Adam Seewald

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USA

- I am a Postdoc at the GRAB Lab at the Department of Mechanical Engineering and Materials Science at Yale University
- My research interests lie at the intersection of robotics, computer science, and optimal control, with a focus on developing autonomous field robots for nature conservation efforts
- I was born on November 27, 1993, in Bratislava, Slovakia and I am fluent in Czech, English, Italian, and Slovak

Education

2018-2022 Ph.D., Engineering Science, University of Southern Denmark

Thesis Energy-aware coverage planning and scheduling for autonomous aerial robots, 🗅

Advisor Prof. Ulrik Pagh Schultz

2016-2018 Master, Computer Science and Engineering, University of Verona, Italy

Thesis Evaluation of optimal trajectories for quadrotors with indirect methods in the presence of intermediate

constraints

Advisor Prof. Paolo Fiorini

2013-2016 Bachelor, Computer Science, University of Verona, Italy

Thesis Analysis, porting and testing of parallel code for images recognition on CUDA Jetson TK1 platform

Advisor Prof. Nicola Bombieri

Experience

Details

2022- Postdoc, GRAB Lab, Dept. of Mechanical Eng. and Materials Science, Yale University

Project Mobile ground-based and aerial robots for biodiversity surveying, ♂

Advisor Prof. Aaron Dollar

I am investigating techniques for navigation, control, and planning of mobile robotics platforms for

Details nature conservation and surveying. These platforms include legged, aerial [c7], and wheeled [c6]

robots jointly developed by multiple lab members.

2018-2021 Ph.D. Researcher, Unmanned Aerial Systems Center, University of Southern Denmark

Project TeamPlay - Time, Energy, and security Analysis for Multi/Many-core heterogeneous PLAtforms, &

Funding European Union's Horizon2020 program under grant agreement number 779882

Advisor Prof. Ulrik Pagh Schultz

My contributions included the development of the aerial robotics use case and an open-source energy modeling tool written in C++ [j1], [c1] used by project partners such as the University of Amsterdam in the Netherlands, the University of Bristol in the United Kingdom, INRIA in France, and Irida Labs in Greece. To this end, I have applied energy optimizing techniques – including MPC and data-driven.

control [c4] – to aerial robots in flight [c2] and simulation using ROS [c3] and MATLAB (R) [c2], [c4]

and investigated other energy-critical systems [w2].

Publications

My publications include one journal article and seven conference articles. Two articles are currently under review.

- [j1] Coarse-grained computation-oriented energy modeling for heterogeneous parallel embedded systems, in: International Journal of Parallel Programming. 2021; vol. 49, no. 2, pp. 136–157. 10.1007/s10766-019-00645-y, Carallel Adam Seewald, Ulrik Pagh Schultz, Emad Ebeid, and Henrik Skov Midtiby
- [c1] Component-based computation-energy modeling for embedded systems, in: Proceedings Companion of the ACM SIGPLAN International Conference on Systems, Programming, Languages, and Applications: Software for Humanity (SPLASH'19), pp. 5–6. 10.1145/3359061.3362775, ©

 Adam Seewald, Ulrik Pagh Schultz, Julius Roeder, Benjamin Rouxel, and Clemens Grelck
- [c2] Mechanical and computational energy estimation of a fixed-wing drone, in: Proceedings of the IEEE International Conference on Robotic Computing (IRC'20), pp. 135–142. 10.1109/IRC.2020.00028, © Adam Seewald, Héctor García de Marina, Henrik Skov Midtiby, and Ulrik Pagh Schultz
- [c3] Energy-aware design of vision-based autonomous tracking and landing of a UAV, in: Proceedings of the IEEE International Conference on Robotic Computing (IRC'20), pp. 294–297. 10.1109/IRC.2020.00054, © Georgios Zamanakos, Adam Seewald, Henrik Skov Midtiby, and Ulrik Pagh Schultz
- [c4] Energy-aware planning-scheduling for autonomous aerial robots, in: Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS'22), pp. 2946–2953. 10.1109/IROS47612.2022.99812 85, ♂
 - Adam Seewald, Héctor García de Marina, Henrik Skov Midtiby, and Ulrik Pagh Schultz
- [c5] The TeamPlay project: Analysing and optimising time, energy, and security for cyber-physical systems, in: Proceedings of the Design, Automation and Test in Europe Conference (DATE'23), pp. 1–6. 10.23919/DATE56975. 2023.10137198, 🗗
 - Benjamin Rouxel, Christopher Brown, Emad Ebeid, Heiko Falk, Clemens Grelck, Jesper Holst, Shashank Jadhav, Yoann Marquer, Marcos Martinez Alejandro, Kris Nikov, Ali Sahafi, Ulrik Pagh Schultz, <u>Adam Seewald</u>, Vangelis Vassalos, Simon Wegener, and Olivier Zendra
- [c6] RB5 Low-cost explorer: Implementing autonomous long-term exploration on low-cost robotic hardware, 2023, submitted for publication, p. 7. ☑ Adam Seewald, Marvin Chancán, Connor M. McCann, Seonghoon Noh, Omeed Fallahi, Hector Castillo, Ian Abraham, and Aaron M. Dollar
- [c7] Energy-aware ergodic search: Continuous exploration for multi-agent systems with battery constraints, 2023, submitted for publication, p. 7. ☑ Adam Seewald, Cameron J. Lerch, Marvin Chancán, Aaron M. Dollar, and Ian Abraham

