

Neural Networks

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Backfed Input Cell

Input Cell

Noisy Input Cell

Hidden Cell

Probabilistic Hidden Cell

Spiking Hidden Cell

Output Cell

Match Input Output Cell

Recurrent Cell

Memory Cell

Different Memory Cell

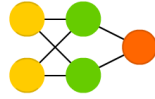
Kernel

Convolution or Pool

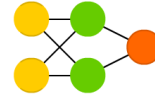
Perceptron (P)



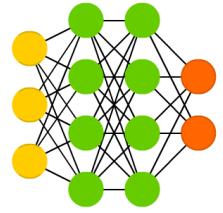
Feed Forward (FF)



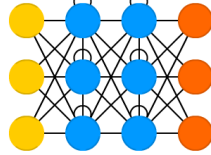
Radial Basis Network (RBF)



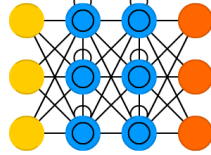
Deep Feed Forward (DFF)



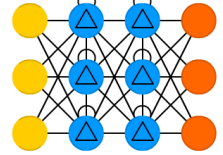
Recurrent Neural Network (RNN)



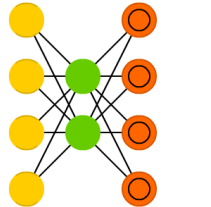
Long / Short Term Memory (LSTM)



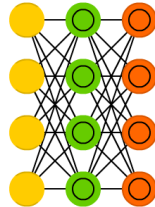
Gated Recurrent Unit (GRU)



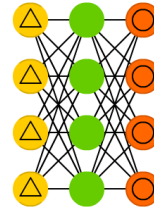
Auto Encoder (AE)



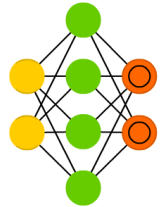
Variational AE (VAE)



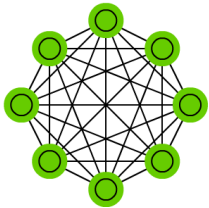
Denoising AE (DAE)



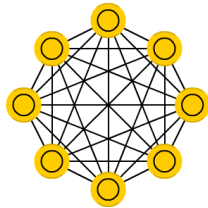
Sparse AE (SAE)



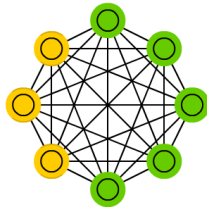
Markov Chain (MC)



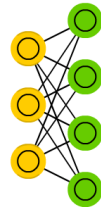
Hopfield Network (HN)



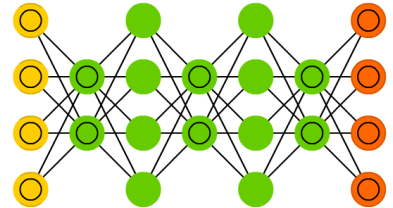
Boltzmann Machine (BM)



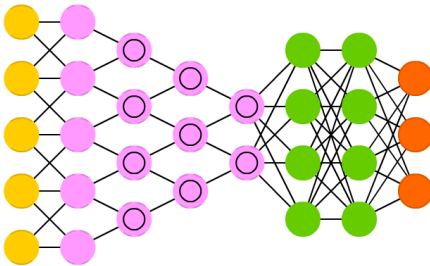
Restricted BM (RBM)



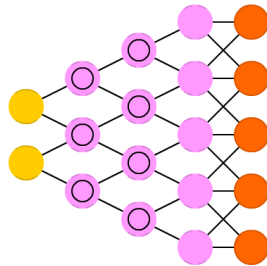
Deep Belief Network (DBN)



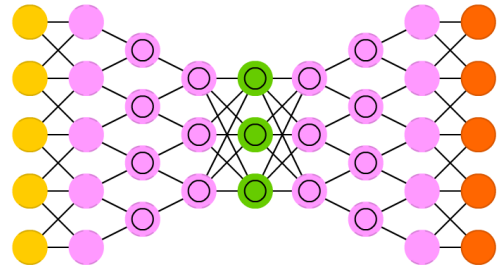
Deep Convolutional Network (DCN)



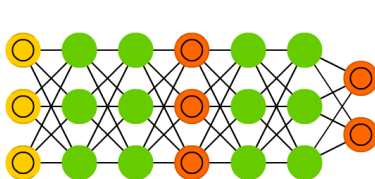
Deconvolutional Network (DN)



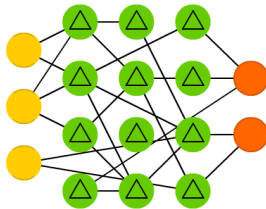
Deep Convolutional Inverse Graphics Network (DCIGN)



