

$A_n$ 

$n$  valores propios

$$Ax = \lambda x$$

$$\lambda > 0, \lambda < 0, \lambda = 0$$

$$A^2 x = \lambda^2 x, A^n x = \lambda^n x$$

$$Ax - \lambda Ix = 0$$

$$(A - \lambda I)x = 0$$

$$\det(A - \lambda I) = 0$$

$$\begin{aligned}\dot{X}_1 &= aX_1 + bX_2 \\ \dot{X}_2 &= cX_1 + dX_2\end{aligned}$$


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$$\dot{\vec{X}} = A \vec{X}$$

$n \times n$

$$\dot{X}_1 = aX_1, \dots$$

$$\dot{X}_2 = \dots + dX_2$$

$$\begin{pmatrix} \dot{X}_1 \\ \dot{X}_2 \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \end{pmatrix}$$

$$X_1 = X_1^0 e^{at}$$

$$X_2 = X_2^0 e^{dt}$$

$$A = P \Lambda P^{-1}$$

$$\begin{pmatrix} \dot{X}_1 \\ \dot{X}_2 \end{pmatrix} = P \Lambda P^{-1} \underbrace{\begin{pmatrix} X_1 \\ X_2 \end{pmatrix}}_{\begin{pmatrix} z_1 \\ z_2 \end{pmatrix}}$$

$$\begin{pmatrix} \dot{z}_1 \\ \dot{z}_2 \end{pmatrix} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$$

$$z_1 = z_0 e^{\lambda_1 t}$$

$$z_2 = z_0 e^{\lambda_2 t}$$

EIGENVECTORS, EIGENVALUES = ..... (A)



$(v_1, v_2)$

$v = \text{EIGENVECTOR}$

$\rightarrow [\lambda_1, \lambda_2]$

$\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$

$$\underset{K \times m}{B} \underset{m \times z}{A} = \underset{K \times z}{C}$$

$\begin{matrix} A & B \\ m \times z & K \times m \end{matrix}$

$$\textcircled{1} \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = A \begin{pmatrix} x \\ y \end{pmatrix} \quad \lambda_1, \lambda_2 \in \mathbb{R}, \lambda_1 \neq \lambda_2 \quad A = P \Lambda P^{-1}$$

$$P^{-1} \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = P^{-1} P \Lambda P^{-1} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$P^{-1} \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} P^{-1} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{pmatrix} \dot{z} \\ \dot{w} \end{pmatrix} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \begin{pmatrix} z \\ w \end{pmatrix}$$

$$\begin{pmatrix} z \\ w \end{pmatrix} = P^{-1} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{pmatrix} \dot{z} \\ \dot{w} \end{pmatrix} = P^{-1} \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix}$$

$$z = z_0 e^{\lambda_1 t}$$

$$w = w_0 e^{\lambda_2 t}$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = P \begin{pmatrix} z \\ w \end{pmatrix}$$

$$\begin{pmatrix} z \\ w \end{pmatrix} = \begin{pmatrix} z_0 e^{\lambda_1 t} \\ w_0 e^{\lambda_2 t} \end{pmatrix}$$



$$\begin{pmatrix} x \\ y \end{pmatrix} = P \begin{pmatrix} z \\ w \end{pmatrix} = \begin{pmatrix} v_1 & v_2 \end{pmatrix} \begin{pmatrix} z_0 e^{\lambda_1 t} \\ w_0 e^{\lambda_2 t} \end{pmatrix}$$

$$\left| \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = A \begin{pmatrix} x \\ y \end{pmatrix} \right.$$

