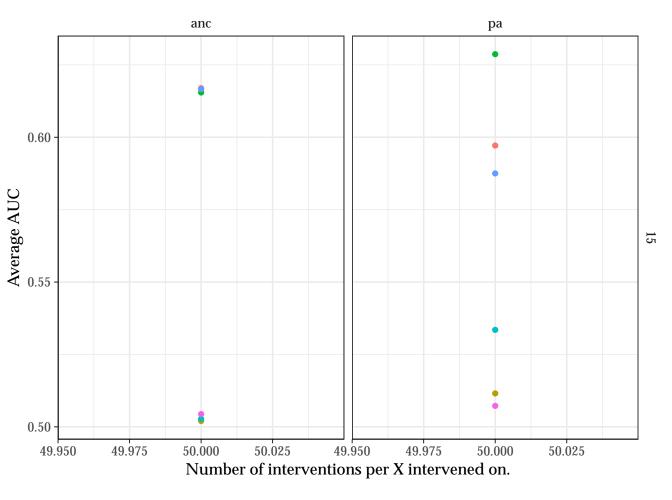
Number of control observations: 2x.

method

Shift noise sd: 7.

Hiddens sd: 5

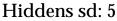


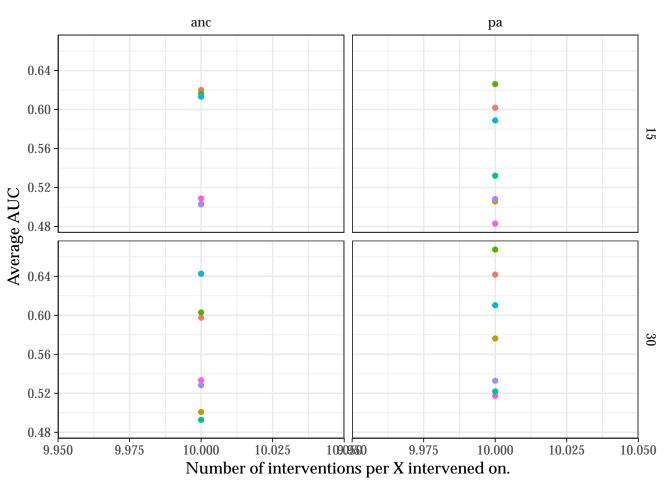
DPOLS-coef → OLS-coef → POLS-coef

Number of control observations: 10x.

Shift noise sd: 7.

method



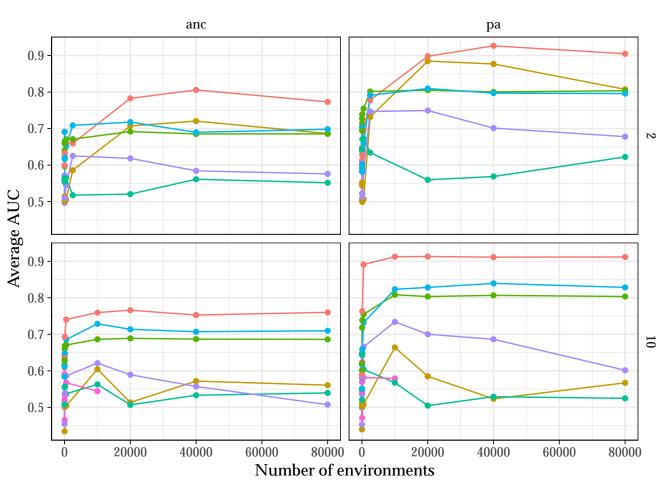


→ DPOLS-coef → OLS-coef → POLS-coef → ICP

obs per environment: 2 resp. 10. Shift noise sd: 7.

Shift noise sd: 7 Hiddens sd: 5

method

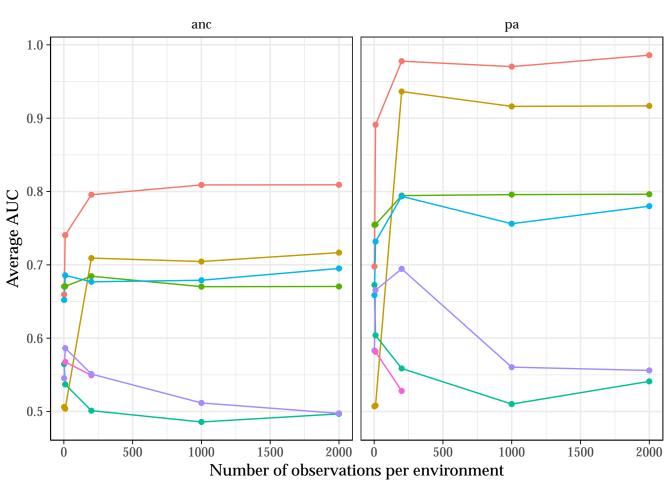


DPOLS-coef → OLS-coef → POLS-coef → ICP

Number of environments: 500.

