ML & LinAlg Math Cheat Sheet

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1 Notation

Vectors are column vectors denoted by lower-case bolded variables, such that

$$oldsymbol{x} = egin{bmatrix} x_1 \ dots \ x_N \end{bmatrix}.$$

A row vector is denoted $\mathbf{x}^{\top} = [x_1 \dots x_N]$. A matrix is indicated by a bolded upper-case variable, such that an $N \times M$ matrix is

$$oldsymbol{A} = \{a_{ij}\} = [oldsymbol{a}_1 \cdots oldsymbol{a}_M] = \left[egin{array}{c} oldsymbol{a}_1^ op \ oldsymbol{a}_N^ op \end{array}
ight] = \left[egin{array}{ccc} a_{1,1}^ op & \cdots & a_{1,M} \ dots & \ddots & dots \ a_N^ op & \cdots & a_{N,M} \end{array}
ight].$$

For some random variable x, let $\mathbb{E}[x]$ denote its expected value.

2 Derivative

2.a Vector Gradient

$$\nabla_{\boldsymbol{x}} \boldsymbol{y} = \left[\frac{\partial \boldsymbol{y}}{\partial x_1}, \dots, \frac{\partial \boldsymbol{y}}{\partial x_N}\right] \tag{1}$$

3 Determinant Operator

3.a Random Properties

For scalar c and $N \times N$ identity matrix I,

$$\det(cI) = c^N$$
.

4 Trace Operator

Defined for $N \times N$ square matrix \boldsymbol{A} as

$$\operatorname{tr}(\boldsymbol{A}) \stackrel{\text{def}}{=} \sum_{i}^{N} a_{ii} \tag{2}$$

4.a Properties

4.a.i
$$\operatorname{tr}(c\mathbf{A} + d\mathbf{B}) = c\operatorname{tr}(\mathbf{A}) + d\operatorname{tr}(\mathbf{B})$$

For scalars c and d, square matrices \boldsymbol{A} and \boldsymbol{B} .

4.a.ii
$$\operatorname{tr}(\boldsymbol{A}\boldsymbol{B}) = \operatorname{tr}(\boldsymbol{B}\boldsymbol{A}) = \operatorname{tr}(\boldsymbol{A}^{\top}\boldsymbol{B}) = \operatorname{tr}(\boldsymbol{A}\boldsymbol{B}^{\top}) = \sum_{i,j} a_{ij}b_{ij}$$

And clearly, also $\operatorname{tr}(\boldsymbol{B}^{\top}\boldsymbol{A}) = \operatorname{tr}(\boldsymbol{B}\boldsymbol{A}^{\top}) = \sum_{i,j} a_{ij}b_{ij} = \operatorname{tr}(\boldsymbol{A}\boldsymbol{B}).$

4.b Derivatives

4.b.i
$$\nabla_{\boldsymbol{x}}\operatorname{tr}(\boldsymbol{x}\boldsymbol{x}^{\top}\boldsymbol{A}) = \boldsymbol{x}^{\top}(\boldsymbol{A} + \boldsymbol{A}^{\top})$$

For square matrix \boldsymbol{A} . Note that $\boldsymbol{x}^{\top}(\boldsymbol{A} + \boldsymbol{A}^{\top}) = 2\boldsymbol{x}^{\top}\boldsymbol{A}$ for symmetric \boldsymbol{A} . See appendix A.a.i for proof.

4.c Relation to Determinant

5 Expected Values

For $\boldsymbol{x} \in \mathbb{R}^d$, with expected value $\mathbb{E}[\boldsymbol{x}] = \boldsymbol{\mu}$ and covariance matrix $\boldsymbol{\Sigma} = \mathbb{E}[(\boldsymbol{x} - \mathbb{E}[\boldsymbol{x}])(\boldsymbol{x} - \mathbb{E}[\boldsymbol{x}])^{\top}]$,

$$\mathbb{E}[x_i^2] = \Sigma_{i,i} + \mu_i^2 \tag{3}$$

$$\mathbb{E}_x \left[(y - \boldsymbol{x}^{\top} \boldsymbol{w})^2 \right] = (y - \boldsymbol{w}^{\top} \boldsymbol{\mu})^2 + \boldsymbol{w}^{\top} \boldsymbol{\Sigma} \boldsymbol{w}. \tag{4}$$

A Proofs

A.a Trace

A.a.i
$$\nabla_{\boldsymbol{x}}\operatorname{tr}(\boldsymbol{x}\boldsymbol{x}^{\top}\boldsymbol{A}) = \boldsymbol{x}^{\top}(\boldsymbol{A} + \boldsymbol{A}^{\top})$$

This proof can likely be generalized to non-square matrixes (and possibly some communicativeness, given the flexibility afforded by the trace), but the restricted case is presented here.

For square $N \times N$ matrix \boldsymbol{A} ,

$$\nabla_{\boldsymbol{x}}\operatorname{tr}(\boldsymbol{x}\boldsymbol{x}^{\top}\boldsymbol{A}) = \frac{d}{d\boldsymbol{x}}\operatorname{tr}(\boldsymbol{x}\boldsymbol{x}^{\top}\boldsymbol{A}) = \frac{d}{d\boldsymbol{x}}\sum_{i}^{N}\sum_{k}^{N}x_{i}x_{k}a_{ik}.$$

Recall eq. (1), and consider for any $j \in \{1, ..., N\}$:

$$\frac{\partial}{\partial x_j} \sum_{i=1}^{N} \sum_{k=1}^{N} x_i x_k a_{ik} = [x_1 a_{1,j} + x_2 a_{2,j} + \dots + x_{j-1} a_{j-1,j} + x_{j+1} a_{j+1,j} + \dots + x_N a_{N,j}]$$

$$+ \frac{\partial}{\partial x_j} \sum_{k=1}^{N} x_j x_k a_{jk}$$

$$= \left[\sum_{i=1}^{N} x_i a_{ij} - x_j a_{jj} \right] + \sum_{k=1}^{N} x_k a_{jk} - x_j a_{jj} + \frac{\partial}{\partial x_j} x_j x_j a_{jj}$$

$$= \sum_{i=1}^{N} x_i a_{ij} + \sum_{k=1}^{N} x_k a_{jk} - 2x_j a_{jj} + 2x_j a_{jj}$$

$$= \mathbf{x}^{\top} \mathbf{a}_j + \mathbf{x}^{\top} [\mathbf{a}^{\top}]_j,$$

where $[\boldsymbol{a}^{\top}]_j$ is the *j*th column of A^{\top} .

This equally applies for any j in $1 \dots N$, and so for the full gradient:

$$\nabla_{\boldsymbol{x}}\operatorname{tr}(\boldsymbol{x}\boldsymbol{x}^{\top}\boldsymbol{A}) = \frac{d}{d\boldsymbol{x}}\sum_{i}^{N}\sum_{k}^{N}x_{i}x_{k}a_{ik} = [\boldsymbol{x}^{\top}\boldsymbol{a}_{1}\cdots\boldsymbol{x}^{\top}\boldsymbol{a}_{N}] + [\boldsymbol{x}^{\top}[\boldsymbol{a}^{\top}]_{1}\cdots\boldsymbol{x}^{\top}[\boldsymbol{a}^{\top}]_{N}]$$
$$= \boldsymbol{x}^{\top}(\boldsymbol{A} + \boldsymbol{A}^{\top}).$$