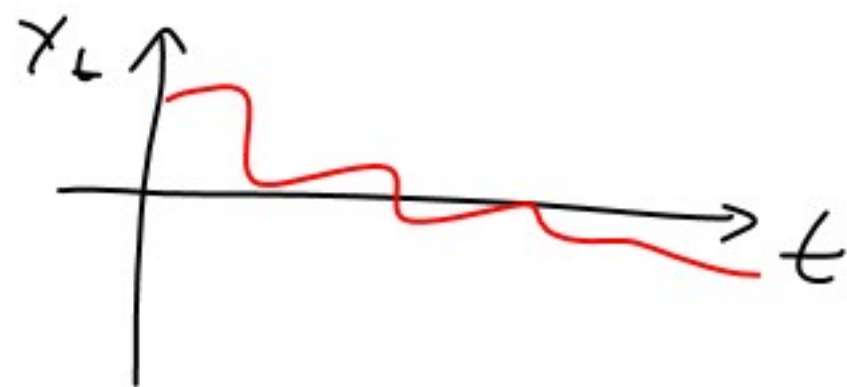
$$\begin{pmatrix} x \\ y \end{pmatrix} = \underline{z_0} e^{\lambda_1 t} v_1 + \underline{w_0} e^{\lambda_2 t} v_2$$

②

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = z_0 \lambda_1 e^{\lambda_1 t} v_1 + w_0 \lambda_2 e^{\lambda_2 t} v_2 = z_0 e^{\lambda_1 t} \lambda_1 v_1 + w_0 e^{\lambda_2 t} \lambda_2 v_2$$

$$A \begin{pmatrix} x \\ y \end{pmatrix} = A \left[ z_0 e^{\lambda_1 t} v_1 + w_0 e^{\lambda_2 t} v_2 \right] = z_0 e^{\lambda_1 t} \underline{A v_1} + w_0 e^{\lambda_2 t} A v_2$$

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = A \begin{pmatrix} x \\ y \end{pmatrix}$$



$$\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

$$\begin{pmatrix} x_t \\ y_t \end{pmatrix} = z_0 e^{\lambda_1 t} v_1 + w_0 e^{\lambda_2 t} v_2$$

Si  $t = 0$

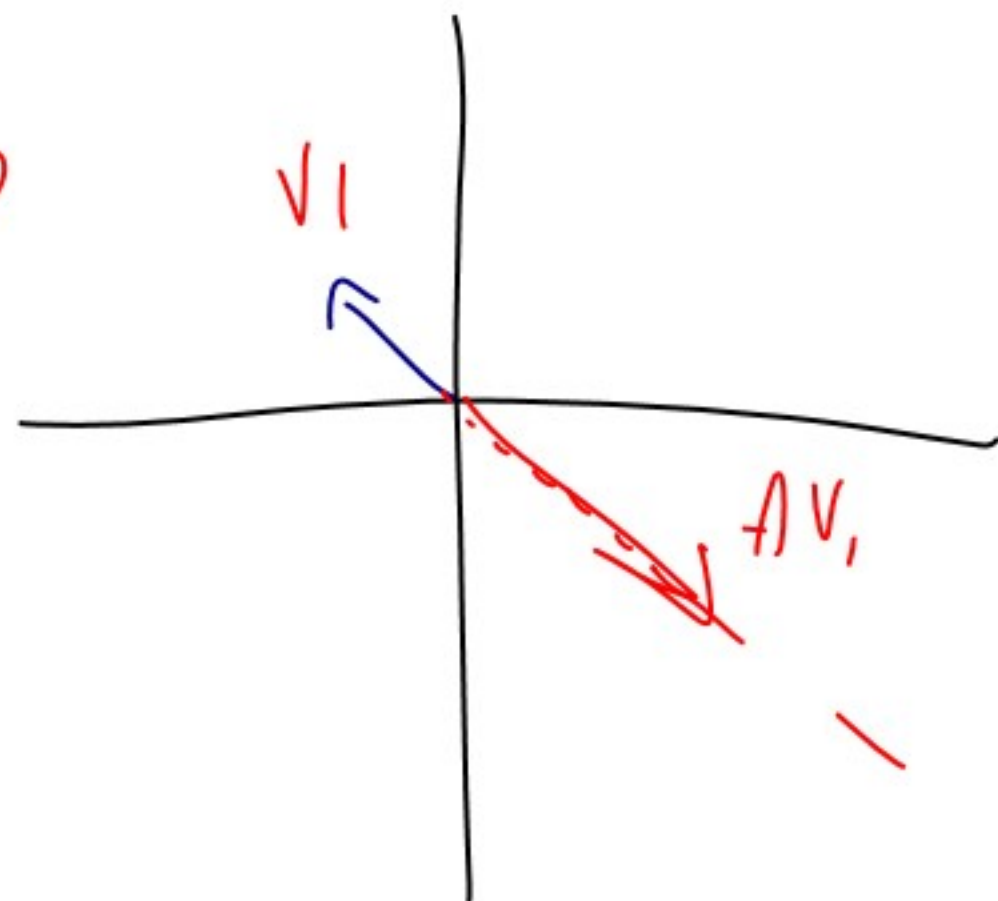
$$\begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = z_0 e^{\lambda_1 \cdot 0} v_1 + w_0 e^{\lambda_2 \cdot 0} v_2$$