method

Shift noise sd: 7. Hiddens sd: 5

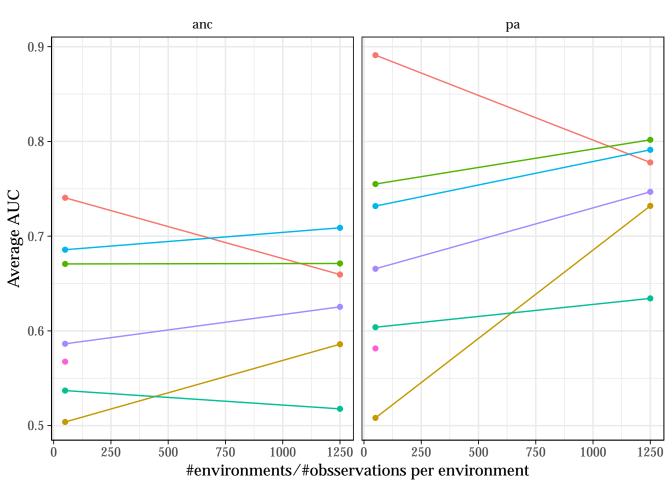


DPOLS-coef → OLS-coef → POLS-coef → ICP

Total number of observations: 5000.

Shift noise sd: 7. Hiddens sd: 5.

method

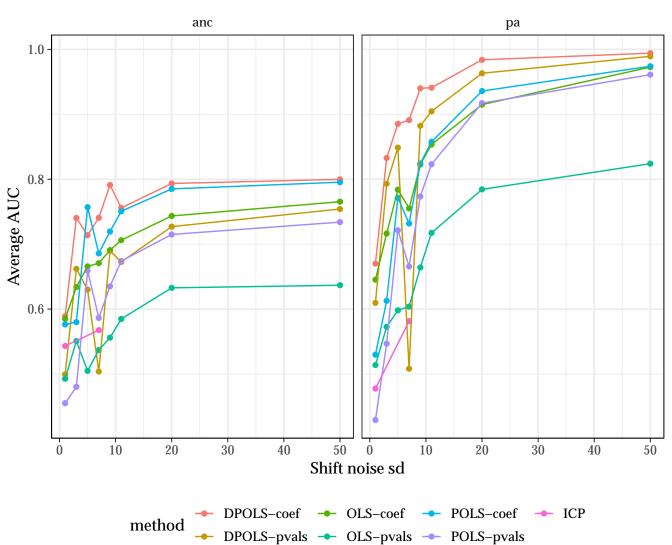


DPOLS-coef → OLS-coef → POLS-coef → ICP

#observations per environment: 10

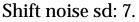
#environments: 500

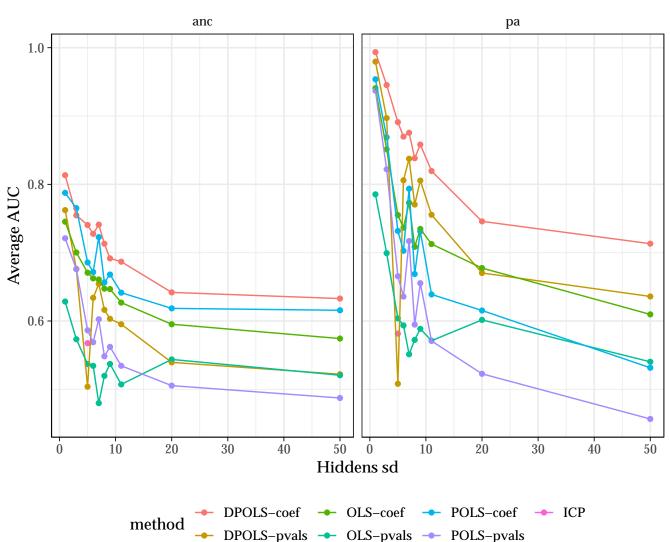
Hiddens sd: 5.



