t^{(\omega)}$  and  $W_s^{(\omega)}$  are i.i.d.,

$$\begin{aligned} \mathbb{E}[(W_t^{(\omega)} - W_s^{(\omega)})^2] &= \mathbb{E}[W_t^{(\omega)2} - 2W_t^{(\omega)}W_s^{(\omega)} + W_s^{(\omega)2}] \\ &= \mathbb{E}[W_t^{(\omega)2}] - 2\mathbb{E}[W_t^{(\omega)}]\mathbb{E}[W_s^{(\omega)}] + \mathbb{E}[W_s^{(\omega)2}] \\ &= \mathbb{E}[W_t^{(\omega)2}] - 2\mathbb{E}[W_t^{(\omega)}]\mathbb{E}[W_t^{(\omega)}] + \mathbb{E}[W_t^{(\omega)2}] \\ &= 2\mathbb{E}[W_t^{(\omega)2}] - 2\mathbb{E}[W_t^{(\omega)}]^2 \\ &= 2\text{Var}[W_t^{(\omega)}] \end{aligned} \quad (3)$$

By (1), we know that (3) goes to zero. Hence,  $W_t^{(\omega)}$  is constant, i.e.,

$$W_t^{(\omega)} = \mathbb{E}[W_t^{(\omega)}] = \mathbb{E}[W_t] = 0$$

3.12. As in Exercise 3.9 we let  $\circ dB_t$  denote Stratonovich differentials.

- (i) Use (3.3.6) to transform the following Stratonovich differential equations into Itô differential equations:
  - (a)  $dX_t = \gamma X_t dt + \alpha X_t \circ dB_t$
  - (b)  $dX_t = \sin X_t \cos X_t dt + (t^2 + \cos X_t) \circ dB_t$
- (ii) Transform the following Itô differential equations into Stratonovich differential equations:
  - (a)  $dX_t = r X_t dt + \alpha X_t dB_t$
  - (b)  $dX_t = 2e^{-X_t} dt + X_t^2 dB_t$

Using

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \frac{1}{2} \int_0^t \sigma'(s, X_s) \sigma(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s, \quad (3.3.6)$$

i.a.)  $dX_t = b(t, x) dt + \frac{1}{2} \sigma'(t, x) \sigma(t, x) ds + \sigma(t, x) dB_t$

$$dX_t = \sigma X_t dt + \frac{1}{2} \alpha^2 X_t dt + \alpha X_t dB_t$$

$$\begin{aligned}\sigma(t, x) &= \alpha x \\ \sigma'(t, x) &= \alpha\end{aligned}$$

i.b.)  $\sigma(t, x) = t^2 + \cos x$

$$\sigma'(t, x) = \frac{\partial \sigma}{\partial x} = -\sin x$$

$$dX_t = \sin X_t \cos X_t + \frac{1}{2} [-\sin X_t (t^2 + \cos X_t)] dt + (t^2 + \cos X_t) dB_t$$

$$= \sin X_t \cos X_t - \frac{1}{2} \sin X_t (t^2 + \cos X_t) dt + (t^2 + \cos X_t) dB_t$$

ii.a)  $dX_t = r X_t dt + \alpha X_t dB_t$

$$dX_t = r X_t dt - \frac{1}{2} \alpha^2 X_t dt + \alpha X_t \circ dB_t$$

ii.b)  $dX_t = 2e^{-X_t} dt + X_t^2 dB_t$

$$dX_t = 2e^{-X_t} dt - X_t^3 dt + X_t^2 \circ dB_t$$

$$\sigma(t, x) = x^2, \quad \sigma_x = 2x$$

- 3.13. A stochastic process  $X_t(\cdot): \Omega \rightarrow \mathbf{R}$  is *continuous in mean square* if  $E[X_t^2] < \infty$  for all  $t$  and

$$\lim_{s \rightarrow t} E[(X_s - X_t)^2] = 0 \quad \text{for all } t \geq 0.$$

a) Prove that Brownian motion  $B_t$  is continuous in mean square.

Since

$$E[B_t^2] = +\infty, \quad \forall t \in \mathbf{R}$$

and

$$\lim_{s \rightarrow t} E[(B_s - B_t)^2] = \lim_{s \rightarrow t} (s - t) = 0, \quad \forall t \geq 0$$

Hence,  $B_t$  is continuous in mean square.

- b) Let  $f: \mathbf{R} \rightarrow \mathbf{R}$  be a Lipschitz continuous function, i.e. there exists  $C < \infty$  such that

$$|f(x) - f(y)| \leq C|x - y| \quad \text{for all } x, y \in \mathbf{R}.$$

Prove that

$$Y_t := f(B_t)$$

is continuous in mean square.

By the fact that  $f$  is Lipschitz,  
 $|Y_t - Y_s| \leq C|t-s|$

i.e.,

$$E|Y_t - Y_s|^2 \leq E[C^2|t-s|^2]$$

Taking the limit as  $t \rightarrow s$ ,

$$\lim_{t \rightarrow s} E|Y_t - Y_s|^2 \leq \lim_{t \rightarrow s} E[C^2|t-s|^2] = E\left[\lim_{t \rightarrow s} (C|t-s|)\right] = 0$$

Dominated

Convergence

Therefore,

$$\lim_{t \rightarrow s} E|Y_t - Y_s|^2 = 0, \quad \forall s > 0$$

Moreover,

$\mathbb{E}[Y_t^2] = \mathbb{E}[f^2(B_T)] < \infty$   
 since  $f$  is continuous.

- c) Let  $X_t$  be a stochastic process which is continuous in mean square and assume that  $X_t \in \mathcal{V}(S, T)$ ,  $T < \infty$ . Show that

$$\int_S^T X_t dB_t = \lim_{n \rightarrow \infty} \int_S^T \phi_n(t, \omega) dB_t(\omega) \quad (\text{limit in } L^2(P))$$

where

$$\phi_n(t, \omega) = \sum_j X_{t_j^{(n)}}(\omega) \mathcal{X}_{[t_j^{(n)}, t_{j+1}^{(n)})}(t), \quad T < \infty.$$

(Hint: Consider

$$E\left[\int_S^T (X_t - \phi_n(t))^2 dt\right] = E\left[\sum_j \int_{t_j^{(n)}}^{t_{j+1}^{(n)}} (X_t - X_{t_j^{(n)}})^2 dt\right].$$

Consider

$$\begin{aligned} \mathbb{E}\left[\int_s^T (X_t - \phi_n(t))^2 dt\right] &= \mathbb{E}\left[\sum_i \int_{t_i^{(n)}}^{t_{i+1}^{(n)}} (X_t - X_{t_i^{(n)}})^2 dt\right] \\ &= \sum_j \int_{t_j^{(n)}}^{t_{j+1}^{(n)}} \mathbb{E}[(X_t - X_{t_j^{(n)}})^2] dt \\ &\leq (T-s) \sup_{[t_{j(n)}, t_{j+1}^{(n)}]} \mathbb{E}[(X_t - X_{t_j^{(n)}})^2] \end{aligned}$$

Taking the limit as  $n \rightarrow \infty$ ,

$$(T-s) \sup_{[t_{j(n)}, t_{j+1}^{(n)}]} \mathbb{E}[(X_t - X_{t_j^{(n)}})^2] \rightarrow 0$$

- 3.14. Show that a function  $h(\omega)$  is  $\mathcal{F}_t$ -measurable if and only if  $h$  is a pointwise limit (for a.a.  $\omega$ ) of sums of functions of the form

$$g_1(B_{t_1}) \cdot g_2(B_{t_2}) \cdots g_k(B_{t_k})$$

where  $g_1, \dots, g_k$  are bounded continuous functions and  $t_j \leq t$  for  $j \leq k$ ,  $k = 1, 2, \dots$

Hint: Complete the following steps:

a) We may assume that  $h$  is bounded.

b) For  $n = 1, 2, \dots$  and  $j = 1, 2, \dots$  put  $t_j^{(n)} = j \cdot 2^{-n}$ . For fixed  $n$  let  $\mathcal{H}_n$  be the  $\sigma$ -algebra generated by  $\{B_{t_j}(\cdot)\}_{t_j \leq t}$ . Then by Corollary C.9

$$h = E[h|\mathcal{F}_t] = \lim_{n \rightarrow \infty} E[h|\mathcal{H}_n] \quad (\text{pointwise a.e. limit})$$

c) Define  $h_n := E[h|\mathcal{H}_n]$ . Then by the Doob-Dynkin lemma (Lemma 2.1.2) we have

$$h_n(\omega) = G_n(B_{t_1}(\omega), \dots, B_{t_k}(\omega))$$

for some Borel function  $G_n: \mathbf{R}^k \rightarrow \mathbf{R}$ , where  $k = \max\{j; j \cdot 2^{-n} \leq t\}$ .

Now use that any Borel function  $G: \mathbf{R}^k \rightarrow \mathbf{R}$  can be approximated pointwise a.e. by a continuous function  $F: \mathbf{R}^k \rightarrow \mathbf{R}$  and complete the proof by applying the Stone-Weierstrass theorem.

Assume that  $h$  is bounded and put  $t_j = t_j^{(n)} = j \cdot 2^{-n}$ ,  
 $n = 1, 2, \dots$ ,  $j = 1, 2, \dots$   
 for a fixed  $n$ , let  $\mathcal{H}_n$  be the  $\sigma$ -algebra generated by  
 $\{B_{t_j}\}_{t_j \leq t}$ . Then, since  $\mathcal{H}_n$  is an increasing family of  $\sigma$ -algebras,  
 and  $\mathcal{F}_t$  is the  $\sigma$ -algebra generated by  $\{\mathcal{H}_n\}_{n=1}^{\infty}$

- The  $\sigma$ -algebra generated by  $\{\mathcal{H}_n\}$  is contained in  $\mathcal{F}_t$ , by the definition of  $\mathcal{H}_n$ .
- Let  $s \leq t$  and  $r \rightarrow \infty$ . By the continuity of B.M.,  $B_r \rightarrow B_s \in \{\mathcal{H}_n\}$ , by definition of  $\mathcal{H}_n$ . Since  $B_s = \limsup B_r$  we know that  $\limsup B_r \in \{\mathcal{H}_n\}$ .
- Now, by definition of  $\mathcal{F}_t$  ( $\sigma$ -algebra generated by  $B_s: s \leq t$ ), we have that  $\mathcal{F}_t \subseteq \{\mathcal{H}_n\}_{n=1}^{\infty}$ .

by the Corollary C.9.,

$$h = E[h|\mathcal{F}_t] = \lim_{n \rightarrow \infty} E[h|\mathcal{H}_n] \quad \text{pointwise a.e.}$$

Let  $h_n = E[h|\mathcal{H}_n]$ . By the Doob-Dynkin lemma,

$$h_n(\omega) = G_n(B_{t_1}(\omega), \dots, B_{t_k}(\omega))$$

for some Borel function  $G_n$ , and where  $K = \max\{j : j \cdot 2^{-n} \leq t\}$ .

Since every Borel function  $G: \mathbb{R}^K \rightarrow \mathbb{R}$  can be approximated pointwise a.e. by a continuous function  $F: \mathbb{R}^K \rightarrow \mathbb{R}$ , by the Stone-Weierstrass Theorem applied on  $[t_1, t_K]$ ,  $F$  can be approximated by a polynomial function  $g_n$ , completing the proof.

**Corollary C.9.** Let  $X \in L^1(P)$ , let  $\{\mathcal{N}_k\}_{k=1}^\infty$  be an increasing family of  $\sigma$ -algebras,  $\mathcal{N}_k \subset \mathcal{F}$  and define  $\mathcal{N}_\infty$  to be the  $\sigma$ -algebra generated by  $\{\mathcal{N}_k\}_{k=1}^\infty$ . Then

$$E[X|\mathcal{N}_k] \rightarrow E[X|\mathcal{N}_\infty] \quad \text{as } k \rightarrow \infty,$$

a.e.  $P$  and in  $L^1(P)$ .

**Lemma 2.1.2.** If  $X, Y: \Omega \rightarrow \mathbf{R}^n$  are two given functions, then  $Y$  is  $\mathcal{H}_X$ -measurable if and only if there exists a Borel measurable function  $g: \mathbf{R}^n \rightarrow \mathbf{R}^n$  such that

$$Y = g(X).$$

3.15. Suppose  $f, g \in \mathcal{V}(S, T)$  and that there exist constants  $C, D$  such that

$$C + \int_S^T f(t, \omega) dB_t(\omega) = D + \int_S^T g(t, \omega) dB_t(\omega) \quad \text{for a.a. } \omega \in \Omega .$$

Show that

$$C = D$$

and

$$f(t, \omega) = g(t, \omega) \quad \text{for a.a. } (t, \omega) \in [S, T] \times \Omega .$$

We'll apply Itô Isometry. Notice that

$$\mathbb{E}[(C-D)^2] = \mathbb{E}\left[\left(\int_S^T (g(t, \omega) - f(t, \omega)) dB_t(\omega)\right)^2\right]$$

$$\stackrel{\text{Itô Isometry}}{=} \mathbb{E}\left[\int_S^T (g(t, \omega) - f(t, \omega))^2 dt\right]$$

Martingale  
+ B.M. starting  
at 0

On the other hand,

$$C - D = \mathbb{E}[(C-D) | \mathcal{F}_S] = \mathbb{E}\left[\int_S^T (g(t, \omega) - f(t, \omega)) dB_t(\omega) \middle| \mathcal{F}_S\right] = 0$$

Hence,  $C = D$ . Moreover,  $(C-D)^2 = 0$  and  $\mathbb{E}[(C-D)^2] = 0$ .  
Therefore,

$$g(t, \omega) = f(t, \omega)$$

- 3.16.** Let  $X: \Omega \rightarrow \mathbf{R}$  be a random variable such that  $E[X^2] < \infty$  and let  $\mathcal{H} \subset \mathcal{F}$  be a  $\sigma$ -algebra. Show that

$$E[(E[X|\mathcal{H}])^2] \leq E[X^2].$$

(See Lemma 6.1.1. See also the Jensen inequality for conditional expectation (Appendix B).)

By Jensen Inequality for Conditional Expectation,

**Theorem B.4 (The Jensen inequality).**

If  $\phi: \mathbf{R} \rightarrow \mathbf{R}$  is convex and  $E[|\phi(X)|] < \infty$  then

$$\phi(E[X|\mathcal{H}]) \leq E[\phi(X)|\mathcal{H}].$$

Since  $\phi(x) = x^2$  is convex,  
 $E[X|\mathcal{H}]^2 \leq E[X^2|\mathcal{H}]$

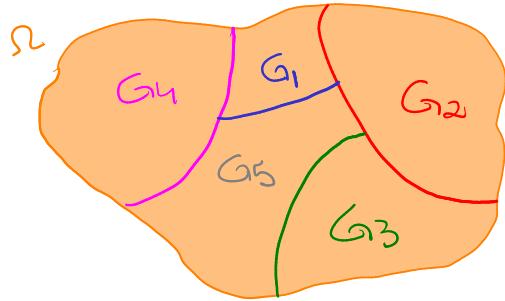
Using the Law of Total Expectation, i.e.,

$$E[E[X|\mathcal{H}]] = E[X]$$

and taking the expectations

$$E[(E[X|\mathcal{H}])^2] \leq E[E[X^2|\mathcal{H}]] = E[X^2]$$

- 3.17.** Let  $(\Omega, \mathcal{F}, P)$  be a probability space and let  $X: \Omega \rightarrow \mathbf{R}$  be a random variable with  $E[|X|] < \infty$ . If  $\mathcal{G} \subset \mathcal{F}$  is a finite  $\sigma$ -algebra, then by Exercise 2.7 there exists a partition  $\Omega = \bigcup_{i=1}^n G_i$  such that  $\mathcal{G}$  consists of  $\emptyset$  and unions of some (or all) of  $G_1, \dots, G_n$ .
- Explain why  $E[X|\mathcal{G}](\omega)$  is constant on each  $G_i$ . (See Exercise 2.7 c.).



**2.7.** a) Suppose  $G_1, G_2, \dots, G_n$  are disjoint subsets of  $\Omega$  such that

$$\Omega = \bigcup_{i=1}^n G_i .$$

Prove that the family  $\mathcal{G}$  consisting of  $\emptyset$  and all unions of some (or all) of  $G_1, \dots, G_n$  constitutes a  $\sigma$ -algebra on  $\Omega$ .

- b) Prove that any finite  $\sigma$ -algebra  $\mathcal{F}$  on  $\Omega$  is of the type described in a).
- c) Let  $\mathcal{F}$  be a finite  $\sigma$ -algebra on  $\Omega$  and let  $X: \Omega \rightarrow \mathbf{R}$  be  $\mathcal{F}$ -measurable. Prove that  $X$  assumes only finitely many possible values. More precisely, there exists a disjoint family of subsets  $F_1, \dots, F_m \in \mathcal{F}$  and real numbers  $c_1, \dots, c_m$  such that

$$X(\omega) = \sum_{i=1}^m c_i \chi_{F_i}(\omega) .$$

By the exercise 2.7, for  $c_i \in \mathbf{R}$ ,  $i=1, \dots, n$ ,

$$E[X|\mathcal{G}](\omega) = E \left[ \underbrace{\sum_{i=1}^n c_i \chi_{G_i}(\omega)}_{\text{constant } C} \right] = E[C] = C$$

- b) Assume that  $P[G_i] > 0$ . Show that

$$E[X|\mathcal{G}](\omega) = \frac{\int_{G_i} X dP}{P(G_i)} \quad \text{for } \omega \in G_i .$$

$$\int_H E[X|\mathcal{H}] dP = \int_H X dP, \text{ for all } H \in \mathcal{H}.$$

gives

$$\int_{G_i} E[X|\mathcal{G}] dP = \int_{G_i} X dP$$

however,

$$\int_{G_i} E[X|\mathcal{G}] dP = E[X|\mathcal{G}] \int_{G_i} dP = E[X|\mathcal{G}] P(G_i)$$

Therefore,

$$E[X|\mathcal{G}] = \frac{\int_{G_i} X dP}{P(G_i)}$$

- c) Suppose  $X$  assumes only finitely many values  $a_1, \dots, a_m$ . Then from elementary probability theory we know that (see Exercise 2.1)

$$E[X|G_i] = \sum_{k=1}^m a_k P[X = a_k | G_i].$$

Compare with b) and verify that

$$E[X|G_i] = E[X|G](\omega) \quad \text{for } \omega \in G_i.$$

Thus we may regard the conditional expectation as defined in Appendix B as a (substantial) generalization of the conditional expectation in elementary probability theory.

Using the previous item,

$$\begin{aligned} E[X|G] &= \frac{\int_{G_i} X dP}{P(G_i)} = \frac{\int_{G_i} \sum_{k=1}^m a_k \chi_{a_k} dP}{P(G_i)} = \sum_{k=1}^m \frac{\int_{G_i} a_k \chi_{a_k} dP}{P(G_i)} \\ &= \sum_{k=1}^m a_k \frac{P(G_i \cap G_k)}{P(G_i)} = \sum_{k=1}^m a_k P[X = a_k | G_i] \end{aligned}$$

Alternative answer

b) Since

$$\mathbb{E}[f|A] = \int f d\mu_A, \quad \mu_A(B) = \frac{\mu(B \cap A)}{\mu(A)}$$

We have

$$\mathbb{E}\left[\sum_{i=1}^n c_i \chi_{G_i}(\omega) \mid G_i\right] = \int_{G_i} \frac{X dP}{P(G_i)}(\omega)$$

c) Given the definition of  $a_k$ ,  $k=1, \dots, m$ ,

$$\mathbb{E}[X|G_i] = \sum_{k=1}^m a_k P[X=a_k|G_i] = \int X dP_{a_k}$$

By the fact that

$$\mu_A(B) = \frac{\mu(B \cap A)}{\mu(A)}$$

we obtain

$$\mathbb{E}[X|G_i] = \int X dP_{G_i} = \int_{G_i} \frac{X dP}{P(G_i)} = \mathbb{E}[X|g]$$

- 4.1. Use Itô's formula to write the following stochastic processes  $X_t$  on the standard form

$$dX_t = u(t, \omega)dt + v(t, \omega)dB_t$$

for suitable choices of  $u \in \mathbf{R}^n$ ,  $v \in \mathbf{R}^{n \times m}$  and dimensions  $n, m$ :

- a)  $X_t = B_t^2$ , where  $B_t$  is 1-dimensional
- b)  $X_t = 2 + t + e^{B_t}$  ( $B_t$  is 1-dimensional)
- c)  $X_t = B_1^2(t) + B_2^2(t)$  where  $(B_1, B_2)$  is 2-dimensional
- d)  $X_t = (t_0 + t, B_t)$  ( $B_t$  is 1-dimensional)
- e)  $X_t = (B_1(t) + B_2(t) + B_3(t), B_2^2(t) - B_1(t)B_3(t))$ , where  $(B_1, B_2, B_3)$  is 3-dimensional.

$\textcircled{a}$  Let  $g(t, x) = x^2$ . By the Itô's formula,

$$dg(t, X_t) = \frac{\partial g}{\partial t}(t, X_t)dt + \frac{\partial g}{\partial x}(t, X_t)dX_t + \frac{1}{2} \frac{\partial^2 g}{\partial x^2}(t, X_t)(dX_t)^2$$

Then,

$$dB_t^2 = 2B_t dB_t + dt$$

$\textcircled{b}$ ,  $X_t = 2t + e^{B_t}$

Let  $g(t, x) = 2t + e^x$ . Then,

$$dX_t = dt + e^{B_t} dB_t + \frac{1}{2} e^{B_t} dt = \left(1 + \frac{1}{2} e^{B_t}\right) dt + e^{B_t} dB_t$$

$\textcircled{c}$ ,  $X_t = B_1^2(t) + B_2^2(t)$

Let  $g(t, x) = x_1^2 + x_2^2$ . Since

$$dY_k = \frac{\partial g_k}{\partial t}(t, X)dt + \sum_i \frac{\partial g_k}{\partial x_i}(t, X)dX_i + \frac{1}{2} \sum_{i,j} \frac{\partial^2 g_k}{\partial x_i \partial x_j}(t, X)dX_i dX_j \quad dB_i dB_j = \delta_{ij} dt$$

We have that

$$\begin{aligned} dX_t &= 2B_1(t) dB_1(t) + 2B_2(t) dB_2(t) + \frac{1}{2} \left[ 2dt + 2dt \right] \\ &= 2dt + 2B_1(t) dB_1(t) + 2B_2(t) dB_2(t) \end{aligned}$$

$$d) X_t = (t_0 + t, B_t)$$

Let  $g(t, x) = (t_0 + t, x)$ .