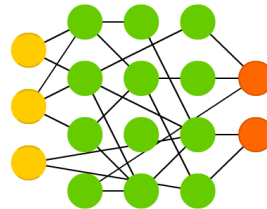
Generative Adversarial Network (GAN)



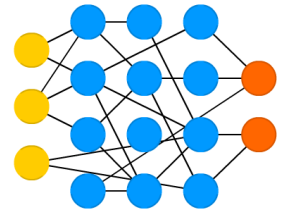
Liquid State Machine (LSM)



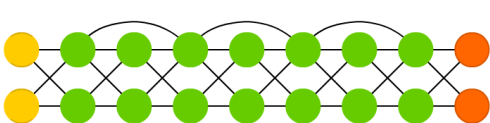
Extreme Learning Machine (ELM)



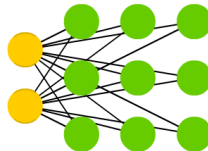
Echo State Network (ESN)



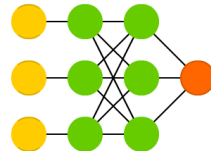
Deep Residual Network (DRN)



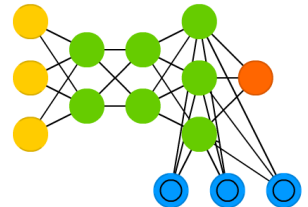
Kohonen Network (KN)



Support Vector Machine (SVM)

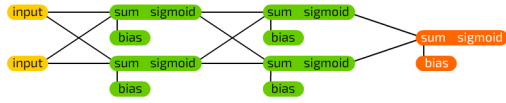


Neural Turing Machine (NTM)

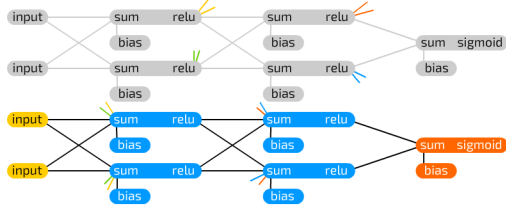
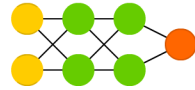


Neural Network Graphs

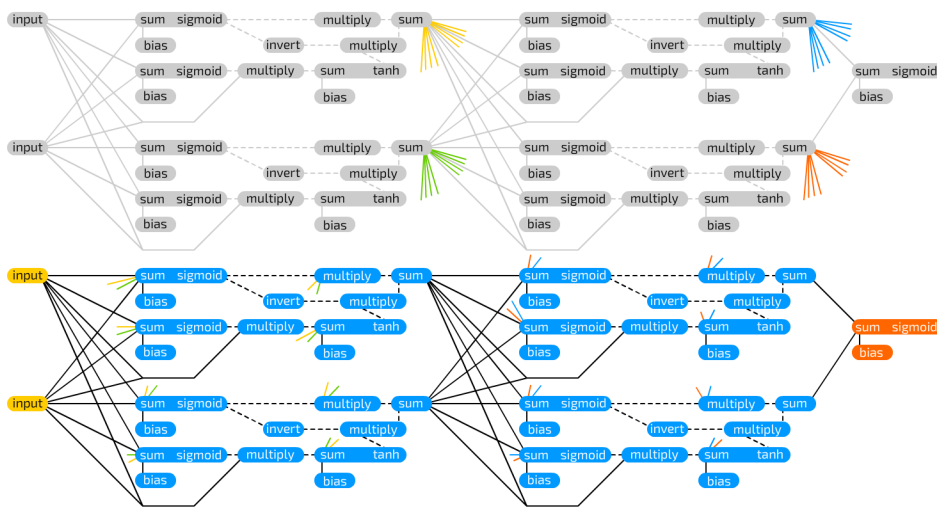
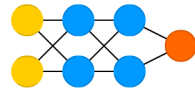
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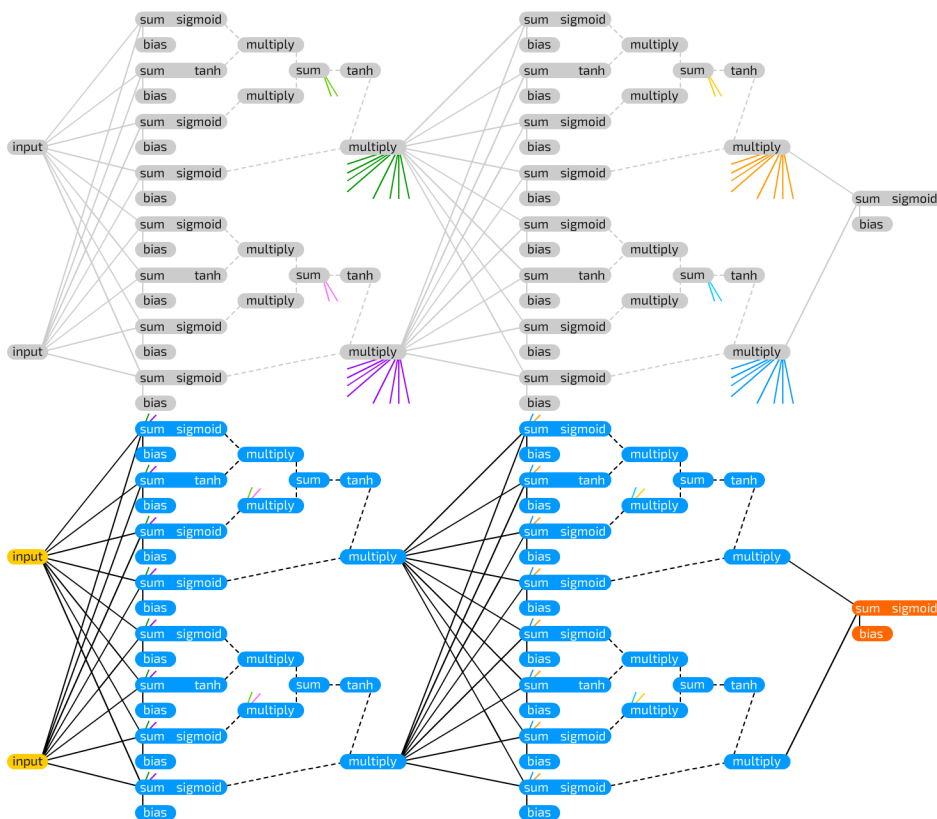
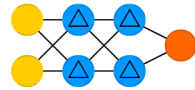
Deep Feed Forward Example



