

# CLASSIFICATION

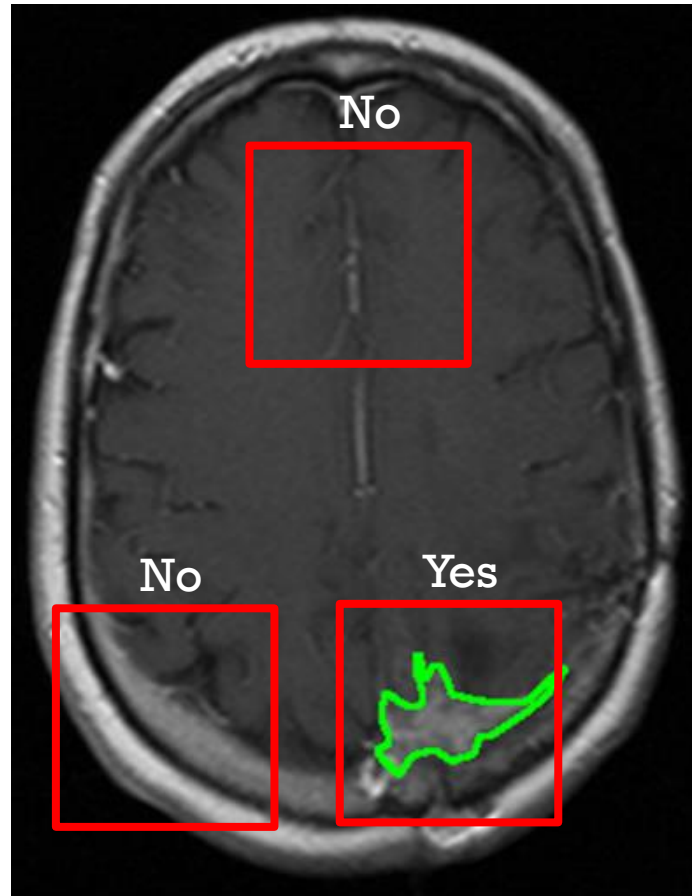


# TUMOR CLASSIFICATION

Tumor?

Yes  $\sim +1$

No  $\sim -1$





# SPAM FILTERS

Spam?

Yes  $\sim +1$

No  $\sim -1$



# CLASSIFICATION

Machine Learning

> Supervised Learning  
> Classification

- **Task.** Find  $h: \mathbb{R}^d \rightarrow \{-1, +1\}$  such that  $y \approx h(x; \theta)$
- **Experience.** Training data  $(x^{(1)}, y^{(1)}), \dots, (x^{(n)}, y^{(n)})$
- **Performance.** Prediction error on test data





