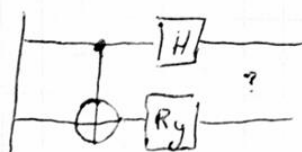


Policzyć stan wyjściowy układu $|x_1 x_0\rangle$:

zad 0. $R_{y\phi} = \begin{bmatrix} \cos \frac{\phi}{2} & -\sin \frac{\phi}{2} \\ \sin \frac{\phi}{2} & \cos \frac{\phi}{2} \end{bmatrix}$ $\phi = \frac{\pi}{3}$ $\cos \frac{\pi}{6} = \frac{\sqrt{3}}{2}$ $H = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$

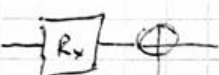
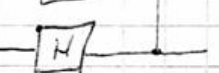
$|x_1\rangle = |1\rangle$  $|x_1\rangle = |1\rangle \rightarrow |1\rangle \rightarrow \frac{1}{\sqrt{2}}|0\rangle - \frac{1}{\sqrt{2}}|1\rangle$

$|x_0\rangle = |1\rangle$  $|x_0\rangle = |1\rangle \rightarrow |0\rangle \rightarrow \approx$

$Z = \begin{bmatrix} \cos \frac{\pi}{6} & -\sin \frac{\pi}{6} \\ \sin \frac{\pi}{6} & \cos \frac{\pi}{6} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \cos \frac{\pi}{6} \\ \sin \frac{\pi}{6} \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{3}}{2} \\ \frac{1}{2} \end{bmatrix}$

$|x\rangle = |x_1 x_0\rangle = \left(\frac{1}{\sqrt{2}}|0\rangle + \frac{1}{\sqrt{2}}|1\rangle \right) \otimes \left(\frac{\sqrt{3}}{2}|0\rangle + \frac{1}{2}|1\rangle \right) = \frac{\sqrt{3}}{\sqrt{2}}|00\rangle + \frac{1}{\sqrt{2}}|01\rangle - \frac{\sqrt{3}}{\sqrt{2}}|10\rangle - \frac{1}{\sqrt{2}}|11\rangle$
 $= \frac{\sqrt{6}}{4}|00\rangle + \frac{\sqrt{2}}{4}|01\rangle - \frac{\sqrt{6}}{4}|10\rangle - \frac{\sqrt{2}}{4}|11\rangle$

zad 1. $R_{x\phi} = \begin{bmatrix} \cos \frac{\phi}{2} & -i \sin \frac{\phi}{2} \\ i \sin \frac{\phi}{2} & \cos \frac{\phi}{2} \end{bmatrix}$ $\phi = \frac{2\pi}{3}$ $|x_1 x_0\rangle = ?$

$|x_0\rangle = |0\rangle$ 
 $|x_1\rangle = |0\rangle$ 

$|x_1\rangle = |0\rangle \rightarrow \frac{1}{\sqrt{2}}|0\rangle + \frac{1}{\sqrt{2}}|1\rangle$ ~~$\frac{1}{\sqrt{2}}|0\rangle - \frac{1}{\sqrt{2}}|1\rangle$~~

$|x_0\rangle = |0\rangle \rightarrow \approx$

$Z = \begin{bmatrix} \cos \frac{\pi}{3} & -i \sin \frac{\pi}{3} \\ i \sin \frac{\pi}{3} & \cos \frac{\pi}{3} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ -i \frac{\sqrt{3}}{2} \end{bmatrix} = \frac{1}{2}|0\rangle - i \frac{\sqrt{3}}{2}|1\rangle$

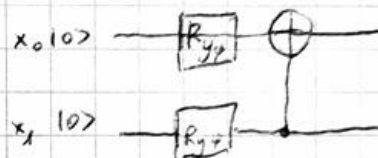
$|x\rangle = |x_1 x_0\rangle = \left(\frac{1}{\sqrt{2}}(|0\rangle + |1\rangle) \right) \otimes \left(\frac{1}{2}|0\rangle - i \frac{\sqrt{3}}{2}|1\rangle \right) = \frac{1}{2\sqrt{2}}|00\rangle - i \frac{\sqrt{3}}{2\sqrt{2}}|01\rangle + \frac{1}{2\sqrt{2}}|10\rangle - i \frac{\sqrt{3}}{2\sqrt{2}}|11\rangle$
 P0 CNOT

$|x\rangle = \frac{1}{\sqrt{2}}|00\rangle - i \frac{\sqrt{3}}{2\sqrt{2}}|01\rangle + \frac{1}{2\sqrt{2}}|11\rangle - i \frac{\sqrt{3}}{2\sqrt{2}}|10\rangle$

$$R_{y,\varphi} = \begin{bmatrix} \cos \frac{\varphi}{2} & -\sin \frac{\varphi}{2} \\ \sin \frac{\varphi}{2} & \cos \frac{\varphi}{2} \end{bmatrix}$$

$$\varphi = \frac{\pi}{3}$$

$$\psi = \frac{\pi}{4}$$



$$|x_0\rangle = |0\rangle \Rightarrow R_{y\frac{\pi}{3}}|0\rangle = \begin{bmatrix} \cos \frac{\pi}{6} & -\sin \frac{\pi}{6} \\ \sin \frac{\pi}{6} & \cos \frac{\pi}{6} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \cos \frac{\pi}{6} \\ \sin \frac{\pi}{6} \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{3}}{2} \\ \frac{1}{2} \end{bmatrix} = \frac{\sqrt{3}}{2}|0\rangle + \frac{1}{2}|1\rangle$$

