8.07 Lecture Slides 22 December 2, 2019

ELECTRODYNAMICS,
CONSERVATION LAWS,
and
ELECTROMAGNETIC WAVES

(Next time)

The Complete Maxwell Equations

$$ec{m{\nabla}} \cdot \vec{m{E}} = rac{
ho}{\epsilon_0}$$
 $ec{m{\nabla}} imes \vec{m{E}} = -rac{\partial \vec{m{B}}}{\partial t}$ $ec{m{\nabla}} \cdot \vec{m{B}} = 0$ $ec{m{\nabla}} imes \vec{m{B}} = \mu_0 \vec{m{J}} + \mu_0 \epsilon_0 rac{\partial \vec{m{E}}}{\partial t}$



The Complete Maxwell Equations

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \qquad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \qquad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

 $\rightarrow \frac{\partial \vec{B}}{\partial t}$ added by Faraday. It restores Galilean relativity: if the magnetic flux through a loop changes, with this addition it does not matter whether \vec{B} changes, or the loop moved.



The Complete Maxwell Equations

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \qquad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \qquad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

- $\rightarrow \frac{\partial \vec{B}}{\partial t}$ added by Faraday. It restores Galilean relativity: if the magnetic flux through a loop changes, with this addition it does not matter whether \vec{B} changes, or the loop moved.
- $\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$ added by Maxwell to make RHS divergenceless.



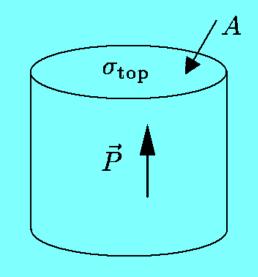
The Complete Maxwell Equations In Matter

There is one more bound charge effect: if \vec{P} changes with time, currents flow.

$$\sigma_{
m top} = \vec{m P} \cdot \hat{m n} \; ,$$

where $\hat{\boldsymbol{n}}$ is the upward normal, the direction of $\vec{\boldsymbol{P}}$. So Q = PA, where $P = |\vec{\boldsymbol{P}}|$, so

$$I = \frac{\mathrm{d}Q}{\mathrm{d}t} = \frac{\mathrm{d}P}{\mathrm{d}t}A \implies |\vec{J}| = \frac{\mathrm{d}P}{\mathrm{d}t}.$$



So

$$ec{J_b} = ec{m{
abla}} imes ec{m{M}} + rac{\partial ec{m{P}}}{\partial t} \; .$$

If polarized material moves, there are other terms, but we'll assume that all our matter is static.



Starting with

$$ec{m{
abla}} \cdot ec{m{E}} = rac{
ho}{\epsilon_0} \qquad ec{m{
abla}} imes ec{m{E}} = -rac{\partial ec{m{B}}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$
 $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

and using

$$ho =
ho_{
m free} - ec{m
abla} \cdot ec{m P} \;, \quad ec{m J} = ec{m J}_{
m free} + ec{m
abla} imes ec{m M} + rac{\partial ec{m P}}{\partial t} \;,$$

and the definitions

$$ec{m{H}} \equiv rac{1}{\mu_0} ec{B} - ec{m{M}} \; , \quad ec{m{D}} \equiv \epsilon_0 ec{m{E}} + ec{m{P}} \; ,$$

one finds

$$ec{m{
abla}}\cdotm{ec{D}}=
ho_{
m free} \qquad ec{m{
abla}} imes m{ec{E}}=-rac{\partial m{ec{B}}}{\partial t}$$

$$ec{m{\nabla}} \cdot ec{m{D}} =
ho_{\mathrm{free}}$$
 $ec{m{\nabla}} imes ec{m{E}} = -rac{\partial ec{m{B}}}{\partial t}$ $ec{m{\nabla}} \cdot ec{m{B}} = 0$ $ec{m{\nabla}} imes ec{m{H}} = ec{m{J}}_{\mathrm{free}} + rac{\partial ec{m{D}}}{\partial t}$



