Adam Seewald, Curriculum Vitae

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- I am currently a postdoc at the Environmental Robotics Lab, ETH Zürich
- My research focuses on robotics and computer science and involves autonomous robots in different environmental use cases
- My fields of research interest are aerial robotics, energy and environment-aware automation, field robots, and motion and path planning, among others

Education

2018-2022 **Ph.D., Engineering Science, University of Southern Denmark**

Thesis	Energy-aware coverage planning and scheduling for autonomous aerial robots,
Advisor	Prof. Ulrik Pagh Schultz

2016-2018 **Master, Computer Science and Engineering, University of Verona, Italy**

Thesis	Evaluation of optimal trajectories for quadrotors with indirect methods in the presence of intermediate constraints
Advisor	Prof. Paolo Fiorini

2013-2016 **Bachelor, Computer Science, University of Verona, Italy**

Experience

2024- **Postdoc, Environmental Robotics Lab, Dept. of Environmental Systems Science, ETH Zürich**

Project	Robot-assisted collection of eDNA for pest detection in precision agriculture, (PI: Stefano Mintchev)
Funding	World Food System Center and Fenaco's research program on smart sustainable farming
Details	Development of techniques (i.e., aerial-physical interaction, RGB-D perception, etc.) for the collection and analysis of environmental DNA samples for the detection of pests in precision agriculture.

2022-2024 **Postdoc, GRAB Lab, Dept. of Mechanical Eng. and Materials Science, Yale University**

Project	Mobile ground-based and aerial robots for biodiversity surveying, (PI: Aaron M. Dollar)
Funding	Yale University's discretionary research fund
Details	Development of mobile robotic autonomy (i.e., navigation, control, and planning algorithms and communication methodologies) for nature conservation and surveying efforts [c7, c6].

2018-2022 **Ph.D. Researcher, Unmanned Aerial Systems Center, University of Southern Denmark**

Project	TeamPlay – Time, Energy, and security Analysis for Multi/Many-core heterogeneous PLAtforms, (PI: Ulrik Pagh Schultz)
Funding	European Union's Horizon2020 program under grant agreement number 779882
Details	Development of the aerial robotics use case [c4] (i.e., fixed-wing aerial robot for precision agriculture). Development of an open-source motion planning/computing energy modeling library [j1, o1] utilized by a network of collaborators including University of Amsterdam, University of Bristol, and INRIA.

Research

Peer-reviewed journal publication:

[j1] • Adam Seewald, Ulrik Pagh Schultz, Emad Ebeid, and Henrik Skov Midtiby, "**Coarse-grained computation-oriented energy modeling for heterogeneous parallel embedded systems**," in International Journal of Parallel Programming. 2021; vol. 49, no. 2, pp. 136–157. 10.1007/s10766-019-00645-y,

Peer-reviewed conference publications (7):

[c7] • Adam Seewald, Cameron J. Lerch, Marvin Chancán, Aaron M. Dollar, and Ian Abraham, "**Energy-aware ergodic search: Continuous exploration for multi-agent systems with battery constraints**," in IEEE International Conference on Robotics and Automation (ICRA'24), pp. 7048–7054.

[c6] • Adam Seewald, Marvin Chancán, Connor M. McCann, Seonghoon Noh, Omeed Fallahi, Hector Castillo, Ian Abraham, and Aaron M. Dollar, "**RB5 Low-cost explorer: Implementing autonomous long-term exploration on low-cost robotic hardware**," in IEEE International Conference on Robotics and Automation (ICRA'24), pp. 5977–5983.

[c5] • Benjamin Rouxel, Christopher Brown, Emad Ebeid, Heiko Falk, Clemens Grelck, Jesper Holst, Shashank Jadhav, Yoann Marquer, Marcos Martinez Alejandro, Kris Nikov, Ali Sahafi, Ulrik Pagh Schultz, Adam Seewald, Vangelis Vassalos, Simon Wegener, and Olivier Zendra, "**The TeamPlay project: Analysing and optimising time, energy, and security for cyber-physical systems**," in Design, Automation and Test in Europe Conference (DATE'23), pp. 1–6. 10.23919/DATE56975.2023.10137198,

[c4] • Adam Seewald, Héctor García de Marina, Henrik Skov Midtiby, and Ulrik Pagh Schultz, "**Energy-aware planning-scheduling for autonomous aerial robots**," in IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS'22), pp. 2946–2953. 10.1109/IROS47612.2022.9981285,

[c3] • Georgios Zamanakos, Adam Seewald, Henrik Skov Midtiby, and Ulrik Pagh Schultz, "**Energy-aware design of vision-based autonomous tracking and landing of a UAV**," in IEEE International Conference on Robotic Computing (IRC'20), pp. 294–297. 10.1109/IRC.2020.00054,

