8.07 Lecture Slides 22 December 2, 2019

## CONSERVATION LAWS, ELECTRODYNAMICS,

and

ELECTROMAGNETIC WAVES

(Next time)

# The Complete Maxwell Equations

$$ec{m{
abla}}\cdot ec{m{E}} = rac{
ho}{\epsilon_0} \qquad ec{m{
abla}} imes ec{m{E}} = -rac{\partial ec{m{B}}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \qquad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

- $\frac{\partial \vec{B}}{\partial t}$  added by Faraday. It restores Galilean relativity: if the magnetic flux through a loop changes, with this addition it does not matter whether  $\vec{\bm{B}}$  changes, or the loop moved.
- $\frac{\partial E}{\partial t}$  added by Maxwell to make RHS divergenceless.





### The Complete Maxwell Equations In Matter

with time, currents flow. There is one more bound charge effect: if  $\vec{P}$  changes

$$\sigma_{\mathrm{top}} = \vec{\boldsymbol{P}} \cdot \hat{\boldsymbol{n}} \; ,$$

 $\sigma_{\text{top}}$ 

Q = PA, where  $P = |\vec{P}|$ , so where  $\hat{n}$  is the upward normal, the direction of  $\vec{P}$ . So

$$I = \frac{\mathrm{d}Q}{\mathrm{d}t} = \frac{\mathrm{d}P}{\mathrm{d}t}A \quad \Longrightarrow \quad |\vec{J}| = \frac{\mathrm{d}P}{\mathrm{d}t}.$$

So

$$ec{J}_b = \vec{m{\nabla}} imes \vec{m{M}} + rac{\partial ec{m{P}}}{\partial t} \ .$$

If polarized material moves, there are other terms, but we'll assume that all our





Starting with

$$ec{m{
abla}}\cdotec{m{E}}=rac{
ho}{\epsilon_0} \qquad ec{m{
abla}} imesec{m{E}}=-rac{\partial ec{m{B}}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \qquad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$ho = 
ho_{
m free} - ec{m{
abla}} \cdot ec{m{P}} \;, \quad ec{m{J}} = ec{m{J}}_{
m free} + ec{m{
abla}} imes ec{m{M}} + rac{\partial ec{m{P}}}{\partial t} \;,$$

and the definitions

$$ec{m{H}}\equivrac{1}{\mu_0}ec{m{B}}-ec{m{M}}\;,\quad ec{m{D}}\equiv\epsilon_0ec{m{E}}+ec{m{P}}\;,$$

one finds

$$ec{m{
abla}}\cdotm{ar{m{D}}}=
ho_{ ext{free}} \qquad ec{m{
abla}} imesm{ar{E}}=-rac{\partialm{ar{B}}}{\partial t}$$

$$ec{m{
abla}} imesec{m{H}}=ec{m{J}}_{ ext{free}}+rac{\partial ec{m{D}}}{\partial t}$$

 $\vec{\nabla} \cdot \vec{B} = 0$ 

## Conductivity: Ohm's Law

$$m{m{J}} = \sigma(m{m{E}} + m{m{v}} imes m{m{B}}) \; ,$$

where  $\vec{v}$  is the velocity of the medium, and

$$\sigma \equiv \text{conductivity}$$
,

$$\rho \equiv \frac{1}{\sigma} = \text{resistivity}.$$

Units:

$$\begin{bmatrix} \vec{J} \end{bmatrix} = \frac{C}{s \cdot m^2} , \quad \begin{bmatrix} \vec{E} \end{bmatrix} = \frac{N}{C} \implies [\sigma] = \frac{C}{s \cdot m^2} \frac{C}{N} = \frac{C^2}{J m s}$$

1 Ohm ( $\Omega$ )  $\equiv \frac{1 \text{ volt}}{\text{ampere}} = \frac{V}{A} = \frac{J/C}{C/s} = \frac{J s}{C^2}$  $\implies [\rho] = \Omega \cdot \mathbf{m}$ 

Numerically, for copper

This is a very crude classical model. Assume:

Drude Model of Resistivity

2) Thermal velocity of electrons is given by

1) Interatomic distance =  $\lambda$ .

$$n = \frac{\text{density}}{\text{atomic weight}} (\text{Avogadro's number})$$

$$= \frac{(8.96 \text{ g/cm}^3)}{(63.5 \text{ g/mole})} \left(6.022 \times 10^{23} \frac{\text{atoms}}{\text{mole}}\right)$$
$$= 8.50 \times 10^{22} / \text{cm}^3 .$$
$$\lambda = \frac{1}{n^{1/3}} = 2.27 \times 10^{-8} \text{ cm}.$$

Drude model gives

$$\rho_{\rm Drude} = 4.3 \times 10^{-7} \; \Omega\text{-m}$$
 ,

while in reality

5) Let f = number of free electrons per atom or molecule.

