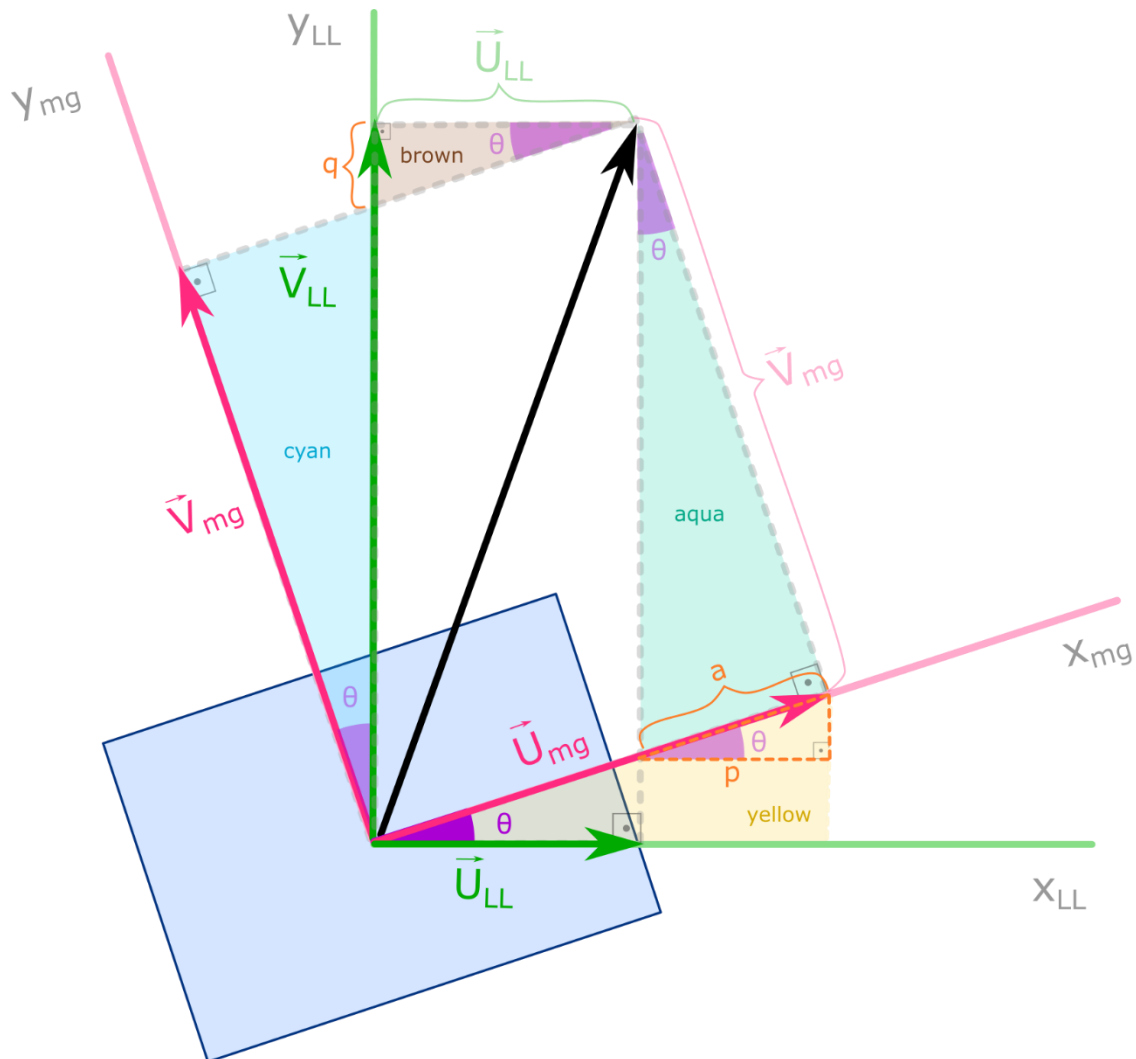


## Rotating U and V components of velocity from model grid to a lat-lon grid

The figure below is a schematic of a model grid cell (in dark blue), the velocity vector in black, the model grid x and y orientation ( $x_{mg}, y_{mg}$  in magenta), U and V components of velocity in the model grid ( $\vec{U}_{mg}, \vec{V}_{mg}$  in magenta), lat-lon grid orientation ( $x_{LL}, y_{LL}$  in green), rotated U and V components of the velocity ( $\vec{U}_{LL}, \vec{V}_{LL}$  in green, what we want to find), and the angle  $\theta$  between the model x ( $x_{mg}$ ) and lat-lon x ( $x_{LL}$ ), in dark purple.

Note that below we will only deal with the magnitude of the vectors, where

$$\begin{aligned}\vec{U}_{LL} &= U_{LL} \cdot \hat{i}_{LL} & \vec{V}_{LL} &= V_{LL} \cdot \hat{j}_{LL} \\ \vec{U}_{mg} &= U_{mg} \cdot \hat{i}_{mg} & \vec{V}_{mg} &= V_{mg} \cdot \hat{j}_{mg}\end{aligned}$$



First, let's find an expression for  $U_{LL}$ .

Looking at the yellow triangle, we can see that

$$\cos \theta = \frac{U_{LL} + p}{U_{mg}} \quad \text{or} \quad U_{LL} = U_{mg} \cdot \cos \theta - p \quad (1)$$

To find  $p$  we first look at the triangle delineated by the dashed orange lines. From this triangle, we see that

$$\cos \theta = \frac{p}{a} \quad \text{or} \quad p = a \cdot \cos \theta \quad (2)$$

From the aqua triangle,

