

Introduction

Capstone Project Submission

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- Scheduled project review date/time: 3/19/2024/1:30pm EST

Business Understanding

It is my task to help companies with computer vision for their A.I. tennis ball machines.

Data Understanding

I created all the data used in this project. I used roughly 6,000 images that consisted of a balanced class of forehand and backhand tennis shots. The limitations of the dataset was that it was a fairly small set of data. The images used only consisted of myself hitting forehand and backhand tennis shots. The data used for this project was useful to build a convolutional neural network for image classification because their was a minimal amount of variance in the data used. The neural net was able to learn specific patterns about forehands and backhands with minimal "noise" in the data because of the consistency of the data used.

Dataset:ForehandsandBackhands

Data Preparation

I started by filming myself in a few different locations hitting approximately 200 forehands and 200 backhands. I then used

an open source editing program called "Shotcut" to edit all of my swings from the start of my swing up until the point of contact with the tennis ball. I then converted these edited video shots into an mp4 format so that they could be extracted into frames. One shot clip yieled roughly 15 images of data. I extracted the frames into folders and labeled the frames as either belonging to one of two classes "1" for forehand and "0" for backhand. I constructed an iterator into my pipeline to be able to call on specific "batches" of data. I then scaled my data in the pipeline to make sure that all the images used were the same size. I then set up a train, test, split which was 80% for training, 10% for validation, and 10% for testing. I then set up a way to save and load my data after it has been trained into my pipeline so that more data could be input in the future.

For reproducibility I uploaded my data to Kaggle and tested my notebook in Google Colab to ensure my notebook would run smoothly. If you wish to access the data and run this notebook on another platform such as Google Colab you will have to have a Kaggle account.

- In the cell below you will have to enter your Kaggle username and API Key. This creating token link will help give you instructions on how to obtain an API key.
- This link is also helpful for more information on how to use Kaggle

```
In [ ]:
         import json
         import os
         from pathlib import Path
         # please enter your Kaggle username and api key here
         username = ''
         key = ''
         # your api key
         api kev = {
         'username': username,
         'key': key}
         # uses pathlib Path
         kaggle path = Path('/root/.kaggle')
         os.makedirs(kaggle path, exist ok=True)
         # opens file and dumps python dict to json object
         with open (kaggle path/'kaggle.json', 'w') as handl:
             json.dump(api key,handl)
```

```
os.chmod(kaggle path/'kaggle.json', 600)
In [ ]:
         # This downloads the images for training and testing
         !kaggle datasets download -d adammarianacci/forehands-and-backhands
         !unzip forehands-and-backhands.zip
In [ ]:
         # Importing the necessary libraries
         import pandas as pd
         import numpv as np
         import matplotlib.pyplot as plt
         import seaborn as sns
         import cv2
         import imghdr
         import os
         import PIL
         import tensorflow as tf
         import pickle
         import hashlib
         from tensorflow import keras
         from tensorflow.keras import layers
         from tensorflow.keras.models import Sequential
         from tensorflow.keras.layers import Conv2D, MaxPooling2D, Dense, Flatten, Dropout
         from tensorflow.keras.metrics import Precision, Recall, BinaryAccuracy
         from tensorflow.keras.models import load model
         from tensorflow.keras.optimizers import Adam, Adamax
         from tensorflow.keras.regularizers import l2
         from sklearn.model selection import train test split, cross val score
         from sklearn.metrics import accuracy score, precision score, confusion matrix
         import warnings
         warnings.filterwarnings('ignore')
```

