ACIT4710 December 16th, 2021

Problem 1 (16%)

Classify the systems below, represented by their difference equation or transfer function, with respect to the following properties:

1. Stability: Stable, marginally stable, or unstable

2. Linearity: Linear or non-linear

3. Causality: Causal or non-causal

4. Time variance: Time invariant or time-variant

Classify all system according to all four properties. The systems are:

a)
$$y(n) = 1.5y(n-1) + nx(n) - x(n-1)$$

b)
$$y(n) = 0.5y(n-1) + x(n) \cdot x(n+1)$$

c)
$$H(z) = \frac{z-0.5}{z-1}$$

d)
$$H(z) = z - z^{-1}$$

Solutions 1

a) Unstable, linear, causal and time variant

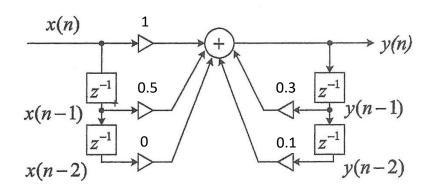
b) Stable, non-linear, non-causal and time invariant

c) Marginally stable, linear, causal, time invariant

d) Stable, linear, non-causal, time invariant.

<u>Problem 2 (21%)</u>

A time discrete circuit is shown below:



a) Determine the difference equation of the circuit.

b) Determine the transfer function of the circuit, H(z) = Y(z)/X(z).

c) Determine the zeros and the poles of the circuit.

d) Determine the impulse response, h(n), of the circuit, the response when $x(t) = \delta(t)$.

Solution 2

a) y(n) = 0.3y(n-1) + 0.1y(n-2) + x(n) + 0.5x(n-1)

b)
$$Y(z)[1 - 0.3z^{-1} - 0.1z^{-2}] = X(z)[1 + 0.5z^{-1}]$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{z^2 + 0.5z}{z^2 - 0.3z - 0.1} = \frac{z(z + 0.5)}{(z - 0.5)(z + 0.2)}$$

c) Zeros: z = 0 and z = -0.5; Poles: z = 0.5 and z = -0.2

d)
$$h(n) = Z^{-1}\{H(z)\}$$

$$\frac{H(z)}{z} = \frac{z + 0.5}{(z - 0.5)(z + 0.2)} = \frac{a}{z - 0.5} + \frac{b}{z + 0.2} = \frac{1.43}{z - 0.5} + \frac{-0.43}{z + 0.2}$$

$$H(z) = \frac{1.43z}{z - 0.5} - \frac{0.43z}{z + 0.2}$$

$$h(n) = [1.43(0.5)^n - 0.43(-0.2)^n]u(n)$$

Problem 3 (21%)

Design a FIR high pass filter using the window design method with the following specifications:

Sampling frequency = 20kHz

Pass band: 5 - 10 kHz with maximum pass band ripple, $\delta p = 1$ dB

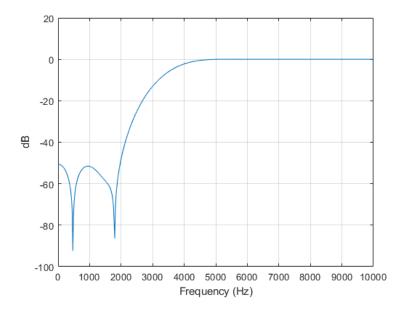
Stop band: 0 - 2kHz with minimum stop band attenuation, $\delta s = 50dB$

- a) Determine the required window function, estimate the required order, and calculate the cut-off frequency, using Table 7.7 in the textbook.
- b) Use MATLAB to calculate the amplitude response of the filter.
- c) Check the gain at 2000Hz and 5000Hz to find out if the filter fulfills all design specification.

Solution 3

a) Hamming window, $\Delta f=3/20$, N=3.3/3*20=22, fc=(2+5)/2=3.5kHz

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b) % Solution 3 b)
fs=20000; % sampling frequency
fc=3500; % cut-off frequency
wn=2*fc/fs; % normalized cut-off
N=22; % filter order
B=fir1(N,wn,'high'); % filter coeffisients, Hamming window as default
[H,f]=freqz(B,1,1000,fs); % frequency response
plot(f,20*log10(abs(H))); grid; xlabel('Frequency (Hz)'); ylabel('dB');
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c)

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% c) Find gain at 2000 and 5000Hz
H1=20*log10(abs(H(201)))
H2=20*log10(abs(H(501)))
H1=-48
H2=-0.022
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The frequency response is well above -1dB from 5000Hz and upwards, the passband criteria is fulfilled. The frequency response is -48dB at 2000Hz and the stopband criteria is therefore marginally violated.