Then,

$$dX_t = \begin{bmatrix} 1 \\ 0 \end{bmatrix} dt + \begin{bmatrix} 0 \\ 1 \end{bmatrix} dB_t + \frac{1}{2} \begin{bmatrix} 0 \\ 0 \end{bmatrix} dt = \begin{bmatrix} dt \\ dB_t \end{bmatrix}$$

$$e) X_t = (B_1 + B_2 + B_3, B_2^2 - B_1 B_3)$$

Let  $g(t, x) = (x_1 + x_2 + x_3, x_2^2 - x_1 x_3)$ . Then,

$$\begin{aligned} dX_t &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} dt + \begin{bmatrix} 1 \\ -B_3 \end{bmatrix} dB_1 + \begin{bmatrix} 1 \\ 2B_2 \end{bmatrix} dB_2 + \begin{bmatrix} 1 \\ -B_1 \end{bmatrix} dB_3 \\ &\quad + \frac{1}{2} \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix} dt + \begin{bmatrix} 0 \\ 2 \end{bmatrix} dt + \begin{bmatrix} 0 \\ 0 \end{bmatrix} dt \right) \\ &= \begin{bmatrix} dB_1 + dB_2 + dB_3 \\ -B_3 dB_1 + 2B_2 dB_2 - B_1 dB_3 + dt \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ 1 \end{bmatrix} dt + \begin{bmatrix} 1 & 1 & 1 \\ -B_3 & 2B_2 & -B_1 \end{bmatrix} \cdot \begin{bmatrix} dB_1 \\ dB_2 \\ dB_3 \end{bmatrix} \end{aligned}$$

4.2. Use Itô's formula to prove that

$$\int_0^t B_s^2 dB_s = \frac{1}{3} B_t^3 - \int_0^t B_s ds .$$

Recall that

$$d_f(X_t) = \frac{df(x_t)}{dt} dt + \frac{df}{dx}(x_t) dX_t + \frac{1}{2} \frac{d^2 f}{dx^2}(x_t) (dB_t)^2$$

Then, let  $g(t, x) = x^3$  we know that  
 $\frac{\partial g}{\partial t}(t, B_t) = 0$        $(dB_t)^2 = dt$   
 $\frac{\partial g}{\partial x}(t, B_t) = 3B_t^2$        $\frac{\partial^2 g}{\partial x^2} = 6B_t$

Therefore,

$$dB_t^3 = 3B_t^2 dB_t + \frac{1}{2} 6B_t dt = 3B_t^2 dB_t + 3B_t dt$$

i.e.,

$$\frac{1}{3} dB_t^3 = B_t^2 dB_t + B_t dt \Leftrightarrow B_t^2 dB_t = \frac{1}{3} dB_t^3 - B_t dt$$

In the integral form,

$$\int_0^t B_s^2 dB_s = \frac{1}{3} B_t^3 - \int_0^t B_s ds$$

4.3. Let  $X_t, Y_t$  be Itô processes in  $\mathbf{R}$ . Prove that

$$d(X_t Y_t) = X_t dY_t + Y_t dX_t + dX_t \cdot dY_t.$$

Deduce the following general *integration by parts formula*

$$\int_0^t X_s dY_s = X_t Y_t - X_0 Y_0 - \int_0^t Y_s dX_s - \int_0^t dX_s \cdot dY_s.$$

Let  $g(t, x, y) = xy$ . By Itô's formula,

$$\begin{aligned} dX_t Y_t &= \frac{\partial g}{\partial t}(t, X_t, Y_t) dt + \frac{\partial g}{\partial x}(t, X_t, Y_t) dX_t + \frac{\partial g}{\partial y}(t, X_t, Y_t) dY_t \\ &\quad + \frac{1}{2} \left[ \frac{\partial^2 g}{\partial x^2}(t, X_t, Y_t) dX_t dY_t + \frac{\partial^2 g}{\partial x^2}(t, X_t, Y_t) (dX_t)^2 \right. \\ &\quad \left. + \frac{\partial^2 g}{\partial y^2}(t, X_t, Y_t) (dY_t)^2 + \frac{\partial^2 g}{\partial x \partial y}(t, X_t, Y_t) dX_t dY_t \right] \\ &= 0 + Y_t dX_t + X_t dY_t + \frac{1}{2} \left( dX_t dY_t + dX_t dY_t \right) \end{aligned}$$

i.e.,

$$dX_t Y_t = Y_t dX_t + X_t dY_t + dX_t dY_t$$

Rearranging

$$X_t dY_t = dX_t Y_t - Y_t dX_t - dX_t dY_t$$

In the integral form,

$$\int_0^t X_s dY_s = \int_0^t dX_s Y_s - \int_0^t Y_s dX_s - \int_0^t dX_s dY_s$$

Hence,

$$\int_0^t X_s dY_s = X_t Y_t - X_0 Y_0 - \int_0^t Y_s dX_s - \int_0^t dX_s dY_s$$

4.4. (Exponential martingales)

Suppose  $\theta(t, \omega) = (\theta_1(t, \omega), \dots, \theta_n(t, \omega)) \in \mathbf{R}^n$  with  $\theta_k(t, \omega) \in \mathcal{V}[0, T]$  for  $k = 1, \dots, n$ , where  $T \leq \infty$ . Define

$$Z_t = \exp \left\{ \underbrace{\int_0^t \theta(s, \omega) dB(s) - \frac{1}{2} \int_0^t \theta^2(s, \omega) ds}_{Y_t} \right\}; \quad 0 \leq t \leq T$$

where  $B(s) \in \mathbf{R}^n$  and  $\theta^2 = \theta \cdot \theta$  (dot product).  $\nearrow Y_t$   
a) Use Itô's formula to prove that

$$dZ_t = Z_t \theta(t, \omega) dB(t).$$

b) Deduce that  $Z_t$  is a martingale for  $t \leq T$ , provided that

$$Z_t \theta_k(t, \omega) \in \mathcal{V}[0, T] \quad \text{for } 1 \leq k \leq n.$$

a) Let  $g(t, x) = e^x$ . Then,

$$\begin{aligned} dZ_t &= \frac{\partial g}{\partial t}(t, Y_t) dt + \frac{\partial g}{\partial x}(t, Y_t) dY_t + \frac{1}{2} \frac{\partial^2 g}{\partial x^2}(t, Y_t) (dY_t)^2 \\ &= 0 + e^{Y_t} dY_t + \frac{1}{2} e^{Y_t} (dY_t)^2 \end{aligned} \quad (1)$$

Where

$$Y_t = \int_0^t \theta(s, \omega) dB(s) - \frac{1}{2} \int_0^t \theta^2(s, \omega) ds$$

$$\text{Define } h(t, x) = \int_0^t \theta(s, \omega) dx(s) - \frac{1}{2} \int_0^t \theta^2(s, \omega) ds$$

then

$$\frac{\partial h}{\partial t}(t, x) = -\frac{1}{2} \theta^2(t, \omega)$$

$$\frac{\partial^2 h}{\partial x^2}(t, x) = \theta(t, \omega), \quad \frac{\partial^2 h}{\partial x^2}(t, \omega) = 0$$

Hence, since  $Y_t = h(t, B_t)$

$$dY_t = -\frac{1}{2} \theta^2(t, \omega) dt + \theta(t, \omega) dB_t \quad (2)$$

Combining (1) and (2):

$$dZ_t = e^{Y_t} dY_t + \frac{1}{2} e^{Y_t} (dY_t)^2$$

And noticing that

$$(dY_t)^2 = \Theta^2(t, \omega) dt$$

We obtain

$$dZ_t = Z_t \left( -\frac{1}{2} \Theta^2(t, \omega) dt + \Theta(t, \omega) dB_t \right) + \frac{1}{2} Z_t \Theta^2(t, \omega) dt$$

i.e.

$$dZ_t = Z_t \Theta(t, \omega) dB_t \quad (3)$$

b) Given that  $\Theta_k \in V[0, T]$ , we know that the Hö integral  
(2) is a martingale.

And given that  $Z_t \Theta_k \in V[0, T]$ , (3) is a martingale.

4.5. Let  $B_t \in \mathbf{R}$ ,  $B_0 = 0$ . Define

$$\beta_k(t) = E[B_t^k] ; \quad k = 0, 1, 2, \dots ; \quad t \geq 0 .$$

Use Itô's formula to prove that

$$\beta_k(t) = \frac{1}{2}k(k-1) \int_0^t \beta_{k-2}(s) ds ; \quad k \geq 2 .$$

Deduce that

$$E[B_t^4] = 3t^2 \quad (\text{see (2.2.14)})$$

and find

$$E[B_t^6] .$$

Notice that:

$$\begin{aligned} K=0 : \beta_0(t) &= E[B_t^0] = 1 \\ K=1 : \beta_1(t) &= E[B_t] \end{aligned}$$

Let  $g_K(t, x) = x^K$  Then, if  
 $\alpha_K(t) = g_K(t, B_t)$ ,  $\beta_K(t) = E[\alpha_K(t)]$

By Itô's formula,  
 $d\alpha_K = K B_t^{K-1} dB_t + \frac{1}{2} K(K-1) B_t^{K-2} dt$

Hence,

$$\alpha_K = \int_0^t K B_s^{K-1} dB_s + \frac{1}{2} \int_0^t K(K-1) B_s^{K-2} ds$$

and

$$\beta_K = E \left[ \int_0^t K B_s^{K-1} dB_s + \frac{1}{2} \int_0^t K(K-1) B_s^{K-2} ds \right]$$

$$= K E \left[ \int_0^t B_s^{K-1} dB_s \right] + \frac{1}{2} K(K-1) E \left[ \int_0^t B_s^{K-2} ds \right]$$

$$= \frac{1}{2} K(K-1) \int_0^t E[B_s^{K-2}] ds = \frac{1}{2} K(K-1) \int_0^t \beta_{K-2} ds$$

With that

$$\mathbb{E}[B_t^4] = 6 \int_0^t \mathbb{E}[B_s^2] ds = 6 \int_0^t s^2 ds = 6 \frac{t^3}{3} = 2t^2$$

and

$$\begin{aligned}\mathbb{E}[B_t^6] &= 15 \int_0^t \mathbb{E}[B_s^4] ds = 15 \int_0^t 3s^2 ds \\ &= 15 \cdot 3 \frac{t^3}{3} = 15t^3\end{aligned}$$

4.6. a) For  $c, \alpha$  constants,  $B_t \in \mathbf{R}$  define

$$X_t = e^{ct + \alpha B_t}.$$

Prove that

$$dX_t = (c + \frac{1}{2}\alpha^2)X_t dt + \alpha X_t dB_t.$$

Let  $g(t, x) = e^{ct + \alpha x} = e^{ct} e^{\alpha x}$ . Then,

$$\begin{aligned} \bullet \frac{\partial g}{\partial t} &= c e^{ct + \alpha x} & \bullet \frac{\partial g}{\partial x} &= \alpha e^{ct + \alpha x} & \bullet \frac{\partial^2 g}{\partial x^2} &= \alpha^2 e^{ct + \alpha x} \end{aligned}$$

By Itô's formula, since  $X_t = g(t, B_t)$ ,

$$dX_t = ce^{ct + \alpha B_t} dt + \alpha e^{ct + \alpha B_t} dB_t + \alpha^2 e^{ct + \alpha x} dt$$

$$\therefore dX_t = \left( c + \alpha^2 \right) X_t dt + \alpha X_t dB_t$$

b) For  $c, \alpha_1, \dots, \alpha_n$  constants,  $B_t = (B_1(t), \dots, B_n(t)) \in \mathbf{R}^n$  define

$$X_t = \exp \left( ct + \sum_{j=1}^n \alpha_j B_j(t) \right).$$

Prove that

$$dX_t = \left( c + \frac{1}{2} \sum_{j=1}^n \alpha_j^2 \right) X_t dt + X_t \left( \sum_{j=1}^n \alpha_j dB_j \right).$$

By the multidimensional Itô's formula, let  $g(t, x) = e^{ct + \alpha x}$

$$X_t = g(t, B_t) = e^{ct + \alpha B_t} = e^{ct + (\alpha_1 B_1 + \dots + \alpha_n B_n)}$$

and

$$dX_t = c X_t dt + \alpha_1 X_t dB_1 + \dots + \alpha_n X_t dB_n + \frac{1}{2} \alpha_1^2 X_t dt$$

$$+ \dots + \frac{1}{2} \alpha_n^2 x_+ dt$$

Hence,

$$dx_+ = \left( c + \frac{1}{2} \sum_{j=1}^n \alpha_j^2 \right) x_+ dt + x_+ \left( \sum_{j=1}^n \alpha_j dB_j \right)$$

4.7. Let  $X_t$  be an Itô integral

$$dX_t = v(t, \omega) dB_t(\omega) \quad \text{where } v \in \mathbf{R}^n, v \in \mathcal{V}(0, T), B_t \in \mathbf{R}^n, 0 \leq t \leq T.$$

a) Give an example to show that  $X_t^2$  is not in general a martingale.

Take  $\sigma=1$ . Then  $X_t = B_t$  and  $X_t^2 = B_t^2$  is not a martingale.

b) Prove that if  $v$  is bounded then

$$M_t := X_t^2 - \int_0^t |v_s|^2 ds \quad \text{is a martingale.}$$

The process  $\langle X, X \rangle_t := \int_0^t |v_s|^2 ds$  is called the *quadratic variation process* of the martingale  $X_t$ . For general processes  $X_t$  it is defined by

$$\langle X, X \rangle_t = \lim_{\Delta t_k \rightarrow 0} \sum_{t_k \leq t} |X_{t_{k+1}} - X_{t_k}|^2 \quad (\text{limit in probability}) \quad (4.3.11)$$

where  $0 = t_1 < t_2 < \dots < t_n = t$  and  $\Delta t_k = t_{k+1} - t_k$ . The limit can be shown to exist for continuous square integrable martingales  $X_t$ . See e.g. Karatzas and Shreve (1991).

- $M_t$  is  $\mathcal{M}_t$ -measurable since  $X_t^2$  is and also

$$\int_0^t |v_s|^2 ds$$

- $E[M_t] < \infty$  for all  $t$

$$\int_0^t X_s dY_s = X_t Y_t - X_0 Y_0 - \int_0^t Y_s dX_s - \int_0^t dX_s \cdot dY_s.$$

By Integration by Parts (4.3), taking  $X_t = Y_t$ ,

$$X_t^2 = X_0^2 + \int_0^t X_s dX_s + \int_0^t X_s dX_s + \int_0^t (dX_s)^2$$

$$= X_0^2 + 2 \int_0^t X_s dX_s + \int_0^t |v_s|^2 ds \quad \uparrow \langle X, X \rangle_t$$

$$= X_0^2 + 2 \int_0^+ X_s \sigma_s dB_s + \int_0^+ |\sigma_s|^2 ds$$

Therefore,

$$M_t = X_0^2 + 2 \int_0^+ X_s \sigma_s dB_s$$

and

$$\begin{aligned} \mathbb{E}[|M_t|] &= \mathbb{E}\left[\left|X_0^2 + 2 \int_0^+ X_s \sigma_s dB_s\right|\right] \\ &\leq X_0^2 + 2 \mathbb{E}\left[\int_0^+ |X_s \sigma_s| dB_s\right] \end{aligned}$$

Since  $\sigma_s$  is bounded, there exists  $C$  such that  $\sigma_s \leq C$ .

By Itô Isometry,

$$\begin{aligned} \mathbb{E}\left[\left(\int_0^+ |X_s \sigma_s| dB_s\right)^2\right] &= \mathbb{E}\left[\int_0^+ |X_s \sigma_s|^2 ds\right] \\ &\leq C^2 \mathbb{E}\left[\int_0^+ |X_s|^2 ds\right] \end{aligned}$$

Using that  $dX_t = \sigma(t, \omega) dB_t$  and Fubini's theorem

$$\begin{aligned} C^2 \mathbb{E}\left[\int_0^+ |X_s|^2 ds\right] &= C^2 \int_0^+ \mathbb{E}\left[\left|\int_0^s \sigma_r dB_r\right|^2\right] ds \\ &= C^2 \int_0^+ \mathbb{E}\left[\int_0^s |\sigma_r|^2 dr\right] ds \\ &\leq C^4 \int_0^+ \mathbb{E}\left[\int_0^s dr\right] ds \\ &= C^4 \int_0^+ s ds = \frac{C^4 t^2}{2} < \infty \end{aligned}$$

$$\bullet \mathbb{E}[M_s | \mathcal{M}_t] = M_t, \quad \forall s > t$$

$$\begin{aligned} \mathbb{E}\left[X_0^2 + 2 \int_0^s X_r \sigma_r dB_r \mid \mathcal{M}_t\right] &= X_0^2 + 2 \mathbb{E}\left[\int_0^s X_r \sigma_r dB_r \mid \mathcal{M}_t\right] \\ &= X_0^2 + 2 \int_0^t X_s \sigma_s dB_s \end{aligned}$$

- 4.8. a) Let  $B_t$  denote  $n$ -dimensional Brownian motion and let  $f: \mathbf{R}^n \rightarrow \mathbf{R}$  be  $C^2$ . Use Itô's formula to prove that

$$f(B_t) = f(B_0) + \int_0^t \nabla f(B_s) dB_s + \frac{1}{2} \int_0^t \Delta f(B_s) ds,$$

where  $\Delta = \sum_{i=1}^n \frac{\partial^2}{\partial x_i^2}$  is the Laplace operator.

By Itô's formula,

$$df(B_t) = \frac{\partial f}{\partial t}(t, B_t) dt + \sum_i \frac{\partial f}{\partial x_i}(t, B_t) dB_{t,i} + \frac{1}{2} \sum_{i,j} \frac{\partial^2 f}{\partial x_i \partial x_j}(t, B_t) dB_{t,i} dB_{t,j}$$

Given that  $f$  does not depend on  $t$ ,

- $\frac{\partial f}{\partial t}(t, B_t) = 0$
- $\sum_i \frac{\partial f}{\partial x_i}(t, B_t) = \nabla f(B_t)$
- $dB_{t,i} dB_{t,j} = \delta_{ij} dt \Rightarrow \sum_{i,j} \frac{\partial^2 f}{\partial x_i \partial x_j}(t, B_t) dB_{t,i} dB_{t,j} = \sum_i \frac{\partial^2 f}{\partial x_i^2}(t, B_t) dt$
- $\int_0^t df(B_s) = \int_0^t \frac{df}{dB_s} dB_s = f(B_s) \Big|_0^t = f(B_t) - f(B_0)$

We have that

$$f(B_t) = f(B_0) + \int_0^t \nabla f(B_s) dB_s + \frac{1}{2} \int_0^t \Delta f(B_s) ds$$

□

- b) Assume that  $g : \mathbf{R} \rightarrow \mathbf{R}$  is  $C^1$  everywhere and  $C^2$  outside finitely many points  $z_1, \dots, z_N$  with  $|g''(x)| \leq M$  for  $x \notin \{z_1, \dots, z_N\}$ . Let  $B_t$  be 1-dimensional Brownian motion. Prove that the 1-dimensional version of a) still holds, i.e.

$$g(B_t) = g(B_0) + \int_0^t g'(B_s) dB_s + \frac{1}{2} \int_0^t g''(B_s) ds .$$

(Hint: Choose  $f_k \in C^2(\mathbf{R})$  s.t.  $f_k \rightarrow g$  uniformly,  $f'_k \rightarrow g'$  uniformly and  $|f''_k| \leq M$ ,  $f''_k \rightarrow g''$  outside  $z_1, \dots, z_N$ . Apply a) to  $f_k$  and let  $k \rightarrow \infty$ ).

Let  $f_k \in C^2(\mathbf{R})$  such that  $f_k \rightarrow g$  uniformly,  $f'_k \rightarrow g'$  uniformly and  $|f''_k| \leq M$  and  $f''_k \rightarrow g''$  outside  $z_1, \dots, z_N$ . Applying a) to  $f_k$ ,

$$f_k(B_t) = f_k(B_0) + \int_0^t f'_k(B_s) dB_s + \frac{1}{2} \int_0^t f''_k(B_s) ds$$

as  $k \rightarrow \infty$ , we have

$$g(B_t) = g(B_0) + \int_0^t g'(B_s) dB_s + \frac{1}{2} \int_0^t g''(B_s) ds$$

□

- 4.9. Prove that we may assume that  $g$  and its first two derivatives are bounded in the proof of the Itô formula (Theorem 4.1.2) by proceeding as follows: For fixed  $t \geq 0$  and  $n = 1, 2, \dots$  choose  $g_n$  as in the statement such that  $g_n(s, x) = g(s, x)$  for all  $s \leq t$  and all  $|x| \leq n$ . Suppose we have proved that (4.1.9) holds for each  $g_n$ . Define the stochastic time

$$\tau_n(\omega) = \inf\{s > 0; |X_s(\omega)| \geq n\}$$

( $\tau_n$  is called a *stopping time* (See Chapter 7)) and prove that

$$\left( \int_0^t v \frac{\partial g_n}{\partial x}(s, X_s) \mathcal{X}_{s \leq \tau_n} dB_s := \right)$$

$$\int_0^{t \wedge \tau_n} v \frac{\partial g_n}{\partial x}(s, X_s) dB_s = \int_0^{t \wedge \tau_n} v \frac{\partial g}{\partial x}(s, X_s) dB_s$$

for each  $n$ . This gives that

$$g(t \wedge \tau_n, X_{t \wedge \tau_n}) = g(0, X_0) + \int_0^{t \wedge \tau_n} \left( \frac{\partial g}{\partial s} + u \frac{\partial g}{\partial x} + \frac{1}{2} v^2 \frac{\partial^2 g}{\partial x^2} \right) ds + \int_0^{t \wedge \tau_n} v \frac{\partial g}{\partial x} dB_s$$

and since

$$P[\tau_n > t] \rightarrow 1 \quad \text{as } n \rightarrow \infty$$

we can conclude that (4.1.9) holds (a.s.) for  $g$ .

derivative of open sets: ok  
the problem is on the border  
show that  $\frac{\partial g}{\partial x} = \frac{\partial g}{\partial x}$

$$g(t, X_t) = g(0, X_0) + \int_0^t \left( \frac{\partial g}{\partial s}(s, X_s) + u_s \frac{\partial g}{\partial x}(s, X_s) + \frac{1}{2} v_s^2 \cdot \frac{\partial^2 g}{\partial x^2}(s, X_s) \right) ds$$

$$+ \int_0^t v_s \cdot \frac{\partial g}{\partial x}(s, X_s) dB_s \quad \text{where } u_s = u(s, \omega), v_s = v(s, \omega). \quad (4.1.9)$$

Let  $t > 0$  be fixed and  $g_n(s, x) = g(s, x) \in C^2([0, \infty) \times \mathbb{R})$  for all  $s \leq t$  and all  $|x| \leq n$ .

Suppose that (4.1.9) holds for each  $g_n$ . Define

$$\tau_n(\omega) = \inf \{s > 0 : |X_s(\omega)| \geq n\}$$

Claim:  $\int_0^{t \wedge \tau_n} v \frac{\partial g_n}{\partial x}(s, X_s) dB_s = \int_0^{t \wedge \tau_n} v \frac{\partial g}{\partial x}(s, X_s) dB_s$

Proof. Since (4.1.9) holds for each  $g_n$ ,

$$g_n(t, X_t) = g_n(0, X_0) + \int_0^t \left( \frac{\partial g_n}{\partial s}(s, X_s) + u_s \frac{\partial g_n}{\partial x}(s, X_s) + \frac{1}{2} v_s^2 \frac{\partial^2 g_n}{\partial x^2}(s, X_s) \right) ds$$

$$+ \int_0^t v_s \frac{\partial g_n}{\partial x}(s, X_s) dB_s$$

Replacing  $t$  by  $t \wedge \tau_n$ , we have that  $s \leq t \wedge \tau_n$  and  $|X_s| \leq n$ . Hence,  $g_n = g$  and the claim holds.

Claim:  $P[\tau_n > t] \rightarrow 1$  as  $n \rightarrow \infty$

Proof. As  $n \rightarrow \infty$ ,  $\inf\{s > 0 : |X_s| \geq \infty\} = \infty = \tau_n$ . Then

$$P[\infty > t] = 1$$

since  $t < \infty$ .

Conclusion. Hence,

$$g_n(t \wedge \tau_n, X_{t \wedge \tau_n}) = g(t \wedge \tau_n, X_{t \wedge \tau_n}) = g(t, X_t)$$

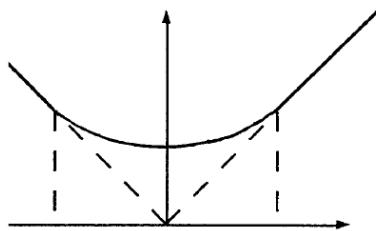
And (H.I.9.) holds a.s. for  $g$ .