Other publications include two peer-reviewed workshop articles, a Ph.D. thesis, and a software.

- [w1] Dynamic energy modelling for SoC boards: Initial experiments, in: Workshop on High-Level Programming for Heterogeneous and Hierarchical Parallel Systems (HLP-GPU'19), p. 4. 🗗

 Adam Seewald, Emad Ebeid, and Ulrik Pagh Schultz
- [w2] Beyond traditional energy planning: The weight of computations in planetary exploration, in: Proceedings of the IROS Workshop on Planetary Exploration Robots: Challenges and Opportunities (PlanRobo'20), p. 3. ETH Zürich. 10.3929/ethz-b-000450120, ☑ Adam Seewald
- [o1] powprofiler computations energy modeling tool, v. 1.0.2, 2021. 10.5281/zenodo.5562457, Carallel Adam Seewald, Ulrik Pagh Schultz, Emad Ebeid, and Henrik Skov Midtiby
- [o2] Energy-aware coverage planning and scheduling for autonomous aerial robots, Ph.D. thesis, p. 184. Syddansk Universitet. Det Tekniske Fakultet, 2021. 10.21996/7ka6-r457, ♂ Adam Seewald

Teaching

I co-taught courses at graduate and undergraduate level.

Fall 2022 You, Your Planet, and a Sustainable Future, course for undergraduate students

Role Teaching assistant
Advisor Prof. Aaron M. Dollar

Details

I prepared lecture material and assisted in the theoretical parts of the course – a survey course for

undergraduate students in engineering and environmental science at Yale University.

Spring 2019, and 2020 Optimization and Control, course for master's students in Robotics

Role Teaching assistant Advisor Prof. Agus Hasan

I taught constrained optimization and sequential quadratic programming and assisted in the practical

Details parts of the course – an elective course for the master's students in robot systems at the University

of Southern Denmark.

Academic Service

- Reviewer for the IEEE International Conference on Soft Robotics (RoboSoft'24), □
- Reviewer for IEEE Robotics and Automation Letters (RA-L), ♂
- Reviewer for the IEEE International Conference on Robotics and Automation (ICRA'24), 🗅
- Program Committee member at the IEEE International Conference on Robotic Computing (IRC'23), ☐
- Reviewer for the IEEE International Conference on Automation Science and Engineering (CASE'23), ☑
- Program Committee member at the IEEE International Conference on Robotic Computing (IRC'22), &
- Reviewer for the IEEE International Conference on Robot and Human Interactive Communication (Ro-man'22), 🖸
- Reviewer for the IEEE International Conference on Unmanned Aircraft Systems (ICUAS'22),
- Reviewer for the International Workshop on Robotics Software Engineering (RoSE'22), &
- Program Committee member at the IEEE International Conference on Robotic Computing (IRC'21), □
- Co-organizer of the Time, Energy, and Security Analysis for Multi/Many-core Heterogeneous Platforms Final Workshop (TeamPlay'21), ♂
- Reviewer for the IEEE International Conference on Unmanned Aircraft Systems (ICUAS'21), &

Prof. Ian Abraham. 2

• Reviewer for the IEEE International Conference on Control, Automation, Robotics and Vision (ICARCV'20), 🗷

References

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Prof. Ulrik Pagh Schultz, © SDU UAS Center

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