# LINEAR CLASSIFICATION



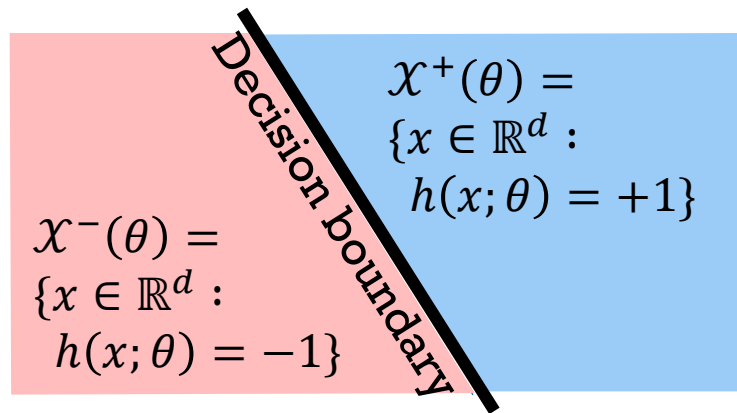
## Training data

$$\mathcal{S}_n = \{ (x^{(i)}, y^{(i)}) \mid i = 1, \dots, n \}$$

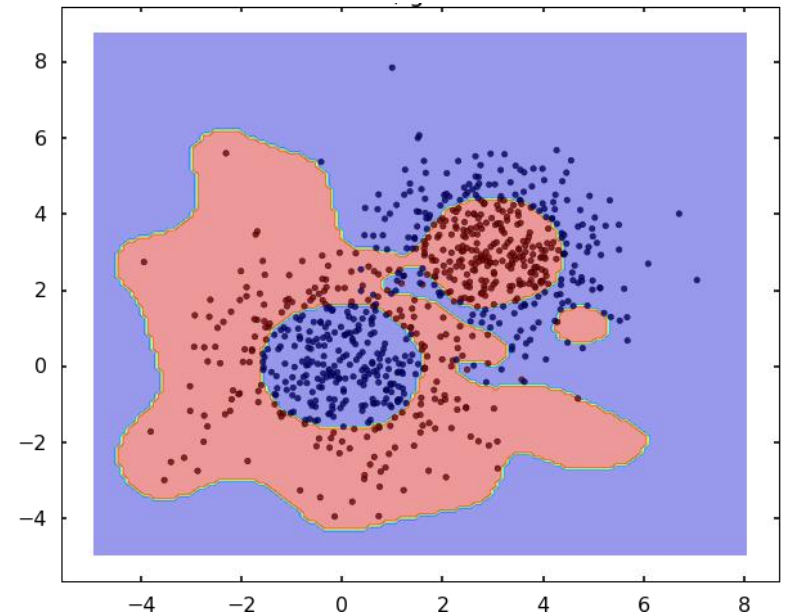
- Features/Inputs  $x^{(i)} = (x_1^{(i)}, \dots, x_d^{(i)})^\top \in \mathbb{R}^d$
- Labels/Output  $y^{(i)} \in \{-1, +1\}$



# DECISION REGIONS



linear classifier



non-linear classifier

A classifier  $h$  partitions the space into **decision regions** that are separated by **decision boundaries**. In each region, all the points map to the same label. Many regions could have the same label.

For linear classifiers, these regions are **half spaces**.

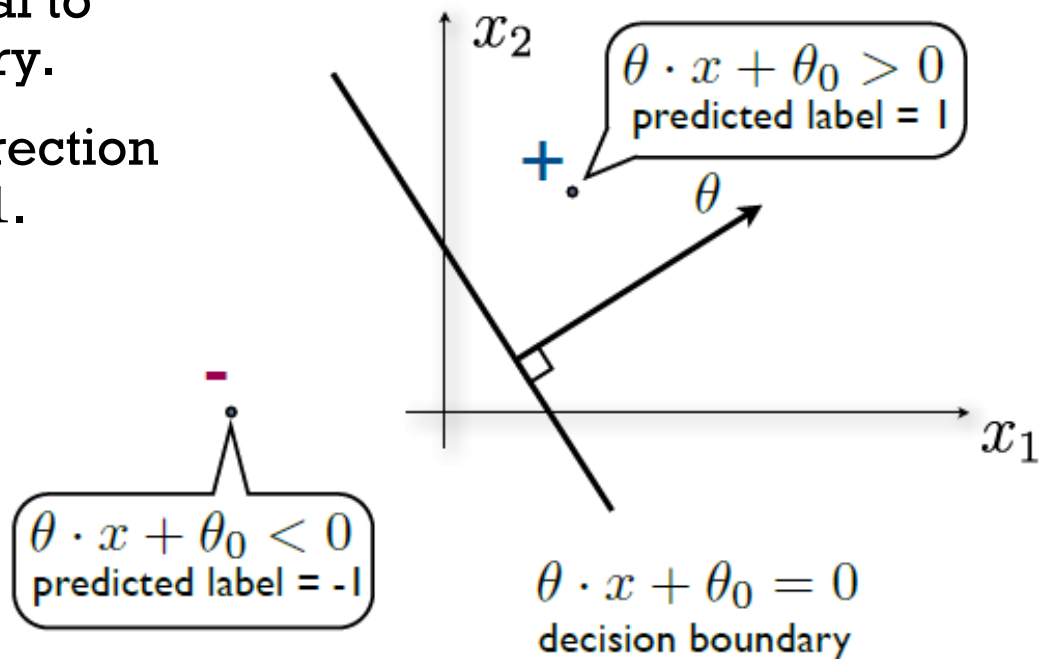


# DECISION BOUNDARIES

For linear classifiers, the decision boundary is a **hyperplane** of dimension  $d - 1$ .

Vector  $\theta$  is orthogonal to the decision boundary.

Vector  $\theta$  points in direction of region labelled +1.