#observations per environment: 10

#environments: 500



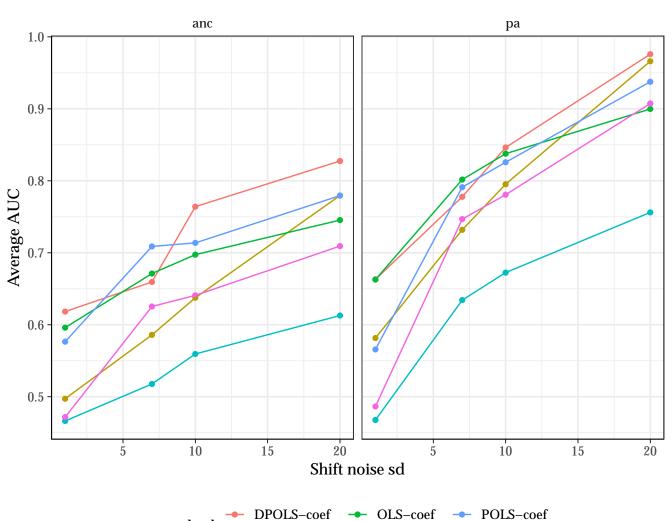


#observations per environment: 2

method

#environments: 2500

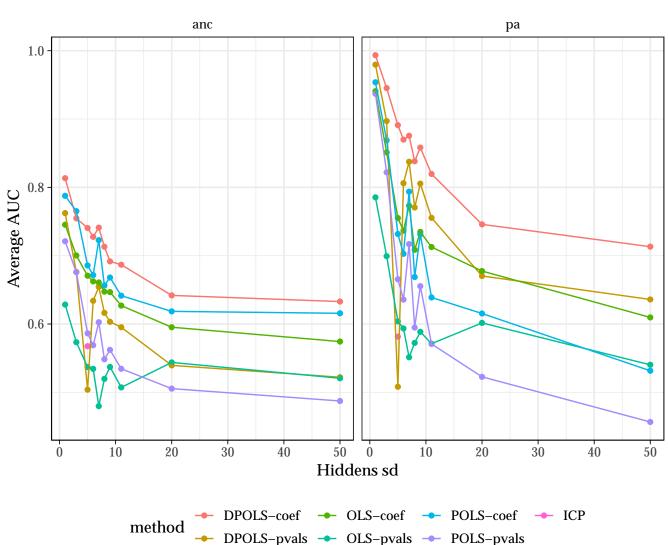
Hiddens sd: 5.

