# **ADAM IANTORNO**

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#### **EDUCATION**

# **University of Waterloo**

Sep 2019 - May 2024

· Candidate for Bachelor of Applied Science, Mechanical Engineering with Artificial Intelligence Option

Appleby College Sep 2014 - June 2019

School Prefect, Captain of Cross Country Team, Model United Nations

#### **SKILLS**

Languages & Frameworks: Python, JavaScript, C++, Shell/Bash, ROS2, Git, ReactJS, Linux, Arduino

Design: SolidWorks, Siemens NX, Altium 365, and MATLAB

# **WORK EXPERIENCE**

#### Robotics Developer, Impossible Metals

Collingwood, Ontario

Sep 2022 - Dec 2022

- Programming 1D0F arm in Python & ROS2; operating a linear actuator and cameras to test seafloor plume
- Created React TypeScript UI to monitor and toggle all vehicle housings through ROS2 service calls.
- Assisting in vehicle deployments on the water by activating vehicle housings and setting control systems

## Mechatronics Engineer, Electrans Technologies Ltd.

Oakville, Ontario

Jan 2022 - April 2022

- Designed and built HIL test fixture to test sensors and pneumatics with custom firmware (see projects)
- Led design of automotive wire harness with diagramming software and sourced IP6k9k connectors
- Created 3D models and engineering drawings using SolidWorks of sheet metal brackets for MVP

#### Software Engineer, GrantMatch

Toronto, Ontario

May 2021 - Oct 2021

- Created web app using Diango and Rest APIs to track and process client invoices and legal documents
- Led software team and collaborated with data team in design of new SaaS product for small businesses
- Developed referral form function with **React JS** front-end framework to acquire new clients for company

#### Autonomous Driving Sensors Diagnostics Lead, Alternative Fuels (Eco-Car) Design Team

Waterloo, Ontario

Sep 2019 - Aug 2020

- Programmed C++ radar diagnostic algorithm in ROS which was implemented into vehicle firmware
- Analyzed collected sensor data using MATLAB to determine sensor error values and ranges
- Designed unit test cases for sensors and diagnostic algorithm by performing DFMEA analysis

## **KEY PROJECTS**

# Personal Website: adamiantorno.ca

• Built using React JS frontend framework and SASS for styling, code available on GitHub

#### Autonomous Pick and Place Robot Arm

In Progress

- Programmed 3DOF robot arm to autonomously control servo and stepper motors with Arduino and drivers
- Developed object-detection algorithm based on HSV color contrast with Python OpenCV

#### Hardware in Loop Testing Fixture

Jan 2022 - March 2022

- Generated SolidWorks model, electrical schematics in Altium, and sourced components for testing fixture
- Created Arduino function that converts UART signals to J1939 CAN to communicate with vehicle