Conductivity: Ohm's Law

$$\vec{J} = \sigma(\vec{E} + \vec{v} \times \vec{B}) ,$$

where $\vec{\boldsymbol{v}}$ is the velocity of the medium, and

$$\sigma \equiv \text{conductivity}$$
,

$$\rho \equiv \frac{1}{\sigma} = \text{resistivity}.$$

Units:

$$\left[\vec{\boldsymbol{J}} \right] = \frac{C}{s \cdot m^2} , \quad \left[\vec{\boldsymbol{E}} \right] = \frac{N}{C} \implies \left[\sigma \right] = \frac{C}{s \cdot m^2} \frac{C}{N} = \frac{C^2}{J \, m \, s}$$

$$1 \text{ Ohm } (\Omega) \equiv \frac{1 \text{ volt}}{\text{ampere}} = \frac{V}{A} = \frac{J/C}{C/s} = \frac{J \, s}{C^2} \implies \left[\rho \right] = \Omega \cdot m .$$



Drude Model of Resistivity

This is a very crude classical model. Assume:

- 1) Interatomic distance = λ .
- 2) Thermal velocity of electrons is given by

$$\frac{1}{2}m_e v_{\rm th}^2 = \frac{3}{2}kT \; ,$$

where k = Boltzmann constant, T = temperature. For $T = 300 \,\text{K}$, $v_{\text{th}} = 1.17 \times 10^7 \,\text{cm/s} = 2.6 \times 10^5 \,\text{mile/hour}$.

- 3) $\Delta t = \lambda/v_{\rm th} = \text{mean time between collisions},$
- 4) $\langle \vec{\boldsymbol{v}} \rangle = \frac{1}{2} \vec{\boldsymbol{a}} \Delta t$, where $\vec{\boldsymbol{a}} = q \vec{\boldsymbol{E}} / m_e$.
- 5) Let f = number of free electrons per atom or molecule.
- 6) Let n = number density of atoms or molecules. Then

$$\vec{\boldsymbol{J}} = fnq \langle \vec{\boldsymbol{v}} \rangle = \left(\frac{nf\lambda q^2}{2mv_{\mathrm{th}}} \right) \vec{\boldsymbol{E}} \implies \sigma = \frac{nf\lambda q^2}{2mv_{\mathrm{th}}} \ .$$

Numerically, for copper

$$n = \frac{\text{density}}{\text{atomic weight}} \text{(Avogadro's number)}$$

$$= \frac{(8.96 \text{ g/cm}^3)}{(63.5 \text{ g/mole})} \left(6.022 \times 10^{23} \frac{\text{atoms}}{\text{mole}} \right)$$

$$= 8.50 \times 10^{22} / \text{cm}^3.$$

$$\lambda = \frac{1}{n^{1/3}} = 2.27 \times 10^{-8} \text{ cm}.$$

Drude model gives

$$\rho_{\rm Drude} = 4.3 \times 10^{-7} \ \Omega \text{-m} ,$$

while in reality

$$\rho_{\text{Copper}} = 1.68 \times 10^{-8} \ \Omega\text{-m}.$$

So copper conducts about 25 times better than the Drude model predicts.



Typical Values of Resistivity

Griffiths, Table 7.1, resistivities in Ω -m:

Conductors:

Silver: 1.59×10^{-8}

Iron: 9.61×10^{-8}

Graphite: 1.6×10^{-5}

Semiconductors:

Sea water: 0.2

Germanium: 0.46

Silicon: 2500

Insulators:

Water (pure): 8.3×10^3

Glass: $10^9 - 10^{14}$

Teflon: $10^{22} - 10^{24}$



Faraday's Law and Inductors

Consider a long thin circular solenoid, of n turns per unit length, length ℓ , radius R, with $\ell \gg R$.

Inside $\vec{B} \approx B_0 \hat{z}$, outside $\vec{B} \approx 0$, since the return flux is spread over an area that grows with ℓ .

Ampere's law, $\oint \vec{B} \cdot d\vec{\ell} = \mu_0 E_{\text{enc}} \implies \vec{B} = n \mu_0 I_0 \hat{z}$.

