```
#include " kernelCore.h"
     #include "osDefs.h"
 3
 4
    //global variables
 5
    extern threadStruct threadCollection[MAX THREADS];
 6
    mutexStruct mutexCollection[MAX THREADS];
    extern int numThreads;
8
    int threadCurr = 0;
 9
    int numMutex = 0;
10
    extern int idleIndex;
11
    bool leaveIdle = false;
12
13
    //set priority of the PendSV interrupt
14
15
    void kernelInit(void) {
16
      //PendSV priority
17
       SHPR3 \mid = 0xFE << 16;
18
       SHPR3 |= 0xFFU << 24; //SysTick priority
19
20
       SHPR2 \mid= 0xFDU << 24; //SVC priority
21
    }
22
23
    //start running the kernel, i.e. the OS
24
    bool osKernelStart() {
25
       threadCurr = 0;
26
       if(numThreads > 0)
27
28
           set CONTROL(1<<1); //enter threading</pre>
29
          set PSP((uint32 t) threadCollection[threadCurr].TSP); //set PSP to the first thread address
30
31
         osLoadFirst(); //begin running threads
32
       }
33
34
       return false; //once called, function should not end unless something went wrong in OS
3.5
    }
36
37
    //create a new mutex in the mutex struct array
38
    void osCreateMutex(){
39
       mutexCollection[numMutex].available = true;
40
       mutexCollection[numMutex].currentOwner = NONE;
41
42
       numMutex++;
43
44
4.5
    //determine if the thread is allowed to run otherwise block
    void osAcquireMutex(int mutexID) {
47
      //if running thread can acquire the mutex, then acquire and proceed running thread
48
      if (mutexCollection[mutexID].available == true) {
49
        mutexCollection[mutexID].available = false;
50
        mutexCollection[mutexID].currentOwner = threadCurr;
51
52
         printf("Mutex %d acquired by Thread %d\n", mutexID, threadCurr+1);
53
       }
54
       //if the mutex is already claimed by another thread, add this thread to the blocked list and switch
55
      else if (mutexCollection[mutexID].available == false && mutexCollection[mutexID].currentOwner !=
     threadCurr) {
56
         threadCollection[threadCurr].status = BLOCKED;
57
         threadCollection[threadCurr].timer = 0; //start counting time blocked
58
         threadCollection[threadCurr].waitMutex = mutexID;
59
        printf("Mutex %d already claimed by Thread %d. Set Thread %d to blocked\n", mutexID,
60
     mutexCollection[mutexID].currentOwner+1, threadCurr+1);
61
62
         //switch out thread, by a mutex yield
         __ASM("SVC #1");
63
64
       }
6.5
       else{
         printf("Repeated claim of mutex %d\n", mutexID);
66
67
     }
68
69
```

```
//make mutex available and/or give it to the next blocked thread
 71
      void osReleaseMutex(int mutexID) {
 72
        int longestWait = 0;
 73
        bool isFound = false;
 74
 75
        //do not do release mutex sequence if called by a thread that is not the mutex owner
 76
        if (mutexCollection[mutexID].currentOwner == threadCurr) {
 77
 78
          for (int i = 0; i < numThreads; i++) {
 79
            //look for at least one thread blocked by the current mutex
 80
            if (threadCollection[i].status == BLOCKED && threadCollection[i].waitMutex == mutexID) {
 81
              isFound = true;
 82
              longestWait = i;
 83
 84
              printf("Found Thread %d. Timer: %d\n", i+1, threadCollection[i].timer);
 8.5
 87
            //if found, start looking for the thread that has been waiting the longest
 88
            if (isFound == true && threadCollection[i].timer < threadCollection[longestWait].timer) {</pre>
 89
              longestWait = i;
 90
 91
              printf("Found Thread %d. Timer: %d\n", i+1, threadCollection[i].timer);
 92
            }
 93
 94
          if (isFound == true) {
 95
            //remove longestWait thread from the blocked queue, so that it is in the round-robin next time
      scheduler() is called
 96
            threadCollection[longestWait].status = WAITING;
 97
            threadCollection[longestWait].timer = threadCollection[longestWait].timeslice;
 98
            threadCollection[longestWait].waitMutex = NONE;
 99
            //give longestWait thread the mutex
100
101
            mutexCollection[mutexID].available = false;
102
            mutexCollection[mutexID].currentOwner = longestWait;
103
104
            printf("Give Mutex %d to Thread %d\n", mutexID, longestWait+1);
105
106
          else{ //if no blocked threads, just make the mutex available
107
            mutexCollection[mutexID].available = true;
108
            mutexCollection[mutexID].currentOwner = NONE;
109
110
            printf("No blocked threads for Mutex %d, is now available\n", mutexID);
111
112
        }
113
114
          printf("Thread %d does not own mutex %d. Will not release.\n", threadCurr, mutexID);
115
116
117
      }
118
119
120
      //start running the first thread, which will lead into context switching between all the threads
121
      void osLoadFirst() {
122
          ICSR |= 1 << 28;
123
           asm("isb");
124
125
126
      //called when a thread yields, starts task switching process