4.10. (Tanaka's formula and local time).

What happens if we try to apply the Itô formula to  $g(B_t)$  when  $B_t$  is 1-dimensional and  $g(x) = |x|$ ? In this case  $g$  is not  $C^2$  at  $x = 0$ , so we modify  $g(x)$  near  $x = 0$  to  $g_\epsilon(x)$  as follows:

$$g_\epsilon(x) = \begin{cases} |x| & \text{if } |x| \geq \epsilon \\ \frac{1}{2}(\epsilon + \frac{x^2}{\epsilon}) & \text{if } |x| < \epsilon \end{cases}$$

where  $\epsilon > 0$ .



a) Apply Exercise 4.8 b) to show that

$$g_\epsilon(B_t) = g_\epsilon(B_0) + \int_0^t g'_\epsilon(B_s) dB_s + \frac{1}{2\epsilon} \cdot |\{s \in [0, t] : B_s \in (-\epsilon, \epsilon)\}|$$

where  $|F|$  denotes the Lebesgue measure of the set  $F$ .

Since

- $g_\epsilon$  is  $C^1$  everywhere
- $g_\epsilon$  is  $C^2$  outside  $0$
- $|g_\epsilon''(x)| = \begin{cases} 0, & |x| \geq \epsilon \\ 1/\epsilon, & |x| < \epsilon \end{cases}$  (\*)

Applying 4.8. b),

$$g(B_t) = g(B_0) + \int_0^t g'(B_s) dB_s + \frac{1}{2} \int_0^t g''(B_s) ds.$$

$$g_\epsilon(B_t) = g_\epsilon(B_0) + \int_0^t g'_\epsilon(B_s) dB_s + \frac{1}{2} \int_0^t g''_\epsilon(B_s) ds$$

Given our expression for  $g_\epsilon''(x)$  in (\*) we see that

$$\int_0^t g''_\epsilon(B_s) ds = \frac{1}{\epsilon} |\{s \in [0, t] : B_s \in (-\epsilon, \epsilon)\}|$$

Hence,

$$g_\epsilon(B_t) = g_\epsilon(B_0) + \int_0^t g'_\epsilon(B_s) dB_s + \frac{1}{2\epsilon} |\{s \in [0, t] : B_s \in (-\epsilon, \epsilon)\}|$$

b) Prove that

$$\int_0^t g'_\epsilon(B_s) \cdot \chi_{B_s \in (-\epsilon, \epsilon)} dB_s = \int_0^t \frac{B_s}{\epsilon} \cdot \chi_{B_s \in (-\epsilon, \epsilon)} dB_s \rightarrow 0$$

in  $L^2(P)$  as  $\epsilon \rightarrow 0$ .

(Hint: Apply the Itô isometry to

$$E \left[ \left( \int_0^t \frac{B_s}{\epsilon} \cdot \chi_{B_s \in (-\epsilon, \epsilon)} dB_s \right)^2 \right].$$

$$(*) \quad g'_\epsilon(x) = \begin{cases} \frac{x}{|x|}, & |x| > \epsilon \\ \frac{x}{\epsilon}, & |x| < \epsilon \end{cases}$$

By the expression for  $g'_\epsilon$  in (\*), we have

$$\int_0^t g'_\epsilon(B_s) \cdot \chi_{B_s \in (-\epsilon, \epsilon)} dB_s = \int_0^t \frac{B_s}{\epsilon} \chi_{B_s \in (-\epsilon, \epsilon)} dB_s$$

Using the Itô's Isometry,

$$\mathbb{E} \left[ \left( \int_0^t \frac{B_s}{\epsilon} \chi_{B_s \in (-\epsilon, \epsilon)} dB_s \right)^2 \right] = \mathbb{E} \left[ \int_0^t \left( \frac{B_s}{\epsilon} \right)^2 \chi_{B_s \in (-\epsilon, \epsilon)} ds \right]$$

$$= \mathbb{E} \left[ \frac{1}{\epsilon^2} \int_0^t B_s^2 \chi_{B_s \in (-\epsilon, \epsilon)} ds \right] \leq \mathbb{E} \left[ \int_0^t \chi_{B_s \in (-\epsilon, \epsilon)} ds \right]$$

$$= \int_0^t \mathbb{E} [\chi_{B_s \in (-\epsilon, \epsilon)}] ds = \int_0^t P[B_s \in (-\epsilon, \epsilon)] ds \rightarrow 0$$

as  $\epsilon \rightarrow 0$ . □

c) By letting  $\epsilon \rightarrow 0$  prove that

$$|B_t| = |B_0| + \int_0^t \text{sign}(B_s) dB_s + L_t(\omega), \quad (4.3.12)$$

where

$$L_t = \lim_{\epsilon \rightarrow 0} \frac{1}{2\epsilon} \cdot |\{s \in [0, t]; B_s \in (-\epsilon, \epsilon)\}| \quad (\text{limit in } L^2(P))$$

and

$$\text{sign}(x) = \begin{cases} -1 & \text{for } x \leq 0 \\ 1 & \text{for } x > 0 \end{cases}.$$

$L_t$  is called the *local time* for Brownian motion at 0 and (4.3.12) is the *Tanaka formula* (for Brownian motion). (See e.g. Rogers and Williams (1987)).

Using the previous items,

$$\begin{aligned} |B_t| &= \lim_{\epsilon \downarrow 0} g_\epsilon(B_t) = \\ &= \lim_{\epsilon \downarrow 0} g_\epsilon(B_0) + \lim_{\epsilon \downarrow 0} \int_0^t g'_\epsilon(B_s) dB_s + \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} |\{s \in [0, t] : B_s \in (-\epsilon, \epsilon)\}| \\ &= |B_0| + \lim_{\epsilon \downarrow 0} \int_0^t \frac{B_s}{|B_0|} \chi_{|B_s| > \epsilon} dB_s + \lim_{\epsilon \downarrow 0} \int_0^t \frac{B_s}{\epsilon} \chi_{B_s \in (-\epsilon, \epsilon)} dB_s + L_t \xrightarrow{\text{pink arrow}} 0 \\ &= |B_0| + \int_0^t \text{sign}(B_s) dB_s + L_t \end{aligned}$$

- 4.11. Use Itô's formula (for example in the form of Exercise 4.3) to prove that the following stochastic processes are  $\{\mathcal{F}_t\}$ -martingales:

- $X_t = e^{\frac{1}{2}t} \cos B_t \quad (B_t \in \mathbf{R})$
- $X_t = e^{\frac{1}{2}t} \sin B_t \quad (B_t \in \mathbf{R})$
- $X_t = (B_t + t)\exp(-B_t - \frac{1}{2}t) \quad (B_t \in \mathbf{R}).$

a) Let  $X_t = g(t, B_t)$  where  $g(t, x) = e^{\frac{1}{2}t} \cos x$ . Then

$$\frac{\partial g}{\partial t} = \frac{1}{2} e^{\frac{1}{2}t} \cos x; \quad \frac{\partial g}{\partial x} = -e^{\frac{1}{2}t} \sin x; \quad \frac{\partial^2 g}{\partial x^2} = -e^{\frac{1}{2}t} \cos x$$

By Itô's formula,

$$dX_t = \frac{1}{2} e^{\frac{1}{2}t} \cos B_t dt - e^{\frac{1}{2}t} \sin B_t dB_t - \frac{1}{2} e^{\frac{1}{2}t} \cos B_t dt$$

Hence,

$$X_t = - \int_0^t e^{\frac{1}{2}s} \sin B_s dB_s$$

Therefore,  $X_t$  is an  $\mathcal{F}_t$ -martingale, since it is an Itô's Integral.

b) Let  $X_t = g(t, B_t)$ , where  $g(t, x) = e^{\frac{1}{2}t} \sin x$ . By Itô's formula,

$$dX_t = \frac{1}{2} e^{\frac{1}{2}t} \sin B_t dt + e^{\frac{1}{2}t} \cos B_t dB_t - \frac{1}{2} e^{\frac{1}{2}t} \sin B_t dt$$

Thus,

$$X_t = \int_0^t e^{\frac{1}{2}s} \cos B_s dB_s \text{ is an } \mathcal{F}_t\text{-martingale}$$

c) Let  $g(t, x) = (x+t)e^{-x-\frac{1}{2}t}$ . Then,  $X_t = g(t, B_t)$  and

- $\frac{\partial g}{\partial t} = e^{-x-\frac{1}{2}t} - \frac{(x+t)e^{-x-\frac{1}{2}t}}{2} = \frac{1}{2}e^{-x-\frac{1}{2}t}(2-x-t)$
- $\frac{\partial g}{\partial x} = e^{-x-\frac{1}{2}t} - (x+t)e^{-x-\frac{1}{2}t} = e^{-x-\frac{1}{2}t}(1-x-t)$
- $\frac{\partial^2 g}{\partial x^2} = -e^{-x-\frac{1}{2}t} - e^{-x-\frac{1}{2}t} + (x+t)e^{-x-\frac{1}{2}t} = e^{-x-\frac{1}{2}t}(x+t-2)$

By Itô's formula,

$$dX_t = \frac{1}{2}e^{-B_t-\frac{1}{2}t}(2-B_t-t)dt + e^{-B_t-\frac{1}{2}t}(1-B_t-t)dB_t + \frac{1}{2}e^{-B_t-\frac{1}{2}t}(B_t+t-2)dt$$

Hence,

$$X_t = \int_0^t e^{-Bs-\frac{1}{2}s}(1-Bs-s) dB_s$$

is an  $\mathcal{F}_+$ -martingale.

□

4.12. Let  $dX_t = u(t, \omega)dt + v(t, \omega)dB_t$  be an Itô process in  $\mathbf{R}^n$  such that

$$E\left[\int_0^t |u(r, \omega)|dr\right] + E\left[\int_0^t |vv^T(r, \omega)|dr\right] < \infty \quad \text{for all } t \geq 0.$$

Suppose  $X_t$  is an  $\{\mathcal{F}_t^{(n)}\}$ -martingale. Prove that

$$u(s, \omega) = 0 \quad \text{for a.a. } (s, \omega) \in [0, \infty) \times \Omega. \quad (4.3.13)$$

Our first step is to show that

If  $X_t$  is an  $\mathcal{F}_t^{(n)}$ -martingale, then deduce that

$$E\left[\int_t^s u(r, \omega)dr \mid \mathcal{F}_t^{(n)}\right] = 0 \quad \text{for all } s \geq t. \quad (1)$$

In order to do that, notice that

$$0 = \mathbb{E}[X_s - X_t \mid \mathcal{F}_t^{(n)}] =$$

$$= \mathbb{E}\left[\left(X_0 + \int_0^s vdr + \int_0^s \sigma dB_r\right) - \left(X_0 + \int_0^t vdr + \int_0^t \sigma dB_r\right) \mid \mathcal{F}_t^{(n)}\right]$$

$$= \mathbb{E}\left[\int_0^s vdr - \int_0^t vdr + \int_0^s \sigma dB_r - \int_0^t \sigma dB_r \mid \mathcal{F}_t^{(n)}\right]$$

$$\text{Thm. 3.2.1} = \mathbb{E}\left[\int_t^s vdr \mid \mathcal{F}_t^{(n)}\right] + \mathbb{E}\left[\int_t^s \sigma dB_r \mid \mathcal{F}_t^{(n)}\right] = \mathbb{E}\left[\int_t^s vdr \mid \mathcal{F}_t^{(n)}\right]$$

Now, we are going to do the following:

Differentiate w.r.t.  $s$  to deduce that

$$E[u(s, \omega) \mid \mathcal{F}_t^{(n)}] = 0 \quad \text{a.s., for a.a. } s > t.$$

Then let  $t \uparrow s$  and apply Corollary C.9.

In fact,

$$\frac{d}{ds} \mathbb{E}\left[\int_t^s u(r, \omega)dr \mid \mathcal{F}_t^{(n)}\right] = \mathbb{E}\left[\frac{d}{ds}\left(\int_t^s u(r, \omega)dr\right) \mid \mathcal{F}_t^{(n)}\right]$$

$$= \mathbb{E} [u(s, \omega) dr \mid \mathcal{F}_+^{(n)}] = 0 \quad (2)$$

which is zero by the R.H.S. of (1).

**Corollary C.9.** Let  $X \in L^1(P)$ , let  $\{\mathcal{N}_k\}_{k=1}^\infty$  be an increasing family of  $\sigma$ -algebras,  $\mathcal{N}_k \subset \mathcal{F}$  and define  $\mathcal{N}_\infty$  to be the  $\sigma$ -algebra generated by  $\{\mathcal{N}_k\}_{k=1}^\infty$ . Then

$$E[X|\mathcal{N}_k] \rightarrow E[X|\mathcal{N}_\infty] \quad \text{as } k \rightarrow \infty,$$

a.e.  $P$  and in  $L^1(P)$ .

By the Corollary C.9. and (2),

$$\lim_{t \uparrow s} \mathbb{E} [u(t, \omega) \mid \mathcal{F}_+^{(n)}] = \mathbb{E} [u(s, \omega) \mid \mathcal{F}_+^{(n)}] = 0$$

Hence,

$$\mathbb{E} [u(s, \omega) \mid \mathcal{F}_+^{(n)}] = u(t, \omega) \quad \text{a.a.}$$

□

$$\begin{aligned} \mathbb{E} \left[ \int_+^s u(r, \omega) dr \mid \mathcal{F}_+^{(n)} \right] &= \mathbb{E} \left[ \int_0^s u(r, \omega) dr - \int_0^+ u(r, \omega) dr \mid \mathcal{F}_+^{(n)} \right] \\ &= \mathbb{E} \left[ \int_0^s u(r, \omega) dr \mid \mathcal{F}_+^{(n)} \right] - \mathbb{E} \left[ \int_0^+ u(r, \omega) dr \mid \mathcal{F}_+^{(n)} \right] \end{aligned}$$

Since  $u$  is  $\mathcal{F}_+^{(n)}$ -measurable,

$$\mathbb{E} \left[ \int_+^s u(r, \omega) dr \mid \mathcal{F}_+^{(n)} \right] = \int_0^+ u(r, \omega) dr - \int_0^+ u(r, \omega) dr = 0 \quad (1)$$

△

- 4.13. Let  $dX_t = u(t, \omega)dt + dB_t$  ( $u \in \mathbf{R}$ ,  $B_t \in \mathbf{R}$ ) be an Itô process and assume for simplicity that  $u$  is bounded. Then from Exercise 4.12 we know that unless  $u = 0$  the process  $X_t$  is not an  $\mathcal{F}_t$ -martingale. However, it turns out that we can construct an  $\mathcal{F}_t$ -martingale from  $X_t$  by multiplying by a suitable exponential martingale. More precisely, define

$$Y_t = X_t M_t$$

where

$$M_t = \exp \left( - \int_0^t u(r, \omega) dB_r - \frac{1}{2} \int_0^t u^2(r, \omega) dr \right).$$

Use Itô's formula to prove that

$$Y_t \text{ is an } \mathcal{F}_t\text{-martingale}.$$

Let

$$Z_+ := - \int_0^+ u(r, \omega) dB_r - \frac{1}{2} \int_0^+ u^2(r, \omega) dr$$

i.e.

$$dZ_+ = -u(t, \omega) dB_+ - \frac{1}{2} u^2(t, \omega) dt \quad (1)$$

With this, it is possible to write  $M_+ = e^{Z_+}$  and apply Itô's formula:

$$\begin{aligned} dM_+ &= \frac{\partial M_+}{\partial t} dt + \frac{\partial M_+}{\partial Z_+} dZ_+ + \frac{1}{2} \frac{\partial^2 M_+}{\partial Z_+^2} (dZ_+)^2 \\ &= e^{Z_+} dZ_+ + \frac{1}{2} e^{Z_+} (dZ_+)^2 \end{aligned} \quad (2)$$

Expanding  $(dZ_+)^2$ ,

$$(dZ_+)^2 = \left( -u(t, \omega) dB_+ - \frac{1}{2} u^2(t, \omega) dt \right)^2 = u^2 dt$$

Hence,

$$dM_+ = e^{Z_+} dZ_+ + \frac{1}{2} e^{Z_+} u^2 dt = M_+ \left( \frac{1}{2} u^2 dt + dZ_+ \right) \quad (3)$$

Let  $X_t, Y_t$  be Itô processes in  $\mathbf{R}$ . Prove that

$$d(X_t Y_t) = X_t dY_t + Y_t dX_t + dX_t \cdot dY_t.$$

Deduce the following general *integration by parts formula*

Now, by Integration by Parts,

$$\int_0^t X_s dY_s = X_t Y_t - X_0 Y_0 - \int_0^t Y_s dX_s - \int_0^t dX_s \cdot dY_s.$$

$$d(X_t M_t) = X_t dM_t + M_t dX_t + dX_t dM_t \quad (4)$$

Since

- $X_t dM_t \stackrel{(3)}{=} X_t M_t \left( \frac{1}{2} u^2 dt + dB_t \right) \stackrel{(1)}{=} X_t M_t (-\gamma(t, \omega) dB_t)$
- $M_t dX_t = M_t (u dt + dB_t)$
- $dX_t dM_t \stackrel{(3)}{=} (u dt + dB_t) M_t \left( \frac{1}{2} u^2 dt + dB_t \right)$
- $\stackrel{(1)}{=} M_t (u dt + dB_t) (-\gamma(t, \omega) dB_t)$
- $= -u M_t dt$

We have that (4) can be written as

$$\begin{aligned} d(X_t M_t) &= X_t M_t (-\gamma(t, \omega) dB_t) + M_t (u dt + dB_t) - u M_t dt \\ &= -u_+ X_t M_t dB_t + M_t dB_t = M_t (1 - u_+ X_t) dB_t \end{aligned}$$

Therefore,

$$Y_t = Y_0 + \int_0^t M_s (1 - u_s X_s) dB_s \quad \text{is a martingale.}$$

- 4.14. In each of the cases below find the process  $f(t, \omega) \in \mathcal{V}[0, T]$  such that (4.3.6) holds, i.e.

$$F(\omega) = E[F] + \int_0^T f(t, \omega) dB_t(\omega).$$

a)  $F(\omega) = B_T(\omega)$

Let  $f(t, \omega) = 1$ . Then, since  $\mathbb{E}[B_T(\omega)] = 0$ , we have

$$\int_0^T dB_t(\omega) = B_T(\omega) = F(\omega)$$

b)  $F(\omega) = \int_0^T B_t(\omega) dt$

Recall that

$$\int_0^T s dB_s = T B_T - \int_0^T B_s ds$$

Note that

$$\mathbb{E}[F(\omega)] = \mathbb{E}\left[\int_0^T B_t dt\right] = \int_0^T \mathbb{E}[B_t] dt = 0$$

Therefore,

$$\begin{aligned} \int_0^T B_t dt &= T B_T - \int_0^T t dB_t = T \int_0^T dB_t - \int_0^T t dB_t \\ &= \int_0^T (T-t) dB_t \Rightarrow \underline{f(t, \omega) = T-t} \end{aligned}$$

c)  $F(\omega) = B_T^2(\omega)$

Recall that

$$\int_0^T B_t dB_t = \frac{1}{2} B_T^2 - \frac{1}{2} T$$

and that  $\mathbb{E}[B_t^2] = t$ . Hence, taking  $f(t, \omega) = B_t(\omega) \cdot 2$ ,

$$B_T^2(\omega) = T + 2 \int_0^T B_s dB_s(\omega)$$

d)  $F(\omega) = B_T^3(\omega)$

Recall that  $\mathbb{E}[B_t^3] = 0$  and

$$\begin{aligned} \int_0^T B_s^2 dB_s &= \frac{1}{3} B_T^3 - \int_0^T B_s ds \\ &= \frac{1}{3} B_T^3 - \int_0^T (T-s) dB_s \end{aligned}$$

Hence,

$$\begin{aligned} B_T^3 &= 3 \left( \int_0^T B_s^2 dB_s + \int_0^T (T-s) dB_s \right) \\ &= 3 \int_0^T (B_s^2 + T - s) dB_s \end{aligned}$$

and  $f(t, \omega) = 3(B_t^2 + T - t)$

$$e) F(\omega) = e^{B_T(\omega)}$$

By Itô's formula

$$de^{B_t(\omega)} = e^{B_t(\omega)} dB_t + \frac{1}{2} e^{B_t(\omega)} dt = e^{B_t(\omega)} \left( \frac{1}{2} dt + dB_t \right)$$

and

$$\begin{aligned} d(e^{B_T(\omega) - \frac{1}{2}T}) &= -\frac{1}{2} e^{B_T - \frac{1}{2}T} dt + e^{B_T - \frac{1}{2}T} dB_T + \frac{1}{2} e^{B_T - \frac{1}{2}T} dt \\ &= e^{B_T - \frac{1}{2}T} dB_T \end{aligned}$$

Let  $U_t = e^{B_t - \frac{1}{2}t}$  and notice that we have the following SDE:

$$dU_t = U_t dB_t, \quad U_0 = 1$$

In the integral form,

$$\begin{aligned} U_T - U_0 &= \int_0^T U_t dB_t \Rightarrow e^{B_T - \frac{1}{2}T} = 1 + \int_0^T e^{B_t - \frac{1}{2}t} dB_t \\ \Leftrightarrow e^{B_T} &= e^{\frac{1}{2}T} + \int_0^T e^{B_t - \frac{1}{2}t} e^{\frac{1}{2}t} dB_t \\ &= e^{\frac{1}{2}T} + \int_0^T e^{B_t + \frac{1}{2}(T-t)} dB_t \end{aligned}$$

$$f) F(\omega) = \sin B_T(\omega)$$

from the exercise 4.11,

$$d(e^{1/2t} \sin B_t) = e^{1/2t} \cos B_t dB_t$$

Hence,

$$e^{1/2t} \sin B_t = \int_0^t e^{1/2s} \cos B_s dB_s$$

and,

$$\sin B_t = \int_0^t e^{1/2(s-t)} \cos B_s dB_s$$

$$\therefore f(t, \omega) = e^{1/2(t-T)} \cos B_t$$

4.15. Let  $x > 0$  be a constant and define

$$X_t = (x^{1/3} + \frac{1}{3}B_t)^3 ; \quad t \geq 0 .$$

Show that

$$dX_t = \frac{1}{3}X_t^{1/3}dt + X_t^{2/3}dB_t ; \quad X_0 = x .$$

Let  $g(t, y) = \left( x^{1/3} + \frac{1}{3}y \right)^3$  and compute

- $\frac{\partial g}{\partial t} = 0$

- $\frac{\partial g}{\partial y} = 3 \left( x^{1/3} + \frac{1}{3}y \right)^2 \cdot \frac{1}{3} = \left( x^{1/3} + \frac{1}{3}y \right)^{3 \cdot \frac{2}{3}}$

- $\frac{\partial^2 g}{\partial y^2} = 2 \left( x^{1/3} + \frac{1}{3}y \right) \cdot \frac{1}{3} = \frac{2}{3} \left( x^{1/3} + \frac{1}{3}y \right)^{3 \cdot \frac{1}{3}}$

By Itô's formula,

$$dX_t = \left( x^{1/3} + \frac{1}{3}y \right)^{3 \cdot \frac{2}{3}} dB_t + \frac{1}{2} \frac{2}{3} \left( x^{1/3} + \frac{1}{3}y \right)^{3 \cdot \frac{1}{3}} dt$$

$$= X_t^{2/3} dB_t + \frac{1}{3} X_t^{1/3} dt$$

- 5.1. Verify that the given processes solve the given corresponding stochastic differential equations: ( $B_t$  denotes 1-dimensional Brownian motion)