Magnetic flux $\Phi_B = \pi R^2(n\mu_0 I_0)$ per turn, so

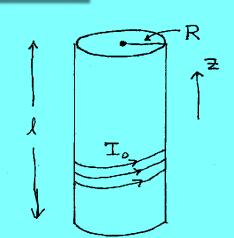
$$\Phi_B = \pi R^2 n^2 \mu_0 I_0 \ell = \mathcal{V} n^2 \mu_0 I_0 ,$$

where $\mathcal{V} = \text{volume} = \pi R^2 \ell$.

Inductance L is defined so that $\Phi_B = I_0 L$, and then

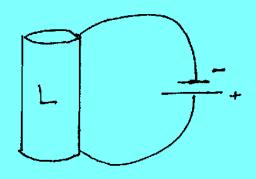
$$\varepsilon = -\frac{d\Phi_B}{dt} = -L\frac{dI_0}{dt}$$

For this system, $L = \mu_0 n^2 \mathcal{V}$



Inductors in Circuits

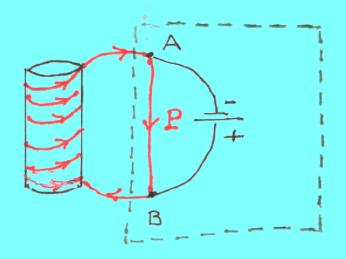
Suppose an inducting solenoid is connected to a battery:



Problem: Since \vec{B} is changing, $\vec{\nabla} \times \vec{E} \neq 0$, so $V(\vec{r})$ is not well-defined.

Solution: If $\vec{B} \approx 0$ outside the inductor, there is a simple solution. (\vec{B} outside is typically small because the return flux spreads out, especially if the length is much larger than the radius. Also, a large number of turns leads to signficant inductance, even if the field inside is not very strong.)

If \vec{B} can be ignored outside the inductor, consider the path shown in red as P, and the region surrounded by the dashed line:



Inside the dashed line, $V(\vec{r})$ can be defined, since $\vec{\nabla} \times \vec{B} \approx 0$, and the region is simply connected (all loops are contractible).

The loop P runs along the center of the wire, except for segment between A and B. If the wire is a good conductor, \vec{E} will vanish inside the wire, so

$$\varepsilon = \oint_P \vec{E} \cdot d\vec{\ell} = \int_A^B \vec{E} \cdot d\vec{\ell} = \frac{\partial \Phi_B}{\partial t} = L \frac{dI}{dt} .$$

So

$$V(A) - V(B) = -L\frac{dI}{dt} .$$

Boundary Conditions from Maxwell Equations

$$egin{aligned} ec{m{
abla}} \cdot ec{m{D}} &=
ho_{\mathrm{free}} &\Longrightarrow & D_1^{\perp} - D_2^{\perp} = \sigma_{\mathrm{free}} \;, \ ec{m{
abla}} \cdot ec{m{E}} &= rac{
ho}{\epsilon_0} &\Longrightarrow & E_1^{\perp} - E_2^{\perp} = rac{\sigma}{\epsilon_0} \;, \ ec{m{
abla}} \cdot ec{m{B}} &= 0 &\Longrightarrow & B_1^{\perp} - B_2^{\perp} = 0 \;, \ ec{m{H}} &\equiv rac{1}{\mu_0} ec{B} - ec{M} &\Longrightarrow & H_1^{\perp} - H_2^{\perp} = M_2^{\perp} - M_1^{\perp} \;. \end{aligned}$$

where 1 = outside material, 2 = inside material.

$$\vec{\nabla} \cdot \vec{\boldsymbol{D}} = \rho_{\text{free}} \quad \Longrightarrow \quad D_1^{\perp} - D_2^{\perp} = \sigma_{\text{free}} \; ,$$

$$\vec{\nabla} \cdot \vec{\boldsymbol{E}} = \frac{\rho}{\epsilon_0} \quad \Longrightarrow \quad E_1^{\perp} - E_2^{\perp} = \frac{\sigma}{\epsilon_0} \; ,$$

$$\vec{\nabla} \cdot \vec{\boldsymbol{B}} = 0 \quad \Longrightarrow \quad B_1^{\perp} - B_2^{\perp} = 0 \; ,$$

