Aiding Measurement Control (0x0D,0x50)

<table>
<tr><td>Description</td><td colspan="2">Enables / disables the specified aiding measurement source.</td></tr>
<tr><td>Notes</td><td colspan="2"></td></tr>
<tr><td>Parameter Name</td><td>Data Type</td><td>Description</td></tr>
<tr><td>Field Length</td><td>u8</td><td>6</td></tr>
<tr><td>Descriptor</td><td>u8</td><td>0x50</td></tr>
<tr><td>Function Selector</td><td>u8</td><td>This command supports the following MIP function selectors:
<code>Write Read Save Load Default [WRSLD]</code></td></tr>
<tr><td>Aiding Source
<code>[WRSLD]</code></td><td>u16
enum</td><td>Aiding measurement source
<table>
<tr><th>Name</th><th>Value</th><th>Description</th></tr>
<tr><td>GNSS_POS_VEL</td><td>0</td><td>GNSS Position and Velocity</td></tr>
<tr><td>GNSS_HEADING</td><td>1</td><td>GNSS Heading (dual antenna)</td></tr>
<tr><td>ALTIMETER</td><td>2</td><td>Pressure altimeter (built-in sensor)</td></tr>
<tr><td>SPEED</td><td>3</td><td>Speed sensor / Odometer</td></tr>
<tr><td>MAGNETOMETER</td><td>4</td><td>Magnetometer (built-in sensor)</td></tr>
<tr><td>EXTERNAL_HEADING</td><td>5</td><td>External heading input</td></tr>
<tr><td>EXTERNAL_ALTIMETER</td><td>6</td><td>External pressure altimeter input</td></tr>
<tr><td>EXTERNAL_MAGNETOMETER</td><td>7</td><td>External magnetomer input</td></tr>
<tr><td>BODY_FRAME_VEL</td><td>8</td><td>External body frame velocity input</td></tr>
<tr><td>ALL</td><td>65535</td><td>Save/load/reset all options</td></tr>
</table></td></tr>
<tr><td>Enable <code>[W]</code></td><td>bool</td><td>Controls the aiding source</td></tr>
<tr><td>Ack/Nack Reply</td><td colspan="2">See standard MIP ack/nack reply format.</td></tr>
<tr><td>Response Data</td><td>Data Type</td><td>Description</td></tr>
<tr><td>Response Length</td><td>u8</td><td>5</td></tr>
<tr><td>Response Descriptor</td><td>u8</td><td>0xD0</td></tr>
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