Runge-Kutta

Sunday, November 1, 2020 5:29 PM

Recall local francation error $T_{i+1}(h) := \frac{1}{h} \left(y_{i+1} - (y_i + h \phi(t_i, y_i)) \right)$ for the method $w_{i+1} = w_i + h \phi(t_i, w_i)$.

Enler's method has 7(h) = 0(h). Higher-order methods do better, e.g., 0(h2)

We saw higher-order Taylor methods based on Taylor expansions of f (recall: our IVP is Y'=f(t,y), $y(a)=y_0$, $t\in [a,b]$)

This lecture: a better way to get higher-order methods

Backgrand: Taylor's Thon in 20

Thm 5.13 Suppose f(t,y) and all its partial derivatives of order $\leq n+1$ are continuous on $D=\{(t,y): a\leq t\leq b, c\leq y\leq d\}$, and let $(t_0,y_0)\in D$. Then $\forall (t,y)\in D$, $\exists \xi$ between t and t_0 and $\exists M$ between y and y_0 with

$$f(t,y) = P_n(t,y) + R_n(t,y)$$
Taylor polynomial error / remainder

$$P_{n}(t,y) = \underbrace{f(t_{o},y_{o})}_{o^{th} orde} + \underbrace{(t-t_{o}) \frac{\partial f}{\partial t}(t_{o},y_{o})}_{1s^{t} order \ terms} + \underbrace{(y-y_{o}) \frac{\partial f}{\partial y}(t_{o},y_{o})}_{1s^{t} order \ terms}$$

$$+ \left(\frac{t-t_0}{z!}\right)^2 \frac{\partial^2 f}{\partial t^2}(t_0, y_0) + \left(t-t_0\right)(y-y_0) \frac{\partial^2 f}{\partial t}(t_0, y_0) + \frac{(y-y_0)^2}{z!} \frac{\partial^2 f}{\partial y^2}(t_0, y_0)$$

$$\frac{\partial^2 f}{\partial t^2}(t_0, y_0) + \frac{\partial^2 f}{\partial y^2}(t_0, y_0) + \frac{(y-y_0)^2}{z!} \frac{\partial^2 f}{\partial y^2}(t_0, y_0)$$

and the remainder term is

$$P_{n}(t,y) = \frac{1}{(n+1)!} \sum_{j=0}^{n+1} {n+1 \choose j} (t-t)^{n+1-j} (y-y_{0})^{j} \frac{\partial^{n+1} f}{\partial t^{n+1-j} \partial y_{0}^{j}} (\xi,\mu)$$

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I dea of Runge-Kutta
                      Carl Ruge 1856-1927, Martin Kutta 1867-1944
                      A family of methods, not a single method
        y(t+h) = y(t) + h \cdot y'(t) + h^{2}y''(t) + o(h^{3})
          So our 1st order Taylor method (Euler's method) is \phi(t,y) = f(t,y)
                  W_{i+1} = W_i + h \phi(t_i, w_i) 3 Generic form of one-step methods
                                                              (of which RK belows)
          and 2nd order Taylor method is \Phi(t_{1}y) = f(t_{1}y) + \frac{h}{2}f'(t_{1}y) etc.
          Focus on for now. We'd like to avoid calculating f'(t,y).
          Let's approximate it with Taylor Series! ( if you haven't noticed yet,
                 that's the theme of this class)
          How many terms to keep in the Taylor series?
                 We already have a O(h2) error in $, so let's keep at some amount
           It gets a bit messy.
                  Recall channing f'(t,y) := \frac{d}{dt}f(t,y) = \frac{d}{dt}f(t,y) + \frac{d}{dy}f(t,y) \cdot \frac{dy}{dt}
                「T(2)(t,y)=f(t,y)+ と また(t,y)+ とまた(t,y)・f(t,y)
           Idea: can we find a, d and B such that
T^{(2)}(t,y) = \alpha \cdot f(t+\alpha,y+\beta) + O(h^2) ?
Taylor expand (20) about f(t,y)
        \alpha \cdot f(t+x,y+\beta) = \alpha \left( f(t,y) + \alpha \frac{\partial f}{\partial t}(t,y) + \beta \frac{\partial f}{\partial y}(t,y) \right)
                                    + a R, (++ d, y+ B)
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So matching terms

