Intro to Numerical Differentiation

Friday, September 25, 2020 1:09 PM

Big Picture

Why lubot? Find/approximate the derivative of a finction $f: \mathbb{R} \to \mathbb{R}$ (or more generally the gradient or Facobian of $F: \mathbb{R}^n \to \mathbb{R}^m$)

Used for

- root-finding /optimization (eg Newton's Method)

- solving UDE/PDE

- misc. calculus

#1 most important numerical computation in Science

Approches

la. By hand (analytical)

16. Symbolic (analytical with help from suftween)

100% exact

OUR FOCUS

Z. "Finite differences"

All based on idea like $f(x) = \lim_{h \to 0} f(x+h) - f(x)$ and choose h small but $h \neq 0$

Fast, but not perfectly accurate, and in fact unstable

Both "truncation erm / approximation erm (h x 2) and floating point / roundoff erm.

3. Algorithmic Differentiation = "Backpropagation" in training neural nots
No approximation error! Need libraries though

We'll lousely follow Burden and Faires, but different derivation (analysis

For equisposed nodes, things aren't so bad

Otherwise, see Bengt tomberg, "Calculation of weights in finite difference formulas", SIAM Review 40(3) 1998.

Our guiding principle will be

- O Interpolate the given function values, then differentiate the interpolant exactly
 - Used for deriving these formulas, but not necessary to check derivation

- we'll use the same principle for integration

and we'll see

- (2) There's a trade-off between truncultion/approximation error and roundoff error
 - (20) Numerical Integration is unstable
 - (26) "Higher-Orde" Methods are more efficient in this regard

First formula and warmup: "Forward Differences"

Recall
$$f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$

Let's say we know f at two points, $\{x_0, Y_i\}$ So let $X = X_0$, $h = X_1 - X_0$

then approximate
$$f'(x_o) \approx f(\underline{x_i}) - f(x_o) = f(\underline{x_o + h}) - f(x_o)$$

If h>0 $(x_1>x_0)$ we call this the Forward Difference formula If h<0 $(x_1< x_0)$ "Backward Difference formula

Error Analysis:

Taylor expand f about
$$x_0$$
:
$$f(x_0 + h) = f(x_0) + f'(x_0)h + f''(\xi)_{z_1}h^2$$

$$\frac{f(x_0+h)-f(x_0)}{h} = \frac{f'(x_0)+f''(\xi)_{\xi_1}h}{\text{what}}$$
approximation what we want

So if
$$f \in C^2[x_0 - \delta, x_0 + \delta]$$
 for some $\delta > 0$

$$\Rightarrow f'' \text{ is continuous on } [x_0 - \delta, x_0 + \delta]$$

$$\Rightarrow f'' \text{ is bounded on } [x_0 - \delta, x_0 + \delta]$$
So then error = constent.

thus if f is smooth then
the err in forward / bookward differences is O(h)
i.e.

Forward / backward differences is a first-order method

(ex. if it had been O(h²), we would have called it a "second order" method)

Higher-order is better (since we care about h->0)

· A 2nd order method is fechnically also a 1st order method, so when we say the order, we say the highest possible order.