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A U S T R A L I A



UNIVERSITY OF NEW SOUTH WALES

SCHOOL OF MATHEMATICS AND STATISTICS

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# Assignment 1

Ergodic Theory

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# 1

Let  $(X_1, \mathcal{B}_1, \mu_1, T_1)$  and  $(X_2, \mathcal{B}_2, \mu_2, T_2)$  be two measure theoretically isomorphic p.p.ts (  $\pi : X_1 \longrightarrow X_2$  ). Suppose  $(X_1, \mathcal{B}_1, \mu_1, T_1)$  is mixing. Then for  $E, F \in \mathcal{B}_2$  see that

$$\begin{aligned}\mu_2(E \cap T_2^{-n}F) &= \mu_1(\pi^{-1}(E \cap T_2^{-n}F)) \\ &= \mu_1(\pi^{-1}(E) \cap T_1^{-n}\pi^{-1}(F))\end{aligned}$$

and since  $\mu_1$  is mixing then

$$\begin{aligned}\lim_{n \rightarrow \infty} \mu_1(\pi^{-1}(E) \cap T_1^{-n}\pi^{-1}(F)) &= \mu_1(\pi^{-1}(E))\mu_1(\pi^{-1}(F)) \\ &= \mu_2(E)\mu_2(F)\end{aligned}$$

and so

$$\lim_{n \rightarrow \infty} \mu_2(E \cap T_2^{-n}F) = \mu_2(E)\mu_2(F)$$

# 2

Consider  $g_t : S^1 \longrightarrow S^1$  where  $g_t(x) \mapsto x + t \pmod{1}$ . The measure space is  $(S^1, \mu_{\mathcal{L}})$  where  $\mu_{\mathcal{L}}$  is the Lebesgue measure. Clearly the flow is ergodic because the only sets which are invariant for all  $t$  are  $S$  and  $\emptyset$ . However if we consider  $g_{\tau}$  with  $\tau = \frac{1}{2}$  then there are lots of invariant sets which are not of full or zero measure. For example  $[0, \frac{1}{4}] \cup [\frac{1}{2}, \frac{3}{4}]$  is invariant but  $\mu_{\mathcal{L}}([0, \frac{1}{4}] \cup [\frac{1}{2}, \frac{3}{4}]) = \frac{1}{2}$  and so  $g_{\frac{1}{2}}$  with the Lebesgue measure is not ergodic.

# 3

(We show the contrapositive)

Suppose  $(X, \mathcal{B}, \mu, T)$  is a p.p.t which is not ergodic. Then there exists another  $T$  invariant measure  $\nu$ . Since  $(X, \mathcal{B}, \mu, T)$  is not ergodic then there exists  $E \in \mathcal{B}$  such that  $T^{-1}E = E$  but  $0 < \mu(E) < 1$ . Fix  $E$  and say  $\mu(E) = \alpha$ . Then we can define a new measure

$$\nu(F) = (1 - \alpha)^{-1}\mu(F \setminus E).$$

$\nu$  is clearly  $\mathcal{B}$  additive so it's a measure. We just have to verify that  $\nu$  is  $T$  invariant.

$$\begin{aligned}\nu(T^{-1}F) &= (1 - \alpha)^{-1}\mu((T^{-1}F) \setminus E) \\ &= (1 - \alpha)^{-1}\mu(\{x : T(x) \in F, x \in E^c\}) \\ &= (1 - \alpha)^{-1}\mu(\{x : T(x) \in (F \cap E^c)\}) \quad \text{because } E^c \text{ is } T \text{ invariant} \\ &= (1 - \alpha)^{-1}\mu(T^{-1}(F \setminus E)) \\ &= (1 - \alpha)^{-1}\mu(F \setminus E) \\ &= \nu(F)\end{aligned}$$

and so the contrapositive is proved.

## 4

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

$A$  is aperiodic and because  $A_{i,j}^n$  represents the number of paths of length  $n$  from  $i$  to  $j$  then if  $A_{1,1}^n \neq 0$  then  $A_{1,2}^n = 0$ . In other words there will never be a  $n$  such that all the entries of the matrix  $A^n$  are non-zero.

Another way of saying this is that state 2 can only be reached from state 1 in an odd number of steps whereas state 1 can only get back to state 1 in an even number of steps.

## 5

### 5.1

(By induction)

In the case  $n = 1$  the result holds trivially.

Suppose  $A_{i,j}^n = \#\{\text{paths from } i \text{ to } j \text{ of length } n\}$  (For all  $j, k \leq N$ .) Then

$$\begin{aligned} A_{i,j}^{n+1} &= (A^n A)_{i,j} \\ &= \sum_{k=1}^N A_{i,k}^n A_{k,j} \\ &= \sum_{k=1}^N \#\{\text{paths from } i \text{ to } k \text{ of length } n\} A_{k,j} \\ &= \sum_{k \in \{1, \dots, N\}, A_{k,j}=1} \#\{\text{paths from } i \text{ to } k \text{ of length } n\} \\ &= \#\{\text{paths from } i \text{ to } j \text{ of length } n\} \end{aligned}$$

### 5.2

(By induction)

The case  $n = 1$  holds by definition of  $P$ .

Suppose  $P_{i,j}^n = \mathcal{P}[\text{going from } i \text{ to } j \text{ in exactly } n \text{ steps}]$ .

Then

$$\begin{aligned}
P_{i,j}^{n+1} &= (P^n P)_{i,j} \\
&= \sum_{k=1}^N P_{i,k}^n P_{k,j} \\
&= \sum_{k=1}^N P_{k,j} \mathcal{P}[\text{going from } i \text{ to } k \text{ in exactly } n \text{ steps}] \\
&= \sum_{k=1}^N \mathcal{P}[\text{going from } k \text{ to } j \text{ in exactly 1 step}] \mathcal{P}[\text{going from } i \text{ to } k \text{ in exactly } n \text{ steps}] \\
&= \sum_{k=1}^N \mathcal{P}[\text{going from } i \text{ to } k \text{ in exactly } n \text{ steps then directly to } j] \\
&= \mathcal{P}[\text{going from } i \text{ to } j \text{ in exactly } n+1 \text{ steps}].
\end{aligned}$$

### 5.3

#### 5.3.1

$$\begin{aligned}
q_j &= \sum_{k=1}^N P_{k,j} q_j \\
&= P_{j,j} q_j
\end{aligned}$$

which implies either  $P_{j,j} = 1$  or  $q_j = 0$ . Suppose  $P_{j,j} = 1$ , then  $P_{j,k} = 0$  for all  $k \neq j$ . This implies

$$\begin{aligned}
P_{j,k}^2 &= \sum_{i=1}^N P_{j,i} P_{i,k} \\
&= P_{j,j} P_{j,k} \\
&= \delta_{j,k}
\end{aligned}$$

and by induction implies  $(P^n)_{j,k} = 0$  for all  $j \neq k$ , which is not allowed, so  $q_j = 0$ .

#### 5.3.2

Group into communicating classes  $[i]$ ,  $[j]$  respectively. (There may be other communicating classes but we can neglect them) Then there is a stochastic matrix

$$R = \begin{bmatrix} \alpha & \alpha - 1 \\ 0 & 1 \end{bmatrix}$$

If  $\mathbf{w}$  is the stationary vector for  $R$  (defined above) then it is easy to see  $w_1 = 0$ . The result for  $q_i$  follows as  $i \in [i]$ .