$$\vec{\boldsymbol{H}} \equiv \frac{1}{\mu_0} \vec{\boldsymbol{B}} - \vec{\boldsymbol{M}} \quad \Longrightarrow \quad H_1^{\perp} - H_2^{\perp} = M_2^{\perp} - M_1^{\perp} \; .$$

$$\vec{\nabla} \times \vec{\boldsymbol{E}} = -\frac{\partial \vec{\boldsymbol{B}}}{\partial t} \neq \infty \quad \Longrightarrow \quad \vec{\boldsymbol{E}}_1^{\parallel} - \vec{\boldsymbol{E}}_2^{\parallel} = 0 \; ,$$

$$\vec{\boldsymbol{D}} = \epsilon_0 \vec{\boldsymbol{E}} + \vec{\boldsymbol{P}} \quad \Longrightarrow \quad \vec{\boldsymbol{D}}_1^{\parallel} - \vec{\boldsymbol{D}}_2^{\parallel} = \vec{\boldsymbol{P}}_1^{\parallel} - \vec{\boldsymbol{P}}_2^{\parallel} \; ,$$

$$\vec{\nabla} \times \vec{\boldsymbol{H}} = \vec{\boldsymbol{J}}_{\text{free}} + \frac{\partial \vec{\boldsymbol{D}}}{\partial t} \quad \Longrightarrow \quad \vec{\boldsymbol{H}}_1^{\parallel} - \vec{\boldsymbol{H}}_2^{\parallel} = -\hat{\boldsymbol{n}} \times \vec{\boldsymbol{K}}_{\text{free}} \; ,$$

$$\vec{\nabla} \times \vec{\boldsymbol{B}} - \mu_0 \vec{\boldsymbol{J}} + \mu_0 \epsilon_0 \frac{\partial \vec{\boldsymbol{E}}}{\partial t} \quad \Longrightarrow \quad \vec{\boldsymbol{B}}_1^{\parallel} - \vec{\boldsymbol{B}}_2^{\parallel} = -\mu_0 \hat{\boldsymbol{n}} \times \vec{\boldsymbol{K}} \; ,$$

where $\hat{\boldsymbol{n}} = \text{unit outward vector}$, $\vec{\boldsymbol{K}} = \text{surface current density}$.



Conservation of Energy: Poynting's Theorem

Conjecture: the electromagnetic energy stored in a volume \mathcal{V} is given by

$$U_{\mathrm{EM},\mathcal{V}} = \frac{1}{2} \int_{\mathcal{V}} \left[\epsilon_0 |\vec{\boldsymbol{E}}|^2 + \frac{1}{\mu_0} |\vec{\boldsymbol{B}}|^2 \right] d^3 x,$$

which is what we found by looking at the energy stored in capacitors and in solenoids. If so, then

$$\frac{\mathrm{d}U_{\mathrm{EM}}}{\mathrm{d}t} = -P_{\mathrm{particles}} - P_{\mathrm{flux}} ,$$

where $P_{\text{particles}}$ is the power transferred to charged particles, and P_{flux} is the power transmitted electromagnetically through the boundary S of \mathcal{V} . We assume that no particles cross the boundary.



$$egin{aligned} P_{ ext{particles}} &= \sum_{n} ec{m{F}}_{n} \cdot ec{m{v}}_{n} \ &= \sum_{n} q_{n} (ec{m{E}}_{n} + ec{m{v}}_{n} imes ec{m{B}}_{n}) \cdot ec{m{v}}_{n} \ &= \sum_{n} q_{n} ec{m{E}}_{n} \cdot ec{m{v}}_{n} \ . \end{aligned}$$

For continuous matter, $q_n \to \rho d^3 x$, so

$$P_{\text{particles}} = \int_{\mathcal{V}} \rho \vec{\boldsymbol{v}} \cdot \vec{\boldsymbol{E}} \, \mathrm{d}^3 x = \int_{\mathcal{V}} \vec{\boldsymbol{J}} \cdot \vec{\boldsymbol{E}} \, , \mathrm{d}^3 x .$$