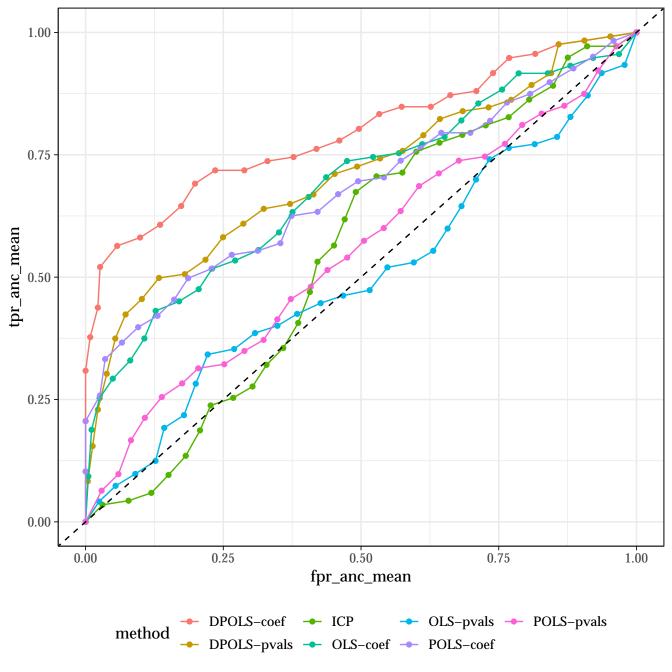


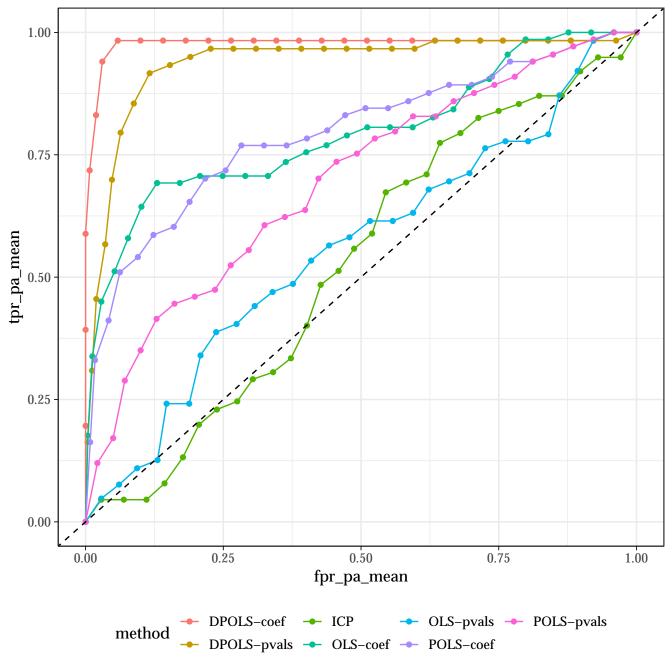
#observations per environment: 2

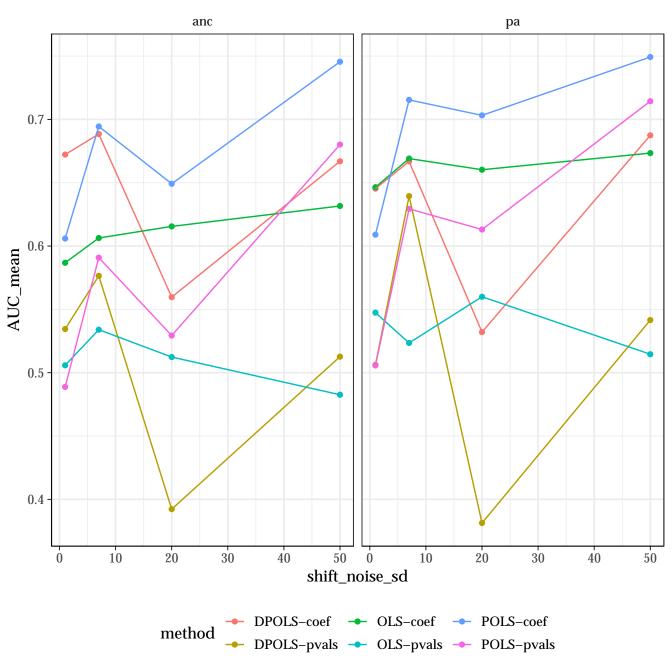
#environments: 2500

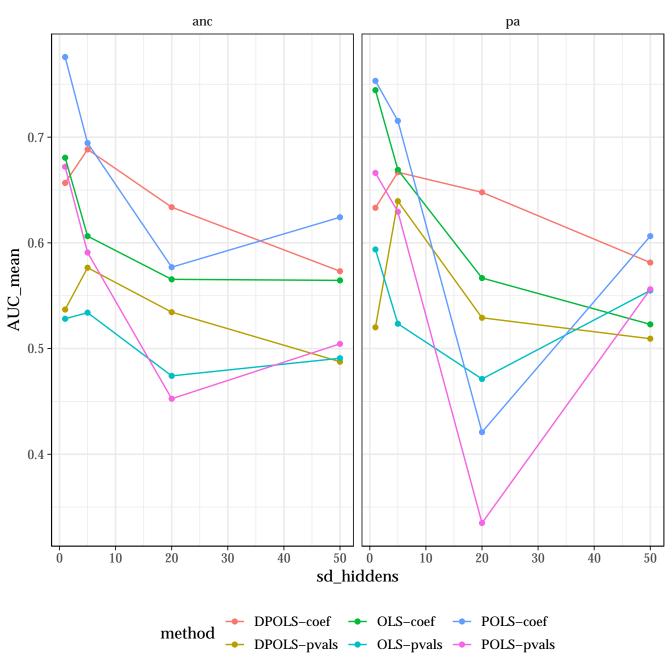
Shift noise sd: 7.

