

TTIC 31230 Fundamentals of Deep Learning

Quiz 4

Problem 1 (25 points) This problem is on Pseudolikelihood. Consider a graphical model with N nodes numbered 1 through N and where each node can take on one of the values 0 or 1. We let \hat{x} be an assignment of a value to every node. We define the score of \hat{x} by

$$s(\hat{x}) = \sum_{i=1}^{N-1} \mathbf{1}[\hat{x}[i] = \hat{x}[i+1]]$$

where

$$\mathbf{1}[S] = \begin{cases} 1 & \text{if statement } S \text{ is true} \\ 0 & \text{otherwise} \end{cases}$$

The probability distribution over assignments is defined by a softmax.

$$Q_s(\hat{x}) = \text{softmax}_{\hat{x}} s(\hat{x})$$

What is the **Pseudolikelihood** of the all ones assignment?

Solution:

$$\tilde{P}_s(\hat{x}) = \prod_i P_s(\hat{x}[i] \mid \hat{x}/i)$$

where \hat{x}/i consists of all components of \hat{x} other than i . In a graphical model $P_s(\hat{x}[i] \mid \hat{x}/i)$ is determined by the neighbors of i and we can consider only how a value is scored against its neighbors. For \hat{x} equal to all ones we have

$$s(\hat{x}) = N - 1$$

$$s(\hat{x}[i] = 0) = \begin{cases} N - 3 & \text{for } 1 < i < N \\ N - 2 & \text{for } i = 1 \text{ or } i = N \end{cases}$$

For $1 < i < N$ we get

$$\begin{aligned} Q_s(\hat{x}[i] = 1 \mid \hat{x}/i) &= \frac{e^{N-1}}{e^{N-1} + e^{N-3}} \\ &= \frac{1}{1 + e^{-2}} \end{aligned}$$

and for $i = 1$ or $i = N$ we get

$$Q_s(\hat{x}[i] = 1 \mid \hat{x}/i) = \frac{1}{1 + e^{-1}}$$

This gives

$$\tilde{Q}(\hat{x}) = (1 + e^{-1})^{-2} (1 + e^{-2})^{-(N-2)}$$

Problem 2. (25 points). Consider a rate-distortion autoencoder.

$$\Phi^* = \underset{\Phi}{\operatorname{argmin}} I_{\Phi}(y, z) + \lambda E_{y \sim \text{pop}, z \sim p_{\Phi}(z|y)} \text{Dist}(y, y_{\Phi}(z)).$$

Here $I_{\Phi}(y, z)$ is defined by the distribution where we draw y from pop and z from $P_{\Phi}(z|y)$ and where the mutual information is defined by

$$I(x, y) = E_{x, y} \ln \frac{p(x, y)}{p(x)p(y)} = KL(p(x, y), p(x)p(y))$$

The distribution $p_{\Phi}(z|y)$ is typically defined by $z = z_{\Phi}(y) + \epsilon$ for some form of random noise ϵ .

(a) Starting from the definition of $I(y, z)$ given above, show

$$I(y, z) = E_y KL(p(z|y), p(z))$$

where $p_{\Phi}(z) = \sum_y \text{pop}(y) P_{\Phi}(z|y)$.

Solution:

$$\begin{aligned} I(z, y) &= KL(p(z, y), p(z)p(y)) \\ &= E_{z, y} \ln \frac{p(z, y)}{p(z)p(y)} \\ &= E_{z, y} \ln \frac{p(y)p(z|y)}{p(y)p(z)} \\ &= E_y \left(E_{z \sim p(z|y)} \ln \frac{p(z|y)}{p(z)} \right) \\ &= E_y KL(p(z|y), p(z)) \end{aligned}$$

(b) Show the variational equation

$$I(y, z) = \inf_q E_{y \sim \text{pop}} KL(p_{\Phi}(z|y), q(z)).$$

Hint: It suffices to show

$$I(y, z) \leq E_{y \sim \text{pop}} KL(p_{\Phi}(z|y), q(z))$$

and that there exists a q achieving equality.

Solution:

$$\begin{aligned}
& I_{\Phi}(y, z) \\
&= E_{y \sim p_{\text{pop}}} KL(p_{\Phi}(z|y), p_{\Phi}(z)) \\
&= E_{y, z \sim P_{\Phi}(z|y)} \left(\ln \frac{p_{\Phi}(z|y)}{q(z)} + \ln \frac{q(z)}{p_{\Phi}(z)} \right) \\
&= E_{y \sim p_{\text{pop}}} KL(p_{\Phi}(z|y), q(z)) + \left(E_{y \sim p_{\text{pop}}, z \sim p_{\Phi}(z|y)} \ln \frac{q(z)}{p_{\Phi}(z)} \right) \\
&= E_y KL(p_{\Phi}(z|y), q(z)) + E_{z \sim p_{\Phi}(z)} \ln \frac{q(z)}{p_{\Phi}(z)} \\
&= E_y KL(p_{\Phi}(z|y), q(z)) - KL(p_{\Phi}(z), q(z)) \\
&\leq E_{y \sim p_{\text{pop}}} KL(p_{\Phi}(z|y), q(z))
\end{aligned}$$

From part (a) equality is achieved when $q(z) = p_{\Phi}(z)$.

(c) Based on the result from part (b) rewrite the definition of rate-distortion autoencoder to be a minimization over two models Φ and Ψ which gives the same meaning for Φ assuming universality for Ψ .