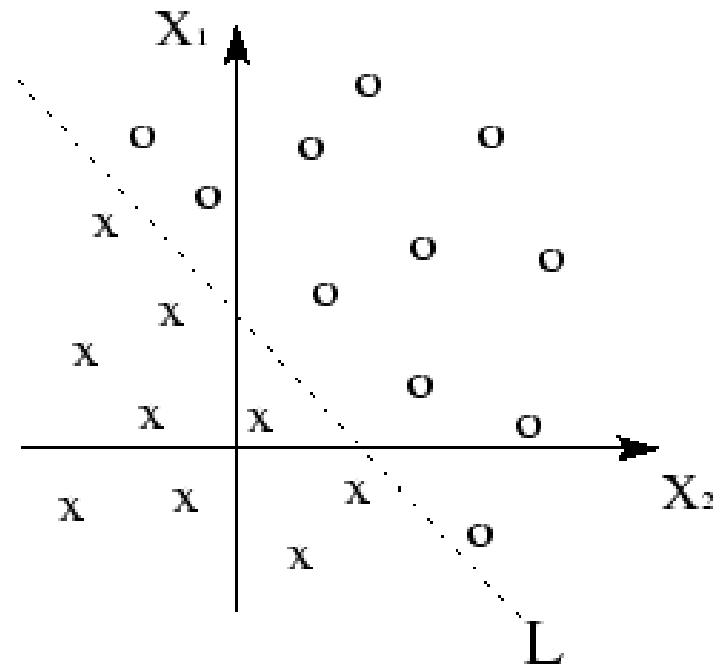




# LINEARLY SEPARABLE

The training data  $\mathcal{S}_n$  is  
**linearly separable**  
if there exists a  
parameters  $\theta$  and  $\theta_0$  such  
that for all  $(x, y) \in \mathcal{S}_n$ ,

$$y(\theta^\top x + \theta_0) > 0.$$



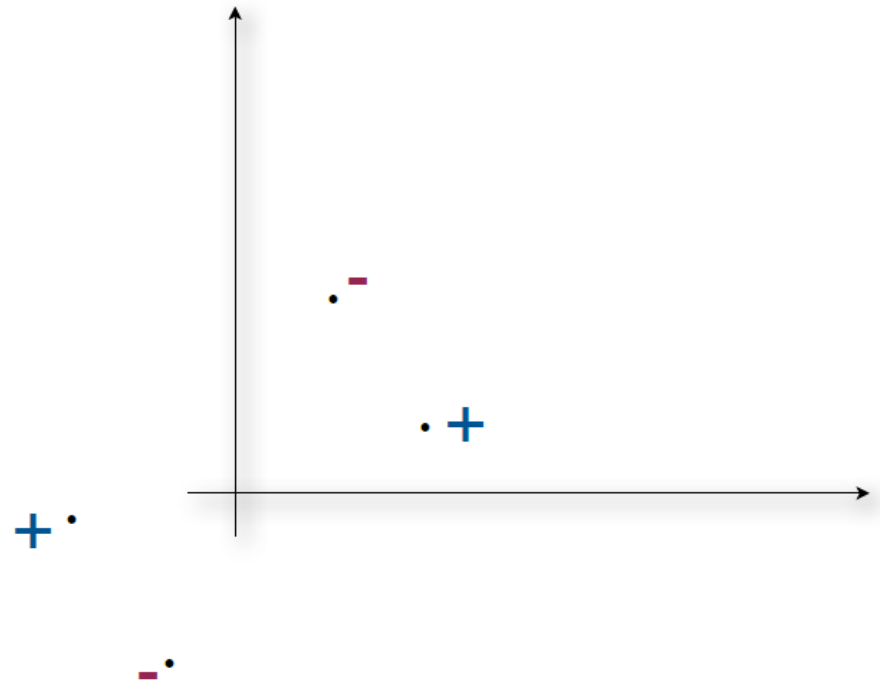
# NOT LINEARLY SEPARABLE

## Challenge

How do you prove  
the training data  
on the right is not  
linearly separable?

## Hint

Draw a line between  
the points labelled  $+1$ ,  
and a line between  
the points labelled  $-1$ .