The cell below enables you to select videos within a specified folder. The function enables you to extract frames from the video file and puts them into a specified folder within the directory. It iterates thru all video files ending with' mp4' and 'avi' and saves the extracted frames into a specified folder. If you wish to use this function uncomment the cell beloew and use your own file paths for the 'video_directory' and 'output directory'

```
# video directory = '/home/adam/Desktop/video test'
# # Output directory for extracted frames
# output directory = '/home/adam/Desktop/frame test'
# # Function to extract frames from a video file
# def extract frames(video file, output dir):
      # Open the video file
      vid = cv2.VideoCapture(video file)
      if not vid.isOpened():
          print(f"Error: Couldn't open video file '{video file}'")
          return
      # Create output directory if it doesn't exist
      os.makedirs(output dir, exist ok=True)
      # Initialize frame counter
      current frame = 0
      # Read frames and save them as images
#
      while True:
          success, frame = vid.read()
          if not success:
              print(f"End of video reached or couldn't read frame from '{video file}'")
              break
          if frame.shape[0] > 0 and frame.shape[1] > 0:
              # Save the frame as an image
              output path = os.path.join(output dir, f'{os.path.splitext(os.path.basename(video file)})
              cv2.imwrite(output path, frame)
              current frame += 1
          else:
              print(f"Error: Invalid frame size in '{video file}'")
      vid.release()
# # Iterate over video files in the directory
# for video file in os.listdir(video directory):
      if video file.endswith('.mp4') or video file.endswith('.avi'):
          video path = os.path.join(video directory, video file)
          extract frames(video path, output directory)
```

```
In [ ]:  # Defining a data directory
    data_dir = 'data'
```

The cell below sets up a variable to recognize different images types.

```
In [ ]:  # Defining image extensions
  image_exts = ['jpeg', 'jpg', 'bmp', 'png']
```

The cell below shows that my data directory contains my 2 classes.

```
In [ ]: # Checking the contents of my data directory
    os.listdir(data_dir)
```

The cell below sets up a for loop that goes thru the folders and all images in the data directory and removes any images that does not have the appropriate image extensions. Note the skipping output is just skipping directories but there are no issues with the actual files in the directories.

```
In [ ]:
         # Iterate through directories containing images
        for image class in os.listdir(data dir):
             class dir = os.path.join(data dir, image class)
             if not os.path.isdir(class dir):
                 continue # Skip if not a directory
             for image in os.listdir(class dir):
                 image path = os.path.join(class dir, image)
                 if not os.path.isfile(image path):
                     print('Skipping non-file:', image path)
                     continue # Skip if not a file
                 try:
                     tip = imghdr.what(image path) # Get image type directly
                     if tip is None or tip not in image exts:
                         print('Image not in ext list or invalid format: {}'.format(image path))
                         os.remove(image path)
                 except Exception as e:
                     print('Issue with image {}: {}'.format(image path, str(e)))
                     # Log the error or handle it appropriately
```

Here we start to preprocess the data, we are starting with approx. 6,000 images belonging to two classes that are

balanced. This sets up the data pipleline and enables access to "batches" of data using the iterator.

```
In [ ]:
         # loading in tensorflow and keras on our data
         data = tf.keras.preprocessing.image dataset from directory('data')
In [ ]:
         # allow acces to generator from the data pipeline
         data iterator = data.as numpy iterator()
In [ ]:
         # allow access to pull a batch (32 images) of data
         batch = data iterator.next()
         batch size of 32, image size of 256x256, 3 (channels of color, RGB)
In [ ]:
         # Images represented as numpy arrays
         batch[0].shape
In [ ]:
         # representing the labels in the batch
          batch[1]
         Below I am plotting some images from a batch to see which classes my images belong to and we can see Forehands = 1 and
         Backhands = 0.
In [ ]:
          # viewing some data to see what class my frames belong to
         fig, ax = plt.subplots(ncols=4, figsize=(20,20))
         for idx, img in enumerate(batch[0][:4]):
              ax[idx].imshow(imq.astype(int))
              ax[idx].title.set text(batch[1][idx])
         The below cell transforms the images "X" to all be scaled for optimization in the data pipeline. I typed in .map function
         using lambda in google and found this solution
In [ ]:
         # scaling data in the pipeline
```