127
      void osYield(void) {
128
        //Call SVC
129
         ASM("SVC #0");
130
131
132
     //determine next available thread to switch to
133
     void scheduler(void) {
134
       bool isFound = false;
        int index = threadCurr;
135
136
        if(threadCurr == idleIndex) {
137
          index = threadCurr-1; //want to cycle through the valid thread indexes
138
139
        if (numThreads > 1) {
140
```

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```
for (int i = 0; i < numThreads && isFound == false; i++) {</pre>
142
            //cycle through the threads in the thread struct array
143
            index = (index+1)%numThreads;
144
           printf("Trying thread %d\n", index+1);
145
146
           //check status: if next thread in round robin is waiting, proceed! else, loop back and look at
     next thread
147
           if (threadCollection[index].status == WAITING) {
148
              threadCurr = index;
149
              isFound = true;
150
151
          }
152
153
          //if no threads are waiting, use idle thread
154
         if(isFound != true){
155
           printf("all the people of the world are asleep\n");
156
           threadCurr = idleIndex;
157
158
       }
159
     }
160
161
     void SysTick Handler(void) {
162
       //printf("thread num %d, timer: %d\n", threadCurr+1, threadCollection[threadCurr].timer);
163
164
        //decrement the running thread's timeslice, sleep timers, and blocked timers
165
        for(int i = 0; i < numThreads; i++) {</pre>
166
          if(threadCollection[i].status != WAITING) {
167
            --threadCollection[threadCurr].timer;
168
169
170
          if(threadCollection[i].status == SLEEPING)
171
172
            /*if(threadCollection[i].timer % 50 == 0){
173
             printf("Thread %d sleeptime: %d \n", (i+1), threadCollection[i].timer);
174
175
176
           //check wake-up status
177
           if (threadCollection[i].timer <= 0)</pre>
178
179
              if(threadCurr == idleIndex) {
180
               leaveIdle = true;
181
182
             threadCollection[i].status = WAITING;
183
             threadCollection[i].timer = threadCollection[i].timeslice;
184
185
         }
186
       }
187
188
        //if timeslice of running thread is up, proceed with task-switching
189
        if((threadCollection[threadCurr].timer <= 0 && threadCollection[threadCurr].status != BLOCKED) ||</pre>
     leaveIdle == true)
190
191
         printf("Thread %d timer complete\n", threadCurr+1);
         192
      lower, since the hardware registers remain on the stack
193
          //prepare current thread to sleep if can sleep
194
          if (threadCollection[threadCurr].sleepTime != 0) {
195
            threadCollection[threadCurr].status = SLEEPING;
            threadCollection[threadCurr].timer = threadCollection[threadCurr].sleepTime;
196
197
198
          //if thread doesn't sleep, set status to waiting and timer to timeslice
199
200
            threadCollection[threadCurr].status = WAITING;
201
            threadCollection[threadCurr].timer = threadCollection[threadCurr].timeslice;
202
203
          //if a thread woke up, return to round robin
204
          if(leaveIdle == true) {
205
            threadCurr = idleIndex-1;
206
            leaveIdle = false;
207
208
209
          scheduler();
```

```
211
          ICSR |= 1 << 28;
          __asm("isb");
212
213
214
      }
215
216
      void SVC Handler Main(uint32 t *svc args)
217
218
        char call = ((char*)svc args[6])[-2];
219
220
        if(call == 0) //from osYield()
221
222
          //move TSP of the running thread 16 memory locations lower, so that next time the thread loads the
      16 context registers, we end at the same PSP
223
          threadCollection[threadCurr].TSP = (uint32 t*)(_get_PSP()-8*4);
224
225
          //if the thread is able to sleep, set it to sleep
226
          if(threadCollection[threadCurr].sleepTime != 0){
227
            threadCollection[threadCurr].status = SLEEPING;
228
            threadCollection[threadCurr].timer = threadCollection[threadCurr].sleepTime; //set timer to
      user-defined sleep timer
229
230
          //otherwise, set it back to waiting
231
          else{
232
            threadCollection[threadCurr].status = WAITING;
233
234
235
          scheduler();
236
237
          ICSR |= 1<<28;
          __asm("isb");
238
239
240
241
        if(call == 1){ //from thread being blocked in osAcquireMutex()
242
          threadCollection[threadCurr].TSP = (uint32 t*)(__get_PSP()-8*4);
243
          scheduler();
244
245
          ICSR |= 1<<28;
          __asm("isb");
246
247
248
249
250
251
      int task switch(void){
252
       //set PSP to the thread we want to start running
253
         set PSP((uint32 t)threadCollection[threadCurr].TSP);
254
        threadCollection[threadCurr].status = ACTIVE;
255
256
        if (threadCurr == numThreads ) {
257
          printf("Running idle thread \n");
258
        }
259
        return 0;
260
261
262
```