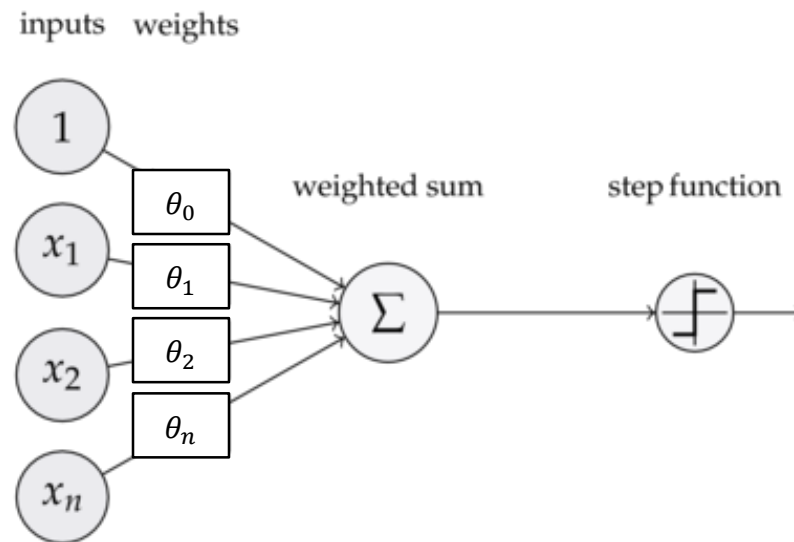


# PERCEPTRON ALGORITHM



# PERCEPTRON

Linear classifiers are often also called **perceptrons**.



Perceptrons (1957) were designed to resemble neurons.



The hypothesis function is given by

$$h_{\theta} \left( x^{(i)} \right) = \text{sgn} \left( \left\langle \theta, x^{(i)} \right\rangle \right),$$

where

$$\text{sgn}(z) = \begin{cases} 1 & \text{if } z \geq 0 \\ -1 & \text{if } z < 0. \end{cases}$$



# Perceptron criterion

- Using the count of the number of misclassified points as a loss function is not good as this is a piecewise constant, which means that its gradient is zero almost everywhere and gradient descent methods will not work.
- Instead we define the perceptron criterion:

$$\mathcal{L}_P(\theta) = - \sum_{i \in \mathcal{M}} y^{(i)} \langle \theta, x^{(i)} \rangle,$$

where  $\mathcal{M}$  is the set of misclassified points.

- Note that this is a piecewise-linear function.

# Perceptron algorithm

- Step 1: pick a point  $x^{(i)}$  and check if  $y^{(i)} \langle \theta(t), x^{(i)} \rangle \geq 0$ .
- Step 2: if yes, do nothing; if no perform the following update rule:

$$\begin{aligned}\theta(t+1) &= \theta(t) - \alpha \nabla \mathcal{L}_P(\theta(t)) \\ &= \theta(t) + \alpha x^{(i)} y^{(i)}\end{aligned}$$

- Cycle through the rest of the data with steps 1 and 2.

- The update rule reduces the error with respect to the selected point because

$$\begin{aligned} -y^{(i)} \langle \theta(t+1), x^{(i)} \rangle &= -y^{(i)} \langle \theta(t), x^{(i)} \rangle - y^{(i)} \langle \alpha x^{(i)} y^{(i)}, x^{(i)} \rangle \\ &< -y^{(i)} \langle \theta(t), x^{(i)} \rangle \end{aligned}$$

since  $\alpha \|y^{(i)} x^{(i)}\|^2 > 0$ .

- However, this does not guarantee that the total error function is reduced at each stage as:
  - the contribution to the error from other misclassified points may have increased;
  - previously correctly classified points may have become misclassified.

# PERCEPTRON CONVERGENCE

**Theorem.** If the training data is linearly separable, then the perceptron algorithm terminates after a finite number of steps.

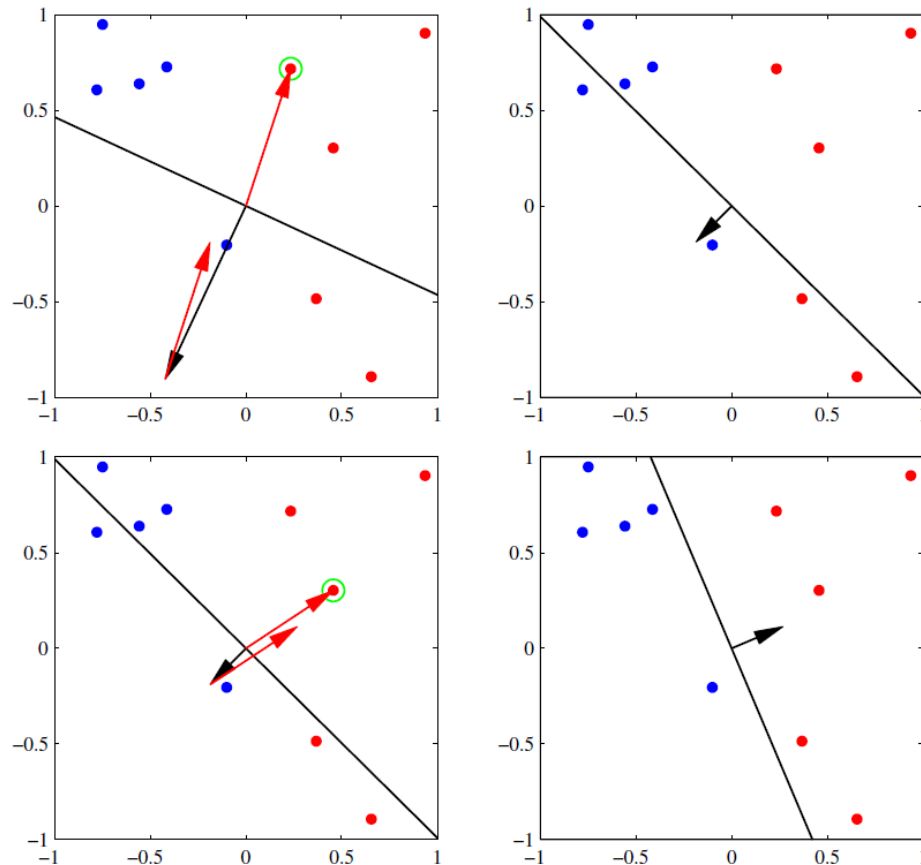
**Proof.** Not in the scope of this class, but it is not difficult. Basic idea is that with every mistake, lower bound for  $\|\theta\|$  grows quickly but upper bound grows slowly. Eventually it must stop.