(i)  $X_t = e^{B_t}$  solves  $dX_t = \frac{1}{2}X_t dt + X_t dB_t$

By Itô's formula,

$$dX_t = e^{B_t} dB_t + \frac{1}{2}e^{B_t} dt = \frac{1}{2}X_t dt + X_t dB_t$$

(ii)  $X_t = \frac{B_t}{1+t}; B_0 = 0$  solves

$$dX_t = -\frac{1}{(1+t)^2}X_t dt + \frac{1}{1+t}dB_t; \quad X_0 = 0$$

$$g(t, x) = \frac{x}{1+t}$$

$$dX_t = \frac{-B_t}{(1+t)^2} dt + \frac{1}{1+t} dB_t = -\frac{1}{1+t} X_t dt + \frac{1}{1+t} dB_t$$

(iii)  $X_t = \sin B_t$  with  $B_0 = a \in (-\frac{\pi}{2}, \frac{\pi}{2})$  solves

$$dX_t = -\frac{1}{2}X_t dt + \sqrt{1-X_t^2} dB_t \text{ for } t < \inf \{s > 0; B_s \notin [-\frac{\pi}{2}, \frac{\pi}{2}]\}$$

$$g(t, x) = \sin x$$

$$dX_t = \cos B_t dB_t - \frac{1}{2} \sin B_t dt = -\frac{1}{2}X_t dt + \sqrt{1-X_t^2} dB_t$$

(iv)  $(X_1(t), X_2(t)) = (t, e^t B_t)$  solves

$$\begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \begin{bmatrix} 1 \\ X_2 \end{bmatrix} dt + \begin{bmatrix} 0 \\ e^{X_1} \end{bmatrix} dB_t \quad g_1(t, x) = t \\ g_2(t, x) = e^x x$$

$$\begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \begin{bmatrix} 1 \\ e^{+B_t} \end{bmatrix} dt + \begin{bmatrix} 0 \\ e^+ \end{bmatrix} dB_t = \begin{bmatrix} 1 \\ X_2 \end{bmatrix} dt + \begin{bmatrix} 0 \\ e^x \end{bmatrix} dB_t$$

(v)  $(X_1(t), X_2(t)) = (\cosh(B_t), \sinh(B_t))$  solves

$$\begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} dt + \begin{bmatrix} X_2 \\ X_1 \end{bmatrix} dB_t.$$

$$\begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \begin{bmatrix} \sinh B_t \\ \cosh B_t \end{bmatrix} dB_t + \frac{1}{2} \begin{bmatrix} \cosh B_t \\ \sinh B_t \end{bmatrix} dt \\ = \frac{1}{2} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} dt + \begin{bmatrix} X_2 \\ X_1 \end{bmatrix} dB_t$$

- 5.2. A natural candidate for what we could call *Brownian motion on the ellipse*

$$\left\{ (x, y); \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1 \right\} \quad \text{where } a > 0, b > 0$$

is the process  $X_t = (X_1(t), X_2(t))$  defined by

$$X_1(t) = a \cos B_t, \quad X_2(t) = b \sin B_t$$

where  $B_t$  is 1-dimensional Brownian motion. Show that  $X_t$  is a solution of the stochastic differential equation

$$dX_t = -\frac{1}{2} X_t dt + M X_t dB_t$$

$$\text{where } M = \begin{bmatrix} 0 & -\frac{a}{b} \\ \frac{b}{a} & 0 \end{bmatrix}.$$

Applying Itô's formula,

$$\begin{aligned} \begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} &= \begin{bmatrix} -a \sin B_t \\ b \cos B_t \end{bmatrix} dB_t + \frac{1}{2} \begin{bmatrix} -a \cos B_t \\ -b \sin B_t \end{bmatrix} dt \\ &= -\frac{1}{2} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} dt + \begin{bmatrix} 0 & -a/b \\ b/a & 0 \end{bmatrix} \cdot \begin{bmatrix} a \cos B_t \\ b \sin B_t \end{bmatrix} dB_t \\ &= -\frac{1}{2} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} dt + \begin{bmatrix} 0 & -a/b \\ b/a & 0 \end{bmatrix} \cdot \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} dB_t \end{aligned}$$

Thus,

$$dX_t = -\frac{1}{2} X_t dt + M X_t dB_t$$

- 5.3. Let  $(B_1, \dots, B_n)$  be Brownian motion in  $\mathbf{R}^n$ ,  $\alpha_1, \dots, \alpha_n$  constants.  
Solve the stochastic differential equation

$$dX_t = rX_t dt + X_t \left( \sum_{k=1}^n \alpha_k dB_k(t) \right); \quad X_0 > 0.$$

(This is a model for exponential growth with several independent white noise sources in the relative growth rate).

Let

$$X_t = X_0 \exp \left( \left( r - \frac{1}{2} \sum_{k=1}^n \alpha_k^2 \right) t + \sum_{k=1}^n \alpha_k B_k(t) \right)$$

Then by Itô's formula,

$$\begin{aligned} dX_t &= \left( r - \frac{1}{2} \sum_{k=1}^n \alpha_k^2 \right) X_t dt + \sum_{k=1}^n \alpha_k X_t dB_k(t) \\ &\quad + \frac{1}{2} \sum_{k=1}^n \alpha_k^2 X_t dt \end{aligned}$$

Hence,

$$dX_t = rX_t dt + X_t \sum_{k=1}^n \alpha_k dB_k(t)$$

5.4. Solve the following stochastic differential equations:

$$(i) \begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} dt + \begin{bmatrix} 1 & 0 \\ 0 & X_1 \end{bmatrix} \begin{bmatrix} dB_1 \\ dB_2 \end{bmatrix}$$

Notice that if  $X_1 = X_{1,0} + B_1(t)$ , then  $dX_1(t) = dt + dB_1(t)$

Similarly,  $dX_2(t) = X_1 dB_2(t) = (X_{1,0} + B_1) dB_2$ . Thus

$$X_2(t) = X_{2,0} + X_{1,0}B_2 + \int_0^t s dB_2 + \int_0^t B_1 dB_2$$

$$(ii) dX_t = X_t dt + dB_t$$

(Hint: Multiply both sides with "the integrating factor"  $e^{-t}$  and compare with  $d(e^{-t}X_t)$ )

Multiplying by  $e^t$ :

$$e^t dX_t = e^t X_t dt + e^t dB_t$$

On the other hand,

$$d(e^t X_t) = -e^t X_t dt + e^{-t} dX_t$$

Thus,

$$d(e^t X_t) = -e^{-t} X_t dt + e^{-t} X_t dt + e^{-t} dB_t = e^{-t} dB_t$$

i.e.,

$$e^t X_t = X_0 + \int_0^t e^{-s} dB_s \Leftrightarrow X_t = e^{-t} X_0 + \int_0^t e^{(t-s)} dB_s$$

$$(iii) \ dX_t = -X_t dt + e^{-t} dB_t.$$

Consider  $X_t = e^{-t} B_t$ . Then

$$dX_t = -e^{-t} B_t dt + e^{-t} dB_t = -X_t dt + e^{-t} dB_t$$

Thus, taking  $X_0 = B_0 = 0$ ,

$$X_t = e^{-t} B_t, \quad X_0 = 0$$

solves the SDE.

5.5. a) Solve the *Ornstein-Uhlenbeck equation* (or *Langevin equation*)

$$dX_t = \mu X_t dt + \sigma dB_t$$

where  $\mu, \sigma$  are real constants,  $B_t \in \mathbf{R}$ .

The solution is called the *Ornstein-Uhlenbeck process*. (Hint: See Exercise 5.4 (ii).)

Multiplying by the integrating factor  $e^{-\mu t}$ ,

$$e^{-\mu t} dX_t = e^{-\mu t} \mu X_t dt + e^{-\mu t} \sigma dB_t \quad (1)$$

Now notice that

$$d(e^{-\mu t} X_t) = -\mu e^{-\mu t} X_t dt + e^{-\mu t} dX_t \quad (2)$$

With (1) and (2)

$$d(e^{-\mu t} X_t) = e^{-\mu t} \sigma dB_t$$

Therefore,

$$e^{-\mu t} X_t = X_0 + \sigma \int_0^t e^{-\mu s} dB_s$$

And hence,

$$X_t = e^{\mu t} X_0 + \sigma \int_0^t e^{-\mu(s-t)} dB_s$$

b) Find  $E[X_t]$  and  $\text{Var}[X_t] := E[(X_t - E[X_t])^2]$ .

- $$\mathbb{E}[X_t] = \mathbb{E} \left[ e^{\mu t} X_0 + \sigma \int_0^t e^{-\mu(s-t)} dB_s \right] = \mathbb{E} [e^{\mu t} X_0]$$

$$= e^{\mu t} \mathbb{E}[X_0]$$

- Notice that

$$\begin{aligned} \mathbb{E}[X_t^2] &= \mathbb{E} \left[ e^{2\mu t} X_0^2 + \sigma^2 \int_0^t e^{-2\mu(s-t)} ds + 2e^{\mu t} X_0 \int_0^t e^{-\mu(s-t)} dB_s \right] \\ &= e^{2\mu t} \mathbb{E}[X_0^2] + \sigma^2 \mathbb{E} \left[ \int_0^t e^{-2\mu(s-t)} ds \right] \\ &= e^{2\mu t} \mathbb{E}[X_0^2] + \sigma^2 \int_0^t e^{-2\mu(s-t)} ds \\ &= e^{2\mu t} \mathbb{E}[X_0^2] + \frac{\sigma^2}{2\mu} (e^{2\mu t} - 1) \end{aligned} \quad (\times)$$

Hence,

$$\begin{aligned} \text{Var}[X_t] &= \mathbb{E}[X_t^2] - \mathbb{E}^2[X_t] \\ &= e^{2\mu t} \mathbb{E}[X_0^2] + \frac{\sigma^2}{2\mu} (e^{2\mu t} - 1) - e^{2\mu t} \mathbb{E}^2[X_0] \\ &= e^{2\mu t} (\mathbb{E}[X_0^2] - \mathbb{E}^2[X_0]) + \frac{\sigma^2}{2\mu} (e^{2\mu t} - 1) \end{aligned}$$

$$\text{Obs: } e^{2\mu t} \int_0^t e^{-2\mu s} ds = e^{2\mu t} \cdot \left[ \frac{e^{-2\mu s}}{-2\mu} \right]_0^t = -\frac{e^{2\mu t}}{2\mu} (e^{-2\mu t} - 1)$$

(\*)

$$= -\frac{1}{2\mu} (1 - e^{2\mu t}) = \frac{1}{2\mu} (e^{2\mu t} - 1)$$

5.6. Solve the stochastic differential equation

$$dY_t = r dt + \alpha Y_t dB_t$$

where  $r, \alpha$  are real constants,  $B_t \in \mathbf{R}$ .

(Hint: Multiply the equation by the 'integrating factor'

$$F_t = \exp\left(-\alpha B_t + \frac{1}{2}\alpha^2 t\right).$$

By the exercise 4.3.

$$d(X_t Y_t) = X_t dY_t + Y_t dX_t + dX_t \cdot dY_t.$$

Then

$$d(F_t Y_t) = F_t dY_t + Y_t dF_t + dF_t \cdot dY_t \quad (1)$$

Since

$$dF_t = \frac{1}{2}\alpha^2 F_t dt - \alpha F_t dB_t + \frac{1}{2}\alpha^2 F_t dt$$

$$= F_t (\alpha^2 dt - \alpha dB_t) \quad (2)$$

then

$$\begin{aligned} dF_t dY_t &= F_t (\alpha^2 dt - \alpha dB_t)(r dt + \alpha Y_t dB_t) \\ &= F_t (-\alpha^2 Y_t dt) \end{aligned} \quad (3)$$

Now we can rewrite (1) as

$$\begin{aligned} d(F_t Y_t) &= F_t (r dt + \alpha Y_t dB_t) + Y_t F_t (\alpha^2 dt - \alpha dB_t) \\ &\quad + F_t (-\alpha^2 Y_t dt) \\ &= r F_t dt + \alpha F_t Y_t dB_t + \alpha^2 F_t Y_t dt - \alpha F_t Y_t dB_t \\ &\quad - \alpha^2 F_t Y_t dt \\ &= r F_t dt \end{aligned}$$

Therefore,

$$F_t Y_t = Y_0 + \int_0^t r F_s ds$$

$$\therefore Y_t = F_t^{-1} \left[ Y_0 + \int_0^t r F_s ds \right]$$

$$= \exp(\alpha B_t - 1/2 \alpha^2 t) \left[ Y_0 + r \int_0^t \exp(-\alpha B_s + 1/2 \alpha^2 s) ds \right]$$

- 5.7. The *mean-reverting Ornstein-Uhlenbeck process* is the solution  $X_t$  of the stochastic differential equation

$$dX_t = (m - X_t)dt + \sigma dB_t$$

where  $m, \sigma$  are real constants,  $B_t \in \mathbf{R}$ .

- a) Solve this equation by proceeding as in Exercise 5.5 a).
- b) Find  $E[X_t]$  and  $\text{Var}[X_t] := E[(X_t - E[X_t])^2]$ .

a) Let  $Y_t = X_t - m$ . By Itô's formula,  $dY_t = dX_t$ . Hence

$$dY_t = -Y_t dt + \sigma dB_t$$

Applying 5.5. ( $\mu = -1$ )

$$Y_t = e^{-t} Y_0 + \sigma \int_0^t e^{(s-t)} dB_s$$

and finally,

$$X_t = m + e^{-t} Y_0 + \sigma \int_0^t e^{(s-t)} dB_s$$

b) By 5.5.,

$$E[X_t] = m + E[Y_t] = m + e^{\mu t} E[X_0] = m + e^{-t} \underline{E[X_0]}$$

$$\text{Var}[X_t] = e^{2\mu t} (E[X_0^2] - E^2[X_0]) + \frac{\sigma^2}{2\mu} (e^{2\mu t} - 1)$$

$$= e^{-2t} (E[X_0^2] - E^2[X_0]) - \frac{\sigma^2}{2} (e^{-2t} - 1)$$


---

5.8. Solve the (2-dimensional) stochastic differential equation

$$dX_1(t) = X_2(t)dt + \alpha dB_1(t)$$

$$dX_2(t) = -X_1(t)dt + \beta dB_2(t)$$

where  $(B_1(t), B_2(t))$  is 2-dimensional Brownian motion and  $\alpha, \beta$  are constants.

This is a model for a vibrating string subject to a stochastic force. See Example 5.1.3.

In matrix notation,

$$dX_t = \underbrace{\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}}_A X_t dt + \underbrace{\begin{bmatrix} \alpha & 0 \\ 0 & \beta \end{bmatrix}}_C dB_t; \quad X_t = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}, \quad B_t = \begin{bmatrix} B_1 \\ B_2 \end{bmatrix}$$

Multiplying by  $\exp(-At)$ ,

$$\exp(-At) dX_t = \exp(-At) A X_t dt + \exp(-At) C dB_t \quad (1)$$

However,

$$d(\exp(-At) X_t) = -A \exp(-At) X_t dt + \exp(-At) dX_t \quad (2)$$

By (1) and (2)

$$d(\exp(-At) X_t) = \exp(-At) C dB_t$$

i.e.,

$$\exp(-At) X_t = X_0 + \int_0^t \exp(-As) C dB_s$$

$$\therefore X_t = \exp(At) \left[ X_0 + \int_0^t \exp(-As) C dB_s \right]$$

- 5.9. Show that there is a unique strong solution  $X_t$  of the 1-dimensional stochastic differential equation

$$dX_t = \ln(1 + X_t^2)dt + \chi_{\{X_t > 0\}} X_t dB_t, \quad X_0 = a \in \mathbf{R}.$$

First we need to show that

$$|b(t, x)| + |\sigma(t, x)| \leq C(1 + |x|), \quad x \in \mathbf{R}^n, t \in [0, T]$$

In fact,  $|\chi_{\{x>0\}} x| \leq |x|$  and

$$\begin{aligned} |\ln(1+x^2)| &= |\ln(1+x^2)| \\ &\leq |\ln(x^2 - 2|x| + 1)| \quad \text{since } 1+x^2 \leq x^2 - 2|x| + 1 \\ &= |\ln(|x| - 1)|^2 \\ &= 2|\ln(|x| - 1)| \\ &\leq 2|x| \quad \text{since } \ln(x) \leq x - 1 \end{aligned}$$

Hence,

$$|\ln(1+x^2)| + |\chi_{\{x>0\}} x| \leq 2|x| + |x| < 3(1 + |x|)$$

Now we need to show that

$$|b(t, x) - b(t, y)| + |\sigma(t, x) - \sigma(t, y)| \leq D|x - y|, \quad x, y \in \mathbf{R}^n, t \in [0, T]$$

However, by the Mean Value Theorem,

$$|\ln(1+x^2) - \ln(1+y^2)| = \left| \frac{\partial z}{\partial z} \right| |x - y|$$

Given that

$$-\frac{(x-1)^2}{1+x^2} \leq 0 \Leftrightarrow \frac{2x-x^2-1}{1+x^2} \leq 0 \Leftrightarrow \frac{2x}{1+x^2} \leq \frac{1+x^2}{1+x^2} = 1$$

We obtain

$$|\ln(1+x^2) - \ln(1+y^2)| \leq |x - y|$$

Thus,  $b$  is Lipschitz. Also

$$|x_{\text{fixed } x} - x_{\text{fixed } y}| \leq |x - y|$$

Hence, a strong solution does exist.

- 5.10. Let  $b, \sigma$  satisfy (5.2.1), (5.2.2) and let  $X_t$  be the unique strong solution of (5.2.3). Show that

$$E[|X_t|^2] \leq K_1 \cdot \exp(K_2 t) \quad \text{for } t \leq T \quad (5.3.2)$$

where  $K_1 = 3E[|Z|^2] + 6C^2T(T+1)$  and  $K_2 = 6(1+T)C^2$ .

(Hint: Use the argument in the proof of (5.2.10)).

First write

$$X_t = X_0 + \int_0^t b_s ds + \int_0^t \sigma_s dB_s$$

Using that  $(x_1 + \dots + x_n)^2 \leq n(x_1^2 + \dots + x_n^2)$ ,

$$E[|X_t|^2] \leq 3E\left[|X_0|^2 + \left|\int_0^t b_s ds\right|^2 + \left|\int_0^t \sigma_s dB_s\right|^2\right] \quad (1)$$

By Cauchy-Schwartz,

$$\left|\int_0^t b_s ds\right|^2 \leq \left(\int_0^t |b_s|^2 ds\right)\left(\int_0^t ds\right) = t \int_0^t |b_s|^2 ds \quad (2)$$

With (2) and Höld's inequality, (1) becomes

$$E[|X_t|^2] \leq 3 \left[ E[|Z|^2] + tE\left[\int_0^t |b_s|^2 ds\right] + E\left[\int_0^t |\sigma_s|^2 ds\right] \right] \quad (3)$$

Now, by 5.2.1,

$$|b_s| \leq C(1+|x|) \text{ and } |\sigma_s| \leq C(1+|x|)$$

then

$$\int_0^t |b_s|^2 ds \leq \int_0^t |C(1+|x|)|^2 ds = t|C(1+|x|)|^2 \leq 2t(C^2 + C^2|x|^2)$$

Therefore,

$$\begin{aligned}\mathbb{E}[|X_t|^2] &\leq 3 \left( \mathbb{E}[|Z|^2] + \mathbb{E}[2 + (C^2 + C^2 |X_{t-}|^2)] + \mathbb{E}[2 + (C^2 + C^2 |X_{t-}|^2)] \right) \\&= 3 \left( \mathbb{E}[|Z|^2] + 2t^2 C^2 + 2t^2 C^2 \mathbb{E}[|X_{t-}|^2] + 2t C^2 + 2t C^2 \mathbb{E}[|X_{t-}|^2] \right) \\&= 3 \mathbb{E}[|Z|^2] + 6C^2(t+1) + 6C^2(t+1) \mathbb{E}[|X_{t-}|^2] \\&= K_1 + K_2 \mathbb{E}[|X_{t-}|^2]\end{aligned}$$

Finally, by Gronwall inequality,

$$\mathbb{E}[|X_t|^2] \leq K_1 \exp(K_2 t)$$

□

**5.11. (The Brownian bridge).**

For fixed  $a, b \in \mathbf{R}$  consider the following 1-dimensional equation

$$dY_t = \frac{b - Y_t}{1-t} dt + dB_t ; \quad 0 \leq t < 1 , \quad Y_0 = a . \quad (5.3.3)$$

Verify that

$$Y_t = a(1-t) + bt + (1-t) \int_0^t \frac{dB_s}{1-s} ; \quad 0 \leq t < 1 \quad (5.3.4)$$

solves the equation and prove that  $\lim_{t \rightarrow 1^-} Y_t = b$  a.s. The process  $Y_t$  is called *the Brownian bridge* (from  $a$  to  $b$ ). For other characterizations of  $Y_t$  see Rogers and Williams (1987, pp. 86–89).

Let  $g(t, x) = a(1-t) + bt + (1-t) \int_0^t \frac{dx}{1-s}$

By Itô's formula,

$$dY_t = \left( -a + b - \int_0^t \frac{dB_s}{1-s} \right) dt + (1-t) \cdot \frac{1}{1-t} dB_t = \left( \frac{b - Y_t}{1-t} \right) dt + dB_t$$

Hence  $Y_t$  solves the equation.

To show that

$$\lim_{t \rightarrow 1^-} Y_t = \lim_{t \rightarrow 1^-} \left[ a(1-t) + bt + (1-t) \int_0^t \frac{dB_s}{1-s} \right] = b$$

notice that the deterministic part  $a(1-t) + bt$  is immediate.

Now, using Itô's isometry,

$$\begin{aligned} \mathbb{E} \left[ \left( (1-t) \int_0^t \frac{dB_s}{1-s} \right)^2 \right] &= \mathbb{E} \left[ (1-t)^2 \int_0^t \frac{ds}{(1-s)^2} \right] \\ &= (1-t)^2 \int_0^t \frac{ds}{(1-s)^2} = (1-t)^2 \cdot \left[ \frac{1}{(1-s)} \right]_0^t = (1-t)^2 \left[ \frac{1}{(1-t)} - 1 \right] \\ &= (1-t) - (1-t)^2 \xrightarrow{t \rightarrow 1^-} 0 \quad \text{as } t \rightarrow 1^- \end{aligned}$$

Thus,

$$\lim_{t \rightarrow 1^-} Y_t = b \quad \text{a.s.}$$

- 5.12. To describe the motion of a pendulum with small, random perturbations in its environment we try an equation of the form

$$y''(t) + (1 + \epsilon W_t)y = 0; \quad y(0), y'(0) \text{ given,}$$

where  $W_t = \frac{dB_t}{dt}$  is 1-dimensional white noise,  $\epsilon > 0$  is constant.