Solution:

$$\Phi^*, \Psi^* = \underset{\Phi, \Psi}{\operatorname{argmin}} E_{y \sim p_{\text{pop}}, z \sim P_{\Phi}(z|y)} \ln \frac{p_{\Phi}(z|y)}{p_{\Psi}(z)} + \lambda \operatorname{Dist}(y, y_{\Phi}(z)).$$

Problem 3. (25 points)

This problem is on the instability of adversarial objectives. Consider the following adversarial objective where x and y are scalars (real numbers).

$$\max_x \min_y xy$$

(a) Write the differential equation for gradient flow of this adversarial objective.

Solution:

$$\begin{aligned}\frac{dx}{dt} &= y \\ \frac{dy}{dt} &= -x\end{aligned}$$

(b) Give a general solution to your differential equation. (Hint: It goes in a circle). Your solution should have parameters allowing for any given initial value of x and y .

Solution:

$$\begin{aligned}x &= r_0 \sin(t + \Theta_0) \\ y &= r_0 \cos(t + \Theta_0)\end{aligned}$$

Problem 4. (25 points)

This problem is on contrastive GANs.

Define the distribution $P \hookrightarrow Q^k$ to be the result of drawing one “positive” from P and k IID “negatives” from Q ; then inserting the positive at a random position among the negatives; and returning (i, y_1, \dots, y_{N+1}) where i is the index of the positive.

Consider a contrastive GAN.

$$\Phi^* = \operatorname{argmin}_{\Phi} \max_{\Psi} E_{(i, y_1, \dots, y_{N+1}) \sim (\text{pop} \hookrightarrow P_{\Phi}^k)} \ln p_{\Psi}(i | y_1, \dots, y_{N+1}) \quad (1)$$

Here the objective function has been negated so that we have a min-max problem rather than a max-min problem.

(a) Convert the above equation to a conditional contrastive GAN for modeling $p_{\Phi}(y|x)$ rather than $p_{\Phi}(y)$ trained by the above equation. Your solution should have the property that the optimum assuming universality is the true conditional distribution $\text{pop}(y|x)$.

Solution:

$$\Phi^* = \operatorname{argmin}_{\Phi} \max_{\Psi} E_{x \sim \text{pop}} E_{(i, y_1, \dots, y_{N+1}) \sim (\text{pop}(y|x) \hookrightarrow p_{\Phi}(y|x)^k)} \ln p_{\Psi}(i | y_1, \dots, y_{N+1}, x)$$

(b) It is shown in the slides that if we restrict $p_{\Psi}(i|y_1, \dots, y_{N+1})$ to be computed from a softmax of a score $s_{\Phi}(y)$, and assume universality, we have

$$p_{\Psi^*}(i|y_1, \dots, y_{N+1}) = \operatorname{softmax}_i \ln \frac{\operatorname{pop}(y_i)}{p_{\Phi}(y_i)}$$

Given this property of Ψ^* , show

$$\begin{aligned} & E_{(i, y_1, \dots, y_{N+1}) \sim \operatorname{pop} \hookrightarrow p_{\Phi}^N} \ln p_{\Psi^*}(i|y_1, \dots, y_{N+1}) \\ & \leq \frac{N}{N+1} (KL(\operatorname{pop}, p_{\Phi}) + KL(p_{\Phi}, \operatorname{pop})) + \ln \frac{1}{N+1} \end{aligned}$$

Note that if $p_{\Phi} = \operatorname{pop}$ then $P(i|y_1, \dots, y_{N+1}) = \frac{1}{N+1}$ in which case this bound is tight.

Solution:

$$\begin{aligned} & E_{(i, y_1, \dots, y_{N+1}) \sim \operatorname{pop} \hookrightarrow p_{\Phi}^N} \ln p_{\Psi^*}(i|y_1, \dots, y_{N+1}) \\ & = E_{(i, y_1, \dots, y_{N+1}) \sim \operatorname{pop} \hookrightarrow p_{\Phi}^N} \ln \left(\operatorname{softmax}_i \ln \frac{\operatorname{pop}(y_i)}{p_{\Phi}(y_i)} \right) [i] \\ & = E_{(i, y_1, \dots, y_{N+1}) \sim \operatorname{pop} \hookrightarrow p_{\Phi}^N} \ln \frac{\operatorname{pop}(y_i)}{p_{\Phi}(y_i)} - \ln \left(\sum_i \frac{\operatorname{pop}(y_i)}{p_{\Phi}(y_i)} \right) \\ & = E_{(i, y_1, \dots, y_{N+1}) \sim \operatorname{pop} \hookrightarrow p_{\Phi}^N} \ln \frac{\operatorname{pop}(y_i)}{p_{\Phi}(y_i)} - \ln \left(\frac{1}{N+1} \sum_i \frac{\operatorname{pop}(y_i)}{p_{\Phi}(y_i)} \right) - \ln (N+1) \\ & \leq E_{(i, y_1, \dots, y_{N+1}) \sim \operatorname{pop} \hookrightarrow p_{\Phi}^N} \ln \frac{\operatorname{pop}(y_i)}{p_{\Phi}(y_i)} - \frac{1}{N+1} \sum_i \ln \frac{\operatorname{pop}(y_i)}{p_{\Phi}(y_i)} - \ln (N+1) \\ & = \frac{N}{N+1} E_{y \sim \operatorname{pop}} \ln \frac{\operatorname{pop}(y)}{p_{\Phi}(y)} - \frac{N}{N+1} E_{y \sim p_{\Phi}} \ln \frac{\operatorname{pop}(y)}{p_{\Phi}(y)} - \ln (N+1) \\ & = \frac{N}{N+1} (KL(\operatorname{pop}, p_{\Phi}) + KL(p_{\Phi}, \operatorname{pop})) - \ln (N+1) \end{aligned}$$