**Non linearly-separable.** In this case, the perceptron algorithm will never terminate, because there will always be a mistake for all values of  $\theta$ . Other learning algorithms are needed.



# Example

Red circles:  $+1$ , Blue circles:  $-1$  (see pg 195 in Bishop)





# Disadvantages of the perceptron

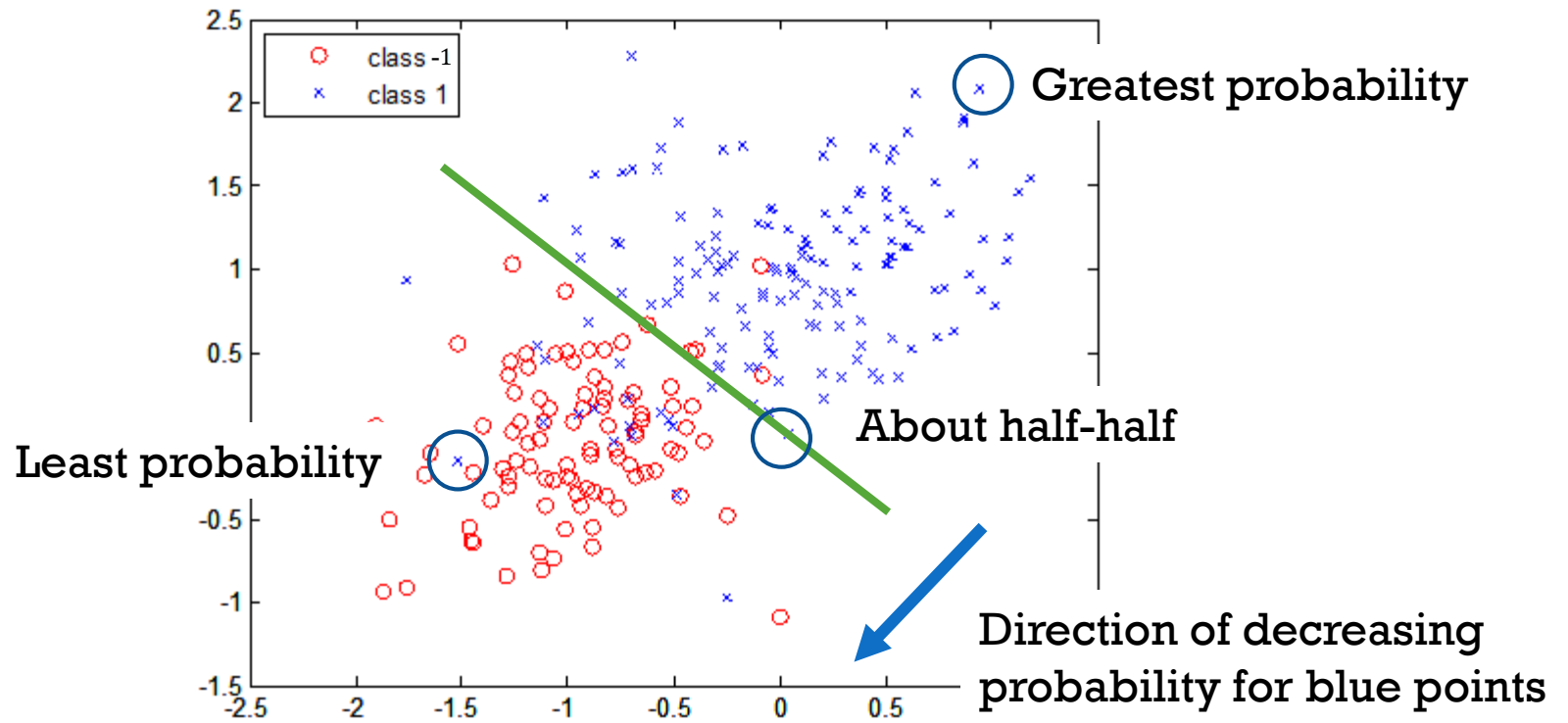
- Learning algorithm difficulties:
  - Not easy to differentiate slow convergence from cases where there will be no convergence due to not having linear separability.
  - Different initialization of the parameters and presentation of the data lead to different solutions.
- Does not provide probabilistic outputs.
- Does not generalize well to more than two classes.

