

Monadic Concurrent Linear Logic Programming

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□ LoliMon

Our paper introduces a new logic-programming language, **LoliMon**, which features:

- Goal-directed, backward-chaining proof search corresponds to **serial computation**
- Saturation-based, forward-chaining proof search corresponds to **concurrent computation**
- Linear logic allows **stateful computation**

A **monad** is used to smoothly integrate forward and backward proof search.

□ Backward Chaining

- Prolog-style logic programming
(e.g. Prolog, λ Prolog, Lolli)
- Goal-directed and Focussed
- Based on asynchronous formulas—
Right rules can always be safely applied
- Serial computation—
Atomic goals are function calls

□ **Forward Chaining**

- Bottom-up logic programming
(e.g. Datalog, Concurrent Constraints, Logical Algorithms)
- Context-driven
- Based on saturation—
System computes until it gets stuck
- Concurrent computation—
Context formulas are processes

□ **Combining Paradigms**

It is useful to have a system which can use both forward and backward reasoning.

- larger, more expressive formula language
- representation of both concurrent and serial computation

We want a principled way to mix search strategies.

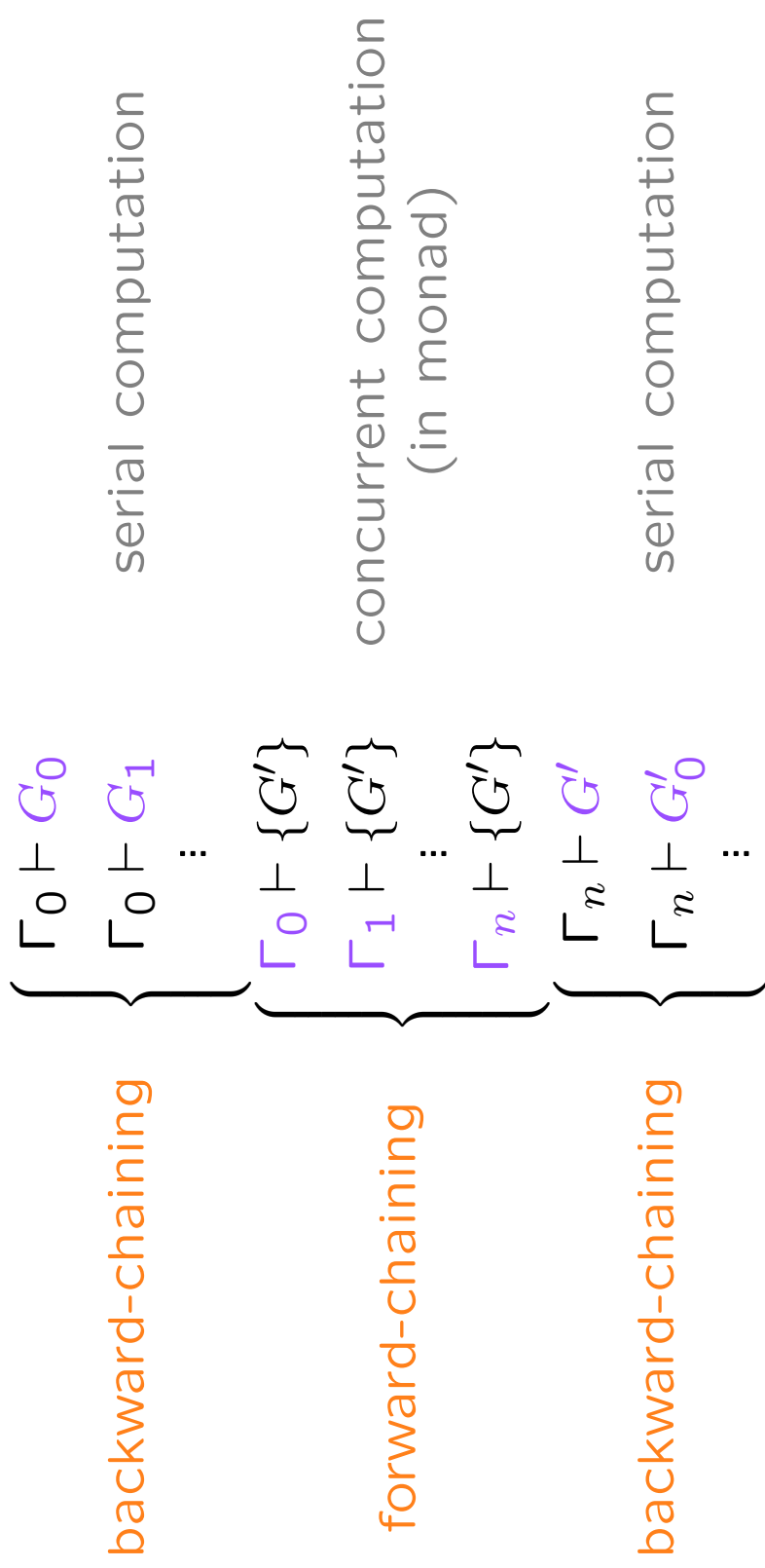
- clean and predictable operational semantics
- computationally useful proof structures

□ Monadic Uniform Proofs

- Uniform proofs (**goal-directed**, **focussed**) underlie Prolog-style languages.
- Synchronous formulas destroy uniformity since they are not goal-directed.
- We can combine synchronous formulas and uniform proof structure with a monad, $\{\cdot\}$.
 - Encapsulate treatment of synchronous formulas.
 - Non goal-directed behavior is analogous to an effect in a functional language.