- a) Discuss this equation, for example by proceeding as in Example 5.1.3.
- b) Show that  $y(t)$  solves a *stochastic Volterra equation* of the form

$$y(t) = y(0) + y'(0) \cdot t + \int_0^t a(t, r)y(r)dr + \int_0^t \gamma(t, r)y(r)dB_r$$

where  $a(t, r) = r - t$ ,  $\gamma(t, r) = \epsilon(r - t)$ .

a) Define

$$X(t) = \begin{bmatrix} X_1(t) \\ X_2(t) \end{bmatrix} = \begin{bmatrix} y(t) \\ y'(t) \end{bmatrix}$$

Therefore,

$$\begin{cases} X_1'(t) = X_2(t) \\ X_2' = -(1 + \epsilon W_t) X_1 \end{cases}$$

In matrix notation,

$$dX_t = AX_t dt + CX_t dB_t$$

where

$$A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \quad C = \begin{bmatrix} 0 & 0 \\ -\epsilon & 0 \end{bmatrix}$$

Now,

$$\exp(-At) dX_t = \exp(-At) AX_t dt + \exp(-At) CX_t dB_t$$

By Itô's formula,

$$d(\exp(-At) X_t) = -A \exp(-At) X_t dt + \exp(-At) dX_t$$

Hence,

$$d(\exp(-At) X_t) = \exp(-At) CX_t dB_t$$

i.e.,

$$\exp(-At)X_t = X_0 + \int_0^t \exp(-As)CX_s dB_s$$

$$\Leftrightarrow X_t = \exp(At) \left[ X_0 + \int_0^t \exp(-As)CX_s dB_s \right]$$

b) Rewriting the solution

Using the Leibniz rule,

$$y'(t) = y'(0) - \int_0^t y(r) dr - \varepsilon \int_0^t y(r) dB_r$$

$$\frac{d}{dx} \left( \int_a^x f(x, t) dt \right) = f(x, x) + \int_a^x \frac{\partial}{\partial x} f(x, t) dt$$

Since  $w_t = \frac{dB_t}{dt}$ , we have

$$y''(t) = -y(t) - \varepsilon y(t)w_t = -y(t)(1 + \varepsilon w_t)$$

i.e.,

$$y''(t) + (1 + \varepsilon w_t)y(t) = 0$$

Another way: notice that

$$Y_t = y_0 + y'_0 t + \int_0^t (t-r) y_r dr + \int_0^t \varepsilon(t-r) y_r \underbrace{w_r dr}_{dB_r} \quad \text{with } dB_t = w_t dt$$

$$= y_0 + y'_0 t + \int_0^t r \frac{(1 + \varepsilon w_r) y_r dr}{-y_r''} - \int_0^t \frac{+ (1 + \varepsilon w_r) y_r dr}{-y_r''}$$

$$= Y_0 + \left. Y'_0 + - r Y'_r \right|_0^+ + \int_0^+ Y'_r dr + \left. + Y'_r \right|_0^+$$

$$= \cancel{Y_0} + \cancel{Y'_0} + - \cancel{+ Y'_r} + Y_r - \cancel{Y_0} + \cancel{+ Y'_r} - \cancel{+ Y'_0} = Y_r \quad \checkmark$$

- 5.13. As a model for the horizontal slow drift motions of a moored floating platform or ship responding to incoming irregular waves John Grue (1989) introduced the equation

$$x_t'' + a_0 x_t' + w^2 x_t = (T_0 - \alpha_0 x_t') \eta W_t , \quad (5.3.5)$$

where  $W_t$  is 1-dimensional white noise,  $a_0, w, T_0, \alpha_0$  and  $\eta$  are constants.

- (i) Put  $X_t = \begin{bmatrix} x_t \\ x_t' \end{bmatrix}$  and rewrite the equation in the form

$$dX_t = AX_t dt + KX_t dB_t + M dB_t ,$$

where

$$A = \begin{bmatrix} 0 & 1 \\ -w^2 & -a_0 \end{bmatrix}, \quad K = \alpha_0 \eta \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix} \quad \text{and} \quad M = T_0 \eta \begin{bmatrix} 0 \\ 1 \end{bmatrix} .$$

- (ii) Show that  $X_t$  satisfies the integral equation

$$X_t = \int_0^t e^{A(t-s)} K X_s dB_s + \int_0^t e^{A(t-s)} M dB_s \quad \text{if } X_0 = 0 .$$

Multiplying the equation by  $\exp(-At)$ ,

$$\exp(-At) dX_t = \exp(-At) A X_t dt + \exp(-At) [K X_t + M] dB_t$$

Applying Itô's formula to  $d(\exp(-At) X_t)$ ,

$$\begin{aligned} d(\exp(-At) X_t) &= -A \exp(-At) X_t dt + \exp(-At) dX_t \\ &= \exp(-At) [K X_t + M] dB_t \end{aligned}$$

Therefore,

$$\exp(-At) X_t = X_0 + \int_0^t \exp(-As) [K X_s + M] dB_s$$

If  $X_0 = 0$ ,

$$X_t = \int_0^t e^{A(t-s)} K X_s dB_s + \int_0^t e^{A(t-s)} M dB_s$$

(iii) Verify that

$$e^{At} = \frac{e^{-\lambda t}}{\xi} \{(\xi \cos \xi t + \lambda \sin \xi t)I + A \sin \xi t\}$$

where  $\lambda = \frac{\alpha_0}{2}$ ,  $\xi = (w^2 - \frac{\alpha_0^2}{4})^{\frac{1}{2}}$  and use this to prove that

$$x_t = \eta \int_0^t (T_0 - \alpha_0 y_s) g_{t-s} dB_s \quad (5.3.6)$$

and

$$y_t = \eta \int_0^t (T_0 - \alpha_0 y_s) h_{t-s} dB_s, \quad \text{with } y_t := x'_t, \quad (5.3.7)$$

where

$$\begin{aligned} g_t &= \frac{1}{\xi} \operatorname{Im}(e^{\zeta t}) \\ h_t &= \frac{1}{\xi} \operatorname{Im}(\zeta e^{\bar{\zeta} t}), \quad \zeta = -\lambda + i\xi \quad (i = \sqrt{-1}). \end{aligned}$$

Idea: write  $A = PDP^{-1}$

and then use that

$$e^{At} = P e^{Dt} P^{-1}$$

So we can solve for  $y_t$  first in (5.3.7) and then substitute in (5.3.6) to find  $x_t$ .

We start by computing the characteristic polynomial of  $A$ :

$$C_A(x) = \begin{vmatrix} x & -1 \\ w^2 & x + \alpha_0 \end{vmatrix} = x(x + \alpha_0) + w^2 = x^2 + x\alpha_0 + w^2$$

Setting  $C_A(x) = 0$ ,

$$x = \frac{-\alpha_0 \pm \sqrt{\alpha_0^2 - 4w^2}}{2} = \frac{-\alpha_0 \pm i\sqrt{w^2 - \alpha_0^2/4}}{2} = -\lambda \pm i\xi$$

Finding the eigenvectors associated with  $-\lambda \pm i\xi$ :

$$\begin{bmatrix} \lambda - i\xi & 1 \\ -w^2 & -\alpha_0 + \lambda - i\xi \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0 \iff \begin{cases} (\lambda - i\xi)x + y = 0 \\ -w^2x + (-\alpha_0 + \lambda - i\xi)y = 0 \end{cases}$$

Then  $y = -(\lambda - i\xi)x$ . Let  $x = 1$  and then  $y = -\lambda + i\xi$ .

For  $-\lambda - i\xi$ , the same calculation yields  $x = 1$  and  $-\lambda - i\xi$ .

Thus, we can write

using the idea

$$e^{At} = \begin{bmatrix} 1 & 1 \\ -\lambda+i\xi & -\lambda-i\xi \end{bmatrix} \cdot \begin{bmatrix} e^{(-\lambda+i\xi)+} & 0 \\ 0 & e^{(-\lambda-i\xi)+} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -\lambda+i\xi & -\lambda-i\xi \end{bmatrix}^{-1} \quad (1)$$

Now let us compute the inverse above.

$$\begin{bmatrix} 1 & 1 \\ -\lambda+i\xi & -\lambda-i\xi \end{bmatrix}^{-1} = \frac{-1}{2\xi i} \begin{bmatrix} -\lambda-i\xi & -1 \\ \lambda-i\xi & 1 \end{bmatrix}$$

Thus

$$\begin{aligned} e^{At} &= \frac{-1}{2\xi i} \begin{bmatrix} 1 & 1 \\ -\lambda+i\xi & -\lambda-i\xi \end{bmatrix} \cdot \begin{bmatrix} e^{(-\lambda+i\xi)+} & 0 \\ 0 & e^{(-\lambda-i\xi)+} \end{bmatrix} \begin{bmatrix} -\lambda-i\xi & -1 \\ \lambda-i\xi & 1 \end{bmatrix} \\ &= \frac{-1}{2\xi i} \begin{bmatrix} 1 & 1 \\ -\lambda+i\xi & -\lambda-i\xi \end{bmatrix} \cdot \begin{bmatrix} -e^{(-\lambda-i\xi)+}(\lambda+i\xi) & -e^{(-\lambda+i\xi)+} \\ e^{(-\lambda-i\xi)+}(\lambda-i\xi) & e^{(-\lambda+i\xi)+} \end{bmatrix} \\ &= \frac{-1}{2\xi i} \begin{bmatrix} F & G \\ H & I \end{bmatrix} \end{aligned} \quad (2)$$

where

$$F = e^{(-\lambda-i\xi)+}(\lambda-i\xi) - e^{(-\lambda+i\xi)+}(\lambda+i\xi)$$

$$G = e^{(-\lambda-i\xi)+} - e^{(-\lambda+i\xi)+}$$

$$H = (-\xi^2 - \lambda^2) e^{(-\lambda-i\xi)+} - (\xi^2 - \lambda^2) e^{(-\lambda+i\xi)+}$$

$$I = (-\lambda+i\xi)(-e^{(-\lambda+i\xi)+}) + (-\lambda-i\xi)(e^{(-\lambda-i\xi)+})$$

Simplifying,

$$\begin{aligned}
 F &= e^{(-\lambda-i\xi)+}(\lambda-i\xi) - e^{(-\lambda+i\xi)+}(\lambda+i\xi) \\
 &= e^{-\lambda+}(\lambda-i\xi)e^{-i\xi t} - e^{-\lambda+}(\lambda+i\xi)e^{i\xi t} \\
 &= e^{-\lambda+}(\lambda-i\xi)(\cos(\xi t) - i \sin(\xi t)) \\
 &\quad - e^{-\lambda+}(\lambda+i\xi)(\cos(\xi t) + i \sin(\xi t)) \\
 &= e^{-\lambda+} \left[ \lambda (\cancel{\cos(\xi t)} - i \sin(\xi t)) - i \xi (\cos(\xi t) - i \sin(\xi t)) \right. \\
 &\quad \left. - \lambda (\cancel{\cos(\xi t)} + i \sin(\xi t)) - i \xi (\cos(\xi t) + i \sin(\xi t)) \right] \\
 &= -2i e^{-\lambda+} [\lambda \sin(\xi t) + \xi \cos(\xi t)] \tag{3}
 \end{aligned}$$

$$\begin{aligned}
 G &= e^{(-\lambda-i\xi)+} - e^{(-\lambda+i\xi)+} = e^{-\lambda+} [e^{-i\xi t} - e^{i\xi t}] \\
 &= -2i e^{-\lambda+} \sin(\xi t) \tag{4}
 \end{aligned}$$

$$\begin{aligned}
 H &= (-\xi^2 - \lambda^2) e^{(-\lambda-i\xi)+} - (\xi^2 - \lambda^2) e^{(-\lambda+i\xi)+} \\
 &= -\omega^2 (e^{(-\lambda-i\xi)+} - e^{(-\lambda+i\xi)+}) \stackrel{(4)}{=} -\omega^2 (-2i e^{-\lambda+} \sin(\xi t)) \tag{5}
 \end{aligned}$$

where we used that  $\lambda^2 + \xi^2 = \omega^2$ .

$$\begin{aligned}
 I &= (-\lambda+i\xi)(-e^{(-\lambda+i\xi)+}) + (\lambda-i\xi)(e^{(-\lambda-i\xi)+}) \\
 &= -(-\lambda+i\xi) e^{-\lambda+} e^{i\xi t} + e^{-\lambda+} (-\lambda-i\xi) e^{-i\xi t}
 \end{aligned}$$

$$\begin{aligned}
&= e^{-\lambda t} \left[ (\lambda - i\xi) (\cos(\xi t) + i \sin(\xi t)) \right. \\
&\quad \left. + (-\lambda - i\xi) (\cos(\xi t) - i \sin(\xi t)) \right] \\
&= e^{-\lambda t} \left[ \lambda (\cancel{\cos(\xi t)} + i \sin(\xi t)) - i\xi (\cos(\xi t) + \cancel{i \sin(\xi t)}) \right. \\
&\quad \left. - \lambda (\cancel{\cos(\xi t)} - i \sin(\xi t)) - i\xi (\cos(\xi t) - \cancel{i \sin(\xi t)}) \right] \\
&= e^{-\lambda t} \left[ 2i\lambda \sin(\xi t) - 2i\xi \cos(\xi t) \right] \\
&= -2i e^{-\lambda t} \left[ \lambda \sin(\xi t) + \xi \cos(\xi t) - 2\lambda \sin(\xi t) \right] \tag{6}
\end{aligned}$$

With (3)-(6) in the matrix (2) we have

$$e^{At} = \frac{e^{-\lambda t}}{\xi} \begin{bmatrix} \lambda \sin(\xi t) + \xi \cos(\xi t) & \sin(\xi t) \\ -\omega^2 \sin(\xi t) & \lambda \sin(\xi t) + \xi \cos(\xi t) - 2\lambda \sin(\xi t) \end{bmatrix}$$

Hence,

$$e^{At} = \frac{e^{-\lambda t}}{\xi} \left[ (\lambda \sin(\xi t) + \xi \cos(\xi t)) I + A \sin(\xi t) \right]$$

Now let  $y_t = x'_t$ , and define  $\zeta = -\lambda + i\xi$ ,

$$g_t = \frac{1}{\xi} \operatorname{Im}(e^{\zeta t}) = \frac{1}{\xi} e^{-\lambda t} \sin(\xi t)$$

and

$$h_t = \frac{1}{\xi} \operatorname{Im}(\zeta e^{\zeta t}) = \frac{1}{\xi} e^{-\lambda t} (\xi \cos(\xi t) - \lambda \sin(\xi t))$$

We'll the solution with the expression for  $e^{At}$  above. For this, let us compute

$$\begin{aligned}
 e^{A(t-s)} K X_s &= \frac{e^{-\lambda(t-s)}}{\xi} \left[ (\lambda \sin(\xi(t-s)) + \xi \cos(\xi(t-s))) I + A \sin(\xi(t-s)) \right] \\
 &\quad \cdot a_0 \eta \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_s \\ x_s' \end{bmatrix} \\
 &= \frac{e^{-\lambda(t-s)}}{\xi} \begin{bmatrix} \lambda \sin(\xi(t-s)) + \xi \cos(\xi(t-s)) & \sin(\xi(t-s)) \\ -\omega^2 \sin(\xi(t-s)) & (\lambda - a_0) \sin(\xi(t-s)) + \xi \cos(\xi(t-s)) \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & -a_0 \eta \end{bmatrix} \begin{bmatrix} x_s \\ x_s' \end{bmatrix} \\
 &= -a_0 \eta \frac{e^{-\lambda(t-s)}}{\xi} \begin{bmatrix} 0 & \sin(\xi(t-s)) \\ 0 & \xi \cos(\xi(t-s)) - \lambda \sin(\xi(t-s)) \end{bmatrix} \begin{bmatrix} x_s \\ x_s' \end{bmatrix} \\
 (7) \quad &= \begin{bmatrix} (-a_0 \eta e^{-\lambda(t-s)} / \xi) \sin(\xi(t-s)) y_s \\ (-a_0 \eta e^{-\lambda(t-s)} / \xi) (\xi \cos(\xi(t-s)) - \lambda \sin(\xi(t-s))) y_s \end{bmatrix} = \begin{bmatrix} -a_0 \eta g_{t-s} y_s \\ -a_0 \eta h_{t-s} y_s \end{bmatrix}
 \end{aligned}$$

and

$$\begin{aligned}
 e^{A(t-s)} M &= \frac{e^{-\lambda(t-s)}}{\xi} \left[ (\lambda \sin(\xi(t-s)) + \xi \cos(\xi(t-s))) I + A \sin(\xi(t-s)) \right] \\
 &\quad \cdot T_0 \eta \begin{bmatrix} 0 \\ 1 \end{bmatrix}
 \end{aligned}$$

$$(8) \quad = T_0 \eta \frac{e^{-\lambda(t-s)}}{\xi} \begin{bmatrix} \sin(\xi(t-s)) \\ \xi \cos(\xi(t-s)) - \lambda \sin(\xi(t-s)) \end{bmatrix} = \begin{bmatrix} \eta T_0 g_{t-s} \\ \eta T_0 h_{t-s} \end{bmatrix}$$

Finally, using the solution from the item (ii), it follows that

$$\begin{bmatrix} X_t \\ Y_t \end{bmatrix} = \int_0^t \begin{bmatrix} -a_0 \eta g_{t-s} y_s \\ -a_0 \eta h_{t-s} y_s \end{bmatrix} dB_s + \int_0^t \begin{bmatrix} \eta T_0 g_{t-s} \\ \eta T_0 h_{t-s} \end{bmatrix} dB_s$$

In particular,

$$X_t = \eta \int_0^t (T_0 - a_0 y_s) g_{t-s} dB_s$$

and

$$Y_t = \eta \int_0^t (T_0 - a_0 y_s) h_{t-s} dB_s$$

- 5.14. If  $(B_1, B_2)$  denotes 2-dimensional Brownian motion we may introduce complex notation and put

$$\mathbf{B}(t) := B_1(t) + iB_2(t) \quad (i = \sqrt{-1}).$$

$\mathbf{B}(t)$  is called *complex Brownian motion*.

- (i) If  $F(z) = u(z) + iv(z)$  is an *analytic* function i.e.  $F$  satisfies the Cauchy-Riemann equations

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}, \quad \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}; \quad z = x + iy$$

and we define

$$Z_t = F(\mathbf{B}(t))$$

prove that

$$dZ_t = F'(\mathbf{B}(t))d\mathbf{B}(t), \quad (5.3.8)$$

where  $F'$  is the (complex) derivative of  $F$ . (Note that the usual second order terms in the (real) Itô formula are not present in (5.3.8)!!)

$$dY_k = \frac{\partial g_k}{\partial t}(t, X)dt + \sum_i \frac{\partial g_k}{\partial x_i}(t, X)dX_i + \frac{1}{2} \sum_{i,j} \frac{\partial^2 g_k}{\partial x_i \partial x_j}(t, X)dX_i dX_j$$

Note that

$$F(B(t)) = u(B(t)) + iv(B(t)) = u(B_1(t) + iB_2(t)) + iv(B_1(t) + iB_2(t))$$

Defining  $g(t, z) = u(z) + iv(z)$ , for  $z = B(t)$  the Itô formula gives

$$dZ_t = dF(B(t)) = \frac{\partial u}{\partial B_1} dB_1 + i \frac{\partial u}{\partial B_2} dB_2 + \frac{1}{2} \left( \frac{\partial^2 u}{\partial B_1^2} dt + \frac{\partial^2 u}{\partial B_2^2} dt \right)$$

$$dB = dB_1 + i dB_2$$

$$+ i \frac{\partial v}{\partial B_1} dB_1 - \frac{\partial v}{\partial B_2} dB_2 + \frac{i}{2} \left( \frac{\partial^2 v}{\partial B_1^2} dt + \frac{\partial^2 v}{\partial B_2^2} dt \right)$$

$$= \left( \frac{\partial u}{\partial B_1} + i \frac{\partial v}{\partial B_1} \right) dB_1 + i \left( \frac{\partial u}{\partial B_2} + i \frac{\partial v}{\partial B_2} \right) dB_2$$

$$= \left( \frac{\partial u}{\partial B} + i \frac{\partial v}{\partial B} \right) dB = F'(B(t))dB$$

(ii) Solve the complex stochastic differential equation

$$dZ_t = \alpha Z_t d\mathbf{B}(t) \quad (\alpha \text{ constant}).$$

For more information about complex stochastic calculus involving analytic functions see e.g. Ubøe (1987).

Let  $F(z) = e^{\alpha z}$ . Clearly,  $F(z)$  is analytic.

$$e^{\alpha z} = e^{\alpha(x+iy)} = e^{\alpha x} \cdot e^{i\alpha y} = \underbrace{e^{\alpha x}}_u \underbrace{(\cos \alpha y + i \sin \alpha y)}_v$$

$$\left\{ \begin{array}{lcl} \frac{\partial u}{\partial x} = \alpha e^{\alpha x} \cos \alpha y & = & \frac{\partial v}{\partial x} = \alpha e^{\alpha x} \cos \alpha y \\ \frac{\partial u}{\partial y} = -\alpha e^{\alpha x} \sin \alpha y & = & -\frac{\partial v}{\partial x} = \alpha e^{\alpha x} \sin \alpha y \end{array} \right.$$

✓

If  $Z_t = F(B(t))$ , by item (i),

$$dZ_t = F'(B(t)) dB(t) = \alpha e^{\alpha B(t)} dB(t) = \alpha Z_t dB(t)$$

■

**5.15. (Population growth in a stochastic, crowded environment)**

The nonlinear stochastic differential equation

$$dX_t = rX_t(K - X_t)dt + \beta X_t dB_t ; \quad X_0 = x > 0 \quad (5.3.9)$$

is often used as a model for the growth of a population of size  $X_t$  in a stochastic, crowded environment. The constant  $K > 0$  is called the *carrying capacity* of the environment, the constant  $r \in \mathbf{R}$  is a measure of the quality of the environment and the constant  $\beta \in \mathbf{R}$  is a measure of the size of the noise in the system.

Verify that

$$X_t = \frac{\exp\{(rK - \frac{1}{2}\beta^2)t + \beta B_t\}}{x^{-1} + r \int_0^t \exp\{(rK - \frac{1}{2}\beta^2)s + \beta B_s\}ds} ; \quad t \geq 0 \quad (5.3.10)$$

is the unique (strong) solution of (5.3.9). (This solution can be found by performing a substitution (change of variables) which reduces (5.3.9) to a linear equation. See Gard (1988), Chapter 4 for details.)

Step 1. Multiply by  $X_t^{-2}$ :

$$X_t^{-2} dX_t = (rX_t^{-1}K - r)dt + \beta X_t^{-1} dB_t$$

Step 2. Substitute  $Y_t = X_t^{-1}$ .

Notice that

$$dY_t = -\frac{dX_t}{X_t^2} + \frac{(dX_t)^2}{X_t^3}$$

Then

$$\begin{aligned} dY_t &= (-rY_t K + r)dt - \beta Y_t dB_t + \beta^2 Y_t dt \\ &= (-rK + \beta^2)Y_t dt - \beta Y_t dB_t + r dt \end{aligned}$$

Step 3. Change of variables.

Let  $Z_t = Y_t e^{(rK - \beta^2)t}$ . By Itô's formula,

$$\begin{aligned} dZ_t &= (rK - \beta^2)Y_t e^{(rK - \beta^2)t} dt + e^{(rK - \beta^2)t} dY_t \\ &= (rK - \beta^2)Y_t e^{(rK - \beta^2)t} dt + e^{(rK - \beta^2)t} ((-rK + \beta^2)Y_t dt - \beta Y_t dB_t + r dt) \end{aligned}$$

Thus,

$$dZ_t = r e^{(rK - \beta^2)t} dt - \beta Z_t dB_t$$

Step 4. Use integrating factor to solve the SDE.