If the original conjecture is true,

$$P_{\text{flux}} = -\frac{1}{2} \frac{d}{dt} \int_{\mathcal{V}} \left[\epsilon_0 |\vec{\boldsymbol{E}}|^2 + \frac{1}{\mu_0} |\vec{\boldsymbol{B}}|^2 \right] d^3x - \int_{\mathcal{V}} \vec{\boldsymbol{J}} \cdot \vec{\boldsymbol{E}} d^3x$$

$$= -\int_{\mathcal{V}} d^3x \left[\epsilon_0 \vec{\boldsymbol{E}} \cdot \frac{\partial \vec{\boldsymbol{E}}}{\partial t} + \frac{1}{\mu_0} \vec{\boldsymbol{B}} \cdot \frac{\partial \vec{\boldsymbol{B}}}{\partial t} + \frac{1}{\mu_0} \vec{\boldsymbol{E}} \cdot \left(\vec{\boldsymbol{\nabla}} \times \vec{\boldsymbol{B}} - \mu_0 \epsilon_0 \frac{\partial \vec{\boldsymbol{E}}}{\partial t} \right) \right]$$

$$= -\int_{\mathcal{V}} d^3x \left[-\frac{1}{\mu_0} \vec{\boldsymbol{B}} \cdot (\vec{\boldsymbol{\nabla}} \times \vec{\boldsymbol{E}}) + \frac{1}{\mu_0} \vec{\boldsymbol{E}} \cdot (\vec{\boldsymbol{\nabla}} \times \vec{\boldsymbol{B}}) \right]$$

$$= \frac{1}{\mu_0} \int_{\mathcal{V}} d^3x \vec{\boldsymbol{\nabla}} \cdot (\vec{\boldsymbol{E}} \times \vec{\boldsymbol{B}}) .$$



$$P_{\text{flux}} = \frac{1}{\mu_0} \int_{\mathcal{V}} d^3 x \vec{\nabla} \cdot (\vec{E} \times \vec{B}) ,$$

so,

$$P_{\mathrm{flux}} = \oint_S \vec{m{S}} \cdot \mathrm{d} m{ec{a}} \; ,$$

where

$$ec{m{S}} = rac{1}{\mu_0} ec{m{E}} imes ec{m{B}} \; ,$$

where \vec{S} is called the Poynting vector. \vec{S} describes the flow of energy in space, with units of joules per meter² per second.

Forms of energy conservation:

$$\frac{\mathrm{d}U_{\mathrm{EM},\mathcal{V}}}{\mathrm{d}t} = -\int_{\mathcal{V}} \vec{\boldsymbol{J}} \cdot \vec{E} \,\mathrm{d}^3 x - \oint_{S} \vec{\boldsymbol{S}} \cdot \,\mathrm{d}\vec{\boldsymbol{a}} ,$$

or in its differential form,

$$rac{\partial u_{
m EM}}{\partial t} = - ec{m{J}} \cdot ec{m{E}} - ec{m{
abla}} \cdot ec{m{S}} \; .$$

The work-energy theorem implies that

$$\int_{\mathcal{V}} \vec{\boldsymbol{J}} \cdot \vec{\boldsymbol{E}} \, d^3 x = \frac{\mathrm{d} U_{\mathrm{mech}}}{\mathrm{d} t} \; ,$$

where U_{mech} is the mechanical energy of the particles, meaning the total kinetic energy plus any non-electromagnetic potential energy (e.g., gravitational energy, spring energy, etc.). Thus we can write

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[U_{\mathrm{EM},\mathcal{V}} + U_{\mathrm{mech},\mathcal{V}} \right] = - \oint_{S} \vec{\boldsymbol{S}} \cdot \, \mathrm{d}\boldsymbol{\boldsymbol{a}} \ .$$

From

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[U_{\mathrm{EM},\mathcal{V}} + U_{\mathrm{mech},\mathcal{V}} \right] = - \oint_{S} \vec{\mathbf{S}} \cdot \,\mathrm{d}\vec{\mathbf{a}} ,$$

we can write the differential form

$$\frac{\partial u}{\partial t} = -\vec{\nabla} \cdot \vec{S} ,$$

where

$$u = u_{\rm EM} + u_{\rm mech}$$
,

where u_{mech} is the density of mechanical energy.

Power Transmission

On the blackboard



Conservation of Momentum

On the blackboard