5 min break



# LOGISTIC REGRESSION

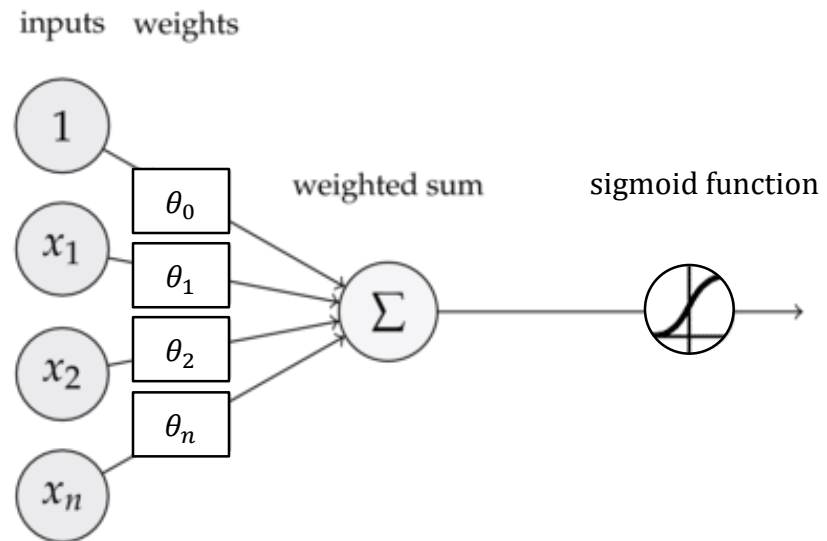




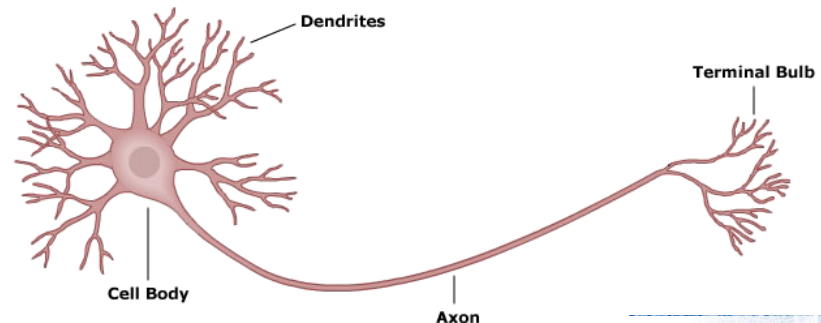
# SIGMOID NEURONS

Model consists of  
**sigmoid neurons.**

They were popular  
in the early days of  
deep learning (2006).



— A Typical Neuron —





# PROBABILISTIC MODEL

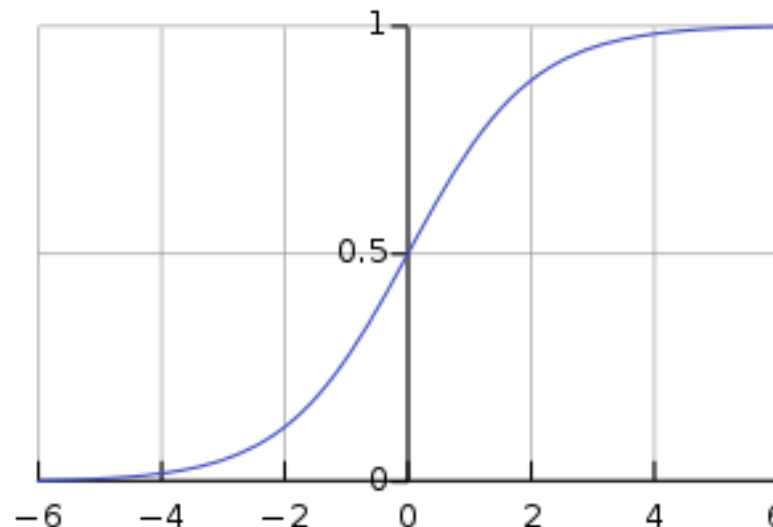
$[0, 1]$  denotes the interval  
 $\{a \in \mathbb{R}: 0 \leq a \leq 1\}$