Let  $N_t$  be such that  $dN_t = \theta_t dt + \gamma_t dB_t$ . By integration by parts (ex. 4.3),

$$d(X_t Y_t) = X_t dY_t + Y_t dX_t + dX_t \cdot dY_t .$$

Thus,

$$\begin{aligned} d(N_t Z_t) &= N_t dZ_t + Z_t dN_t + dN_t dZ_t \\ &= N_t r e^{(rK - \beta^2)t} dt - \beta N_t Z_t dB_t + \theta_t Z_t dt + \gamma_t Z_t dB_t - \beta \gamma_t Z_t dt \end{aligned}$$

Setting  $\theta_t = \beta \gamma_t$  and  $\gamma_t = \beta N_t$  we have

$$dN_t = \beta^2 N_t dt + \beta N_t dB_t$$

Then (see ex. 5.3 and example 5.1.2 of my notes),

$$N_t = N_0 \exp\left(\frac{1}{2}\beta^2 t + \beta B_t\right)$$

and

$$d(N_t Z_t) = N_t r e^{(rK - \beta^2)t} = N_0 r \exp\left(\beta B_t + \left(rK - \frac{1}{2}\beta^2\right)t\right)$$

Choosing  $N_0 = 1$ ,

$$N_t Z_t = Z_0 + \int_0^t r \exp\left(\beta B_s + \left(rK - \frac{1}{2}\beta^2\right)s\right) ds$$

Thus, using that  $Z_t = Y_t e^{(rK - \beta^2)t}$  and  $Y_t = X_t^{-1}$ ,  $Z_0 = X_0^{-1} = x^{-1}$ ,

$$X_t = Y_t^{-1} = Z_t^{-1} e^{(rK - \beta^2)t}$$

$$= \frac{e^{(rK - \beta^2)t} N_t}{Z_0 + \int_0^t r \exp\left(\beta B_s + \left(rK - \frac{1}{2}\beta^2\right)s\right) ds}$$

$$= \frac{\exp\left[(rK - 1/2\beta^2)t + \beta B_t\right]}{x^{-1} + r \int_0^t \exp\left[(rK - 1/2\beta^2)s + \beta B_s\right] ds}$$

- 5.16. The technique used in Exercise 5.6 can be applied to more general nonlinear stochastic differential equations of the form

$$dX_t = f(t, X_t)dt + c(t)X_t dB_t, \quad X_0 = x \quad (5.3.11)$$

where  $f: \mathbf{R} \times \mathbf{R} \rightarrow \mathbf{R}$  and  $c: \mathbf{R} \rightarrow \mathbf{R}$  are given continuous (deterministic) functions. Proceed as follows:

- a) Define the 'integrating factor'

$$F_t = F_t(\omega) = \exp \left( - \int_0^t c(s) dB_s + \frac{1}{2} \int_0^t c^2(s) ds \right). \quad (5.3.12)$$

Show that (5.3.11) can be written

$$d(F_t X_t) = F_t \cdot f(t, X_t) dt. \quad (5.3.13)$$

We start by applying Itô's formula to  $F_t$ .

$$\text{If } g(t, X_t) = \exp \left( - \int_0^t c(s) dX_s + \frac{1}{2} \int_0^t c^2(s) ds \right), \quad F_t = g(t, B_t),$$

- $\frac{\partial g}{\partial t} = \frac{1}{2} c^2(t) \cdot g(t, X_t)$
- $\frac{\partial^2 g}{\partial x^2} = c^2(t) g(t, X_t)$
- $\frac{\partial g}{\partial x} = -c(t) \cdot g(t, X_t)$

Thus,

$$\begin{aligned} dF_t &= \frac{1}{2} c^2(t) \cdot g(t, B_t) dt - c(t) \cdot g(t, B_t) dB_t + \frac{1}{2} c^2(t) \cdot g(t, B_t) dt \\ &= c^2(t) g(t, B_t) dt - c(t) \cdot g(t, B_t) dB_t \end{aligned} \quad (1)$$

Using Integration by Parts (ex. 4.3),

$$d(F_t X_t) = F_t dX_t + X_t dF_t + dF_t dX_t \quad (2)$$

Computing  $dF_t dX_t$ ,

$$\begin{aligned}
 dF_t dx_t &= (c^2(t) g(t, B_t) dt - c(t) \cdot g(t, B_t) dB_t) \\
 &\quad (f(t, x_t) dt + c(t) x_t dB_t) \\
 &= -c^2(t) g(t, B_t) x_t dt
 \end{aligned} \tag{3}$$

By (2),

$$\begin{aligned}
 d(F_t x_t) &= g(t, B_t) (f(t, x_t) dt + c(t) x_t dB_t) \\
 &\quad + x_t (c^2(t) g(t, B_t) dt - c(t) \cdot g(t, B_t) dB_t) \\
 &\quad - c^2(t) g(t, B_t) x_t dt \\
 &= F_t f(t, x_t) dt
 \end{aligned} \tag{4}$$

b) Now define

$$Y_t(\omega) = F_t(\omega) X_t(\omega) \tag{5.3.14}$$

so that

$$X_t = F_t^{-1} Y_t. \tag{5.3.15}$$

Deduce that equation (5.3.13) gets the form

$$\frac{dY_t(\omega)}{dt} = F_t(\omega) \cdot f(t, F_t^{-1}(\omega) Y_t(\omega)); \quad Y_0 = x. \tag{5.3.16}$$

Note that this is just a *deterministic* differential equation in the function  $t \rightarrow Y_t(\omega)$ , for each  $\omega \in \Omega$ . We can therefore solve (5.3.16) with  $\omega$  as a parameter to find  $Y_t(\omega)$  and then obtain  $X_t(\omega)$  from (5.3.15).

Notice that

$$dY_t = d(F_t x_t) = F_t f(t, x_t) dt$$

Thus,

$$\frac{dY_t}{dt} = F_t f(t, F_t^{-1} Y_t) \tag{5}$$

c) Apply this method to solve the stochastic differential equation

$$dX_t = \frac{1}{X_t} dt + \alpha X_t dB_t ; \quad X_0 = x > 0 \quad (5.3.17)$$

where  $\alpha$  is constant.

Define

$$F_t = \exp \left( - \int_0^t \alpha dB_s + \frac{1}{2} \int_0^t \alpha^2 ds \right) = \exp \left( - \alpha B_t + \frac{1}{2} \alpha^2 t \right)$$

By (5), if  $Y_t = F_t X_t$ ,

$$\begin{aligned} \frac{dY_t}{dt} &= F_t f(t, F_t^{-1} Y_t) = F_t \cdot \frac{1}{F_t^{-1} Y_t} = \left[ \exp \left( - \alpha B_t + \frac{1}{2} \alpha^2 t \right) \right]^2 Y_t \\ &= \frac{1}{Y_t} \exp \left( \alpha^2 t - 2\alpha B_t \right) \end{aligned}$$

Solving by separable equation, we can write  $Y_t dY_t - F_t^2 dt = 0$ .

Let

$$G(Y_t) = \int Y_t dY_t = \frac{Y_t^2}{2} + C$$

$$F(t) = \int F_t^2 dt = \int e^{-2\alpha B_t} \cdot e^{\alpha^2 t} dt = \frac{e^{\alpha^2 t - 2\alpha B_t}}{\alpha^2} + C$$

Thus,

$$G(Y_t) - F(x) = \frac{Y_t^2}{2} - \int e^{\alpha^2 s - 2\alpha B_s} ds = C$$

and

$$Y_t^2 = 2C + 2 \int_0^t e^{\alpha^2 s - 2\alpha B_s} ds$$

i.e.,

$$Y_t = \sqrt{Y_0^2 + 2 \int_0^t e^{\alpha^2 s - 2\alpha B_s} ds}$$

Since  $X_t = F_t^{-1} Y_t$ ,

$$X_t = e^{\alpha B_t - \frac{1}{2}\alpha^2 t} \sqrt{x^2 + 2 \int_0^t e^{\alpha^2 s - 2\alpha B_s} ds}$$

- d) Apply the method to study the solutions of the stochastic differential equation

$$dX_t = X_t^\gamma dt + \alpha X_t dB_t ; \quad X_0 = x > 0 \quad (5.3.18)$$

where  $\alpha$  and  $\gamma$  are constants.

For what values of  $\gamma$  do we get explosion?

We'll use  $F_t$  as defined in the previous item.

By (5), if  $Y_t = F_t X_t$ ,

$$\frac{dY_t}{dt} = F_t f(t, F_t^{-1} Y_t) = F_t (F_t^{-1} Y_t)^\gamma = F_t^{1-\gamma} Y_t^\gamma$$

Solving by separable equation, we can write  $Y_t^{-\gamma} dY_t - F_t^{1-\gamma} dt = 0$ .  
Let

$$G(Y_t) = \int Y_t^{-\gamma} dY_t = \frac{Y_t^{-\gamma+1}}{-\gamma+1} + C$$

$$\begin{aligned} F(t) &= \int \exp\left(-\alpha B_t + \frac{1}{2}\alpha^2 t\right)^{1-\gamma} dt \\ &= \int \exp\left(-(1-\gamma)\alpha B_t + (1-\gamma)\frac{\alpha^2}{2} t\right) dt \end{aligned}$$

Therefore,

$$G(Y_t) - F(t) = \frac{Y_t^{-\gamma+1}}{-\gamma+1} - \int \exp\left(-(1-\gamma)\alpha B_s + (1-\gamma)\frac{\alpha^2 s}{2}\right) ds = C$$

and,

$$Y_t^{1-\gamma} = (-\gamma+1)C + (1-\gamma) \int_0^t \exp\left(-(1-\gamma)\alpha B_s + (1-\gamma)\frac{\alpha^2 s}{2}\right) ds$$

i.e.,

$$Y_t = \left( Y_0^{1-\gamma} + (1-\gamma) \int_0^t \exp\left(-(1-\gamma)\alpha B_s + (1-\gamma)\frac{\alpha^2 s}{2}\right) ds \right)^{\frac{1}{1-\gamma}}$$

Since  $X_t = F_t^{-1} Y_t$ ,

$$X_t = e^{\alpha B_t - \frac{1}{2} \alpha^2 t} \left( X_0^{1-\gamma} + (1-\gamma) \int_0^t \exp\left(-(1-\gamma)\alpha B_s + (1-\gamma)\frac{\alpha^2 s}{2}\right) ds \right)^{\frac{1}{1-\gamma}}$$

**5.17.** (The Gronwall inequality)

Let  $v(t)$  be a nonnegative function such that

$$v(t) \leq C + A \int_0^t v(s) ds \quad \text{for } 0 \leq t \leq T$$

for some constants  $C, A$ . Prove that

$$v(t) \leq C \exp(At) \quad \text{for } 0 \leq t \leq T. \quad (5.3.19)$$

Define

$$g(t) = A \exp\left(-\int_0^t A s ds\right) \int_0^t v(s) ds = A \exp(-At) \int_0^t v(s) ds$$

and compute

$$\begin{aligned} g'(t) &= A \exp(-At) \left[ -A \int_0^t v(s) ds + v(t) \right] \\ &\leq A \exp(-At) \left[ -A \int_0^t v(s) ds + C + A \int_0^t v(s) ds \right] \\ &= AC \exp(-At) \end{aligned}$$

Integrating,

$$g(t) \leq AC \int_0^t \exp(-As) ds = AC \left[ \frac{1}{A} (1 - e^{-At}) \right] = C (1 - e^{-At})$$

Thus,

$$A \int_0^t v(s) ds = \exp(At) g(t) \leq e^{At} C (1 - e^{-At})$$

Finally,

$$v(t) \leq C + e^{At} C (1 - e^{-At}) = C \exp(At)$$

7.1. Find the generator of the following Itô diffusions:

- a)  $dX_t = \mu X_t dt + \sigma dB_t$  (The Ornstein-Uhlenbeck process) ( $B_t \in \mathbf{R}$ ;  $\mu, \sigma$  constants).

We'll use the formula

$$Af(x) = \sum_i \mu_i(x) \frac{\partial f}{\partial x_i} + \frac{1}{2} \sum_{i,j} (\sigma \sigma^T)_{i,j}(x) \frac{\partial^2 f}{\partial x_i \partial x_j}$$

$$\text{If } X_t = f(B_t), \quad Af(x) = \mu x f'(x) + \frac{1}{2} \sigma^2 f''(x)$$

- b)  $dX_t = r X_t dt + \alpha X_t dB_t$  (The geometric Brownian motion) ( $B_t \in \mathbf{R}$ ;  $r, \alpha$  constants).

$$Af(x) = r x f'(x) + \frac{1}{2} (\alpha x)^2 f''(x)$$

- c)  $dY_t = r dt + \alpha Y_t dB_t$  ( $B_t \in \mathbf{R}$ ;  $r, \alpha$  constants)

$$Af(x) = r f'(x) + \frac{1}{2} (\alpha x)^2 f''(x)$$

- d)  $dY_t = \begin{bmatrix} dt \\ dX_t \end{bmatrix}$  where  $X_t$  is as in a)

$$Af(x) = \frac{\partial f}{\partial x_1} + \mu x \frac{\partial f}{\partial x_2} + \frac{1}{2} \sigma^2 \frac{\partial^2 f}{\partial x_2^2}$$

- e)  $\begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \begin{bmatrix} 1 \\ X_2 \end{bmatrix} dt + \begin{bmatrix} 0 \\ e^{X_1} \end{bmatrix} dB_t \quad (B_t \in \mathbf{R})$

$$Af(x) = \frac{\partial f}{\partial x_1} + x_2 \frac{\partial f}{\partial x_2} + \frac{1}{2} e^{2x_1} \frac{\partial^2 f}{\partial x_2^2}$$

$$f) \quad \begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} dt + \begin{bmatrix} 1 & 0 \\ 0 & X_1 \end{bmatrix} \begin{bmatrix} dB_1 \\ dB_2 \end{bmatrix}$$

$$\Delta f(x) = \frac{\partial^2 f}{\partial x_1^2} + \frac{1}{2} \left( \frac{\partial^2 f}{\partial x_1^2} + x_1^2 \frac{\partial^2 f}{\partial x_2^2} \right)$$

g)  $\tilde{X}(t) = (\tilde{X}_1, \tilde{X}_2, \dots, \tilde{X}_n)$ , where

$$dX_k(t) = r_k X_k dt + X_k \cdot \sum_{j=1}^n \alpha_{kj} dB_j ; \quad 1 \leq k \leq n$$

(( $B_1, \dots, B_n$ ) is Brownian motion in  $\mathbf{R}^n$ ,  $r_k$  and  $\alpha_{kj}$  are constants).

$$\Delta f(x) = \sum_{i=1}^n r_i x_i \frac{\partial^2 f}{\partial x_i^2} + \frac{1}{2} \sum_{i,j=1}^n x_i x_j \left( \sum_{k=1}^n \alpha_{ik} \alpha_{jk} \right) \frac{\partial^2 f}{\partial x_i \partial x_j}$$

- 7.2. Find an Itô diffusion (i.e. write down the stochastic differential equation for it) whose generator is the following:

- $Af(x) = f'(x) + f''(x); f \in C_0^2(\mathbf{R})$
- $Af(t, x) = \frac{\partial f}{\partial t} + cx \frac{\partial f}{\partial x} + \frac{1}{2}\alpha^2 x^2 \frac{\partial^2 f}{\partial x^2}; f \in C_0^2(\mathbf{R}^2)$ , where  $c, \alpha$  are constants.
- $Af(x_1, x_2) = 2x_2 \frac{\partial f}{\partial x_1} + \ln(1 + x_1^2 + x_2^2) \frac{\partial f}{\partial x_2}$   
 $+ \frac{1}{2}(1 + x_1^2) \frac{\partial^2 f}{\partial x_1^2} + x_1 \frac{\partial^2 f}{\partial x_1 \partial x_2} + \frac{1}{2} \cdot \frac{\partial^2 f}{\partial x_2^2}; f \in C_0^2(\mathbf{R}^2).$

a) Let  $f(B_t) = X_t$ . Then

$$dX_t = dt + \sqrt{2} dB_t$$

b)

$$\begin{bmatrix} dX_1(t) \\ dX_2(t) \end{bmatrix} = \begin{bmatrix} 1 \\ cX_2(t) \end{bmatrix} dt + \begin{bmatrix} 0 \\ \alpha X_2(t) \end{bmatrix} dB_t$$

c) Start by noticing that

$$\sigma^\top = \begin{bmatrix} 1 + X_1^2(t) & X_1(t) \\ X_1(t) & 1 \end{bmatrix}$$

To find  $\sigma$ , we compute

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} a & c \\ b & d \end{bmatrix} \Rightarrow \begin{cases} a^2 + b^2 = 1 + X_1^2(t) \\ ac + bd = X_1(t) \\ c^2 + d^2 = 1 \end{cases}$$

Take  $a = X_1(t)$ ,  $b = c = 1$  and  $d = 0$ , i.e.,  $\sigma = \begin{bmatrix} X_1(t) & 1 \\ 1 & 0 \end{bmatrix}$

Then, an Itô diffusion for the generator is

$$\begin{bmatrix} dX_1(t) \\ dX_2(t) \end{bmatrix} = \begin{bmatrix} 2X_2(t) \\ \ln(1 + X_1^2(t) + X_2^2(t)) \end{bmatrix} dt + \begin{bmatrix} X_1(t) & 1 \\ 1 & 0 \end{bmatrix} dB_t$$

7.3. Let  $B_t$  be Brownian motion on  $\mathbf{R}$ ,  $B_0 = 0$  and define

$$X_t = X_t^x = x \cdot e^{ct + \alpha B_t},$$

where  $c, \alpha$  are constants. Prove directly from the definition that  $X_t$  is a Markov process.

Denote the  $\sigma$ -algebra generated by the B.M. as  $\mathcal{F}_t$ .

Start by noticing that

$$\begin{aligned} \mathbb{E}^x[X_{t+h} | \mathcal{F}_t] &= \mathbb{E}^x[x e^{c(t+h) + \alpha B_{t+h}} | \mathcal{F}_t] \\ &= \mathbb{E}^{\mathcal{B}_t}[x e^{c(t+h) + \alpha B_h}] \end{aligned}$$

Therefore, we can write

$$\begin{aligned} \mathbb{E}^x[X_{t+h} | X_t] &= \mathbb{E}^x[\mathbb{E}^x[\mathbb{E}^{\mathcal{B}_t}[x e^{c(t+h) + \alpha B_h}] | \mathcal{F}_t] | X_t] \\ &= \mathbb{E}^x[\mathbb{E}^{\mathcal{B}_t}[x e^{c(t+h) + \alpha B_h}] | X_t] \\ &= \mathbb{E}^{\mathcal{B}_t}[x e^{c(t+h) + \alpha B_h}] \\ &= \mathbb{E}^x[X_{t+h} | \mathcal{F}_t] \end{aligned}$$

7.4. Let  $B_t^x$  be 1-dimensional Brownian motion starting at  $x \in \mathbf{R}^+$ . Put

$$\tau = \inf\{t > 0; B_t^x = 0\}.$$

- a) Prove that  $\tau < \infty$  a.s.  $P^x$  for all  $x > 0$ . (Hint: See Example 7.4.2, second part).
- b) Prove that  $E^x[\tau] = \infty$  for all  $x > 0$ . (Hint: See Example 7.4.2, first part).

o) Let  $K > x$  and define the stopping times

$$\bar{\tau}_0 = \bar{\tau} \quad \text{and} \quad \bar{\tau}_K = \inf\{t > 0 : B_t = K\},$$

Also let  $T_K = \tau_0 \wedge \bar{\tau}_K$ .

Since the Brownian motion has continuous paths,

$$\lim_{K \rightarrow \infty} \bar{\tau}_K = +\infty$$

and note that

$$E^x[B_{T_K}] = E^x[B_0] = x$$

Then,

$$x = E^x[B_{T_K}] = 0 \cdot P^x[\tau_0 < \bar{\tau}_K] + K P^x[\tau_0 > \bar{\tau}_K]$$

Rewriting

$$P^x[\tau_0 < \bar{\tau}_K] = 1 - P^x[\tau_0 > \bar{\tau}_K] = 1 - \frac{x}{K}$$

i.e.,

$$P^x[\tau_0 < \infty] = \lim_{K \rightarrow \infty} P^x[\tau_0 < \bar{\tau}_K] = 1$$

b) Let  $f(x) = x^2$ . By Itô's formula,

$$B_t^2 = 0 + 2 \int_0^t B_s dB_s + \int_0^t ds$$

Thus,

$$\mathbb{E}[B_{t \wedge \gamma_k}^2] = \mathbb{E}[t \wedge \gamma_k]$$

Now notice that

$$\begin{aligned}\mathbb{E}[\tau_0] &= \lim_{k \rightarrow \infty} \mathbb{E}[\gamma_k] \\ &= \lim_{k \rightarrow \infty} \mathbb{E}[B_{\gamma_k}^2] \\ &= \lim_{k \rightarrow \infty} b^2 P[\tau_0 > \tau_k] \\ &= \lim_{k \rightarrow \infty} K^2 \frac{x}{k} = \infty\end{aligned}$$

- 7.5. Let the functions  $b, \sigma$  satisfy condition (5.2.1) of Theorem 5.2.1, with a constant  $C$  independent of  $t$ , i.e.

$$|b(t, x)| + |\sigma(t, x)| \leq C(1 + |x|) \quad \text{for all } x \in \mathbf{R}^n \text{ and all } t \geq 0.$$

Let  $X_t$  be a solution of

$$dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t.$$

Show that

$$E[|X_t|^2] \leq (1 + E[|X_0|^2])e^{Kt} - 1$$

for some constant  $K$  independent of  $t$ .

(Hint: Use Dynkin's formula with  $f(x) = |x|^2$  and  $\tau = t \wedge \tau_R$ , where  $\tau_R = \inf\{t > 0; |X_t| \geq R\}$ , and let  $R \rightarrow \infty$  to achieve the inequality

$$E[|X_t|^2] \leq E[|X_0|^2] + K \cdot \int_0^t (1 + E[|X_s|^2])ds,$$

which is of the form (5.2.9).)

Let  $\tau_R = \inf\{t > 0 : |X_t| \geq R\}$  and  $\tau = \min\{t, \tau_R\}$ .

By Dynkin's formula applied to  $f(x) = |x|^2$ ,

$$E[|X_\tau|^2] = E[|X_0|^2] + E\left[\int_0^\tau A|X_s|^2 ds\right] \quad (1)$$

Using the following fact

$$A|X_0|^2 \leq K(1 + |X_0|^2) \quad (\times)$$

then

$$E\left[\int_0^\tau A|X_s|^2 ds\right] \leq E\left[\int_0^\tau K(1 + |X_s|^2) ds\right]$$

$$= K E\left[\int_0^\tau (1 + |X_s|^2) ds\right]$$

$$= K \int_0^\tau (1 + E[|X_s|^2]) ds \quad (3)$$

By (1) and (3),

$$\mathbb{E}[|X_\tau|^2] \leq \mathbb{E}[|X_0|^2] + K \int_0^\tau (1 + \mathbb{E}[|X_s|^2]) ds$$

To use the Gronwall inequality, write

$$1 + \mathbb{E}[|X_\tau|^2] \leq 1 + \mathbb{E}[|X_0|^2] + K \int_0^\tau (1 + \mathbb{E}[|X_s|^2]) ds$$

Thus,

$$\mathbb{E}[|X_\tau|^2] \leq (1 + \mathbb{E}[|X_0|^2]) e^{K\tau} - 1$$

□

Proof of (\*):

Start by writing

$$A_f(x) = 2 \sum_{i=1}^n b_i(+, x) x_i + \sum_{i=1}^n \sigma_i^2(+, x)$$

Since

$$2 \sum_{i=1}^n b_i(+, x) x_i \leq \sum_{i=1}^n |b_i|^2 + \sum_{i=1}^n |x_i|^2 = |b|^2 + |x|^2$$

we obtain

$$A_f(x) \leq |b|^2 + |x|^2 + |\sigma|^2$$

By the conditions (5.2.1),

$$\begin{aligned} A_f(x) &\leq C^2(1+|x|)^2 + |x|^2 = C^2(1+2|x|+|x|^2) + |x|^2 \\ &= C^2 + 2C^2|x| + (C^2+1)|x|^2 \end{aligned}$$

Since  $(|x|+1)^2 = |x|^2 + 1 + 2|x|$ , we have  $2C^2|x| \leq C^2|x|^2 + C^2$ .

