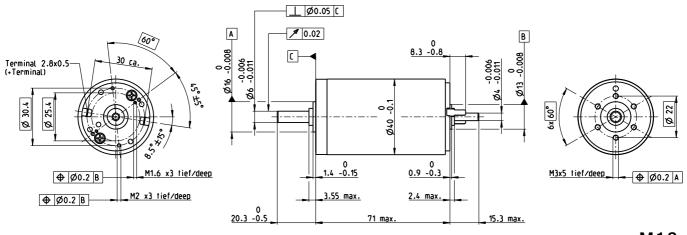
Part Numbers



M 1:2

9	Stock program
	Standard program
	Special program (on request)

			148866	148867	148877	218008	218009	218010	218011	218012	218013	218014
M	otor Data											
	Values at nominal voltage											
1	Nominal voltage	V	12	24	48	48	48	48	48	48	48	48
2	No load speed	rpm	6920	7580	7590	6420	5560	3330	2690	2130	1720	1420
3	No load current	mA	241	137	68.6	53.7	43.7	21.9	16.6	12.5	9.66	7.76
4	Nominal speed	rpm	6380	6940	7000	5810	4930	2710	2060	1510	1080	781
5	Nominal torque (max. continuous torque)	mNm	94.9	177	187	186	180	189	190	192	192	190
6	Nominal current (max. continuous curren	t) A	6	6	3.17	2.66	2.23	1.4	1.13	0.909	0.73	0.6
7	Stall torque	mNm	1720	2420	2560	2040	1620	1020	814	655	523	424
8	Stall current	Α	105	80.2	42.4	28.6	19.7	7.43	4.79	3.06	1.97	1.32
9	Max. efficiency	%	88	91	92	91	91	89	89	88	86	85
	Characteristics											
10	Terminal resistance	Ω	0.115	0.299	1.13	1.68	2.44	6.46	10	15.7	24.4	36.3
11	Terminal inductance	mH	0.024	0.082	0.33	0.46	0.613	1.7	2.62	4.14	6.41	9.32
12	Torque constant	mNm/A	16.4	30.2	60.3	71.3	82.2	137	170	214	266	321
13	Speed constant	rpm/V	581	317	158	134	116	69.7	56.2	44.7	35.9	29.8
14	Speed / torque gradient	rpm/mNm	4.05	3.14	2.97	3.16	3.45	3.29	3.31	3.27	3.29	3.37
15	Mechanical time constant	ms	5.89	4.67	4.28	4.2	4.19	4.16	4.15	4.15	4.15	4.16
16	Rotor inertia	gcm ²	139	142	137	127	116	121	120	121	120	118

Thermal data n [rpm] Continuous operation 4.7 K/W Thermal resistance housing-ambient In observation of above listed thermal resistance Thermal resistance winding-housing 1.9 K/W 150 W (lines 17 and 18) the maximum permissible winding 19 Thermal time constant winding 20 Thermal time constant motor 41.5 s 12000 148877 temperature will be reached during continuous 809 s operation at 25°C ambient. Ambient temperature -30...+100°C 8000 = Thermal limit. 22 Max. winding temperature +155°C Mechanical data (ball bearings) Short term operation 4000 23 Max. speed 24 Axial play 12000 rpm The motor may be briefly overloaded (recurring). 0.05 - 0.15 mm Radial play 0.025 mm Assigned power rating 5.6 N 110 N Max. axial load (dynamic) 150 50 100 200 M [mNm] Max. force for press fits (static) (static, shaft supported) 1.0 2.0 3.0 1200 N 28 Max. radial load, 5 mm from flange 28 N

Other specifications

- 29 Number of pole pairs30 Number of commutator segments
- Weight of motor

Values listed in the table are nominal. Explanation of the figures on page 72.

Option

Preloaded ball bearings

Industrial version with radial shaft seal ring (resulting in increased no load current). IP54 protection only if mounted on brush side, in compliance with maxon modular system.

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480 g

Planetary Gearhead Ø42 mm 3 - 15 Nm Page 396 Planetary Gearhead Recommended Electronics: Ø52 mm **Notes** Page **34** 4 - 30 Nm ESCON Mod. 50/5 487 Page 401 ESCON Mod. 50/8 (HE)

ESCON 50/5

EPOS4 50/5

EPOS4 70/15

EPOS2 P 24/5

ESCON 70/10

EPOS4 Mod./Comp. 50/5 EPOS4 Module 50/8

EPOS4 Comp. 50/8 CAN

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Encoder MR 256 - 1024 CPT, 3 channels Page 464 Encoder HED_ 5540 500 CPT, 3 channels Page 471/474 Brake AB 28 24 VDC 0.4 Nm Page 519 Industrial Version IP54* Encoder HEDL 9140 Page 478 Brake AB 28 Page 520 End cap Page 525

Details on catalog page 34

maxon DC motor 141 April 2020 edition / subject to change