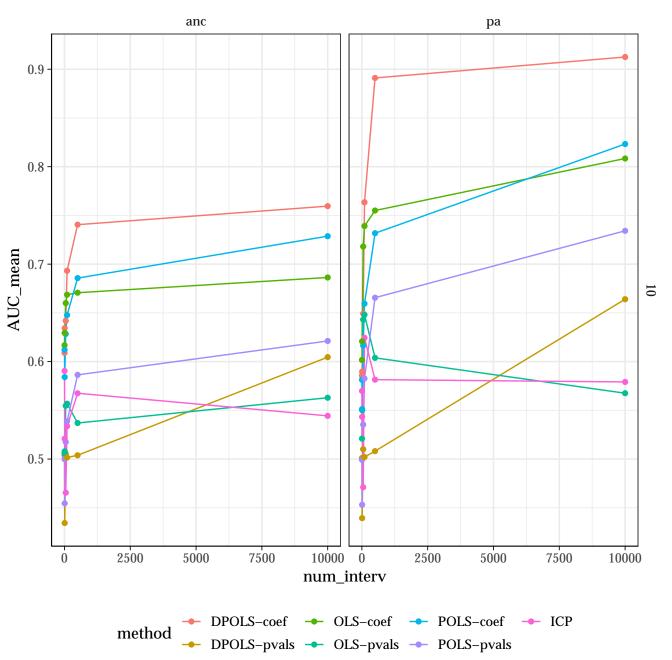






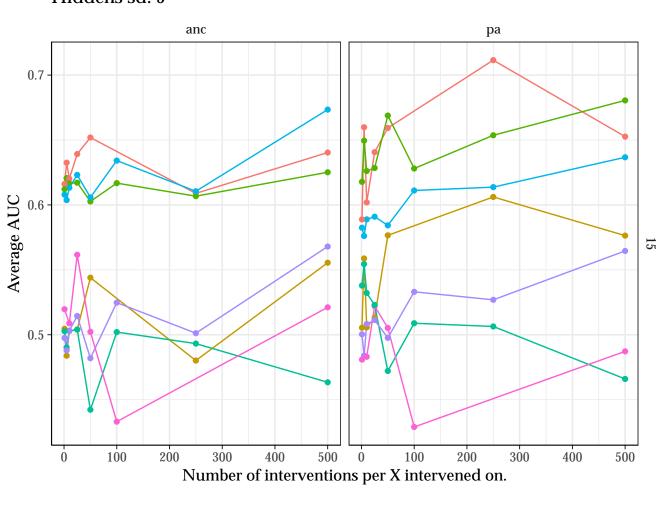






Singletargets. Control obs: 2x. Shift noise sd: 7. Hiddens sd: 5

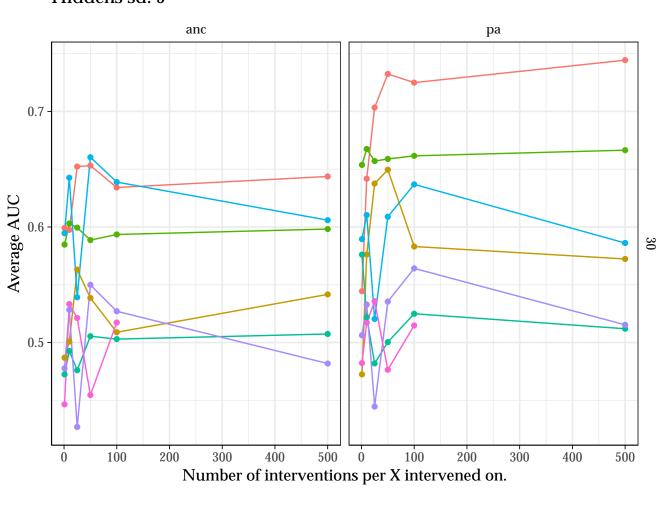
method



DPOLS-coef → OLS-coef → POLS-coef → ICP

Singletargets. Control obs: 2x. Shift noise sd: 7. Hiddens sd: 5

method



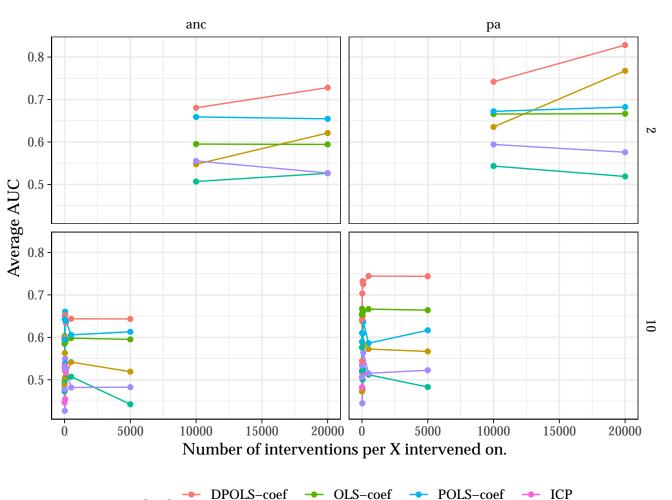
DPOLS-coef → OLS-coef → POLS-coef → ICP

Control obs: 100.

X's intervened on: 30.

method