Model the probability that the label  $y$  is  $+1$  given the feature is  $x$ .

$$h: \mathbb{R}^d \rightarrow [0, 1]$$

$$h(x; \theta) = \mathbb{P}(y = +1 | x) = \text{sigmoid}(\theta^\top x)$$

For small  $\theta^\top x$ ,  
the label is very  
likely to be  $-1$ .



For large  $\theta^\top x$ ,  
the label is very  
likely to be  $+1$ .



# Logistic regression

- The formula for the sigmoid function  $\sigma(z)$  is given by

$$\sigma(z) = \frac{1}{1 + e^{-z}},$$

and the hypothesis function is thus

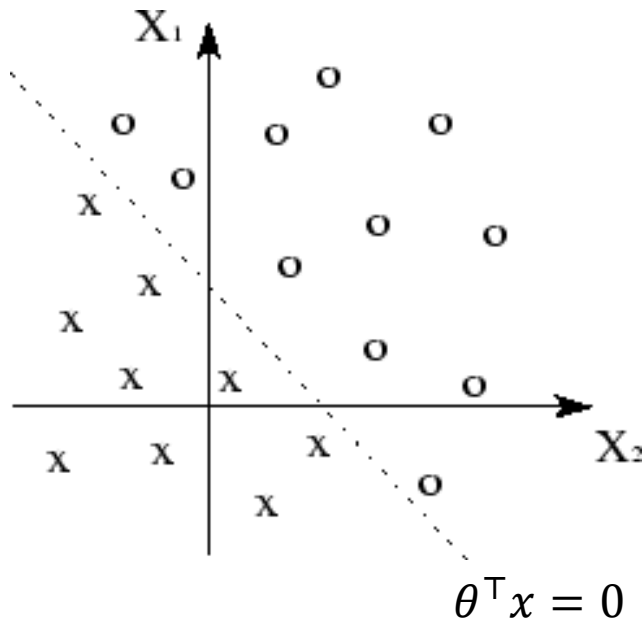
$$h_{\theta}(x^{(i)}) = \sigma(\langle \theta, x^{(i)} \rangle) = \frac{1}{1 + e^{-\langle \theta, x^{(i)} \rangle}}.$$

- The sigmoid function is also known as the logistic function.

# DECISION BOUNDARY

$$h(x; \theta) \geq \frac{1}{2} \iff \text{sigmoid}(\theta^\top x) \geq \frac{1}{2} \iff \theta^\top x \geq 0$$

$$h(x; \theta) < \frac{1}{2} \iff \text{sigmoid}(\theta^\top x) < \frac{1}{2} \iff \theta^\top x < 0$$



The decision boundary  
is described by  $\theta^\top x = 0$ .



## Formulas for the sigmoid function

$$(i) \quad \sigma(z) = \frac{1}{1 + e^{-z}} = \frac{e^z}{e^z + 1} = 1 - \sigma(-z)$$

$$\begin{aligned}(ii) \quad \sigma'(z) &= \frac{e^{-z}}{(1 + e^{-z})^2} \\&= \left( \frac{1}{1 + e^{-z}} \right) \left( \frac{e^{-z}}{1 + e^{-z}} \right) \\&= \left( \frac{1}{1 + e^{-z}} \right) \left( 1 - \frac{1}{1 + e^{-z}} \right) \\&= \sigma(z) (1 - \sigma(z)) = \sigma(z) \sigma(-z)\end{aligned}$$

- With  $z^{(i)}$  denoting  $\langle \theta, x^{(i)} \rangle$ , we have

$$p_{\theta} \left( y = 1 \mid x^{(i)} \right) = \sigma \left( z^{(i)} \right),$$

which means that

$$p_{\theta} \left( y = 0 \mid x^{(i)} \right) = 1 - \sigma \left( z^{(i)} \right) = \sigma \left( -z^{(i)} \right).$$