Problem 4 (21%)

Design an IIR bandpass filter using the bilinear transform of a Butterworth filter with the following specifications:

Sampling frequency: 20kHz

Pass band: 4 - 6kHz, with maximum pass band ripple, $\delta p = 1dB$

Stop band: 0 - 2kHz and 8 - 10kHz, with minimum stop band attenuation, $\delta s = 40dB$

- a) Determine the required order of the prototype filter and the design frequencies (-3dB-frequencies)
- b) Determine the discrete transfer function of the filter, H(z).
- c) Plot the amplitude response

Solution 4

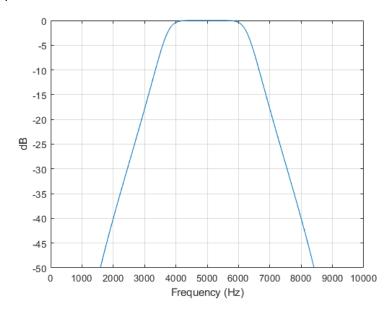
- a) N=4; Design frequencies: 3693 and 6307
- b) Order of bandpass filter is 8.

$$\begin{split} B = & [0.011823318211291, 0, -0.047293272845165, 0, 0.070939909267747, 0, \\ & 0.047293272845165, 0, 0.011823318211291] \end{split}$$

A=[1,-2.109423746787797e-15,1.877826823427847,-1.346145417358002e-15,1.621355274174814,-2.498001805406602e-16,0.663018614948618,0,0.108663255582310]

$$H(z) = \frac{0.0118z^8 - 0.0473z^6 + 0.0709z^4 - 0.0473z^2 + 0.0118}{z^8 + 1.878z^6 + 1.621z^4 + 0.6630z^2 + 0.1087}$$

c)



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% Solution 4
fs=20000; % sampling frequency
wp=[4000 6000]*2/fs; % passband
ws=[2000 8000]*2/fs; % stopband
dp=1; % passband rippel
ds=40; % stopband attenuation
[N,wn]=buttord(wp,ws,dp,ds); % prototype filter
[B,A]=butter(N,wn); % Butterworth filter
[H,f]=freqz(B,A,512,fs); % frequency response
plot(f,20*log10(abs(H))); grid; xlabel('Frequency (Hz)');
ylabel('dB');
axis([0 10000 -50 0])
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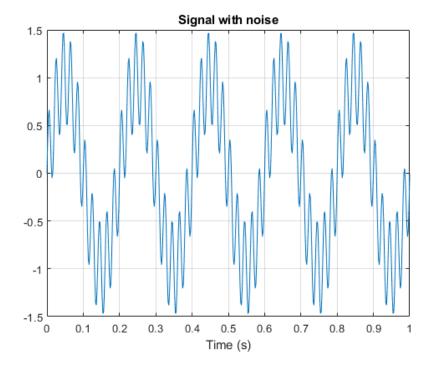
Problem 5 (21%)

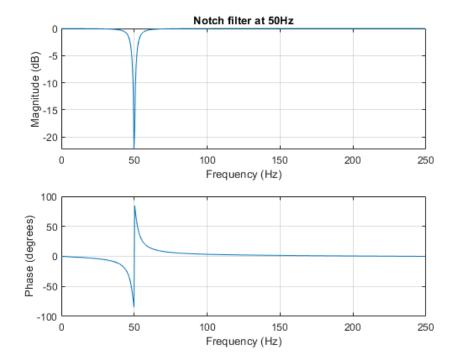
- a) Generate a signal $x(nT) = \sin(2\pi 5nT) + 0.5\sin(2\pi 50nT)$. The 5Hz signal is the signal you want to measure, but the signal is contaminated with a 50Hz that we regard as noise. Plot the signal with noise for a period of 1 sec. Use a sampling period of T=2ms.
- b) Design a notch filter by placing the zeros at $z = \exp(\pm j\theta)$ and the poles at $z = r \cdot \exp(\pm j\theta)$. Determine r and θ for the filter when the 3dB-band width should be 5Hz and the center frequency is matched to the 50Hz noise signal above. Plot the frequency response of the filter.
- c) Filter the signal generated in a) with the filter designed in b) and plot the filtered signal as function of time for 1 sec.

Solution 5

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% Solution 5
% a) generate signal and noise
         % sampling period
T=0.002;
t= 0:T:1;
          % time axis
f1=5;
          % signal frequency
f2=50;
          % noise frequency
x=sin(2*pi*f1*t)+0.5*sin(2*pi*f2*t); % signal + noise
plot(t,x); grid; title('Signal with noise'); xlabel('Time (s)');
% b) Design of Notch filter
fs=1/T; % sampling frequency
th=(50/fs)*2*pi; % angle for 50Hz
r=1-(5/fs)*pi;
                  % radius of poles
K = (1-2*r*cos(th)+r^2)/(2-2*cos(th));
                                      % gain
B=K*[1 -2*cos(th) 1]; % nummerator of H(z)
A=[1 -2*r*cos(th) r^2];
                           % denominator of H(z)
figure;
freqz(B,A,512,fs); title('Notch filter at 50Hz')
% c) Filtering of signal
y=filter(B,A,x);
figure;
plot(t,y); grid; title('Filtered signal'); xlabel('Time (s)')
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a)





c)