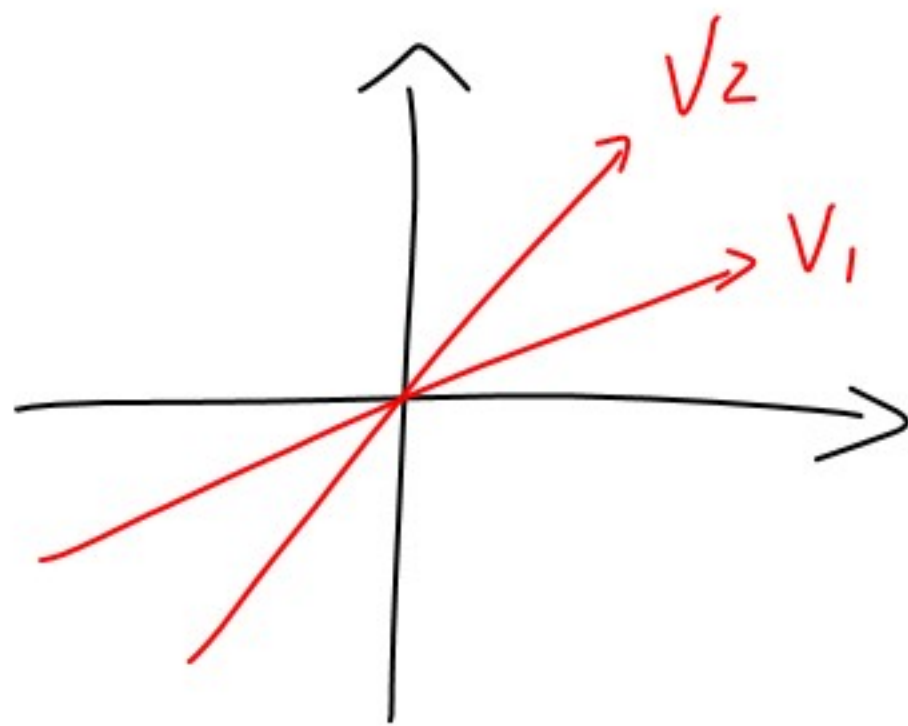
$$\boxed{\begin{pmatrix} z_0 \\ w_0 \end{pmatrix} = P^{-1} \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}}$$

$$\begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = z_0 v_1 + w_0 v_2 = \begin{pmatrix} v_1 & v_2 \end{pmatrix} \begin{pmatrix} z_0 \\ w_0 \end{pmatrix}$$

