

# Adam Conkey

adam.conkey@gmail.com  
adamconkey.github.io  
(330) 224-1159

## EDUCATION

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- **University of Utah** Salt Lake City, UT  
*Ph.D. Computing: Robotics – GPA: 3.9* Aug 2016 – Dec 2022
- **DePaul University** Chicago, IL  
*M.S. Computer Science: Artificial Intelligence – GPA: 4.0* Jan 2014 – Jun 2016
- **Carnegie Mellon University** Pittsburgh, PA  
*B.S. Mathematics and Philosophy – GPA: 3.4* Aug 2007 – May 2011

## PROFESSIONAL EXPERIENCE

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- **HRL Laboratories** Malibu, CA  
*Robotics Machine Learning Research Scientist* Aug 2022 – Present
  - Developing mission-focused solutions for autonomous robot manipulation in undersea environments.
- **Utah Learning Lab for Manipulation Autonomy** Salt Lake City, UT  
*Graduate Research Assistant (Advisor: Tucker Hermans)* Aug 2016 – Dec 2022
  - Investigated deep learning approaches to multisensory representation learning for skill planning.
  - Formulated and implemented a new algorithm for robot motion planning under uncertainty.
  - Developed novel methods for learning robot skills from human demonstration with movement primitives.
- **Amazon Robotics** North Reading, MA  
*Research Scientist Intern: Advanced Robotics* May 2019 – Aug 2019
  - Implemented an end-to-end robotic system for performing a material handling task using C++ and ROS.
  - Developed a Python application for discrete event simulation, visualization, and timing analysis.
- **Accenture** Austin, TX  
*Associate Software Engineer* Apr 2015 – Jul 2016
  - Developed new front-end and back-end application features for state healthcare exchanges.
  - Engaged as a versatile member of an Agile Scrum team for Java, SQL, and user interface development.
- **United States Patent and Trademark Office** Alexandria, VA  
*Patent Examiner in Computer Science* May 2012 – Nov 2013
  - Examined patent applications in the art of compiler design and software development tools.
  - Conducted exhaustive searches of prior art to issue decisions on the patentability of claimed inventions.

## SKILLS

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- **Languages:** Python (*Advanced*) C++ (*Intermediate*), Java (*Beginner*), Rust (*Learning*)
- **Software:** ROS1, ROS2, MoveIt, PyTorch, TensorFlow (Keras API), OpenCV, Qt (rviz plugins)
- **Simulators:** Drake, NVIDIA Isaac Gym, Gazebo, DART, CoppeliaSim, PyBullet
- **Robots:** Orion 7P, KUKA iiwa, KUKA LBR4+, FANUC Cobot, Rethink Robotics Baxter
- **Sensors:** RealSense RGB-D cameras, Kinect RGB-D cameras, Optoforce 6-Axis Force/Torque sensor
- **Misc:** Linux, Git, Docker, Jenkins, LaTeX

## PUBLICATIONS

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- Y. Huang, A. Conkey, and T. Hermans. “Planning for Multi-Object Manipulation with Graph Neural Network Relational Classifiers”. *International Conference on Robotics and Automation (ICRA)*, 2023.
- A. Conkey “Skill Planning Under State and Goal Uncertainty for Robot Manipulation Tasks”. *Ph.D. dissertation*, 2022.
- A. Conkey and T. Hermans. “Planning under Uncertainty to Goal Distributions”. *arXiv preprint*, 2021.
- A. Conkey, “Representation Learning for Multisensory Perception and Planning.” *Robotics: Science and Systems (RSS) Pioneers Workshop*, 2020.
- A. Conkey and T. Hermans. “Active Learning of Probabilistic Movement Primitives.” *IEEE-RAS International Conference on Humanoid Robots (Humanoids)*, 2019.
- A. Conkey and T. Hermans. “Learning Task Constraints from Demonstration for Hybrid Force/Position Control.” *IEEE-RAS International Conference on Humanoid Robots (Humanoids)*, 2019.