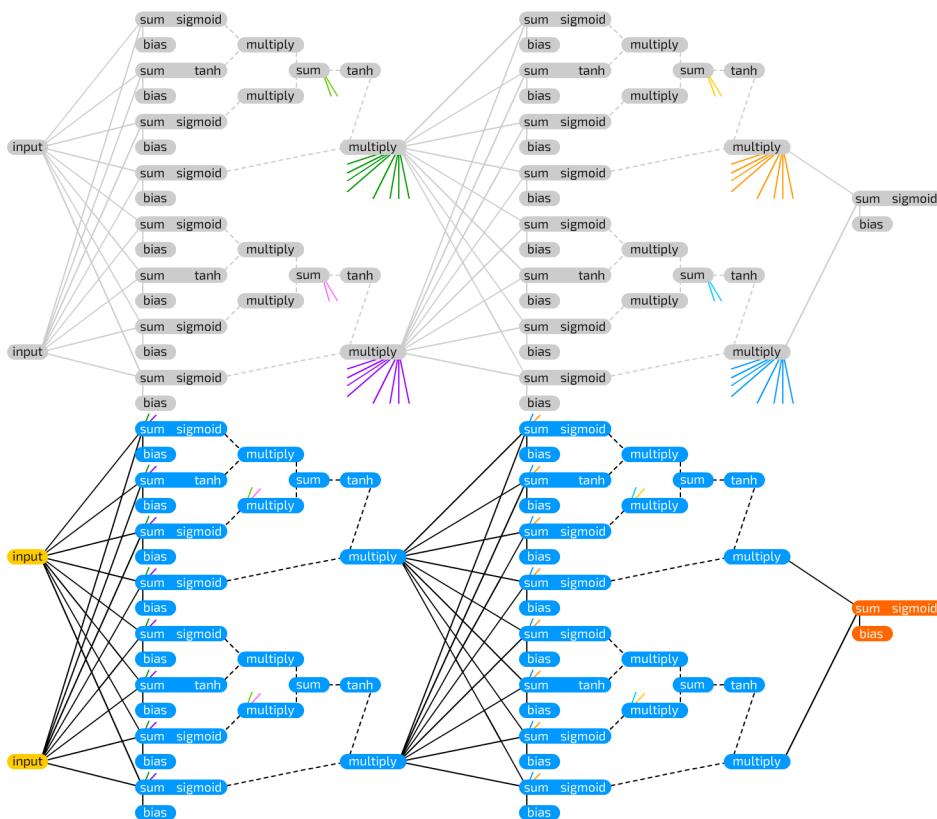
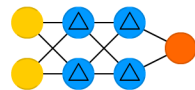
Deep Recurrent Example
(previous iteration)