$$AV_1 = \lambda_1 V_1$$

$$V_1 \neq 0$$





$$\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$$

BASIS  
CANONICA

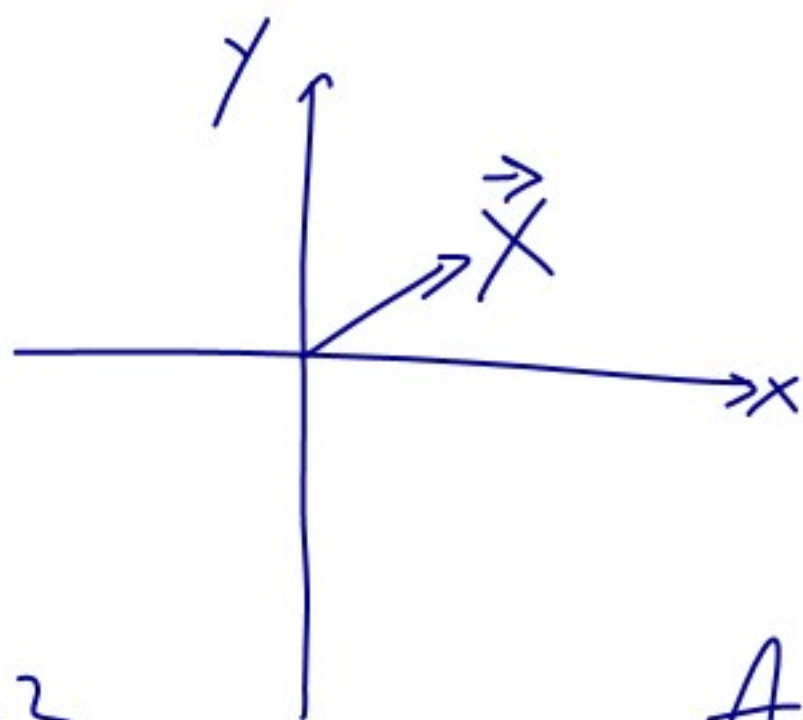
$$\{v_1, v_2\}$$

BASIS  
VECTORES  
NOVIOS

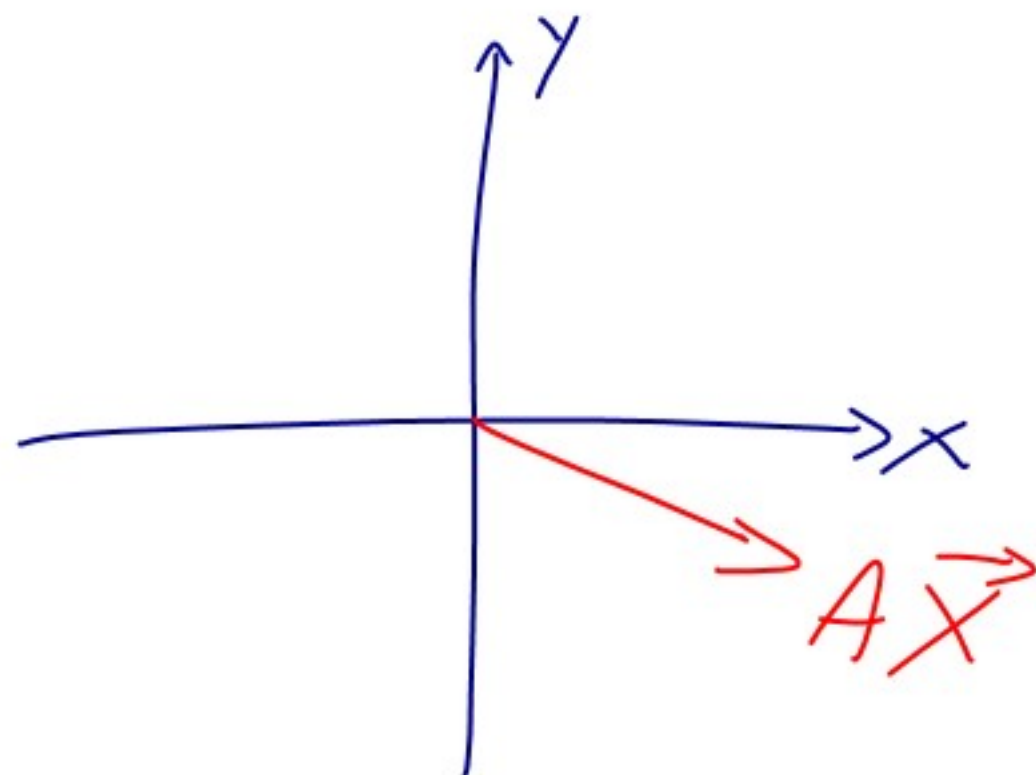