data = data.map(lambda X,y: (X/255, y))

```
In [ ]:
         # The iterator is now scaled from 0 to 1
         scaled iterator = data.as numpy iterator()
In [ ]:
          # renaming the variable batch so that it will always be scaled
         batch = scaled iterator.next()
In [ ]:
         # confirming the min is 0
         batch[0].min()
In [ ]:
         # confirming max is 1
         batch[0].max()
         Here we are visualizing another batch of data to make sure everything is working on the scaled data.
In [ ]:
         # viewing a batch of data to see what class my frames belong to
         fig, ax = plt.subplots(ncols=4, figsize=(20,20))
         for idx, img in enumerate(batch[0][:4]):
              ax[idx].imshow(img)
              ax[idx].title.set text(batch[1][idx])
         Here I am ready to start my train, test, split. I check the length of the data (in batches) and we see we have 89 batches
In [ ]:
         # Checking the length of the data in batches
          len(data)
         I shuffled the data so that when I eventually use it for modeling it is not biased by learning about the images in any
         particular order.
In [ ]:
          # Shuffle the dataset
         data shuffled = data.shuffle(buffer size=len(data))
```

This splits that data for training, testing, and validation by the number by batches. I designated 80% to training which is 158

batches, 10% testing which is 15 batches, and 10% for validation which is 15 batches.

```
In [ ]:
    # Splitting data into 80% training, 10% testing, 10% validation
    train_size = int(len(data_shuffled)*.8)
    val_size = int(len(data_shuffled)*.1)+1
    test_size = int(len(data_shuffled)*.1)+1
```

Confirming the splits equal to 198 batches.

```
In [ ]: # 198 batches
    train_size+val_size+test_size
```

The cell below now sets up the variables to either take or skip certain batches.

```
In [ ]:
    train = data_shuffled.take(train_size)
    val = data_shuffled.skip(train_size).take(val_size)
    test = data_shuffled.skip(train_size + val_size).take(test_size)
```

Modeling

```
In [ ]: model = Sequential()
```

The first layer is a convolutional layer with 16 filters, it is 3 pixels x 3pixels, and a stride of 1 so it goes pixel by pixel. The relu activation function takes into account any non linear patterns. The input shape is the size of our images. The next 2 layers are condensing the rows and width. The last 2 layers are dense fully connected layers and a sigmoid activation function is applied for the output to be between 0 and 1. An output of closer to 1 will be part of the forehand class, and an output of 0 will be closer to the Backhand class.

```
In [ ]: model.add(Conv2D(16, (3,3), 1, activation='relu', input_shape=(256,256,3)))
    model.add(MaxPooling2D())
    model.add(Conv2D(32, (3,3), 1, activation='relu'))
    model.add(MaxPooling2D())
```

```
model.add(Conv2D(16, (3,3), 1, activation='relu'))
model.add(MaxPooling2D())

model.add(Flatten())
model.add(Dense(256, activation='relu'))
model.add(Dense(1, activation='sigmoid'))
```

The cell below passes through an optomizer, and BinaryCrossentropy to our loss because we are dealing with Binary Classification, and the metrics we are going to be evaluating on will be accuracy.

```
In [ ]: model.compile('adam', loss=tf.losses.BinaryCrossentropy(), metrics=['accuracy'])
```

The cell below shows how the model takes in the data.

```
In [ ]: model.summary()

In [ ]: # Creating a log directory that is my logs folder logdir = 'logs'
```

The cell below creates a variable 'tensorboard' callback' which allows you to log the model training while it trains.

```
In [ ]: tensorboard_callback = tf.keras.callbacks.TensorBoard(log_dir=logdir)
```

The cell below sets up the training process at 20 epochs for the baseline model. It will also be evaluating on our validation data as well. The below cell is commented out to save time as it takes around 45 minutes to run. The model was quickly overfitting after a few epochs so to save time I adjusted the model to 3 epochs which is currently our best performing model. This also saves the model as an h5 file in the specified folder 'models'

```
In [ ]: # This line of code will initiate training, it will take approx 45 minutes
    # hist = model.fit(train, epochs=20, validation_data=val, callbacks=[tensorboard_callback])
    # model.save(os.path.join('models', 'forehandbackhandmodel_20.h5'))
```

```
# III15 LINE OF CODE WILL INILIATE LEATINING, IL WILL LAKE APPROX 15 MINULES
hist = model.fit(train, epochs=3, validation data=val, callbacks=[tensorboard callback])
model.save(os.path.join('models', 'forehandbackhandmodel 3.h5'))
```