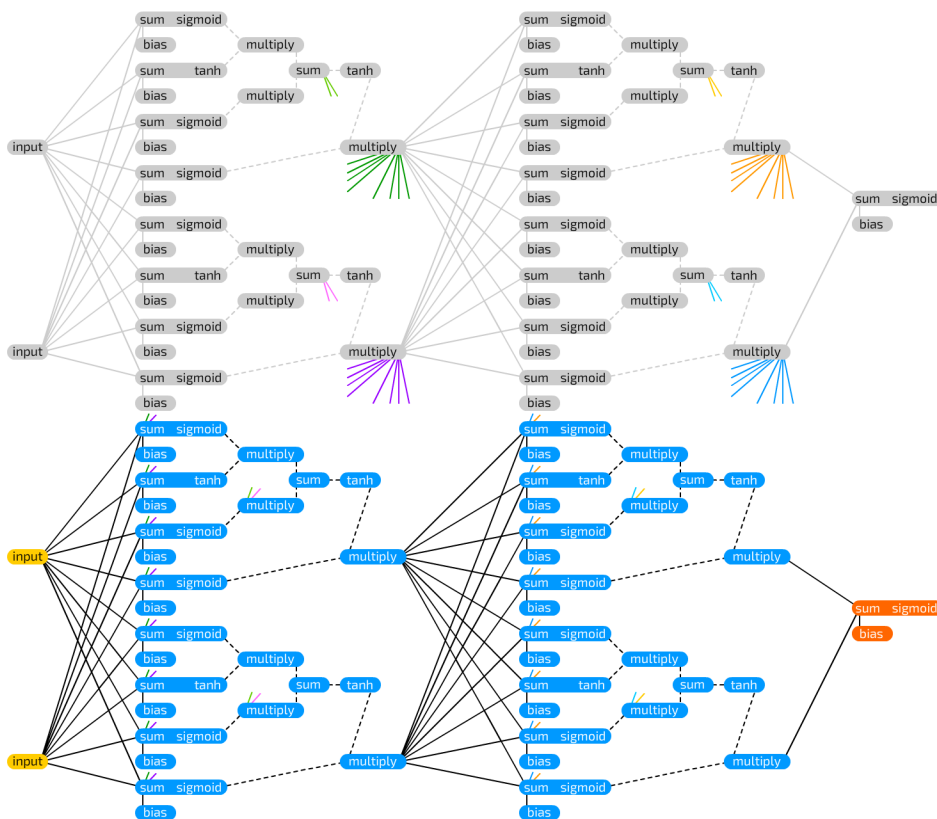
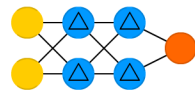
Deep GRU Example
(previous iteration)



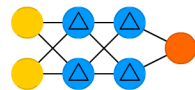
Deep GRU Example



Deep LSTM Example
(previous iteration)



Deep LSTM Example



Linear Vector Spaces:

Definition: A linear vector space, X , is a set of elements (vectors) defined over a scalar field, F , that satisfies the following conditions:

- 1) if $x \in X$ and $y \in X$ then $x+y \in X$.
- 2) $x+y = y+x$.
- 3) $(x+y)+z = x+(y+z)$.
- 4) There is a unique vector $0 \in X$, such that $x+0 = x$ for all $x \in X$.
- 5) For each vector $x \in X$ there is a unique vector in X , to be called $(-x)$, such that $x+(-x) = 0$.
- 6) multiplication, for all scalars $a \in F$, and all vectors $x \in X$, $7) \text{ For any } x \in X, 1x = x \text{ (for scalar 1).}$
- 8) For any two scalars $a \in F$ and $b \in F$ and any $x \in X$, $a(bx) = (ab)x$.
- 9) $(a+b)x = ax + bx$.
- 10) $a(x+y) = ax + ay$.

Linear Independence: Consider n vectors $\{x_1, x_2, \dots, x_n\}$. If there exists n scalars a_1, a_2, \dots, a_n , at least one of which is nonzero, such that $a_1x_1 + a_2x_2 + \dots + a_nx_n = 0$, then the $\{x_i\}$ are linearly dependent.

Spanning a Space:

Let X be a linear vector space and let $\{u_1, u_2, \dots, u_n\}$ be a subset of vectors in X . This subset spans X if and only if for every vector $x \in X$ there exist scalars x_1, x_2, \dots, x_n such that $x = x_1u_1 + x_2u_2 + \dots + x_nu_n$.

Inner Product: (x, y) for any scalar function of x and y .

1. $(x, y) = (y, x)$
2. $(x, ay_1 + by_2) = a(x, y_1) + b(x, y_2)$
3. $(x, x) \geq 0$, where equality holds iff x is the zero vector.