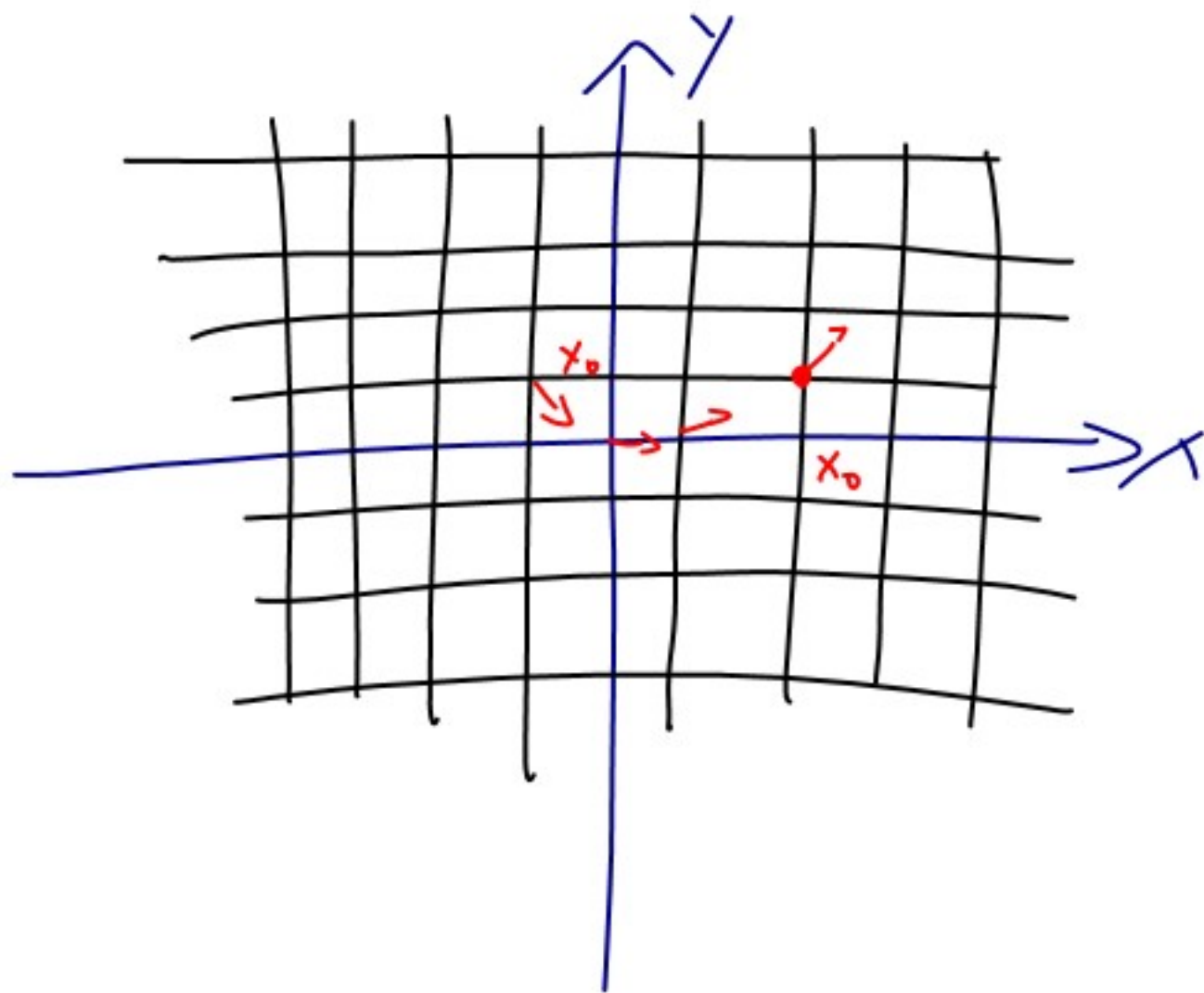
$$A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\vec{x} \mapsto A\vec{x}$$



$$A\vec{v} = \lambda\vec{v}$$





$$\dot{X} = aX + bY$$

$$\dot{Y} = cX + dY$$

$$\dot{X}(X_0, Y_0) = aX_0 + bY_0$$

$$\dot{Y}(X_0, Y_0) = cX_0 + dY_0$$