- We can combine both expressions as

$$p_{\theta} \left( y = y^{(i)} \mid x^{(i)} \right) = \sigma \left( z^{(i)} \right)^{y^{(i)}} \sigma \left( -z^{(i)} \right)^{1-y^{(i)}}.$$



# Log-likelihood function

The log-likelihood function is thus

$$\begin{aligned}\ell(\theta) &= \log \prod_{i=1}^m p\left(y = y^{(i)} \mid x^{(i)}\right) \\ &= \log \prod_{i=1}^m \sigma\left(z^{(i)}\right)^{y^{(i)}} \sigma\left(-z^{(i)}\right)^{1-y^{(i)}} \\ &= \sum_{i=1}^m y^{(i)} \log\left(\sigma\left(z^{(i)}\right)\right) + \left(1 - y^{(i)}\right) \log\left(\sigma\left(-z^{(i)}\right)\right).\end{aligned}$$

The gradient of this loss function is

$$\begin{aligned}\frac{\partial \ell(\theta)}{\partial \theta_j} &= \sum_{i=1}^m \frac{y^{(i)} x_j^{(i)}}{\sigma(z^{(i)})} \sigma(z^{(i)}) \sigma(-z^{(i)}) - \frac{(1 - y^{(i)}) x_j^{(i)}}{\sigma(-z^{(i)})} \sigma(z^{(i)}) \sigma(-z^{(i)}) \\ &= \sum_{i=1}^m y^{(i)} x_j^{(i)} \sigma(-z^{(i)}) - (1 - y^{(i)}) x_j^{(i)} \sigma(z^{(i)}) \\ &= \sum_{i=1}^m x_j^{(i)} \left[ y^{(i)} (1 - \sigma(z^{(i)})) - (1 - y^{(i)}) \sigma(z^{(i)}) \right] \\ &= \sum_{i=1}^m x_j^{(i)} (y^{(i)} - \sigma(z^{(i)})).\end{aligned}$$

- We can then use the gradient to perform gradient ascent to maximize the likelihood:

$$\theta_j(t+1) = \theta_j(t) + \alpha \sum_{i=1}^m \left( y^{(i)} - \sigma \left( \langle \theta(t), x^{(i)} \rangle \right) \right) x_j^{(i)}, \quad j = 1, \dots, n.$$

- Do you see the similarity with linear regression?

# MULTICLASS CLASSIFICATION

**Example.** Predict color preference (e.g. yellow, green, blue).

**Solution.**

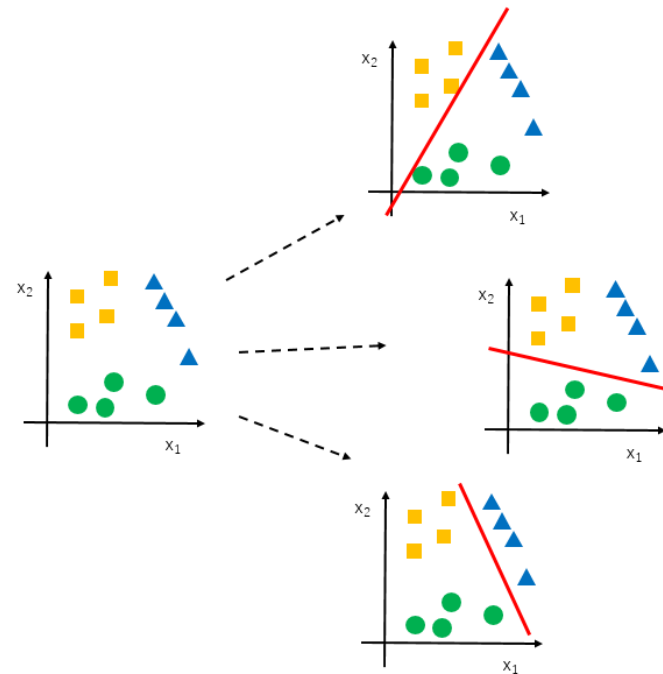
Learn a 'one-vs-rest'  
function for each class.

$$h_{\text{yellow}}(x) = \text{sigmoid}(\alpha^T x)$$

$$h_{\text{green}}(x) = \text{sigmoid}(\beta^T x)$$

$$h_{\text{blue}}(x) = \text{sigmoid}(\gamma^T x)$$

Rank the function values to  
predict the best class.



We will discuss a better method for multiclass classification next week called softmax classification.