

# Appendix 1. Stability selection

## Methods

We applied stability selection (Meinshausen and Bühlmann 2010, Shah and Samworth 2013) to identify base-learners, and thus covariates, that were commonly selected in the majority of 100 randomly *drawn* subsamples *of size*  $\lfloor n/2 \rfloor$  of the data. *As proposed by Shah and Samworth (2013), we used  $B = 50$  complementary pairs subsamples, i.e., we randomly split the data into two halves and used both to independently fit the model. This led to 100 subsamples all together.* We set the number of selected base-learners per boosting model ( $q$ ) to 35 and established an upper bound of two for the per-family error rate (PFER; Meinshausen and Bühlmann 2010, Shah and Samworth 2013, see also Hofner et al. 2015 for details in the context of boosting)  $\sim \sim$  which, given the 48 base-learners in the occupancy and count models (see Equation 1 in manuscript),  $\sim \sim$ . *This error bound* corresponded to an upper bound of  $\alpha = 0.042$  for the per-comparison error rate *in the occupancy model and an upper bound of  $\alpha = 0.021$  in the count model.* *The choice of  $q$  is rather arbitrary as long as it is large enough to incorporate all important variables in the model (Hofner et al. 2015).* *We used the unimodality assumption for the computation of the error bounds in the occupancy model and, to be less conservative, we used the r-concavity assumption in the count model (Shah and Samworth 2013, Hofner et al. 2015).*

~~Benjamin: can you check my calculation? Also, should we explain why we chose  $q = 35$ , or describe complementary pairs subsampling and our choice of unimodal vs. r-concavity assumptions for the two model type (occupancy vs. count)? Any other relevant details to include?~~

*BH: As you can see from the different thresholds we have a different number of base-learners in the two models. The occupancy model really has 48 base-learners but the count model has twice as many, i.e., 96 base-learners, 48 for the mean and 48 for the dispersion parameter. Furthermore, if you print any of the stabsel objects, you will find the (realized) PCER given as 0.0208 ( $= 1/48$ ) for the occupancy model and 0.0188 ( $= 1.8 / 96$ ) for the count model.*

*BH: I need to check here why the upper bound for the PFER is specified as 2 but the PFER is then given as 1.*

*BH: We could (and should) state the further assumptions (unimodality and r-concavity). Do you remember the reason why we use different assumptions for the two models? I added a sentence. Is this correct and do we want to keep it? Perhaps it raises more questions than it answers.*