[c2] • Adam Seewald, Héctor García de Marina, Henrik Skov Midtiby, and Ulrik Pagh Schultz, "**Mechanical and computational energy estimation of a fixed-wing drone**," in IEEE International Conference on Robotic Computing (IRC'20), pp. 135–142. 10.1109/IRC.2020.00028,

[c1] • Adam Seewald, Ulrik Pagh Schultz, Julius Roeder, Benjamin Rouxel, and Clemens Grelck, "**Component-based computation-energy modeling for embedded systems**," in ACM SIGPLAN International Conference on Systems, Programming, Languages, and Applications: Software for Humanity (SPLASH'19), pp. 5–6. 10.1145/3359061.3362775,

Peer-reviewed workshop publications (2):

[w2] • Adam Seewald, "**Beyond traditional energy planning: The weight of computations in planetary exploration**," in IROS Workshop on Planetary Exploration Robots: Challenges and Opportunities (PlanRobo'20), p. 3. ETH Zürich. 10.3929/ethz-b-000450120,

[w1] • Adam Seewald, Emad Ebeid, and Ulrik Pagh Schultz, "**Dynamic energy modelling for SoC boards: Initial experiments**," in Workshop on High-Level Programming for Heterogeneous and Hierarchical Parallel Systems (HLP-GPU'19), p. 4.

Others (2):

[o2] • Adam Seewald, "**Energy-aware coverage planning and scheduling for autonomous aerial robots**," Ph.D. thesis, p. 184. Syddansk Universitet. Det Tekniske Fakultet, 2021. 10.21996/7ka6-r457,

[o1] • Adam Seewald, Ulrik Pagh Schultz, Emad Ebeid, and Henrik Skov Midtiby, "`powprofiler` **computations energy modeling tool**," v. 1.0.2, 2021. 10.5281/zenodo.5562457,

Invited lectures

- **Innovations in robotics for sustainable crop production**. Invited Talk at the Innovations for Sustainable Local Food Systems day at ETH Zürich World Food System Center. June 14, 2024.
- **Ergodic control applications: Energy optimal control**. Invited Speaker at the ICRA Tutorial on Ergodic Control, IEEE International Conference on Robotics and Automation. May 13, 2024.
- **Energy-aware dynamic planning: Merging path planning and computations scheduling for the drone use-case**. Invited Talk at the TeamPlay Final Workshop, (Virtual Event). May 27, 2021.
- **Energy estimation and modeling for the drone use-case**. Invited Talk at the TeamPlay Workshop, European Network on High-Performance Embedded Architecture and Compilation Conference. January 22, 2020.

Teaching and advising

Teaching at graduate and undergraduate levels (3):

Fall 2024	**Introduction to Agricultural Robotics**, ETH Zürich	
	Role	Teaching assistant (PI: Stefano Mintchev)
	Details	Elective introductory course on robotics techniques in precision agriculture for master's students from different backgrounds.
Fall 2022	**You, Your Planet, and a Sustainable Future**, Yale University	
	Role	Teaching assistant (PI: Aaron M. Dollar)
	Details	Survey course on sustainable technologies for undergraduate students in engineering and environmental science.
Spring 2019,'20	**Optimization and Control**, University of Southern Denmark	
	Role	Teaching assistant (PI: Agus Hasan)
	Details	Elective course on numerical optimization, methods and solvers, for master's students in robot systems.

Advising of graduate and undergraduate students (2):

- **Omeed Fallahi**, undergraduate student in computer science, Yale University, 2022–2023
- **Magnus O. C. Liisberg**, master's student in robot systems, University of Southern Denmark, 2018–2019

Professional and outreach activities

- **Member**, Institute of Electrical and Electronics Engineers (IEEE), 2019–
- **Member**, Association for Computing Machinery (ACM), 2019–
- **Organizer** of the Time, Energy, and Security Analysis for Multi/Many-core Heterogeneous Platforms Final Workshop (TeamPlay'21)
- **Program Committee member**, IEEE International Conference on Robotic Computing (IRC'23,'22,'21),
- **Reviewer**, IEEE Robotics and Automation Letters (RA-L),
- **Reviewer**, International Symposium on Distributed Autonomous Robotic Systems (DARS'24),

- **Reviewer**, IEEE International Conference on Soft Robotics (RoboSoft'24),
- **Reviewer**, IEEE International Conference on Robotics and Automation (ICRA'24),
- **Reviewer**, IEEE International Conference on Automation Science and Engineering (CASE'23),
- **Reviewer**, IEEE International Conference on Robot and Human Interactive Communication (Ro-man'22)
- **Reviewer**, IEEE International Conference on Unmanned Aircraft Systems (ICUAS'22),
- **Reviewer**, International Workshop on Robotics Software Engineering (RoSE'22),
- **Reviewer**, IEEE International Conference on Unmanned Aircraft Systems (ICUAS'21)
- **Reviewer**, IEEE International Conference on Control, Automation, Robotics and Vision (ICARCV'20)

References

Prof. Aaron M. Dollar,
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