Thus,

$$\begin{aligned} A_f(x) &\leq 2C^2 + (2C^2+1)|x|^2 \\ &\leq K(1+|x|^2) \end{aligned}$$

by taking  $K > (2C^2+1)$ .

7.6. Let  $g(x, \omega) = f \circ F(x, t, t+h, \omega)$  be as in the proof of Theorem 7.1.2.

Assume that  $f$  is continuous.

- a) Prove that the map  $x \rightarrow g(x, \cdot)$  is continuous from  $\mathbf{R}^n$  into  $L^2(P)$  by using (5.2.9).

Recall that

$$F(x, t, r, \omega) = X_r^{t,x}(\omega) \quad \text{for } r \geq t,$$

We want to show that

$$\lim_{h \rightarrow 0} \mathbb{E}[|g(x+h, \cdot) - g(x, \cdot)|^2] = 0$$

Since  $f$  is continuous, our task is simplified. What needs to be proved is that

$$\lim_{s \rightarrow 0} \mathbb{E}[|F(x+s, t, t+h, \omega) - F(x, t, t+h, \omega)|^2] = 0$$

Now remember that

So the function

$$v(t) = E[|X_t - \hat{X}_t|^2]; \quad 0 \leq t \leq T$$

satisfies

$$v(t) \leq F + A \int_0^t v(s) ds, \quad (5.2.9)$$

where  $F = 3E[|Z - \hat{Z}|^2]$  and  $A = 3(1+T)D^2$ .

Let

$$g(t) = \mathbb{E}[|F(x+s, t, t+h, \omega) - F(x, t, t+h, \omega)|^2]$$

By Gronwall inequality,

$$g(t) \leq F \exp(At)$$

Notice that

$$Z - \hat{Z} = (x+s) - x = s$$

thus

$$\lim_{s \rightarrow 0} F = \lim_{s \rightarrow 0} 3s^2 = 0$$

Since  $\exp(At) < \infty$ , it follows that  $\lim_{s \rightarrow 0} \phi(t) = 0$ , i.e.,

$$\lim_{s \rightarrow 0} \mathbb{E}[|F(x+s, t, t+h, \omega) - F(x, t, t+h, \omega)|^2] = 0$$

□

For simplicity assume that  $n = 1$  in the following.

- b) Use a) to prove that  $(x, \omega) \mapsto g(x, \omega)$  is measurable. (Hint: For each  $m = 1, 2, \dots$  put  $\xi_k = \xi_k^{(m)} = k \cdot 2^{-m}$ ,  $k = 1, 2, \dots$ . Then

$$g^{(m)}(x, \cdot) := \sum_k g(\xi_k, \cdot) \cdot \chi_{\{\xi_k \leq x < \xi_{k+1}\}}$$

converges to  $g(x, \cdot)$  in  $L^2(P)$  for each  $x$ . Deduce that  $g^{(m)} \rightarrow g$  in  $L^2(dm_R \times dP)$  for all  $R$ , where  $dm_R$  is Lebesgue measure on  $\{|x| \leq R\}$ . So a subsequence of  $g^{(m)}(x, \omega)$  converges to  $g(x, \omega)$  for a.a.  $(x, \omega)$ .)

By the hint and the previous item,  $g^m(x, \cdot) \rightarrow g(x, \cdot)$  in  $L^2(P)$ .

Since the function is bounded and composition of continuous and measurable functions is measurable, the result follows.

□

- 7.7. Let  $B_t$  be Brownian motion on  $\mathbf{R}^n$  starting at  $x \in \mathbf{R}^n$  and let  $D \subset \mathbf{R}^n$  be an open ball centered at  $x$ .
- Use Exercise 2.15 to prove that the harmonic measure  $\mu_D^x$  of  $B_t$  is rotation invariant (about  $x$ ) on the sphere  $\partial D$ . Conclude that  $\mu_D^x$  coincides with normalized surface measure  $\sigma$  on  $\partial D$ .
  - Let  $\phi$  be a bounded measurable function on a bounded open set  $W \subset \mathbf{R}^n$  and define

$$u(x) = E^x[\phi(B_{\tau_W})] \quad \text{for } x \in W.$$

Prove that  $u$  satisfies the classical mean value property:

$$u(x) = \int_{\partial D} u(y) d\sigma(y)$$

for all balls  $D$  centered at  $x$  with  $\bar{D} \subset W$ .

a) First we want to show that

**Definition 6.2.6 (Harmonic Measure).** The **harmonic measure** of  $X$  on  $\partial G$ , denoted by  $\mu_G^x$ , is defined as

$$\mu_G^x(F) = Q^x[X_{\tau_G} \in F], \quad \text{for } F \subset \partial G, x \in G$$

$$\mu_D^x(UF) = \mu_D^x(F)$$

where  $U$  is a rotation (i.e., orthogonal matrix on  $\mathbf{R}^{n \times n}$ ).

By the exercise 2.15,

- 2.15. Let  $B_t$  be  $n$ -dimensional Brownian motion starting at 0 and let  $U \in \mathbf{R}^{n \times n}$  be a (constant) orthogonal matrix, i.e.  $UU^T = I$ . Prove that

$$\tilde{B}_t := UB_t$$

is also a Brownian motion.

it follows that

$$\begin{aligned} Q^x[B_{\tau_D} \in F] &= Q^x[U B_{\tau_D} \in UF] \\ &= Q^x[\tilde{B}_{\tau_D} \in UF] \\ &= Q^x[B_{\tau_D} \in UF] \end{aligned}$$

Hence,  $\mu_D^x(UF) = \mu_D^x(F)$ .

To show that  $\mu_D^x = \sigma$  on  $\partial D$ , notice that

$$\begin{aligned} \int_{\partial D} f(x) d\sigma(x) &= \int_{S(\partial D)} \int_{\partial D} f(gx) d\sigma(x) d\sigma(g) && \text{where } \sigma \text{ is left-inv.} \\ &= \int_{\partial D} \int_{S(\partial D)} f(gx) d\sigma(g) d\sigma(x) && \text{measure on } S(\partial D) \\ &= \int_{\partial D} \int_{\partial D} f(y) d\mu_D^x(y) d\sigma(x) && \text{by Fubini's thm.} \\ &= \int_{\partial D} f(y) d\mu_D^x(y) && \text{since } \mu_D^x \text{ is} \\ &&& \text{rot. invariant} \\ &&& \text{since } \sigma \text{ is a} \\ &&& \text{normalized surf. meas.} \end{aligned}$$

Since  $f$  is arbitrary,  $\sigma = \mu_D^x$  on  $\partial D$  as desired.

b) We know that

$$\mathbb{E}^X[f(X_{\tau_H})] = \mathbb{E}^X[\mathbb{E}^{X_{\tau_H}}[f(X_{\tau_H})]] = \int_{\partial G} \mathbb{E}^y[f(X_{\tau_H})] Q^x[X_{\tau_H} \in dy]$$

for  $x \in G$ .

Plus the fact that  $\sigma = \mu_D^x$  on  $\partial D$ , it follows that

$$v(x) = \mathbb{E}^x[\varphi(B_{\tau_\omega})] = \int_{\partial D} \mathbb{E}^y[\varphi(B_{\tau_\omega})] \mu_D^x(dy)$$

$$= \int_{\partial D} v(y) d\mu_D^x(y) = \int_{\partial D} v(y) d\sigma(y)$$

□

- 7.8. Let  $\{\mathcal{N}_t\}$  be a right-continuous family of  $\sigma$ -algebras of subsets of  $\Omega$ , containing all sets of measure zero.

- a) Let  $\tau_1, \tau_2$  be stopping times (w.r.t.  $\mathcal{N}_t$ ). Prove that  $\tau_1 \wedge \tau_2$  and  $\tau_1 \vee \tau_2$  are stopping times.

$$\begin{aligned}
 & \cdot \{ \tau_1 \wedge \tau_2 \leq t \} = \{ \omega : \tau_1(\omega) \leq t \text{ and } \tau_2(\omega) \leq t \} \\
 &= \{ \omega : \tau_1(\omega) \leq t \text{ or } \tau_2(\omega) \leq t \} \\
 &= \{ \omega : \tau_1(\omega) \leq t \} \cup \{ \omega : \tau_2(\omega) \leq t \} \\
 &= \{ \tau_1 \leq t \} \cup \{ \tau_2 \leq t \} \in \mathcal{N}_t \\
 & \cdot \{ \tau_1 \vee \tau_2 \leq t \} = \{ \omega : \tau_1(\omega) \leq t \text{ and } \tau_2(\omega) \leq t \} \\
 &= \{ \omega : \tau_1(\omega) \leq t \} \cap \{ \omega : \tau_2(\omega) \leq t \} \\
 &= \{ \tau_1 \leq t \} \cap \{ \tau_2 \leq t \} \in \mathcal{N}_t
 \end{aligned}$$

- b) If  $\{\tau_n\}$  is a decreasing family of stopping times prove that  $\tau := \lim_n \tau_n$  is a stopping time.

We need to show that  $\{\tau \leq t\} \in \mathcal{N}_t$ . In fact, since  $\{\tau_n\}$  is decreasing

$$\{\tau \leq t\} = \bigcap_n \{\tau_n \leq t\} = \bigcap_n \{\tau_n > t\}^c = \left( \bigcup_n \{\tau_n > t\} \right)^c \in \mathcal{N}_t$$

Since  $\{\tau_n \leq t\} \in \mathcal{N}_t$  implies that  $\{\tau_n \leq t\}^c = \{\tau_n > t\} \in \mathcal{N}_t$ .

- c) If  $X_t$  is an Itô diffusion in  $\mathbf{R}^n$  and  $F \subset \mathbf{R}^n$  is closed, prove that  $\tau_F$  is a stopping time w.r.t.  $\mathcal{M}_t$ . (Hint: Consider open sets decreasing to  $F$ ).

Let  $\{F_n\}$  be a family of open sets decreasing to  $F$ . Now we define  $\{\tau_{F_n}\}$  as the family of stopping times given by

$$\{\tau_{F_n}\} = \inf \{t > 0 : X_t \notin F_n\}$$

Since each  $F_n$  is open, by the Example 7.2.2, each  $\tau_{F_n}$  is a stopping time w.r.t.  $\mathcal{M}_t$ . By the previous item, its limit  $\tau_F$  is a stopping time w.r.t.  $\mathcal{M}_t$ .

7.9. Let  $X_t$  be a geometric Brownian motion, i.e.

$$dX_t = rX_t dt + \alpha X_t dB_t, \quad X_0 = x > 0$$

where  $B_t \in \mathbf{R}$ ;  $r, \alpha$  are constants.

- a) Find the generator  $A$  of  $X_t$  and compute  $Af(x)$  when  $f(x) = x^\gamma$ ;  
 $x > 0$ ,  $\gamma$  constant.

The generator is given by

$$A = r \times \frac{\partial}{\partial x} + \frac{1}{2} \alpha^2 x^2 \frac{\partial^2}{\partial x^2}$$

Thus,

$$Af(x) = r \times \gamma x^{\gamma-1} + \frac{1}{2} \alpha^2 x^2 \gamma(\gamma-1) x^{\gamma-2}$$

$$= \left( r\gamma + \frac{1}{2} \alpha^2 \gamma(\gamma-1) \right) x^\gamma$$

- b) If  $r < \frac{1}{2}\alpha^2$  then  $X_t \rightarrow 0$  as  $t \rightarrow \infty$ , a.s.  $Q^x$  (Example 5.1.1).  
 But what is the probability  $p$  that  $X_t$ , when starting from  $x < R$ , ever hits the value  $R$ ? Use Dynkin's formula with  $f(x) = x^{\gamma_1}$ ,  $\gamma_1 = 1 - \frac{2r}{\alpha^2}$ , to prove that

$$p = \left( \frac{x}{R} \right)^{\gamma_1}.$$

First step: define the stopping time.

Take  $0 < K < x < R$  and define

- $\tau_R = \inf \{ t > 0 : X_t = R \}$

- $\tau = \min \{ K, \tau_R \}$

Second step: apply Dynkin's formula.

Notice that  $f \in C_0^2$  and  $\tau$  is a stopping time with finite expected value. Then,

$$\mathbb{E}^x[f(X_\tau)] = f(x) + \mathbb{E}^x\left[\int_0^\tau Af(X_s)ds\right]$$

$$= x^{\alpha_1} + \mathbb{E}^x\left[\int_0^\tau \left(r\alpha_1 + \frac{1}{2}\alpha^2\alpha_1(\alpha_{i-1})\right)X_s^{\alpha_1}ds\right]$$

$$= x^{\alpha_1} + \underbrace{\mathbb{E}^x\left[\int_0^\tau \left(r + \frac{1}{2}\alpha^2 \left(-\frac{2r}{\alpha^2}\right)\right) \left(1 - \frac{2r}{\alpha^2}\right) X_s^{1-2r/\alpha^2} ds\right]}_{=0}$$

Hence,

$$\mathbb{E}^x[f(X_\tau)] = f(x)$$

Third step: compute the expected value

Since  $\lim \tau < \infty$ , by taking  $K \rightarrow \infty$ ,

$$\mathbb{E}^x[f(X_{\tau_K})] = f(x)$$

And notice that  $X_\tau \in \{K, R\}$ . Define

$$p = P[X_\tau = R] \text{ and } 1-p = P[X_\tau = K]$$

Then

$$\begin{aligned} \mathbb{E}^x[f(X_T)] &= f(x) = p f(R) + (1-p) f(K) \\ \Leftrightarrow x^{1-2r/\alpha^2} &= p R^{1-2r/\alpha^2} + (1-p) K^{1-2r/\alpha^2} \end{aligned} \quad (*)$$

Taking the limit and noticing that  $\gamma_1 > 0$ ,

$$\lim_{K \downarrow 0} \mathbb{E}^x[f(X_T)] = p R^{1-2r/\alpha^2} = x^{1-2r/\alpha^2}$$

and thus

$$p = \left( \frac{x}{R} \right)^{\gamma_1}$$

c) If  $r > \frac{1}{2}\alpha^2$  then  $X_t \rightarrow \infty$  as  $t \rightarrow \infty$ , a.s.  $Q^x$ . Put

$$\tau = \inf\{t > 0; X_t \geq R\}.$$

Use Dynkin's formula with  $f(x) = \ln x$ ,  $x > 0$  to prove that

$$E^x[\tau] = \frac{\ln \frac{R}{x}}{r - \frac{1}{2}\alpha^2}.$$

(Hint: First consider exit times from  $(\rho, R)$ ,  $\rho > 0$  and then let  $\rho \rightarrow 0$ . You need estimates for

$$(1 - p(\rho)) \ln \rho,$$

where

$$p(\rho) = Q^x[X_t \text{ reaches the value } R \text{ before } \rho],$$

which you can get from the calculations in a), b.).)

By Dynkin's formula for  $f(x) = \ln x$

$$\mathbb{E}^x[f(X_T)] = f(x) + \mathbb{E}^x \left[ \int_0^T A f(X_s) ds \right]$$

Given that

$$Af(x) = r - \frac{1}{2}x^2$$

we have

$$\begin{aligned} \mathbb{E}^x[f(X_\tau)] &= f(x) + \mathbb{E}^x \left[ \int_0^\tau \left( r - \frac{1}{2}x^2 \right) ds \right] \\ &= \ln x + \left( r - \frac{1}{2}x^2 \right) \mathbb{E}^x[\tau] \end{aligned}$$

Then

$$\mathbb{E}^x[\tau] = \frac{\mathbb{E}^x[f(X_\tau)] - \ln x}{r - x^2/2}$$

and using the given  $p(\rho)$ ,

$$\mathbb{E}^x[\tau] = \frac{p(\rho)f(R) + (1-p(\rho))f(\rho) - \ln x}{r - x^2/2} \quad (**)$$

Taking  $(*)$  with  $K = \rho$ ,

$$x^{\gamma_1} = pR^{\gamma_1} + (1-p)\rho^{\gamma_1} \Leftrightarrow p = \frac{x^{\gamma_1} - \rho^{\gamma_1}}{R^{\gamma_1} - \rho^{\gamma_1}} = \frac{\frac{1}{x^{\gamma_1}} - \frac{1}{\rho^{\gamma_1}}}{\frac{1}{R^{\gamma_1}} - \frac{1}{\rho^{\gamma_1}}} = \frac{\frac{\rho^{-\gamma_1} - x^{-\gamma_1}}{x^{\gamma_1}\rho^{\gamma_1}}}{\frac{\rho^{-\gamma_1} - R^{-\gamma_1}}{R^{\gamma_1}\rho^{\gamma_1}}}$$

Thus,

$$p = \frac{\left( \frac{-\gamma_1}{x^{\gamma_1}} - \frac{-\gamma_1}{\rho^{\gamma_1}} \right)}{\left( \frac{-\gamma_1}{x^{\gamma_1}} - \frac{-\gamma_1}{R^{\gamma_1}} \right)} = \frac{R^{-\gamma_1} \left( \rho^{-\gamma_1} - x^{-\gamma_1} \right)}{x^{-\gamma_1} \left( \rho^{-\gamma_1} - R^{-\gamma_1} \right)}$$

Since  $r > \alpha^2/2$ ,  $\sigma_1 < 0$ ,

$$\lim_{\rho \rightarrow 0} p = 1 \quad \text{and} \quad \lim_{\rho \rightarrow 0} [(1-p(\rho)) \ln p] = 0$$

Plugging into (2):

$$E^x[\tau] = \frac{\ln R - \ln x}{r - \alpha^2/2} = \frac{\ln \frac{R}{x}}{r - \alpha^2/2}$$

□

7.10. Let  $X_t$  be the geometric Brownian motion

$$dX_t = rX_t dt + \alpha X_t dB_t.$$

Find  $E^x[X_T | \mathcal{F}_t]$  for  $t \leq T$  by  
a) using the Markov property

By the Markov property,

$$\mathbb{E}^x[X_T | \mathcal{F}_t] = \mathbb{E}^{X_t}[X_T]$$

Given that  $X_t$  is of the form

$$X_t = x + \int_0^t rX_s ds + \int_0^t \alpha X_s dB_s$$

applying the expectation operator gives

$$\mathbb{E}^x[X_t] = x + r \int_0^t \mathbb{E}^x[X_s] ds$$

Note that this function  $\mathbb{E}^x[X_t]$  evaluated at zero must return  $x$ . This inspires us to build the following initial value problem.

Let

$$f(t) = x + r \int_0^t \mathbb{E}^x[X_s] ds = x + r \int_0^t f(s) ds$$

then our problem is

$$f'(t) = rf(t), \text{ with } f(0) = x$$

with solution

$$\mathbb{E}^x[X_t] = f(t) = x e^{rt}$$

Thus,

$$\mathbb{E}^{X_+}[X_{T-}] = X_+ e^{r(T-t)}$$

and

b) writing  $X_t = x e^{rt} M_t$ , where

$$M_t = \exp(\alpha B_t - \frac{1}{2}\alpha^2 t) \quad \text{is a martingale.}$$

Notice that

$$\begin{aligned} \mathbb{E}^x[X_T | \mathcal{F}_+] &= \mathbb{E}^x[x e^{rT} M_T | \mathcal{F}_+] \\ &= x e^{rT} \mathbb{E}^x[M_T | \mathcal{F}_+] \\ &= x e^{rT} M_+ \\ &= x e^{rT} \frac{1}{x e^{rt}} X_+ \\ &= X_+ e^{r(T-t)} \end{aligned}$$

- 7.11. Let  $X_t$  be an Itô diffusion in  $\mathbf{R}^n$  and let  $f: \mathbf{R}^n \rightarrow \mathbf{R}$  be a function such that

$$E^x \left[ \int_0^\infty |f(X_t)| dt \right] < \infty \quad \text{for all } x \in \mathbf{R}^n.$$

Let  $\tau$  be a stopping time. Use the strong Markov property to prove that

$$E^x \left[ \int_\tau^\infty f(X_t) dt \right] = E^x[g(X_\tau)],$$

where

$$g(y) = E^y \left[ \int_0^\infty f(X_t) dt \right].$$

We begin using a change of variables

$$\int_\tau^\infty f(X_t) dt = \int_0^\infty f(X_{\tau+s}) ds$$

And notice that by the law of the iterated expectation,

$$E^x \left[ \int_0^\infty f(X_{\tau+s}) ds \right] = E^x \left[ E^x \left[ \int_0^\infty f(X_{\tau+s}) ds \mid \mathcal{F}_\tau \right] \right]$$

Then, using the Strong Markov Property,

$$\begin{aligned} E^x \left[ E^x \left[ \int_0^\infty f(X_{\tau+s}) ds \mid \mathcal{F}_\tau \right] \right] &= E^x \left[ E^{X_\tau} \left[ \int_0^\infty f(X_s) ds \right] \right] \\ &= E^x [g(X_\tau)] \end{aligned}$$

□

### 7.12. (Local martingales)

An  $\mathcal{N}_t$ -adapted stochastic process  $Z(t) \in \mathbf{R}^n$  is called a *local martingale* with respect to the given filtration  $\{\mathcal{N}_t\}$  if there exists an increasing sequence of  $\mathcal{N}_t$ -stopping times  $\tau_k$  such that

$$\tau_k \rightarrow \infty \quad \text{a.s. as } k \rightarrow \infty$$

and

$$Z(t \wedge \tau_k) \quad \text{is an } \mathcal{N}_t\text{-martingale for all } k.$$

- a) Show that if  $Z(t)$  is a local martingale and there exists a constant  $T \leq \infty$  such that the family  $\{Z(\tau)\}_{\tau \leq T}$  is uniformly integrable (Appendix C) then  $\{Z(t)\}_{t \leq T}$  is a martingale.

1.  $\{Z(t)\}_{t \leq T}$  is  $\mathcal{N}_t$ -adapted, i.e., is  $\mathcal{N}_t$ -measurable for all  $t$ .

2. We'll use the following result:

**Theorem C.4.** Suppose  $\{f_k\}_{k=1}^\infty$  is a sequence of real measurable functions on  $\Omega$  such that

$$\lim_{k \rightarrow \infty} f_k(\omega) = f(\omega) \quad \text{for a.a. } \omega.$$

Then the following are equivalent:

- 1)  $\{f_k\}$  is uniformly integrable
- 2)  $f \in L^1(P)$  and  $f_k \rightarrow f$  in  $L^1(P)$ , i.e.  $\int |f_k - f| dP \rightarrow 0$  as  $k \rightarrow \infty$ .

Since  $\{Z(\tau)\}_{\tau \leq T} = \{Z_\tau\}$  is uniformly integrable, and

$$\lim_{k \rightarrow \infty} Z_\tau = Z_+ \quad \text{since } \tau = t \wedge \tau_k$$

then  $Z_+ \in L^1(P)$  and  $\lim_{k \rightarrow \infty} \int |Z_\tau - Z_+| dP = 0$

$$\text{i.e., } \mathbb{E}[|Z_+|] < \infty$$

3. Since  $Z_{\tau_k \wedge t}$  is an  $\mathcal{N}_t$ -martingale, for  $s \leq t$ ,

$$\mathbb{E}^x[Z_{\tau_k \wedge t} | \mathcal{N}_s] = Z_{\tau_k + s} \xrightarrow{k \rightarrow \infty} Z_s$$

$$\text{Thus, } \mathbb{E}^x[Z_+ | \mathcal{N}_s] = \lim_{k \rightarrow \infty} \mathbb{E}^x[Z_{\tau_k \wedge t} | \mathcal{N}_s] = Z_s$$

- b) In particular, if  $Z(t)$  is a local martingale and there exists a constant  $K < \infty$  such that

$$E[Z^2(\tau)] \leq K$$

for all stopping times  $\tau \leq T$ , then  $\{Z(t)\}_{t \leq T}$  is a martingale.

