

# Antonio Adaldo

Osquldas väg 10 – 10044 Stockholm – Sweden

☎ +46 (7) 266 2195 • ✉ [adaldo@kth.se](mailto:adaldo@kth.se) • 🌐 [people.kth.se/~adaldo](https://people.kth.se/~adaldo)  
in [antonio-adaldo-8458b863](#) • 🌐 [adaldo](#)

## Current Employment

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**PhD Student in Automatic Control, KTH:** 2014/2–2018/8

**Supervisors:** Karl H. Johansson, Dimos V. Dimarogonas

**Research topic:** Hybrid control of multi-agent systems

**Research Projects Involvement:** Horizon 2020 AEROWORKS, KTH Smart Mobility Lab, KTH Cluster for Underwater Technology, SSF COLMAN

## Education

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**MSc:** Automation Engineering, University of Naples, Dec 2013, with Honors

**BSc:** Automation Engineering, University of Naples, Sep 2011, with Honors

## Teaching Experience

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**T.A.:** *Hybrid and Embedded Control Systems*, KTH, 2017, with Dimos V. Dimarogonas

**T.A.:** *Automatic Control, Project Course* KTH, 2016, with Jonas Mantersson

**T.A.:** *Automatic Control, General Course*, KTH, 2015–2016, with Henrik Sandberg

**Supervisor:** Six MSc Thesis and one undergraduate summer project to date.

## Skillset

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**Theoretical expertise:** Hybrid systems, multi-agent systems, aerial robotics

**Working tools:** Python, ROS, Matlab/Simulink®, TeX, git

**Side tools:** HTML, CSS, Javascript, C/C++, Mathematica®, JuliaLang

## References

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Up to three reference letters available upon request.

A (small) part of my ROS projects are available through my *Github* page [github.com/adaldo](https://github.com/adaldo).

My papers are reachable through my webpage [people.kth.se/~adaldo](https://people.kth.se/~adaldo).

## Publications

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### Journal Papers

### Conference Papers

### Thesis

**Book Chapters**

**Under Review**

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**Journal Papers**

**Conference Papers**