Norm: A scalar function $\|x\|$ is called a norm if it satisfies:

1. $\|x\| \geq 0$
2. $\|x\| = 0$ if and only if $x = 0$.
3. $\|ax\| = |a|\|x\|$
4. $\|x + y\| \leq \|x\| + \|y\|$

Angle: The angle θ bet. 2 vectors x and y is defined by $\cos \theta = \frac{(x, y)}{\|x\| \|y\|}$

Orthogonality: 2 vectors $x, y \in X$ are said to be orthogonal if $(x, y) = 0$.

Gram Schmidt Orthogonalization:

Assume that we have n independent vectors y_1, y_2, \dots, y_n . From these vectors we will obtain n orthogonal vectors v_1, v_2, \dots, v_n .

$$v_1 = y_1, \quad v_k = y_k - \sum_{i=1}^{k-1} \frac{(y_k, v_i)}{(v_i, v_i)} v_i,$$

where $\frac{(y_k, v_i)}{(v_i, v_i)} v_i$ is the projection of y_k on v_i

Vector Expansions:

$$x = \sum_{i=1}^n x_i v_i = x_1 v_1 + x_2 v_2 + \dots + x_n v_n,$$

$$\text{for orthogonal vectors, } x_j = \frac{(v_j, x)}{(v_j, v_j)}$$

Reciprocal Basis Vectors:

$$(r_i, v_j) = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}, \quad x_j = (r_j, x)$$

To compute the reciprocal basis vectors: set $B = [v_1 \ v_2 \ \dots \ v_n]$,

$R = [r_1 \ r_2 \ \dots \ r_n]$, $R^T = B^{-1}$ In matrix form: $x^T = B^{-1} x^s$

Transformations:

A transformation consists of three parts:

domain: $X = \{x_i\}$, range: $Y = \{y_i\}$, and a rule relating each $x_i \in X$ to an element $y_i \in Y$.

Linear Transformations: transformation A is linear if:

1. for all $x_1, x_2 \in X$, $A(x_1 + x_2) = A(x_1) + A(x_2)$
2. for all $x \in X, a \in R$, $A(ax) = aA(x)$

Matrix Representations:

Let $\{v_1, v_2, \dots, v_n\}$ be a basis for vector space X , and let $\{u_1, u_2, \dots, u_n\}$ be a basis for vector space Y . Let A be a linear transformation with domain X and range Y : $A(x) = y$

The coefficients of the matrix representation are obtained from

$$A(v_j) = \sum_{i=1}^m a_{ij} u_i$$

Change of Basis: $B_t = [t_1 \ t_2 \ \dots \ t_n]$, $B_w = [w_1 \ w_2 \ \dots \ w_n]$
 $A' = [B_w^{-1} A B_t]$

Eigenvalues & Eigenvectors: $Az = \lambda z$, $||A - \lambda I|| = 0$

Diagonalization: $B = [z_1 \ z_2 \ \dots \ z_n]$,

where $\{z_1, z_2, \dots, z_n\}$ are the eigenvectors of a square matrix A ,
 $[B^{-1}AB] = \text{diag}([\lambda_1 \ \lambda_2 \ \dots \ \lambda_n])$

Perceptron Architecture:

$$a = \text{hardlim}(Wp + b), \quad W = [w_1^T \ w_2^T \ \dots \ w_s^T]^T, \\ a_i = \text{hardlim}(n_i) = \text{hardlim}(w_i^T p + b_i)$$

Decision Boundary: $w^T p + b_i = 0$

The decision boundary is always orthogonal to the weight vector. Single-layer perceptrons can only classify linearly separable vectors.

Perceptron Learning Rule

$$W^{new} = W^{old} + ep^T, \quad b^{new} = b^{old} + e, \\ \text{where } e = t - a$$

Hebb's Postulate: "When an axon of cell A is near enough to excite a cell B and repeatedly or persistently takes part in firing it, some growth process or metabolic change takes place in one or both cells such that A's efficiency, as one of the cells firing B, is increased."