6) Let n = number density of atoms or molecules. Then

 $\vec{J} = fnq \langle \vec{v} \rangle = \left( \frac{nf\lambda q^2}{2mv_{
m th}} \right)$ 

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 $\sigma = rac{nf\lambda q^2}{2mv_{
m th}}$ 

4)  $\langle \vec{\boldsymbol{v}} \rangle = \frac{1}{2} \vec{\boldsymbol{a}} \Delta t$ , where  $\vec{\boldsymbol{a}} = q \vec{\boldsymbol{E}} / m_e$ .

3)  $\Delta t = \lambda/v_{\rm th} = \text{mean time between collisions},$ 

where k= Boltzmann constant, T= temperature. For  $T=300\,\rm K,~v_{th}=1.17\times10^7~cm/s=2.6\times10^5$  mile/hour.

 $\frac{1}{2}m_e v_{\rm th}^2 = \frac{3}{2}kT \; ,$ 

$$\rho_{\text{Copper}} = 1.68 \times 10^{-8} \,\Omega\text{-m}.$$

So copper conducts about 25 times better than the Drude model predicts.

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## Typical Values of Resistivity

Griffiths, Table 7.1, resistivities in  $\Omega$ -m:

Conductors:

Silver:  $1.59 \times 10^{-8}$ 

Iron:  $9.61 \times 10^{-8}$ 

Graphite:  $1.6 \times 10^{-5}$ 

Semiconductors:

Sea water: 0.2

Germanium: 0.46

Silicon: 2500

Insulators:

Water (pure):  $8.3 \times 10^3$ 

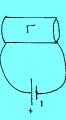
Glass:  $10^9 - 10^{14}$ 

Teflon:  $10^{22} - 10^{24}$ 

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## Inductors in Circuits

Suppose an inducting solenoid is connected to a battery:



Problem: Since  $\vec{B}$  is changing,  $\vec{\nabla} \times \vec{E} \neq 0$ , so  $V(\vec{r})$  is not well-defined.

Solution: If  $\vec{B} \approx 0$  outside the inductor, there is a simple solution. ( $\vec{B}$  outside is typically small because the return flux spreads out, especially if the length is much larger than the radius. Also, a large number of turns leads to significant inductance, even if the field inside is not very strong.)

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# Faraday's Law and Inductors

Consider a long thin circular solenoid, of n turns per unit length, length  $\ell$ , radius R, with  $\ell \gg R$ .

Inside  $\vec{B} \approx B_0 \hat{z}$ , outside  $\vec{B} \approx 0$ , since the return flux is spread over an area that grows with  $\ell$ .

Ampere's law,  $\oint \vec{B} \cdot d\vec{\ell} = \mu_0 E_{\rm enc} \implies \vec{B} = n \mu_0 I_0 \hat{z}$ .

Magnetic flux  $\Phi_B = \pi R^2 (n\mu_0 I_0)$  per turn, so

 $\Phi_B = \pi R^2 n^2 \mu_0 I_0 \ell = \mathcal{V} n^2 \mu_0 I_0 \; ,$ 

where  $\mathcal{V} = \text{volume} = \pi R^2 \ell$ .

Inductance L is defined so that  $\Phi_B = I_0 L$ , and then

$$\varepsilon = -\frac{d\Phi_B}{dt} = -L\frac{dI_0}{dt}$$

For this system,  $L = \mu_0 n^2 \mathcal{V}$ 

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If  $\vec{B}$  can be ignored outside the inductor, con-

sider the path shown in red as P, and the region surrounded by the dashed line:  $\vec{P} = \vec{P} = \vec{$ 

Inside the dashed line,  $V(\vec{r})$  can be defined, since  $\vec{\nabla} \times \vec{B} \approx 0$ , and the region is simply connected (all loops are contractible).

The loop P runs along the center of the wire, except for segment between A and B. If the wire is a good conductor,  $\vec{E}$  will vanish inside the wire, so

$$\varepsilon = \oint_P \vec{E} \cdot d\vec{\ell} = \int_A^B \vec{E} \cdot d\vec{\ell} = \frac{\partial \Phi_B}{\partial t} = L \frac{dI}{dt}$$

So

$$V(A) - V(B) = -L\frac{dI}{dt} \ .$$

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# **Boundary Conditions from Maxwell Equations**

$$\vec{\nabla} \cdot \vec{\boldsymbol{D}} = \rho_{\mathrm{free}} \quad \Longrightarrow \quad D_1^{\perp} - D_2^{\perp} = \sigma_{\mathrm{free}} \; ,$$
 
$$\vec{\nabla} \cdot \vec{\boldsymbol{E}} = \frac{\rho}{\epsilon_0} \quad \Longrightarrow \quad E_1^{\perp} - E_2^{\perp} = \frac{\sigma}{\epsilon_0} \; ,$$
 
$$\vec{\nabla} \cdot \vec{\boldsymbol{B}} = 0 \quad \Longrightarrow \quad B_1^{\perp} - B_2^{\perp} = 0 \; ,$$
 
$$\vec{\boldsymbol{H}} \equiv \frac{1}{\mu_0} \vec{\boldsymbol{B}} - \vec{\boldsymbol{M}} \quad \Longrightarrow \quad H_1^{\perp} - H_2^{\perp} = M_2^{\perp} - M_1^{\perp} \; .$$

where 1 = outside material, 2 = inside material.