□ LoliMon Execution

The main branch of a LoliMon execution has the following form:



Monadic goal signals switch to forward-chaining.

□ Lollimon Execution– Details

The forward-chaining section of a Lollimon execution has following (simplified) form:

$$\frac{\Gamma_n \vdash G'}{\Gamma_n \vdash \{G'\}} \quad \vdots \quad \frac{\frac{\Gamma' \vdash A_1 \quad B_0 \vdash B_0}{\Gamma' \vdash A_0} \quad \frac{B_0, B_1, B_0 \supset \{C_0\}, \Gamma' \vdash \{G'\}}{B_0, A_1 \supset \{B_1\}, B_0 \supset \{C_0\}, \Gamma' \vdash \{G'\}} \quad \frac{C_0, B_1, \Gamma' \vdash \{G'\}}{A_0 \supset \{B_0\}, A_1 \supset \{B_1\}, B_0 \supset \{C_0\}, \Gamma' \vdash \{G'\}}$$

Only monadic-headed clauses used during forward chaining steps.

□ Concurrent Interpretation

New independent subgoals can be executed in parallel:

$$\frac{\frac{\Gamma' \vdash A_0 \quad \Gamma' \vdash A_1}{\Gamma' \vdash A_0, A_1 \supset \{B_0\}, A_1 \supset \{B_1\}, B_0 \supset \{C_0\}, \Gamma' \vdash \{G'\}} \quad \frac{B_0 \vdash B_0}{B_0, B_1, B_0 \supset \{C_0\}, \Gamma' \vdash \{G'\}} \quad \frac{C_0, B_1, \Gamma' \vdash \{G'\}}{\Gamma_n \vdash \{G'\}}}{\Gamma_n \vdash G'}$$

Each new subgoal-derivation is an atomic step—
 A_0, A_1, B_0 will each only be derived once.

□ LolliMon Computational Interpretation

- Backward-chaining— (Serial Programming)
 - Goal formula is currently executing function.
 - Prolog-style backtracking behavior.
- Forward-chaining— (Concurrent Programming)
 - Process execution denotes an atomic step.
Incomplete proof search strategy.
 - Forward chaining stops upon saturation.
- Program clauses are unrestricted (intuitionistic) hypotheses.
- Data are (usually) linear hypotheses.

□ **Pi-calculus in LolliMon**

- Directly interpret Pi-calculus connectives with LolliMon formulas.
- Processes are linear hypotheses.
- Pi-calculus operational semantics are monadic-headed program clauses (i.e. rewrite rules).
- Entirely forward-chaining, execute with $\{\top\}$ as goal:

$$\Delta_I \vdash \{\top\} \quad \rightsquigarrow \quad \Delta_O \vdash \{\top\}$$

where Δ_I and Δ_O are the start and stop process states.

□ Pi-calculus signature

$\text{expr} : \text{type}. \quad \text{chan} : \text{type}.$

$\text{par} : \text{expr} \rightarrow \text{expr} \rightarrow \text{expr}.$

$\text{zero} : \text{expr}.$

$\text{new} : (\text{chan} \rightarrow \text{expr}) \rightarrow \text{expr}.$

$\text{in} : \text{chan} \rightarrow (\text{chan} \rightarrow \text{expr}) \rightarrow \text{expr}.$

$\text{rin} : \text{chan} \rightarrow (\text{chan} \rightarrow \text{expr}) \rightarrow \text{expr}.$

$\text{out} : \text{chan} \rightarrow \text{chan} \rightarrow \text{expr}.$

Interpretation

$$\begin{array}{ll} \ulcorner P \mid Q \urcorner & = \text{par } \ulcorner P \urcorner \ulcorner Q \urcorner \\ \ulcorner 0 \urcorner & = \text{zero} \\ \ulcorner \nu c. P(c) \urcorner & = \text{new } (\ulcorner \lambda c : \text{chan}. P(c) \urcorner) \\ \ulcorner c(x). P(x) \urcorner & = \text{in } c \ (\ulcorner \lambda x : \text{chan}. P(x) \urcorner) \\ \ulcorner !c(x). P(x) \urcorner & = \text{rin } c \ (\ulcorner \lambda x : \text{chan}. P(x) \urcorner) \\ \ulcorner \bar{c} \langle v \rangle \urcorner & = \text{out } c \ v \end{array}$$

□ Pi-calculus operational semantics

proc : expr \rightarrow o.

msg : chan \rightarrow chan \rightarrow o.

proc (par P Q) \rightarrow o {proc P, proc Q}.

proc zero \rightarrow o {one}.

proc (new (x \ P x)) \rightarrow o {sigma (c \ proc (P c))}.

proc (out C V) \rightarrow o {msg C V}.

proc (in C (x \ P x)) \rightarrow o {pi (V \ msg C V \rightarrow o {proc (P V)})}.

proc (rin C (x \ P x)) \rightarrow o {!pi (V \ msg C V \rightarrow o {proc (P V)})}.