Linear Associator: $a = \text{purelin}(Wp)$

The Hebb Rule: Supervised Form: $w_{ij}^{new} = w_{ij}^{old} + t_{qi} p_{qi}$

$$W = t_1 P_1^T + t_2 P_2^T + \dots + t_q P_q^T$$

$$W = [t_1 \ t_2 \ \dots \ t_q] \begin{bmatrix} p_1^T \\ p_2^T \\ \vdots \\ p_q^T \end{bmatrix} = TP^T$$

Pseudoinverse Rule: $W = TP^+$

When the number, R , of rows of P is greater than the number of columns, Q , of P and the columns of P are independent, then the pseudoinverse can be computed by $P^+ = (P^T P)^{-1} P^T$

Variations of Hebbian Learning:

Filtered Learning (Ch.14): $W^{new} = (1 - \gamma)W^{old} + \alpha t_q p_q^T$

Delta Rule (Ch.10): $W^{new} = W^{old} + \alpha(t_q - a_q)p_q^T$

Unsupervised Hebb (Ch.13): $W^{new} = W^{old} + \alpha a_q p_q^T$

Taylor: $F(x) = F(x^*) + \nabla F(x^T)|_{x=x^*} (x - x^*) + \frac{1}{2} (x - x^*)^T \nabla^2 F(x^T)|_{x=x^*} (x - x^*) + \dots$

$$\text{Grad } \nabla F(x) = \left[\frac{\partial}{\partial x_1} F(x) \quad \frac{\partial}{\partial x_2} F(x) \quad \dots \quad \frac{\partial}{\partial x_n} F(x) \right]^T$$

Hessian: $\nabla^2 F(x) =$

$$\begin{bmatrix} \frac{\partial^2}{\partial x_1^2} F(x) & \frac{\partial^2}{\partial x_1 \partial x_2} F(x) & \dots & \frac{\partial^2}{\partial x_1 \partial x_n} F(x) \\ \frac{\partial^2}{\partial x_2 \partial x_1} F(x) & \frac{\partial^2}{\partial x_2^2} F(x) & \dots & \frac{\partial^2}{\partial x_2 \partial x_n} F(x) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2}{\partial x_n \partial x_1} F(x) & \frac{\partial^2}{\partial x_n \partial x_2} F(x) & \dots & \frac{\partial^2}{\partial x_n^2} F(x) \end{bmatrix}$$

Directional Derivatives:

$$\text{1st Dir.Der.: } \frac{p^T \nabla F(x)}{\|p\|}, \quad \text{2nd Dir.Der.: } \frac{p^T \nabla^2 F(x) p}{\|p\|^2}$$

Minima:

Strong Minimum: if a scalar $\delta > 0$ exists, such that $F(x) < F(x + \Delta x)$ for all Δx such that $\delta > \|\Delta x\| > 0$.

Global Minimum: if $F(x) < F(x + \Delta x)$ for all $\Delta x \neq 0$

Weak Minimum: if it is not a strong minimum, and a scalar $\delta > 0$ exists, such that $F(x) \leq F(x + \Delta x)$ for all Δx such that $\delta > \|\Delta x\| > 0$.

Necessary Conditions for Optimality:

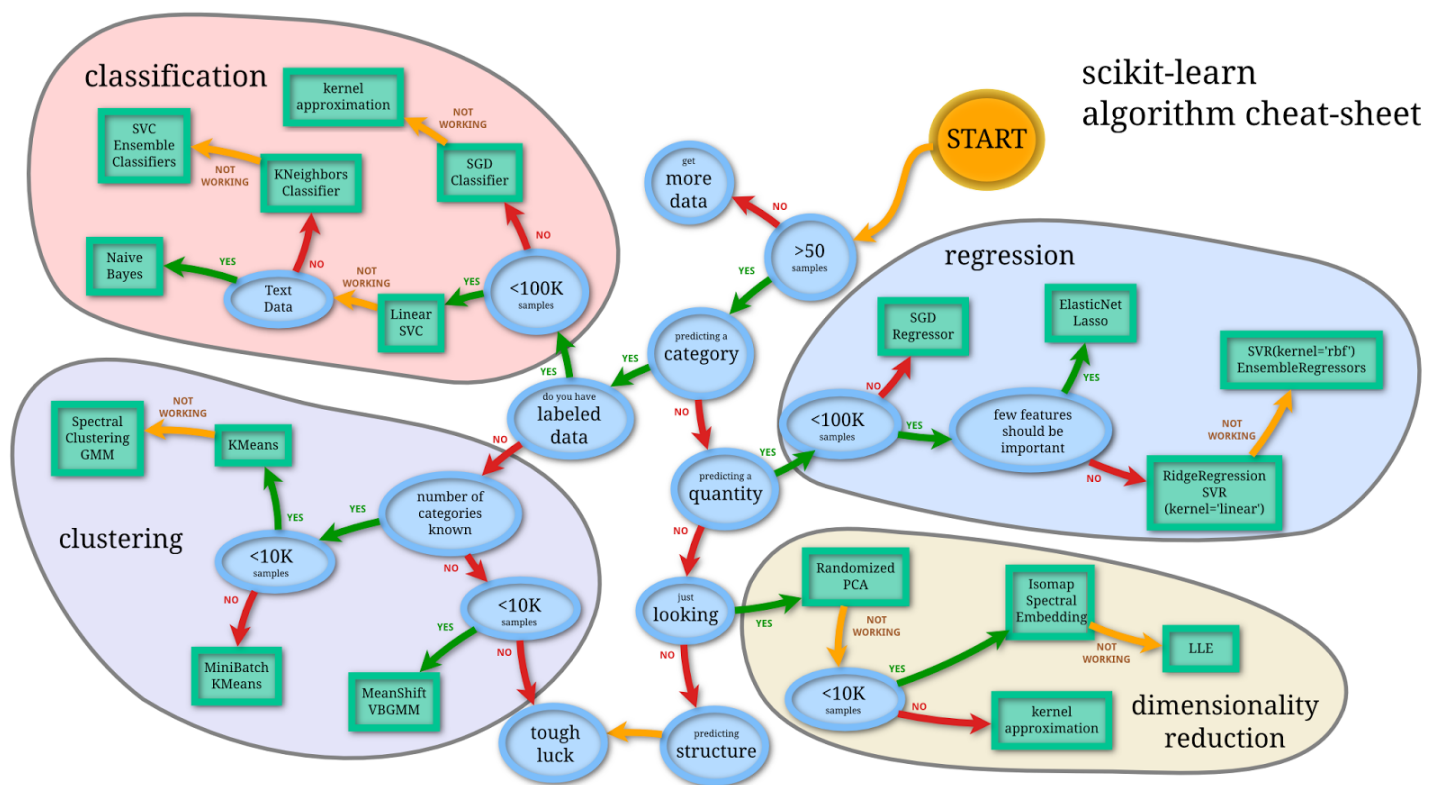
1st-Order Condition: $\nabla F(x)|_{x=x^*} = 0$ (Stationary Points)