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## Conservation of Energy: Poynting's Theorem

Conjecture: the electromagnetic energy stored in a volume  $\mathcal V$  is given by

$$U_{\mathrm{EM},\mathcal{V}} = \frac{1}{2} \int_{\mathcal{V}} \left[ \epsilon_0 |\vec{\boldsymbol{E}}|^2 + \frac{1}{\mu_0} |\vec{\boldsymbol{B}}|^2 \right] \, \mathrm{d}^3 x,$$

which is what we found by looking at the energy stored in capacitors and in solenoids. If so, then

$$\frac{\mathrm{d}U_{\rm EM}}{\mathrm{d}t} = -P_{\rm particles} - P_{\rm flux} \ , \label{eq:equation_equation}$$

where  $P_{\text{particles}}$  is the power transferred to charged particles, and  $P_{\text{flux}}$  is the power transmitted electromagnetically through the boundary S of  $\mathcal{V}$ . We assume that no particles cross the boundary.

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 $\vec{\nabla} \cdot \vec{\boldsymbol{D}} = \rho_{\text{free}} \implies D_1^{\perp} - D_2^{\perp} = \sigma_{\text{free}} \;,$   $\vec{\nabla} \cdot \vec{\boldsymbol{E}} = \frac{\rho}{\epsilon_0} \implies E_1^{\perp} - E_2^{\perp} = \frac{\sigma}{\epsilon_0} \;,$   $\vec{\nabla} \cdot \vec{\boldsymbol{B}} = 0 \implies B_1^{\perp} - B_2^{\perp} = 0 \;,$   $\vec{\boldsymbol{H}} \equiv \frac{1}{\mu_0} \vec{\boldsymbol{B}} - \vec{\boldsymbol{M}} \implies H_1^{\perp} - H_2^{\perp} = M_2^{\perp} - M_1^{\perp} \;.$   $\vec{\nabla} \times \vec{\boldsymbol{E}} = -\frac{\partial \vec{\boldsymbol{B}}}{\partial t} \neq \infty \implies \vec{\boldsymbol{E}}_1^{\parallel} - \vec{\boldsymbol{E}}_2^{\parallel} = 0 \;,$   $\vec{\boldsymbol{D}} = \epsilon_0 \vec{\boldsymbol{E}} + \vec{\boldsymbol{P}} \implies \vec{\boldsymbol{D}}_1^{\parallel} - \vec{\boldsymbol{D}}_2^{\parallel} = \vec{\boldsymbol{P}}_1^{\parallel} - \vec{\boldsymbol{P}}_2^{\parallel} \;,$   $\vec{\boldsymbol{\nabla}} \times \vec{\boldsymbol{H}} = \vec{\boldsymbol{J}}_{\text{free}} + \frac{\partial \vec{\boldsymbol{D}}}{\partial t} \implies \vec{\boldsymbol{H}}_1^{\parallel} - \vec{\boldsymbol{H}}_2^{\parallel} = -\hat{\boldsymbol{n}} \times \vec{\boldsymbol{K}}_{\text{free}} \;,$   $\vec{\boldsymbol{\nabla}} \times \vec{\boldsymbol{B}} - \mu_0 \vec{\boldsymbol{J}} + \mu_0 \epsilon_0 \frac{\partial \vec{\boldsymbol{E}}}{\partial t} \implies \vec{\boldsymbol{B}}_1^{\parallel} - \vec{\boldsymbol{B}}_2^{\parallel} = -\mu_0 \hat{\boldsymbol{n}} \times \vec{\boldsymbol{K}} \;,$ where  $\hat{\boldsymbol{n}}$  = unit outward vector,  $\vec{\boldsymbol{K}}$  = surface current density.