$$|x_1\rangle = |0\rangle \Rightarrow R_{y\frac{\pi}{4}}|0\rangle = \begin{bmatrix} \cos \frac{\pi}{4} & -\sin \frac{\pi}{4} \\ \sin \frac{\pi}{4} & \cos \frac{\pi}{4} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \cos \frac{\pi}{4} \\ \sin \frac{\pi}{4} \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \end{bmatrix} = \frac{\sqrt{2}}{2}|0\rangle + \frac{\sqrt{2}}{2}|1\rangle$$

$$|x_1 x_0\rangle = \frac{\sqrt{6}}{4}|00\rangle + \frac{\sqrt{6}}{4}|10\rangle + \frac{\sqrt{2}}{4}|01\rangle + \frac{\sqrt{2}}{4}|11\rangle$$

NOT

$$|x_1 x_0\rangle = \frac{\sqrt{6}}{4}|00\rangle + \frac{\sqrt{6}}{4}|11\rangle + \frac{\sqrt{2}}{4}|01\rangle + \frac{\sqrt{2}}{4}|10\rangle$$

Wyjasnienie: kontrolowana bramka Hadamarda włącza działanie bramki H na qbicie docelowym (tutaj młodszy qbit) jesli qbit kontrolny (tutaj starszy qbit) jest ustawiony na $|1\rangle$. Czyli działanie na stany bazowe wygląda tak:

$$\text{Ctrl-H } |00\rangle = |00\rangle$$

$$\text{Ctrl-H } |01\rangle = |01\rangle$$

$$\text{Ctrl-H } |10\rangle = |1\rangle \otimes H|0\rangle$$

$$\text{Ctrl-H } |11\rangle = |1\rangle \otimes H|1\rangle$$

Zadanie znaleźć **jednoqbitowe** bramki (t.j. macierze unitarne 2×2 działające na poszczególne qbity) potrzebne do wyprodukowania stanu $|\psi\rangle = \frac{1}{\sqrt{3}}|00\rangle + \frac{1}{\sqrt{3}}|01\rangle + \frac{1}{\sqrt{3}}|10\rangle$, zakładając, że:

- startujemy ze stanu $|00\rangle$
- na końcu, po znalezionych przez nas bramkach, zostanie użyta bramka Ctrl-H.

$\text{CTRL-H } |00\rangle = |00\rangle$
 $\text{CTRL-H } |01\rangle = |01\rangle$
 $\text{CTRL-H } |10\rangle = |1\rangle \otimes H|0\rangle$
 $\text{CTRL-H } |11\rangle = |1\rangle \otimes H|1\rangle$

$|\psi\rangle = \frac{1}{\sqrt{3}}|00\rangle + \frac{1}{\sqrt{3}}|01\rangle + \frac{1}{\sqrt{3}}|10\rangle$

$|\psi\rangle = \text{CTRL-H}(U_1 \circ U_0)|00\rangle$

$U_0|0\rangle = a|0\rangle + b|1\rangle$
 $U_1|0\rangle = c|0\rangle + d|1\rangle$

$U_1 \circ U_0 = a|00\rangle + b|01\rangle + d|10\rangle + c|11\rangle = *$

$\begin{cases} a = \frac{1}{\sqrt{3}} \\ b = \frac{1}{\sqrt{3}} \\ c = \frac{1}{\sqrt{3}} \\ d = 0 \end{cases}$

$\text{CTRL-H } |00\rangle = |\psi\rangle = \text{CTRL-H}(*): a|00\rangle + b|01\rangle + \frac{1}{\sqrt{2}}bd|10\rangle + \frac{1}{\sqrt{2}}ad|11\rangle = \frac{1}{\sqrt{2}}bd|10\rangle - \frac{1}{\sqrt{2}}ad|11\rangle$

$\sqrt{b^2 + d^2} = 1 \Rightarrow a = \frac{1}{\sqrt{2}} = b$

$\begin{cases} ac = \frac{1}{\sqrt{3}} \\ bc = \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}}(ad + bd) = \frac{1}{\sqrt{3}} \Leftrightarrow \frac{1}{\sqrt{2}}d(a+b) = \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}}(ad - bd) = 0 \Leftrightarrow \frac{1}{\sqrt{2}}d(a-b) = 0 \end{cases} \Rightarrow \begin{cases} b = \frac{1}{\sqrt{3}} \\ \frac{2}{\sqrt{2}}db = \frac{1}{\sqrt{3}} \\ a = b \end{cases}$

$\begin{cases} c = \sqrt{\frac{2}{3}} \\ d = \frac{1}{\sqrt{3}} \\ b = \frac{1}{\sqrt{3}} \\ a = \frac{1}{\sqrt{3}} \end{cases} \Rightarrow U_0 = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$

$U_1 = \begin{bmatrix} \frac{1}{\sqrt{3}} & c \\ \frac{1}{\sqrt{3}} & d \end{bmatrix} \quad U_1 U_1^\dagger = I$

$\begin{cases} f = \frac{1}{\sqrt{3}} \\ e = \frac{1}{\sqrt{3}} \end{cases}$