Shift noise sd: 7. Hiddens sd: 5

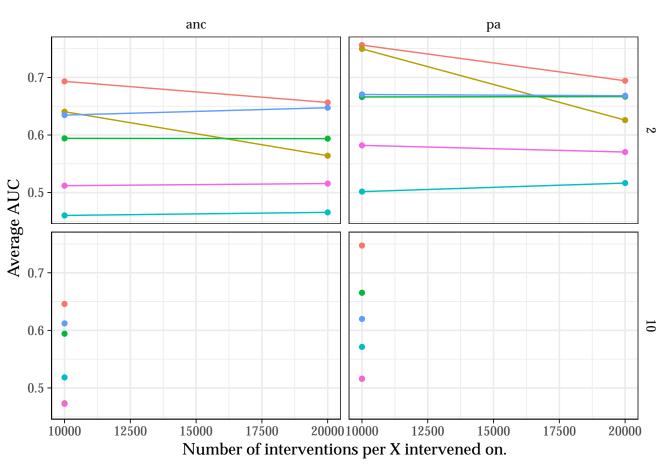


Control obs: 10000.

X's intervened on: 30.

method

Shift noise sd: 7. Hiddens sd: 5



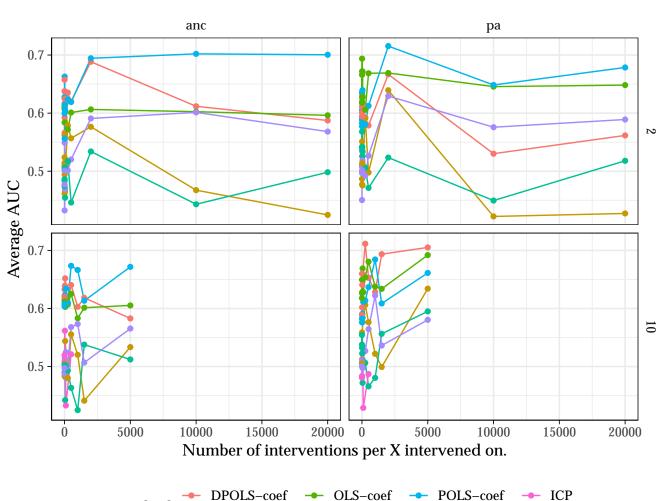
DPOLS-coef → OLS-coef → POLS-coef

Control obs: 100.

X's intervened on: 15.

method

Shift noise sd: 7. Hiddens sd: 5

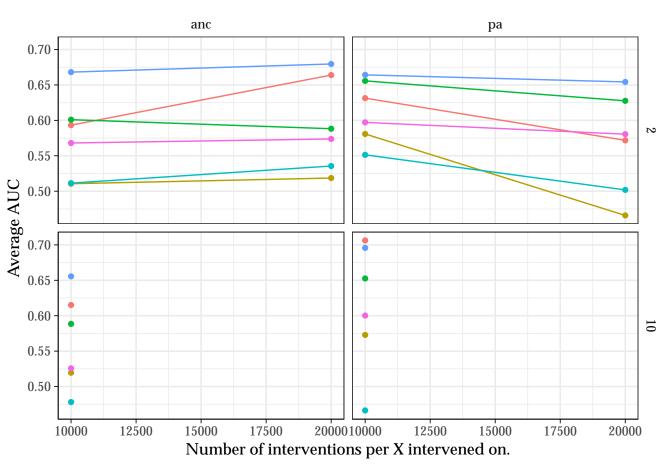


Control obs: 10000.

X's intervened on: 15.

method

Shift noise sd: 7. Hiddens sd: 5



DPOLS-coef → OLS-coef → POLS-coef