(1)
$$\Rightarrow \alpha = 1$$

(2) $\Rightarrow \alpha = \frac{h}{2}$ So $\alpha = \frac{h}{2}$

(3) $\Rightarrow \alpha \beta = \frac{h}{2} \cdot f(t_{1}y)$ So $\beta = \frac{h}{2} f(t_{1}y)$

and if f(t,y) and all of its partial derivatives up to degree $\leq z$ are are bounded, then $R, (...) = O(h^2)$

We just derived the

Midpoint Method, a.k.a. Improved Euler (an example of a Zunge-Kutta method)

$$w_{i+1} = w_i + h \cdot f(t_i + \frac{h}{2}, w_i + \frac{h}{2}f(t_i, w_i))$$
Still "single step" but we call it "multistage"

Another way to write it:

Given w_i , $K_1 = h f(t_i, w_i)$ Twice the cost per iteration, compared to Euler, but usually definitely worth it. $K_2 = h f(t_i + h/z, w_i + t/z, K_1)$ $w_{i+1} = w_i + K_2$

General form of Ruge Kutta methods ARK are multi-stage one-step methods, NOT multi-step we can generalize above, adding more parameters to get higher-orders

RK methods. All S-stage explicit Ruge-Kutta methods can be described by their "Butcher array"

O meaning

$$C_1$$
 α_{11}
 C_2
 α_{21}
 α_{22}
 α_{s-1}
 $\alpha_{s-1,1}$
 $\alpha_{s-1,2}$
 $\alpha_{s-1,s-1}$
 $\alpha_{s-1,s-1}$
 $\alpha_{s-1,s-1}$

reaning
$$K_1 = h f(t_1, w_1)$$

 $k_2 = h f(t_1 + c_1 h, w_1 + a_{11} k_1)$
 $k_3 = h f(t_1 + c_2 h, w_1 + a_{21} k_1 + a_{22} k_2)$
 \vdots
 $k_5 = h f(t_1 + c_{5-1} h, w_1 + a_{5-1} k_1 + ...)$
 b_5
 $w_{i+1} = w_i + b_1 k_1 + b_2 k_2 + ... + b_5 k_5$

Ex Improved Euler $K_{1} = h f(t_{i}, w_{i})$ $K_{2} = h f(t_{i} + h/z, w_{i} + \frac{1}{2} K_{1})$ $W_{i+1} = w_{i} + K_{2}$ $U_{2} = h f(t_{2} + h/z, w_{i} + \frac{1}{2} K_{1})$ $W_{i+1} = w_{i} + K_{2}$ $U_{2} = h f(t_{3} + h/z, w_{i} + \frac{1}{2} K_{1})$ $U_{3} = h f(t_{3} + h/z, w_{i} + \frac{1}{2} K_{1})$ $U_{4} = w_{5} + K_{2}$ $U_{5} = h f(t_{3} + h/z, w_{i} + \frac{1}{2} K_{1})$

Ex Modified Euler (also a 2-stage, 2nd order method) Our book defines it as with = wit = { [f(ti, w) + f(ti, with f(ti, wi))] $= w_{i} + \frac{1}{2} h f(t_{i}, w_{i}) + \frac{1}{2} h f(t_{i}, w_{i} + h f(t_{i}, w_{i}))$ $b_{1} = \frac{1}{2} b_{2} = \frac{1}{2}$ So the Butcher array is

Another ex. of a 2-stage, 2nd order method is Henr's 2-stage method

nut the same as our book's 3-stage, 3rd order Heun's method.

2/3 2/3

1/4 3/4 & note: bi's always sum to 1 (for consistency)

There are systematic ways to derive these, but complicated and ... it only has to be done once. We can just use them

The Zoo of RK methods: higher-order RK, and which ones to use?