$$\tan \theta = \frac{a}{V_{mg}} \quad \text{or} \quad a = V_{mg} \cdot \frac{\sin \theta}{\cos \theta} \quad (3)$$

Substituting (3) in (2),

$$p = V_{mg} \cdot \frac{\sin \theta}{\cos \theta} \cdot \cos \theta \quad \text{or} \quad p = V_{mg} \cdot \sin \theta \quad (4)$$

and (4) in (1)

$$U_{LL} = U_{mg} \cdot \cos \theta - V_{mg} \cdot \sin \theta \quad (5)$$

Great! Now let's find an expression for  $V_{LL}$ .

Looking at the cyan triangle,

$$\cos \theta = \frac{V_{mg}}{V_{LL} - q} \quad \text{or} \quad V_{LL} = \frac{V_{mg}}{\cos \theta} + q \quad (6)$$

Now, from the brown triangle,

$$\tan \theta = \frac{q}{U_{LL}} \quad \text{or} \quad q = U_{LL} \cdot \frac{\sin \theta}{\cos \theta} \quad (7)$$

Substituting the  $U_{LL}$  expression (5) into (7),

$$q = (U_{mg} \cdot \cos \theta - V_{mg} \cdot \sin \theta) \cdot \frac{\sin \theta}{\cos \theta}$$

$$q = U_{mg} \cdot \sin \theta - V_{mg} \cdot \frac{\sin^2 \theta}{\cos \theta} \quad (8)$$

Replacing (8) into (6), we have

$$V_{LL} = \frac{V_{mg}}{\cos \theta} + U_{mg} \cdot \sin \theta - V_{mg} \cdot \frac{\sin^2 \theta}{\cos \theta}$$

$$V_{LL} = V_{mg} \left( \frac{1 - \sin^2 \theta}{\cos \theta} \right) + U_{mg} \cdot \sin \theta$$

We know that  $\sin^2 \theta + \cos^2 \theta = 1$ , so replacing  $1 - \sin^2 \theta$  by  $\cos^2 \theta$ , we finally get

$$V_{LL} = V_{mg} \cdot \cos \theta + U_{mg} \cdot \sin \theta \quad (9)$$