

(i)
$$X_t = e^{B_t}$$
 solves $dX_t = \frac{1}{2}X_t dt + X_t dB_t$

$$dX_{+} = e^{B_{+}}dB_{+} + Le^{B_{+}}dt = LX_{+}dt + X_{+}dB_{+}$$

(ii)
$$X_t = \frac{B_t}{1+t}$$
; $B_0 = 0$ solves

$$dX_t = -\frac{1}{1+t}X_tdt + \frac{1}{1+t}dB_t; X_0 = 0$$

$$\frac{dX_{+} = -B_{+}}{(1+1)^{2}} \frac{dX_{+}}{1+1} = -\frac{1}{1+1} \frac{X_{+} dX_{+}}{1+1} \frac{1}{1+1} \frac{dB_{+}}{1+1}$$

(iii)
$$X_t = \sin B_t$$
 with $B_0 = a \in (-\frac{\pi}{2}, \frac{\pi}{2})$ solves

$$dX_t = -\frac{1}{2}X_t dt + \sqrt{1 - X_t^2} dB_t \text{ for } t < \inf\left\{s > 0; B_s \notin \left[-\frac{\pi}{2}, \frac{\pi}{2}\right]\right\}$$

(iv)
$$(X_1(t), X_2(t)) = (t, e^t B_t)$$
 solves
$$\begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \begin{bmatrix} 1 \\ X_2 \end{bmatrix} dt + \begin{bmatrix} 0 \\ e^{X_1} \end{bmatrix} dB_t$$

$$\begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \begin{bmatrix} 1 \\ e^{\dagger}B_{+} \end{bmatrix} dI + \begin{bmatrix} 0 \\ e^{\dagger} \end{bmatrix} dB_{+} = \begin{bmatrix} 1 \\ X_2 \end{bmatrix} dI + \begin{bmatrix} 0 \\ e^{X_1} \end{bmatrix} dB_{+}$$

(v)
$$(X_1(t), X_2(t)) = (\cosh(B_t), \sinh(B_t))$$
 solves

$$\begin{bmatrix} dX_1 \\ dX_2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} dt + \begin{bmatrix} X_2 \\ X_1 \end{bmatrix} dB_t .$$