□ Pi-calculus example

$$a(u).\text{print}(u) \mid a(v).\text{print}(a) \mid \bar{a}\langle b \rangle$$

where we assume `a:chan` and `b:chan`

Context starts with one process:

```
proc (par (in a (u print u)) (par (in a (v print a)) (out a b)))
```

Two uses of `par` rewriting rule produce:

```
proc (in a (u print u)), proc (in a (v print a)), proc (out a b)
```

`in` and `out` rewriting rules produce:

```
pi (V msg a V -o proc (print V)), pi (V msg a V -o proc (print a)), msg a b
```

Finally, first process consumes `msg`:

```
proc (print b), pi (V msg a V -o proc (print a))
```

Note: other result also possible.

□ Graph Bipartiteness Checking

LolliMon version of Ganzinger-McAllester logical algorithm.

- Store graph (nodes and edges) in unrestricted context.
- Stores labelling information in unrestricted context, relies on saturation to finish label propagation.
- Deletion modeled by linear hypotheses— unlabeled nodes stored in linear context.
- Priorities modeled by monadically separated phases.

□ Phases of Bipartite Checking

```
(* start program *)  
notbipartite Us <= {init Us -o {iterate}}.
```

```
(* create symmetric closure *)  
!edge U V -o {!edge V U}.
```

```
(* initialize nodes as unlabeled *)  
init (U::Us) -o {unlabeled U, init Us}.  
init (nil) -o {one}.
```

```
(* label propagation *)  
iterate o- sigma U \ !labeled U a, !labeled U b, top.  
iterate o- sigma U \ unlabeled U, (labeled U a => {iterate}).
```


□ Graph Label Propagation

```
(* propagate label constraints *)
!labeled U a,
!edge U V
-o {!labeled V b}.
```



```
!labeled U b,
!edge U V
-o {!labeled V a}.
```



```
(* remove all nodes that have been labeled *)
!labeled U K,
unlabeled U
-o {one}.
```

□ Bipartite Checking Execution

Initial Context

$\Delta =$

$\Gamma = \text{edge } n1 \ n2, \text{ edge } n1 \ n3, \text{ edge } n2 \ n3$

Symmetric Closure

$\Delta =$

$\Gamma = \text{edge } n1 \ n2, \text{ edge } n2 \ n1, \text{ edge } n1 \ n3, \text{ edge } n3 \ n1, \text{ edge } n2 \ n3, \text{ edge } n3 \ n2$

Initialize nodes

$\Delta = \text{init } (n1::n2::n3),$

$\Gamma = \text{edge } n1 \ n2, \text{ edge } n2 \ n1, \text{ edge } n1 \ n3, \text{ edge } n3 \ n1, \text{ edge } n2 \ n3, \text{ edge } n3 \ n2$
:

$\Delta = \text{unlabeled } n1, \text{ unlabeled } n2, \text{ unlabeled } n3$

$\Gamma = \text{edge } n1 \ n2, \text{ edge } n2 \ n1, \text{ edge } n1 \ n3, \text{ edge } n3 \ n1, \text{ edge } n2 \ n3, \text{ edge } n3 \ n2$

□ More Bipartite Checking Execution

Label propagation

$\Delta =$ unlabeled n2, unlabeled n3

$\Gamma =$ labeled n1 a,

edge n1 n2, edge n2 n1, edge n1 n3, edge n3 n1, edge n2 n3, edge n3 n2
:

$\Delta =$

$\Gamma =$ labeled n1 a, labeled n1 b, labeled n2 a, labeled n2 b,

labeled n3 a, labeled n3 b

edge n1 n2, edge n2 n1, edge n1 n3, edge n3 n1, edge n2 n3, edge n3 n2

Saturation reached.

New propagation phase ends immediately since there exists a node with both labels.

Graph is not bipartite.

□ **Other Examples**

- Linear destination passing operational semantics.
- Other logical algorithms— parsing, union-find, etc.
- Meta-circular interpreter
- Simple Theorem Provers
- Petri-nets
- Lolli programs

□ **Future Work**

- More algorithms– e.g. "linear logical" algorithms
- Better implementation techniques
- Integration of full-theorem prover or model checker

□ **Related Work**

- CLF
- Prolog-style linear logic programming—
Lolli, Lygon
- Concurrent linear logic programming—
LO, ACL
- Complete linear logic programming/specification Forum
- Harlan et. al.—
Mixing forward and backward linear logic reasoning
- Bozzano et. al.—
Bottom-up linear logic programming

□ Summary

LolliMon is a novel logic-programming language.

- Conservative extension of Lolli
- Integrates backward chaining and forward chaining.
- New (we think) use of monad in logic programming.

Prototype implementation at: www.cs.cmu.edu/~fp/lollimon