Assignment 1 ELEC-E7460 Modeling and Simulation, fall 2018 Adam Ilyas 725819

Problem 1: Simulation of a simple general Markov process

```
In[2]:= Needs["HypothesisTesting`"]
   In[3] := \mathbf{Q} = \{
           {-3, 1, 0, 0, 2},
            \{0, -2, 2, 0, 0\},\
           \{1, 1, -3, 1, 0\},\
            \{1, 0, 0, -3, 2\},\
            \{0, 0, 0, 1, -1\}
  \text{Out}(3) = \left\{ \left\{ -3, 1, 0, 0, 2 \right\}, \left\{ 0, -2, 2, 0, 0 \right\}, \left\{ 1, 1, -3, 1, 0 \right\}, \left\{ 1, 0, 0, -3, 2 \right\}, \left\{ 0, 0, 0, 1, -1 \right\} \right\}
   In[4]:= MatrixForm[Q]
Out[4]//MatrixForm=
   In[@]:= generateEventTimes[Q_, state_] :=
           Table[
             If[Q[[state, nextState]] > 0,
              RandomVariate[ExponentialDistribution[Q[[state, nextState]]]],
              Infinity],
             {nextState, 1, Length[Q]}
           ];
```

```
ln[•]:= state = 1;
     simLength = 30;
     simTime = 0;
     step = 0;
     While[simTime ≤ simLength,
       eventTimes = generateEventTimes[Q, state];
       timeInState = Min[eventTimes];
       simTime += timeInState;
       state = Position[eventTimes, timeInState][[1, 1]];
       #Print[{timeInState, state}];
      ];
     Here we build a simulator that returns the simulation time if a cycle from to 1 back to 1 happened.
In[*]:= cycleSimulator[Q_, st_] := Module[
         {simTime, eventTimes, timeInState, res, state},
         state = st;
         simTime = 0;
         res = {};
        While[True,
          eventTimes = generateEventTimes[Q, state];
          timeInState = Min[eventTimes];
          simTime += timeInState;
          state = Position[eventTimes, timeInState][[1, 1]];
          res = Append[res, {simTime, state}];
          If[state = st, Break[], True];
         ];
         simTime
       ];
     res = simulator[Q, 1]
Out[*]= 2.26813
     We repeat the simulation a large enough number of times, each time storing the simulation time in a
     table
     and we find the mean and the confidence interval of this table.
In[*]:= simResult = Table[simulator[Q, 1], 1000]
     Mean[simResult]
     MeanCI[simResult]
Out[ • ]= 3.91614
     General: 0.00383984<sup>499.5</sup> is too small to represent as a normalized machine number; precision may be lost.
Out[\bullet] = \{3.69906, 4.13322\}
     Our expected time that a cycle from an initial state 1 back, back to state 1, after a 1000 simulation is
```

3.91. Our confidence interval is {3.69906,4.13322}

Problem 2: estimate the fractions π_i by simulation

```
In[*]:= piSimulator[Q_, simLength_] := Module[
         {simTime, eventTimes, timeInState, state, pi},
        state = 1;
        simTime = 0;
        pi = ConstantArray[0, 5];
        While True,
          eventTimes = generateEventTimes[Q, state];
          timeInState = Min[eventTimes];
          pi[[state]] += timeInState / simLength;
          simTime += timeInState;
          state = Position[eventTimes, timeInState][[1, 1]];
          If[simTime > simLength, Break[], True];
        ];
        рi
       ];
     piSimulator[Q, 1000]
Out[\circ] = \{0.0810011, 0.0749499, 0.0477375, 0.211173, 0.585492\}
In[*]:= piResult = Table[piSimulator[Q, 1000], 1000]
In[*]:= meanPi = Mean[piResult]
     meanCI = MeanCI[piResult]
Out[\bullet] = \{0.0854831, 0.0641268, 0.0427434, 0.212814, 0.595549\}
     General: 0.00383984<sup>499.5</sup> is too small to represent as a normalized machine number; precision may be lost.
Outf = \{\{0.0850497, 0.063532, 0.0423492, 0.212237, 0.594459\},\}
      \{0.0859166, 0.0647216, 0.0431376, 0.213391, 0.596638\}\}
     The mean fraction of time for each state, and its confidence interval is as follows:
ln[\bullet]:= For[i=1, i \le 5, i++,
      Print[StringForm["State `` mean: ``, Confidence Interval: ``",
        i, meanPi[[i]], meanCI[[1, i]]], meanCI[[2, i]]]
     ]
     State 1 mean: 0.08548314615260438', Confidence Interval: 0.08504973874723055'0.0859166
     State 2 mean: 0.06412677261454684', Confidence Interval: 0.0635319881298627'0.0647216
     State 3 mean: 0.04274341189428288', Confidence Interval: 0.04234924214065339'0.0431376
     State 4 mean: 0.2128141923355341, Confidence Interval: 0.21223726265939785, 0.213391
     State 5 mean: 0.595548635607118', Confidence Interval: 0.5944592307478451'0.596638
```