2nd-Order Condition: $\nabla^2 F(x)|_{x=x^*} \geq 0$ (Positive Semi-definite Hessian Matrix).

Quadratic fn.: $F(x) = \frac{1}{2} x^T A x + d^T x + c$

$$\nabla F(x) = Ax + d, \quad \nabla^2 F(x) = A, \quad \lambda_{\min} \leq \frac{p^T A p}{\|p\|^2} \leq \lambda_{\max}$$

scikit-learn algorithm cheat-sheet



Python For Data Science Cheat Sheet

Scikit-Learn

Learn Python for data science Interactively at [www.DataCamp.com](https://www.datacamp.com)



Scikit-learn

Scikit-learn is an open source Python library that implements a range of machine learning, preprocessing, cross-validation and visualization algorithms using a unified interface.



A Basic Example

```
>>> from sklearn import neighbors, datasets, preprocessing
>>> from sklearn.cross_validation import train_test_split
>>> iris = datasets.load_iris()
>>> X, y = iris.data[:, :2], iris.target
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=33)
>>> scaler = preprocessing.StandardScaler().fit(X_train)
>>> X_train = scaler.transform(X_train)
>>> X_test = scaler.transform(X_test)
>>> knn = neighbors.KNeighborsClassifier(n_neighbors=5)
>>> knn.fit(X_train, y_train)
>>> y_pred = knn.predict(X_test)
>>> accuracy_score(y_test, y_pred)
```

Loading The Data

Also see NumPy & Pandas

Your data needs to be numeric and stored as NumPy arrays or SciPy sparse matrices. Other types that are convertible to numeric arrays, such as Pandas DataFrame, are also acceptable.

```
>>> import numpy as np
>>> X = np.random.random((10,5))
>>> y = np.array(['M','M','F','F','M','F','M','F','F','F'])
>>> X[X < 0.7] = 0
```

Training And Test Data

```
>>> from sklearn.cross_validation import train_test_split
>>> X_train, X_test, y_train, y_test = train_test_split(X,
y,
random_state=0)
```

Preprocessing The Data

Standardization

```
>>> from sklearn.preprocessing import StandardScaler
>>> scaler = StandardScaler().fit(X_train)
>>> standardized_X = scaler.transform(X_train)
>>> standardized_X_test = scaler.transform(X_test)
```

Normalization

```
>>> from sklearn.preprocessing import Normalizer
>>> scaler = Normalizer().fit(X_train)
>>> normalized_X = scaler.transform(X_train)
>>> normalized_X_test = scaler.transform(X_test)
```

Binarization

```
>>> from sklearn.preprocessing import Binarizer
>>> binarizer = Binarizer(threshold=0.0).fit(X)
>>> binary_X = binarizer.transform(X)
```