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$$egin{align} P_{ ext{particles}} &= \sum_{n} ec{m{F}}_{n} \cdot ec{m{v}}_{n} \ &= \sum_{n} q_{n} (ec{m{E}}_{n} + ec{m{v}}_{n} imes ec{m{B}}_{n}) \cdot ec{m{v}}_{n} \ &= \sum_{n} q_{n} ec{m{E}}_{n} \cdot ec{m{v}}_{n} \ . \end{split}$$

For continuous matter,  $q_n \to \rho d^3 x$ , so

$$P_{\rm particles} = \int_{\mathcal{V}} \rho \vec{\boldsymbol{v}} \cdot \vec{\boldsymbol{E}} \, \mathrm{d}^3 x = \int_{\mathcal{V}} \vec{\boldsymbol{J}} \cdot \vec{\boldsymbol{E}} \, \, \mathrm{d}^3 x \; .$$

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If the original conjecture is true,

$$\begin{split} P_{\text{flux}} &= -\frac{1}{2} \frac{\mathrm{d}}{\mathrm{d}t} \int_{\mathcal{V}} \left[ \epsilon_0 |\vec{\boldsymbol{E}}|^2 + \frac{1}{\mu_0} |\vec{\boldsymbol{B}}|^2 \right] \mathrm{d}^3 x - \int_{\mathcal{V}} \vec{\boldsymbol{J}} \cdot \vec{\boldsymbol{E}} \, \mathrm{d}^3 x \\ &= -\int_{\mathcal{V}} \mathrm{d}^3 x \left[ \epsilon_0 \vec{\boldsymbol{E}} \cdot \frac{\partial \vec{\boldsymbol{E}}}{\partial t} + \frac{1}{\mu_0} \vec{\boldsymbol{B}} \cdot \frac{\partial \vec{\boldsymbol{B}}}{\partial t} + \frac{1}{\mu_0} \vec{\boldsymbol{E}} \cdot \left( \vec{\nabla} \times \vec{\boldsymbol{B}} - \mu_0 \epsilon_0 \frac{\partial \vec{\boldsymbol{E}}}{\partial t} \right) \\ &= -\int_{\mathcal{V}} \mathrm{d}^3 x \left[ -\frac{1}{\mu_0} \vec{\boldsymbol{B}} \cdot (\vec{\nabla} \times \vec{\boldsymbol{E}}) + \frac{1}{\mu_0} \vec{\boldsymbol{E}} \cdot (\vec{\nabla} \times \vec{\boldsymbol{B}}) \right] \\ &= \frac{1}{\mu_0} \int_{\mathcal{V}} \mathrm{d}^3 x \vec{\nabla} \cdot (\vec{\boldsymbol{E}} \times \vec{\boldsymbol{B}}) \ . \end{split}$$

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## $P_{\text{flux}} = \frac{1}{\mu_0} \int_{\mathcal{V}} d^3 x \vec{\nabla} \cdot (\vec{E} \times \vec{B}) ,$

so,

$$P_{\text{flux}} = \oint_{S} \vec{\boldsymbol{S}} \cdot \mathrm{d} \boldsymbol{a} \; ,$$

$$m{ec{S}} = rac{1}{\mu_0} m{ec{E}} imes m{ec{B}} \; ,$$

with units of joules per meter<sup>2</sup> per second. where  $\vec{S}$  is called the Poynting vector.  $\vec{S}$  describes the flow of energy in space,

## Forms of energy conservation:

$$\frac{\mathrm{d}U_{\mathrm{EM},\gamma}}{\mathrm{d}t} = -\int_{\gamma} \vec{\boldsymbol{J}} \cdot \vec{E} \, \mathrm{d}^3 x - \oint_{S} \vec{\boldsymbol{S}} \cdot \mathrm{d} \vec{\boldsymbol{a}} \;,$$

or in its differential form,

$$rac{\partial u_{
m EM}}{\partial t} = - ec{m{J}} \cdot ec{m{E}} - ec{m{
abla}} \cdot ec{m{S}} \; .$$

The work-energy theorem implies that

$$\int_{\mathcal{V}} \vec{\boldsymbol{J}} \cdot \vec{\boldsymbol{E}} \, d^3 x = \frac{\mathrm{d} U_{\mathrm{mech}}}{\mathrm{d} t} \,,$$

energy plus any non-electromagnetic potential energy (e.g., gravitational energy, spring energy, etc.). Thus we can write where  $U_{\mathrm{mech}}$  is the mechanical energy of the particles, meaning the total kinetic

$$\frac{\mathrm{d}}{\mathrm{d}t} [U_{\mathrm{EM}, \nu} + U_{\mathrm{mech}, \nu}] = -\oint_{S} \vec{\mathbf{S}} \cdot \mathrm{d}\vec{a} .$$

From

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[ U_{\mathrm{EM}, \mathcal{V}} + U_{\mathrm{mech}, \mathcal{V}} \right] = - \oint_{S} \vec{\boldsymbol{S}} \cdot \mathrm{d} \vec{\boldsymbol{a}} \; ,$$

we can write the differential form

$$\frac{\partial u}{\partial t} = -\vec{\nabla} \cdot \vec{S} \; ,$$

$$u = u_{\rm EM} + u_{\rm mech}$$
,

where  $u_{\text{mech}}$  is the density of mechanical energy.

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