Since  $Z_\varepsilon \rightarrow Z_+$  in  $L^1(P)$  and  $Z_+ \in L^1(P)$ ,  $\{Z_+\}$  is uniformly integrable.

By the previous item, the result follows.

- c) Show that if  $Z(t)$  is a lower bounded local martingale, then  $Z(t)$  is a supermartingale (Appendix C).

We already verified that  $Z(t)$  is  $N_t$ -adapted and  $E[Z(t)] < \infty$ . Now we need to show that

$$Z(s) \geq E[Z(+)|N_s], \quad t > s$$

Notice that, assuming  $Z_+ \geq 0$ ,

$$E[Z_+|N_s] \leq \lim_{\varepsilon \rightarrow 0} E[Z_\varepsilon|N_s] = E[Z_+|N_s] = Z_s$$

7.13. a) Let  $B_t \in \mathbf{R}^2$ ,  $B_0 = x \neq 0$ . Fix  $0 < \epsilon < R < \infty$  and define

$$X_t = \ln |B_{t \wedge \tau}| ; \quad t \geq 0$$

where

$$\tau = \inf \{t > 0; |B_t| \leq \epsilon \text{ or } |B_t| \geq R\} .$$

Prove that  $X_t$  is an  $\mathcal{F}_{t \wedge \tau}$ -martingale. (Hint: Use Exercise 4.8.)  
Deduce that  $\ln |B_t|$  is a local martingale (Exercise 7.12).

Let  $f(B_t) = \ln |B_t|$ . Then  $X_t = f(B_{t \wedge \tau})$ . Using that

$$f(B_t) = f(B_0) + \int_0^t \nabla f(B_s) dB_s + \frac{1}{2} \int_0^t \Delta f(B_s) ds ,$$

We have

$$\begin{aligned} f(B_t) &= f(B_0) + \int_0^t \left( \frac{(B_1(s), B_2(s))}{|B_s|^2} \right) dB_s \\ &\quad + \cancel{\frac{1}{2} \int_0^t \left( \frac{|B_s|^2 - 2B_1^2 + |B_s|^2 - 2B_2^2}{|B_s|^4} \right) ds} \circ \end{aligned}$$

Thus,

$$f(B_t) = f(B_0) + \int_0^t \frac{B_s}{|B_s|^2} dB_s$$

is a martingale and it follows that  $X_t$  is an  $\mathcal{F}_{t \wedge \tau}$ -martingale.

To show that  $\ln |B_t|$  is a local martingale, let

$$\tau_R = \inf \{t > 0 : |B_{t \wedge \tau}| \geq R\}$$

Since  $\tau_R \rightarrow \infty$  as  $R \rightarrow \infty$  and we already showed that  $\ln |B_{t \wedge \tau}|$  is a martingale, what remains to be proved is that

$$\tau_\varepsilon = \inf\{t > 0 : |B_t| \leq \varepsilon\}$$

satisfies  $\tau_\varepsilon \rightarrow \infty$  as  $\varepsilon \downarrow 0$ . i.e., we need to prove that

$$\lim_{\varepsilon \downarrow 0} P^*(\tau_\varepsilon < \infty) = \lim_{R \rightarrow \infty} \lim_{\varepsilon \downarrow 0} P^*(\tau_\varepsilon < \tau_R) = 0$$

Note that

$$\ln|x| = E^*[\ln|B_{\tau_\varepsilon \wedge \tau_R}|] = P^*(\tau_\varepsilon < \tau_R) \ln \varepsilon + P^*(\tau_\varepsilon > \tau_R) \ln R$$

Hence

$$\ln|x| = P^*(\tau_\varepsilon < \tau_R) \ln \varepsilon + (1 - P^*(\tau_\varepsilon < \tau_R)) \ln R$$

$$\Leftrightarrow P^*(\tau_\varepsilon < \tau_R) = \frac{\ln R - \ln|x|}{(\ln R - \ln \varepsilon)}$$

implies that

$$\lim_{R \rightarrow \infty} \lim_{\varepsilon \downarrow 0} P^*(\tau_\varepsilon < \tau_R) = 0$$

□

b) Let  $B_t \in \mathbf{R}^n$  for  $n \geq 3$ ,  $B_0 = x \neq 0$ . Fix  $\epsilon > 0$ ,  $R < \infty$  and define

$$Y_t = |B_{t \wedge \tau}|^{2-n}; \quad t \geq 0$$

where

$$\tau = \inf\{t > 0; |B_t| \leq \epsilon \text{ or } |B_t| \geq R\}.$$

Prove that  $Y_t$  is an  $\mathcal{F}_{t \wedge \tau}$ -martingale.

Deduce that  $|B_t|^{2-n}$  is a local martingale.

Define  $f(B_t) = |B_t|^{2-n}$ . Then

$$f(B_t) = f(B_0) + \int_0^t \nabla f(B_s) dB_s + \frac{1}{2} \int_0^t \Delta f(B_s) ds$$

$$= |x|^{2-n} + \int_0^t (2-n) \|B_s\|^{-n} B_s dB_s + \cancel{\frac{1}{2} \int_0^t \Delta f(B_s) ds}$$

Thus,

$$f(B_t) = |x|^{2-n} + \int_0^t (2-n) \|B_s\|^{-n} B_s dB_s$$

is a martingale and it follows that  $Y_t$  is an  $\mathcal{F}_{t \wedge \tau}$ -martingale.

To prove that  $|B_t|^{2-n}$  is a local martingale we use the same argument as before. Notice that

$$|x|^{2-n} = \mathbb{E}^x [|B_{t \wedge \tau}|^{2-n}] = P(\tau_\epsilon < \tau_R) |\epsilon|^{2-n} + P(\tau_\epsilon > \tau_R) |R|^{2-n}$$

i.e.,

$$|x|^{2-n} = P(\tau_\epsilon < \tau_R) \epsilon^{2-n} + (1 - P(\tau_\epsilon < \tau_R)) R^{2-n}$$

$$\Leftrightarrow P(\tau_\epsilon < \tau_R) = \frac{|R|^{2-n} - |x|^{2-n}}{(R^{2-n} - \epsilon^{2-n})} = \frac{1/R^{n-2} - 1/|x|^{n-2}}{1/R^{n-2} - 1/\epsilon^{n-2}} = \frac{\frac{|x|^{n-2} - R^{n-2}}{R^{n-2} |x|^{n-2}}}{\frac{\epsilon^{n-2} - R^{n-2}}{R^{n-2} \epsilon^{n-2}}}$$

$$= \frac{(|x|^{n-2} - R^{n-2})}{|x|^{n-2} R^{n-2}} \cdot \frac{R^{n-2} \epsilon^{n-2}}{(\epsilon^{n-2} - R^{n-2})} = \frac{\epsilon^{n-2}}{|x|^{n-2}} \frac{(|x|^{n-2} - R^{n-2})}{(\epsilon^{n-2} - R^{n-2})}$$

Therefore,

$$\lim_{\epsilon \downarrow 0} P^*(\bar{\tau}_\epsilon < \infty) = \lim_{R \rightarrow \infty} \lim_{\epsilon \downarrow 0} P^*(\bar{\tau}_\epsilon < \bar{\tau}_R) = 0$$

Thus,  $|B_t|^{2^{-n}}$  is a local martingale. □

$$\begin{aligned}
 \Delta f(B_s) &= \sum_i (2^{-n}) \left[ -_n \|B_s\|^{-n-2} B_i^2 + \|B_s\|^{-n} \right] \\
 &= \sum_i \frac{(2^{-n})}{\|B_s\|^n} \left[ -_n \|B_s\|^{-2} B_i^2 + 1 \right]
 \end{aligned}$$

7.14. (Doob's  $h$ -transform)

Let  $B_t$  be  $n$ -dimensional Brownian motion,  $D \subset \mathbf{R}^n$  a bounded open set and  $h > 0$  a harmonic function on  $D$  (i.e.  $\Delta h = 0$  in  $D$ ). Let  $X_t$  be the solution of the stochastic differential equation

$$dX_t = \nabla(\ln h)(X_t)dt + dB_t$$

More precisely, choose an increasing sequence  $\{D_k\}$  of open subsets of  $D$  such that  $\overline{D}_k \subset D$  and  $\bigcup_{k=1}^{\infty} D_k = D$ . Then for each  $k$  the equation above can be solved (strongly) for  $t < \tau_{D_k}$ . This gives in a natural way a solution for  $t < \tau := \lim_{k \rightarrow \infty} \tau_{D_k}$ .

a) Show that the generator  $A$  of  $X_t$  satisfies

$$Af = \frac{\Delta(hf)}{2h} \quad \text{for } f \in C_0^2(D).$$

In particular, if  $f = \frac{1}{h}$  then  $\mathcal{A}f = 0$ .

$$\begin{aligned} Af(x) &= \sum_i \mu_i(x) \frac{\partial f}{\partial x_i}(x) + \frac{1}{2} \sum_{i,j} (\sigma \sigma^\top)_{i,j}(x) \frac{\partial^2 f}{\partial x_i \partial x_j}(x) \\ &= \sum_i \frac{\partial(\ln h)}{\partial x_i}(x) \frac{\partial f}{\partial x_i}(x) + \frac{1}{2} \sum_i \frac{\partial^2 f}{\partial x_i^2}(x) \\ &= \sum_i \frac{1}{h} \frac{\partial h}{\partial x_i}(x) \frac{\partial f}{\partial x_i}(x) + \frac{1}{2} \Delta f(x) \\ &= \frac{1}{h} \nabla h(x) \nabla f(x) + \frac{1}{2} \Delta f(x) \\ &= \frac{2 \nabla h(x) \nabla f(x) + h \Delta f(x)}{2h} = \frac{\Delta(hf)}{2h} \end{aligned}$$

Obs:  $\Delta(hf) = f \Delta h + 2 \nabla h \nabla f + h \Delta f$

b) Use a) to show that if there exists  $x_0 \in \partial D$  such that

$$\lim_{x \rightarrow y \in \partial D} h(x) = \begin{cases} 0 & \text{if } y \neq x_0 \\ \infty & \text{if } y = x_0 \end{cases}$$

(i.e.  $h$  is a *kernel function*), then

$$\lim_{t \rightarrow \tau} X_t = x_0 \text{ a.s.}$$

(Hint: Consider  $E^x[f(X_T)]$  for suitable stopping times  $T$  and with  $f = \frac{1}{h}$ )

In other words, we have imposed a drift on  $B_t$  which causes the process to exit from  $D$  at the point  $x_0$  only. This can also be formulated as follows:  $X_t$  is obtained by *conditioning  $B_t$  to exit from  $D$  at  $x_0$* . See Doob (1984).

DRAFT

Define the stopping time

Let  $T_k = \inf \{t > 0 : X_t \notin D_k\}$  and notice that as  $k \rightarrow \infty$  we have that

$$T_k \rightarrow T = \inf \{t > 0 : X_t \notin D\} = \tau$$

More than that, by hypothesis,  $\lim_{k \rightarrow \infty} T_k < \infty$ .

Apply Dynkin's formula with  $f = 1/h$

$$E^x \left[ f(X_\tau) \right] = f(x) + E^x \left[ \int_0^\tau A f(s) ds \right] = f(x)$$

Open the expected value:

$$f(x) = P[X_\tau \in D] f(x) + (1 - P[X_\tau \in D]) f(y)$$

$$P[X_\tau \in D] = \frac{f(x) - f(y)}{f(x) - f(y)} \xrightarrow{x \rightarrow y} 1 \text{ since } f(y) = 1/h(y)$$

7.15. Let  $B_t$  be 1-dimensional and define

$$F(\omega) = (B_T(\omega) - K)^+$$

where  $K > 0$ ,  $T > 0$  are constants.

By the Itô representation theorem (Theorem 4.3.3) we know that there exists  $\phi \in \mathcal{V}(0, T)$  such that

$$F(\omega) = E[F] + \int_0^T \phi(t, \omega) dB_t .$$

How do we find  $\phi$  explicitly? This problem is of interest in mathematical finance, where  $\phi$  may be regarded as the replicating portfolio for the contingent claim  $F$  (see Chapter 12). Using the Clark-Ocone formula (see Karatzas and Ocone (1991) or Øksendal (1996)) one can deduce that

$$\phi(t, \omega) = E[\chi_{[K, \infty)}(B_T) | \mathcal{F}_t] ; \quad t < T . \quad (7.5.3)$$

Use (7.5.3) and the Markov property of Brownian motion to prove that for  $t < T$  we have

$$\phi(t, \omega) = \frac{1}{\sqrt{2\pi(T-t)}} \int_K^\infty \exp\left(-\frac{(x - B_t(\omega))^2}{2(T-t)}\right) dx . \quad (7.5.4)$$

Recall the Markov Property:

**Theorem 6.2.1** (Markov Property for Itô Diffusions). Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be a bounded Borel function.

For  $t, h \geq 0$ ,

$$\mathbb{E}^x[f(X_{t+h}) | \mathfrak{F}_t^{(m)}]_{(\omega)} = \mathbb{E}^{X_t(\omega)}[f(X_h)] \quad (6.2)$$

where  $\mathbb{E}^x$  denotes the expected value w.r.t. the probability measure  $Q^x$ , i.e.,  $\mathbb{E}^x[f(X_h)] = [f(X_h^x)]$  w.r.t. the probability measure  $P^0$ .

Using it, for  $t < T$ , we have

$$\phi(t, \omega) = \mathbb{E}\left[\chi_{[K, \infty)}(B_T) | \mathcal{F}_t\right] = \mathbb{E}^{B_t} \left[\chi_{[K, \infty)}(B_{T-t})\right]$$

By the exercise 2.8.c.

$$E[f(B_t)] = \frac{1}{\sqrt{2\pi t}} \int_{\mathbb{R}} f(x) e^{-\frac{x^2}{2t}} dx$$

it follows that

$$\begin{aligned} \mathbb{E}^{B_t} \left[\chi_{[K, \infty)}(B_{T-t})\right] &= \frac{1}{\sqrt{2\pi(T-t)}} \int_{\mathbb{R}} \chi_{[K, \infty)}(x) \exp\left(-\frac{(x - B_t)^2}{2(T-t)}\right) dx \\ &= \frac{1}{\sqrt{2\pi(T-t)}} \int_K^\infty \exp\left(-\frac{(x - B_t)^2}{2(T-t)}\right) dx \end{aligned}$$

- 7.16.** Let  $B_t$  be 1-dimensional and let  $f: \mathbf{R} \rightarrow \mathbf{R}$  be a bounded function.  
 Prove that if  $t < T$  then

$$E^x[f(B_T) | \mathcal{F}_t] = \frac{1}{\sqrt{2\pi(T-t)}} \int_{\mathbf{R}} f(x) \exp\left(-\frac{(x - B_t(\omega))^2}{2(T-t)}\right) dx . \quad (7.5.5)$$

(Compare with (7.5.4).)

By the Markov property,

$$E^x[f(B_T) | \mathcal{F}_t] = E^{B_t} [f(B_{T-t})]$$

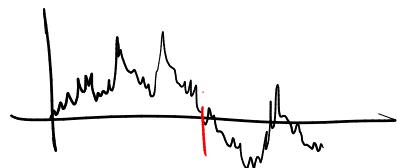
$$= \frac{1}{\sqrt{2\pi(T-t)}} \int_{\mathbf{R}} f(x) \exp\left(-\frac{(x - B_t)^2}{2(T-t)}\right) dx$$

7.17. Let  $B_t$  be 1-dimensional and put

$$X_t = (x^{1/3} + \frac{1}{3}B_t)^3 ; \quad t \geq 0 .$$

Then we have seen in Exercise 4.15 that  $X_t$  is a solution of the stochastic differential equation

$$dX_t = \frac{1}{3}X_t^{1/3}dt + X_t^{2/3}dB_t ; \quad X_0 = x . \quad (7.5.6)$$



Define

$$\tau = \inf\{t > 0; X_t = 0\}$$

and put

$$Y_t = \begin{cases} X_t & \text{for } t \leq \tau \\ 0 & \text{for } t > \tau . \end{cases}$$

Prove that  $Y_t$  is also a (strong) solution of (7.5.6). Why does not this contradict the uniqueness assertion of Theorem 5.2.1?

(Hint: Verify that

$$Y_t = x + \int_0^t \frac{1}{3}Y_s^{1/3}ds + \int_0^t Y_s^{2/3}dB_s$$

for all  $t$  by splitting the integrals as follows:

$$\int_0^t = \int_0^{t \wedge \tau} + \int_{t \wedge \tau}^t . )$$

We'll break into two pieces:  $t \leq \tau$  and  $t > \tau$ .

For  $t \leq \tau$ ,

$$Y_t = X_t = x + \int_0^t \frac{1}{3}X_s^{1/3}ds + \int_0^t X_s^{2/3}dB_s$$

For  $t > \tau$ ,

$$Y_t = X_\tau = x + \int_0^\tau \frac{1}{3}X_s^{1/3}ds + \int_0^\tau X_s^{2/3}dB_s$$

Now, for any  $t \geq 0$ ,

$$Y_t = x + \int_0^{t \wedge \tau} \frac{1}{3}Y_s^{1/3}ds + \int_0^{t \wedge \tau} Y_s^{2/3}dB_s + \int_{t \wedge \tau}^t \frac{1}{3}Y_s^{1/3}ds + \int_{t \wedge \tau}^t Y_s^{2/3}dB_s$$

$$= x + \int_0^t \frac{1}{3}Y_s^{1/3}ds + \int_0^t Y_s^{2/3}dB_s \Rightarrow Y_t \text{ is a strong solution}$$

Notice that the functions  $\frac{1}{3}x_+^{1/3}$  and  $x_+^{2/3}$  are not Lipschitz (their derivatives "explode" as  $x \rightarrow 0$ ). Hence, the conditions of the theorem aren't met.

7.18. a) Let

$$dX_t = b(X_t)dt + \sigma(X_t)dB_t ; \quad X_0 = x$$

be a 1-dimensional Itô diffusion with characteristic operator  $\mathcal{A}$ . Let  $f \in C^2(\mathbf{R})$  be a solution of the differential equation

$$\mathcal{A}f(x) = b(x)f'(x) + \frac{1}{2}\sigma^2(x)f''(x) = 0 ; \quad x \in \mathbf{R} . \quad (7.5.7)$$

Let  $(a, b) \subset \mathbf{R}$  be an open interval such that  $x \in (a, b)$  and put

$$\tau = \inf\{t > 0; X_t \notin (a, b)\} .$$

Assume that  $\tau < \infty$  a.s.  $Q^x$  and define

$$p = P^x[X_\tau = b] .$$

Use Dynkin's formula to prove that if  $f(b) \neq f(a)$  then

$$p = \frac{f(x) - f(a)}{f(b) - f(a)} . \quad (7.5.8)$$

In other words, the harmonic measure  $\mu_{(a,b)}^x$  of  $X$  on  $\partial(a, b) = \{a, b\}$  is given by

$$\mu_{(a,b)}^x(b) = \frac{f(x) - f(a)}{f(b) - f(a)} , \quad \mu_{(a,b)}^x(a) = \frac{f(b) - f(x)}{f(b) - f(a)} . \quad (7.5.9)$$

Since  $\mathcal{A}f(x) = 0$ , by Dynkin's formula,

$$\mathbb{E}[f(X_\tau)] = f(x)$$

Using the definition of  $P$ ,

$$pf(b) + (1-p)f(a) = f(x)$$

i.e.,

$$\frac{f(x) - f(a)}{f(b) - f(a)} = p \quad (*)$$

b) Now specialize to the process

$$X_t = x + B_t ; \quad t \geq 0 .$$

Prove that

$$p = \frac{x - a}{b - a} . \quad (7.5.10)$$

Notice that  $\mathcal{A}f(x) = \frac{1}{2}f''(x)$

Taking  $f(x) = x$ ,  $\mathcal{A}f(x) = 0$  and the result follows from (\*).

c) Find  $p$  if

$$X_t = x + \mu t + \sigma B_t ; \quad t \geq 0$$

where  $\mu, \sigma \in \mathbf{R}$  are nonzero constants.

Here,

$$Af(x) = \mu f'(x) + \frac{1}{2} \sigma^2 f''(x)$$

Solving the ODE  $Af(x)=0$ :

Characteristic equation:

$$\frac{1}{2} \sigma^2 \lambda^2 + \mu \lambda = 0 \iff \lambda \left( \frac{1}{2} \sigma^2 \lambda + \mu \right) = 0$$

$$\iff \lambda = 0 \text{ or } \frac{1}{2} \sigma^2 \lambda + \mu = 0 \iff \lambda = -\frac{2\mu}{\sigma^2}$$

Let  $f(x) = e^{-2\mu x / \sigma^2}$  and notice that, since

$$f'(x) = -\frac{2\mu}{\sigma^2} e^{-2\mu x / \sigma^2} \quad \text{and} \quad f''(x) = \frac{4\mu^2}{\sigma^4} e^{-2\mu x / \sigma^2}$$

$f(x)$  solves the ODE.

Using that,

$$P = \frac{f(x) - f(a)}{f(b) - f(a)} = \frac{e^{-2\mu x / \sigma^2} - e^{-2\mu a / \sigma^2}}{e^{-2\mu b / \sigma^2} - e^{-2\mu a / \sigma^2}}$$

7.19. Let  $B_t^x$  be 1-dimensional Brownian motion starting at  $x > 0$ . Define

$$\tau = \tau(x, \omega) = \inf\{t > 0; B_t^x(\omega) = 0\}.$$

From Exercise 7.4 we know that

$$\tau < \infty \text{ a.s. } P^x \text{ and } E^x[\tau] = \infty.$$

What is the distribution of the random variable  $\tau(\omega)$ ?

a) To answer this, first find the *Laplace transform*

$$g(\lambda) := E^x[e^{-\lambda\tau}] \quad \text{for } \lambda > 0.$$

(Hint: Let  $M_t = \exp(-\sqrt{2\lambda} B_t - \lambda t)$ . Then

$\{M_{t \wedge \tau}\}_{t \geq 0}$  is a bounded martingale.

[Solution:  $g(\lambda) = \exp(-\sqrt{2\lambda} x)$ .]

Notice that

$$E^x[M_+] = E^x[M_0] = e^{-\sqrt{2\lambda} x}$$

and

$$M_\tau = e^{-\sqrt{2\lambda} B_\tau} \cdot e^{-\lambda \tau} = e^{-\lambda \tau}$$

Thus

$$g(\lambda) = E^x[e^{-\lambda \tau}] = E^x[M_\tau] = E^x[M_0] = e^{-\sqrt{2\lambda} x}$$

- b) To find the density  $f(t)$  of  $\tau$  it suffices to find  $f(t) = f(t, x)$  such that

$$\int_0^\infty e^{-\lambda t} f(t) dt = \exp(-\sqrt{2\lambda} x) \quad \text{for all } \lambda > 0$$

i.e. to find the *inverse Laplace transform* of  $g(\lambda)$ . Verify that

$$f(t, x) = \frac{x}{\sqrt{2\pi t^3}} \exp\left(-\frac{x^2}{2t}\right); \quad t > 0.$$

Define  $g(\lambda, x) = \int_0^\infty e^{-\lambda t} f(t) dt$

and notice that it satisfies the ODE  $g'' = 2\lambda g$  with solution

$$c_1 e^{\sqrt{2\lambda} x} + c_2 e^{-\sqrt{2\lambda} x}$$

Showing that  $c_1 = 0$  and  $c_2 = 1$ , the result follows.