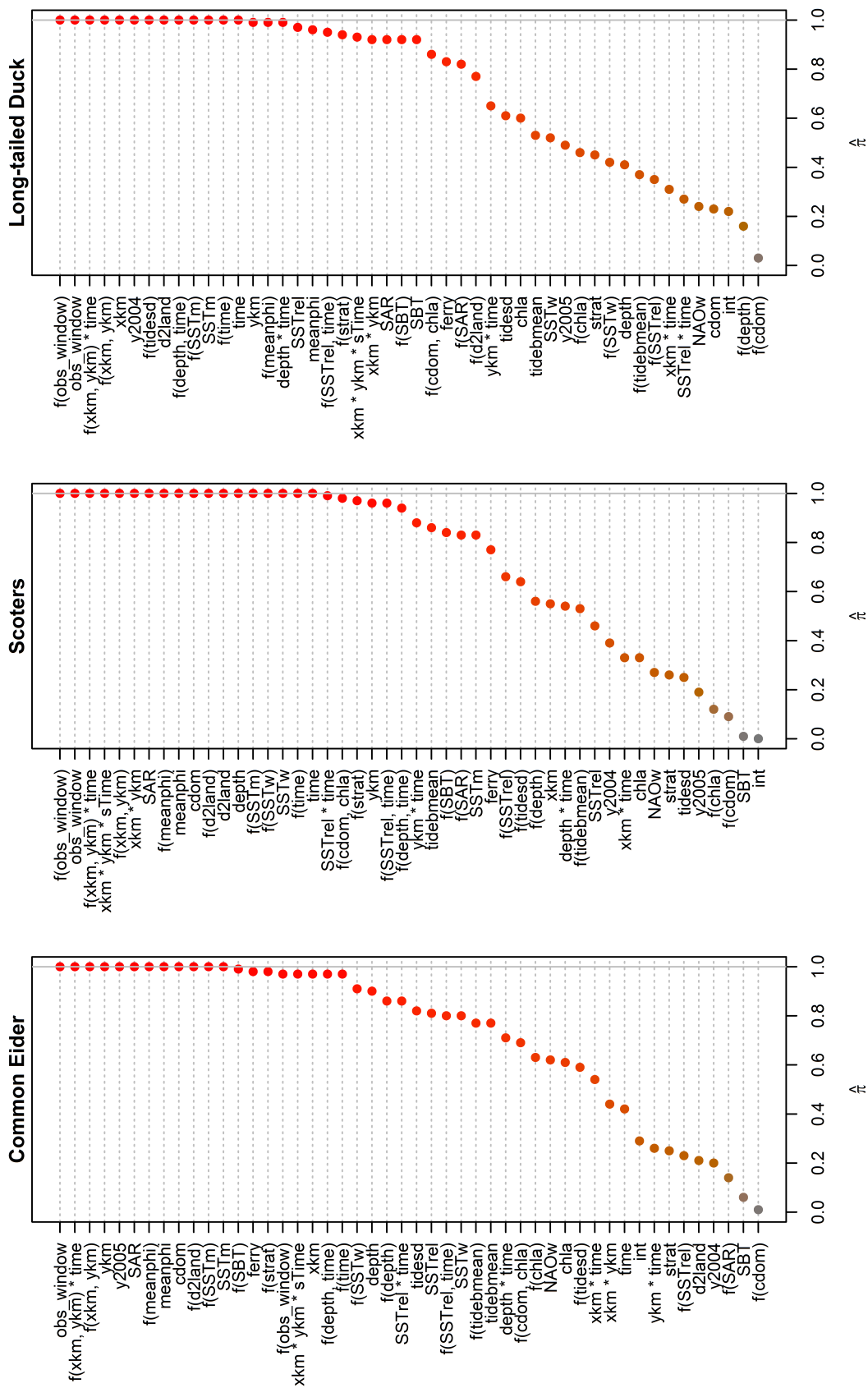
## Results

### Occupancy models

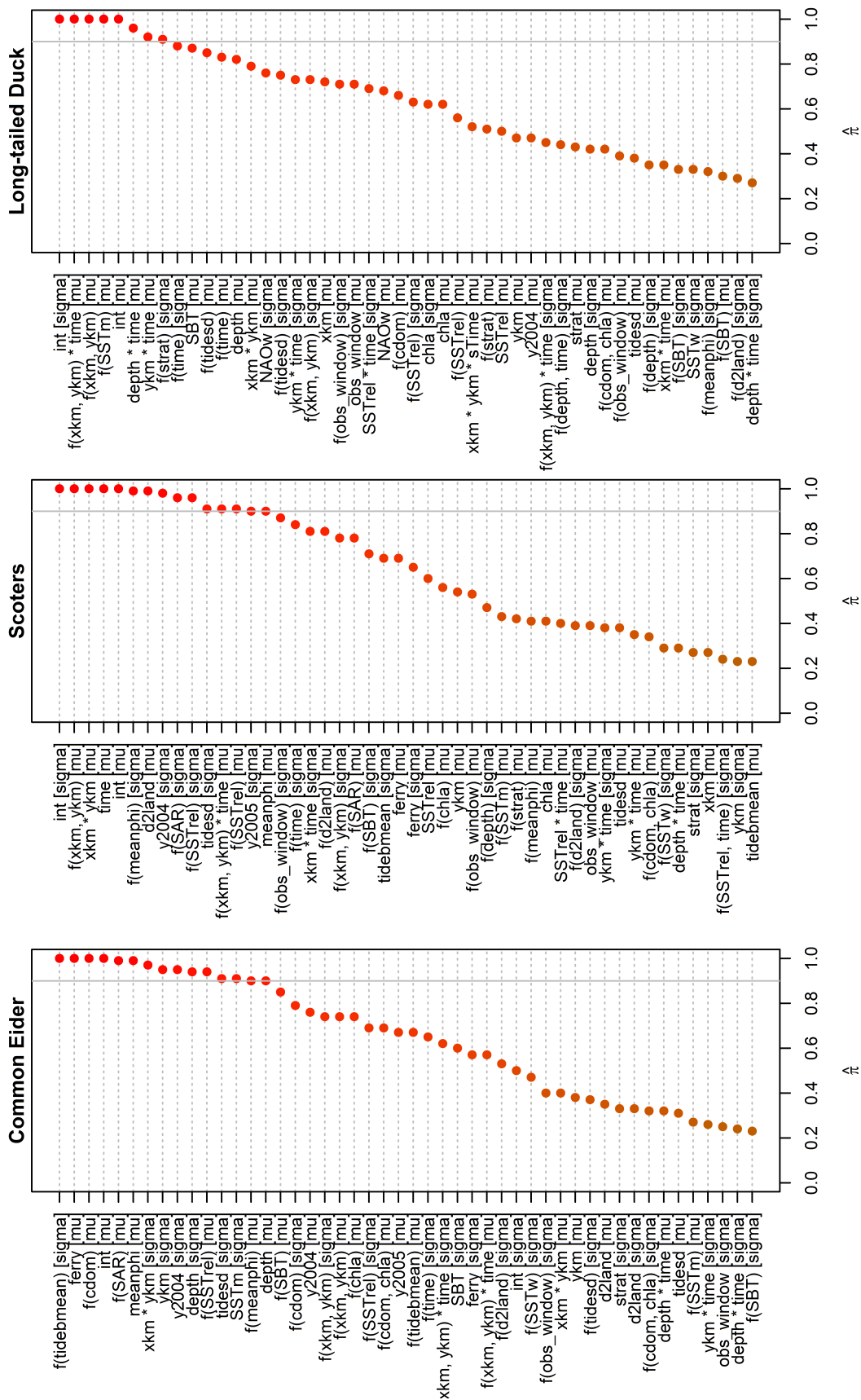
Given our specifications ( $q = 35$ ; PFER upper-bound = 2, ***unimodality assumption***), only base-learners selected in all 100 subsamples (i.e.,  $\hat{\pi} = 1$ ) were identified as stable (Figure 1.1).

### Count models

Given our specifications ( $q = 35$ ; PFER upper-bound = 2, ***r-concavity assumption***), only base-learners selected in at least 90 of the 100 subsamples (i.e.,  $\hat{\pi} = 0.9$ ) were identified as stable; this threshold applies to the selection of base-learners for the conditional mean ( $\mu$ ) and conditional overdispersion ( $\sigma$ ) ***simultaneously***.



**Figure 1.1** Stability selection using complementary pairs subsampling and unimodality assumption for sea duck occupancy models. The number of selected base-learners in each model run was set to  $q = 35$ . Base-learners with selection frequencies above the threshold ( $\hat{\pi}$ ; vertical gray line) were considered stable with upper bound  $\text{PFER} = 2$ .



**Figure 1.2** Stability selection using complementary pairs subsampling and r-concavity assumption for sea duck conditional count models. The number of selected base-learners in each model run was set to  $q = 35$ . Base-learners with selection frequencies above the threshold ( $\hat{\pi}$ ; vertical gray line) were considered stable with upper bound PFER = 2. Only the top 48 base-learners are illustrated. Brackets indicate the parameter (conditional mean,  $\mu$ , or overdispersion,  $\sigma$ ) to which the base-learner applies.

## Literature cited

- Hofner, B., L. Boccuto, and M. Göker. 2015. Controlling false discoveries in high-dimensional situations: Boosting with stability selection. *BMC Bioinformatics* 16:144.
- Meinshausen, N., and P. Bühlmann. 2010. Stability selection (with discussion). *Journal of the Royal Statistical Society: Series B (Statistical Methodology)* 72:417–473.
- Shah, R. D., and R. J. Samworth. 2013. Variable selection with error control: another look at stability selection. *Journal of the Royal Statistical Society: Series B (Statistical Methodology)* 75:55–80.