Encoding Categorical Features

```
>>> from sklearn.preprocessing import LabelEncoder
>>> enc = LabelEncoder()
>>> y = enc.fit_transform(y)
```

Imputing Missing Values

```
>>> from sklearn.preprocessing import Imputer
>>> imp = Imputer(missing_values=0, strategy='mean', axis=0)
>>> imp.fit_transform(X_train)
```

Generating Polynomial Features

```
>>> from sklearn.preprocessing import PolynomialFeatures
>>> poly = PolynomialFeatures(5)
>>> poly.fit_transform(X)
```

Create Your Model

Supervised Learning Estimators

Linear Regression

```
>>> from sklearn.linear_model import LinearRegression
>>> lr = LinearRegression(normalize=True)
```

Support Vector Machines (SVM)

```
>>> from sklearn.svm import SVC
>>> svc = SVC(kernel='linear')
```

Naive Bayes

```
>>> from sklearn.naive_bayes import GaussianNB
>>> gnb = GaussianNB()
```

KNN

```
>>> from sklearn import neighbors
>>> knn = neighbors.KNeighborsClassifier(n_neighbors=5)
```

Unsupervised Learning Estimators

Principal Component Analysis (PCA)

```
>>> from sklearn.decomposition import PCA
>>> pca = PCA(n_components=0.95)
```

K Means

```
>>> from sklearn.cluster import KMeans
>>> k_means = KMeans(n_clusters=3, random_state=0)
```

Model Fitting

Supervised learning

```
>>> lr.fit(X, y)
>>> knn.fit(X_train, y_train)
>>> svc.fit(X_train, y_train)
```

Fit the model to the data

Unsupervised Learning

```
>>> k_means.fit(X_train)
>>> pca_model = pca.fit_transform(X_train)
```

Fit the model to the data
Fit to data, then transform it

Prediction

Supervised Estimators

```
>>> y_pred = svc.predict(np.random.random((2,5)))
>>> y_pred = lr.predict(X_test)
```

Predict labels
Predict labels
Estimate probability of a label

Unsupervised Estimators

```
>>> y_pred = k_means.predict(X_test)
```

Predict labels in clustering algos

Evaluate Your Model's Performance

Classification Metrics

Accuracy Score

```
>>> knn.score(X_test, y_test)
>>> from sklearn.metrics import accuracy_score
>>> accuracy_score(y_test, y_pred)
```

Estimator score method
Metric scoring functions

Classification Report

```
>>> from sklearn.metrics import classification_report
>>> print(classification_report(y_test, y_pred))
```

Precision, recall, f1-score
and support

Confusion Matrix

```
>>> from sklearn.metrics import confusion_matrix
>>> print(confusion_matrix(y_test, y_pred))
```

Regression Metrics

Mean Absolute Error

```
>>> from sklearn.metrics import mean_absolute_error
>>> y_true = [3, -0.5, 2]
>>> mean_absolute_error(y_true, y_pred)
```

Mean Squared Error

```
>>> from sklearn.metrics import mean_squared_error
>>> mean_squared_error(y_test, y_pred)
```

R² Score

```
>>> from sklearn.metrics import r2_score
>>> r2_score(y_true, y_pred)
```

Clustering Metrics

Adjusted Rand Index

```
>>> from sklearn.metrics import adjusted_rand_score
>>> adjusted_rand_score(y_true, y_pred)
```

Homogeneity

```
>>> from sklearn.metrics import homogeneity_score
>>> homogeneity_score(y_true, y_pred)
```

V-measure

```
>>> from sklearn.metrics import v_measure_score
>>> metrics.v_measure_score(y_true, y_pred)
```

Cross-Validation

```
>>> from sklearn.cross_validation import cross_val_score
>>> print(cross_val_score(knn, X_train, y_train, cv=4))
>>> print(cross_val_score(lr, X, y, cv=2))
```

Tune Your Model

Grid Search

```
>>> from sklearn.grid_search import GridSearchCV
>>> params = {"n_neighbors": np.arange(1,3),
"metric": ["euclidean", "cityblock"]}
>>> grid = GridSearchCV(estimator=knn,
param_grid=params)
>>> grid.fit(X_train, y_train)
>>> print(grid.best_score_)
>>> print(grid.best_estimator_.n_neighbors)
```

Randomized Parameter Optimization

```
>>> from sklearn.grid_search import RandomizedSearchCV
>>> params = {"n_neighbors": range(1,5),
"weights": ["uniform", "distance"]}
>>> rsearch = RandomizedSearchCV(estimator=knn,
param_distributions=params,
cv=4,
n_iter=8,
random_state=5)
>>> rsearch.fit(X_train, y_train)
>>> print(rsearch.best_score_)
```

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