Plotting the performance which led to 100% and a decreasing loss close that dropped close to 0.

```
In [ ]:
         val loss, val accuracy = model.evaluate(val)
         print(f"Val Loss: {val loss}")
         print(f"Val Accuracy: {val accuracy}")
In [ ]:
         # Visualizing our loss
         fig = plt.figure()
         plt.plot(hist.history['loss'], color='teal', label='loss')
         plt.plot(hist.history['val loss'], color='orange', label='val loss')
         fig.suptitle('Loss', fontsize=20)
         plt.legend(loc="upper left")
         plt.show()
In [ ]:
         # Visualizing our accuracy
         fig = plt.figure()
         plt.plot(hist.history['accuracy'], color='teal', label='accuracy')
         plt.plot(hist.history['val accuracy'], color='orange', label='val accuracy')
         fig.suptitle('Accuracy', fontsize=20)
         plt.legend(loc="upper left")
         plt.show()
```

After we have trained on our model on training and validation data and have visualized the loss and metrics of accuracy we can see how it performs on testing images.

```
In [ ]:
         # loading in a newly trained model to evaluate on testing images
         new model = load model(os.path.join('models', 'forehandbackhandmodel 3.h5'))
```

Evaluating performance on our testing data

```
In [ ]:
         precision = Precision()
         recall = Recall()
         accuracy = BinaryAccuracy()
In [ ]:
         for batch in test.as numpy iterator():
             X, y = batch
             y hat = model.predict(X)
             precision.update state(y, y hat)
             recall.update state(y, y hat)
             accuracy.update state(y, y hat)
        Our testing data is performing at 100% accuracy.
In [ ]:
         print(f'Precision:{precision.result().numpy()}, Recall:{recall.result().numpy()}, Accuracy:{accuracy
In [ ]:
         # Performing a test on an image not in our batch
         img = cv2.imread('data/backhands/frames/backhandvids 1004.jpg')
         plt.imshow(cv2.cvtColor(img, cv2.COLOR BGR2RGB))
         plt.show()
In [ ]:
         resize = tf.image.resize(img, (256,256))
         plt.imshow(resize.numpy().astype(int))
         plt.show()
         Predicting on a random image the model has never seen before. This preprocesses an image an image array and feeds it
        into the NN 'model' and returns a prediction probability score.
In [ ]:
         y hat = model.predict(np.expand dims(resize/255, 0))
In [ ]:
         # It is predicting what our image is
         y hat
```

The cell below is a conditional statement that prints out what the predicted class is. We are taking the probability score of 'v hat' which is our target class prediction and setting a threshold of 0.5. If the probability score is greather than 0.5 the

predicted class will be a forehand and if it is less than 0.5 the predicted class will be a backhand.

```
if y_hat > 0.5:
    print(f'Predddicted class is Forehand')
else:
    print(f'Predicted class is Backhand')
```

Model Evaluation

My best performing model was the CNN with an 'Adam' optomizer and loss function set to 'Binary Cross-Entropy' trained over 3 epochs. I adjusted the model from 20 epochs to 3 because the model was quickly acheiving a 100% accuracy score so this approximately saved about 1 hour of training time. The model was showing 100% accuracy scores on training and testing data. The model is most likely overfitting due to the low variance in my data making it over confident.

Conclusions

The model showed scores of 100% on accuracy, precision, and recall. The model is performing perfectly most likely due to the low variance in my dataset leading to it's overconfidence. To build a more robust model 10x more data with high variance needs to be inputted into to the model.

Limitations

Limited amount of data was used. The data consisted only of myself from one camera angle in a few different locations with minimal background "noise". Additionally the model only learned about two-handed backhand shots and not one-handed backhand shots.

Recommendations

We need to increase the amount of variance in the dataset. Since the current model is performing so well we can start to add images from the start of swing preparation until the completion of the swing and not just up until the point of contact

with the ball.