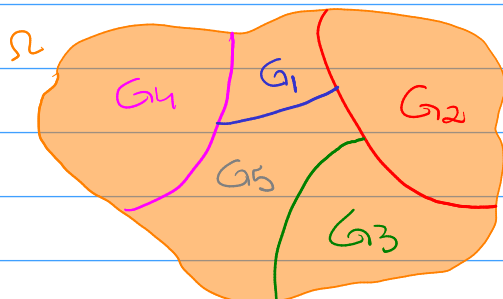


- 3.17. Let (Ω, \mathcal{F}, P) be a probability space and let $X: \Omega \rightarrow \mathbf{R}$ be a random variable with $E[|X|] < \infty$. If $\mathcal{G} \subset \mathcal{F}$ is a *finite* σ -algebra, then by Exercise 2.7 there exists a partition $\Omega = \bigcup_{i=1}^n G_i$ such that \mathcal{G} consists of \emptyset and unions of some (or all) of G_1, \dots, G_n .
- a) Explain why $E[X|\mathcal{G}](\omega)$ is constant on each G_i . (See Exercise 2.7 c).)



2.7. a) Suppose G_1, G_2, \dots, G_n are disjoint subsets of Ω such that

$$\Omega = \bigcup_{i=1}^n G_i.$$

Prove that the family \mathcal{G} consisting of \emptyset and all unions of some (or all) of G_1, \dots, G_n constitutes a σ -algebra on Ω .

b) Prove that any *finite* σ -algebra \mathcal{F} on Ω is of the type described in a).

c) Let \mathcal{F} be a *finite* σ -algebra on Ω and let $X: \Omega \rightarrow \mathbf{R}$ be \mathcal{F} -measurable. Prove that X assumes only finitely many possible values. More precisely, there exists a disjoint family of subsets $F_1, \dots, F_m \in \mathcal{F}$ and real numbers c_1, \dots, c_m such that

$$X(\omega) = \sum_{i=1}^m c_i \chi_{F_i}(\omega).$$

By the exercise 2.7, for $c_i \in \mathbf{R}$, $i=1, \dots, n$,

$$E[X|\mathcal{G}](\omega) = E\left[\underbrace{\sum_{i=1}^n c_i \chi_{G_i}(\omega)}_{\text{constant } C}\right] = E[C] = C$$

b) Assume that $P[G_i] > 0$. Show that

$$E[X|\mathcal{G}](\omega) = \frac{\int_{G_i} X dP}{P(G_i)} \quad \text{for } \omega \in G_i.$$

$$\int_H E[X|\mathcal{H}] dP = \int_H X dP, \text{ for all } H \in \mathcal{H}.$$

gives

$$\int_{G_i} E[X|\mathcal{G}] dP = \int_{G_i} X dP$$

however,

$$\int_{G_i} E[X|\mathcal{G}] dP = E[X|\mathcal{G}] \int_{G_i} dP = E[X|\mathcal{G}] P(G_i)$$

therefore,

$$E[X|\mathcal{G}] = \frac{\int_{G_i} X dP}{P(G_i)}$$

- c) Suppose X assumes only finitely many values a_1, \dots, a_m . Then from elementary probability theory we know that (see Exercise 2.1)

$$E[X|G_i] = \sum_{k=1}^m a_k P[X = a_k | G_i] .$$

Compare with b) and verify that

$$E[X|G_i] = E[X|\mathcal{G}](\omega) \quad \text{for } \omega \in G_i .$$

Thus we may regard the conditional expectation as defined in Appendix B as a (substantial) generalization of the conditional expectation in elementary probability theory.

Using the previous item,

$$\begin{aligned} E[X|G] &= \frac{\int_{G_i} X dP}{P(G_i)} = \frac{\int_{G_i} \sum_{k=1}^m a_k \chi_{a_k} dP}{P(G_i)} = \sum_{k=1}^m \frac{\int_{G_i} a_k \chi_{a_k} dP}{P(G_i)} \\ &= \sum_{k=1}^m a_k \frac{P(G_i \cap G_k)}{P(G_i)} = \sum_{k=1}^m a_k P[X = a_k | G_i] \end{aligned}$$

Alternative answer

b) Since

$$\mathbb{E}[f|A] = \int f d\mu_A, \quad \mu_A(B) = \frac{\mu(B \cap A)}{\mu(A)}$$

We have

$$\mathbb{E}\left[\sum_{i=1}^n c_i X_{G_i}(\omega) \mid G_i\right] = \int_{G_i} \frac{X dP(\omega)}{P(G_i)}$$

c) Given the definition of a_k , $k=1, \dots, m$,

$$\mathbb{E}[X|G_i] = \sum_{k=1}^m a_k P[X=a_k|G_i] = \int X dP_{G_i}$$

By the fact that

$$\mu_A(B) = \frac{\mu(B \cap A)}{\mu(A)}$$

we obtain

$$\mathbb{E}[X|G_i] = \int X dP_{G_i} = \int_{G_i} \frac{X dP}{P(G_i)} = \mathbb{E}[X|g]$$