# **Backpropagation Algorithm**

- // In a multilayer network, there is no given target value for the perceptrons in the
- // hidden layer; hence their error values cannot be directly calculated.
- // Rather, the error must be propagated backwards from the output layer and used to
- // appropriately adjust the weights (to minimize error and produce correct output).

## Initialize all weights to small random numbers

Repeat until termination condition is met:

For each training example, do

- 1. Feed the input forward through the network
  - a. Input instance and calculate output of each unit // use the output function (e.g. sigmoid)
- 2. Propagate the errors backward through the network
  - a. For each output unit j, calculate the error

$$E_j = (t_j - y_j)y_j(1 - y_j)$$
 // note: derivative of sigmoid func

b. For each hidden unit *i*, calculate the error

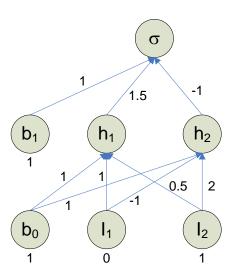
$$E_i = h_i (1 - h_i) \sum_k w_{ik} E_k$$

c. Update each network weight

$$w_j = w_j + \eta E_j z_j$$
 // connecting hidden to output  
 $w_i = w_i + \eta E_i x_i$  // connecting input to hidden

#### Multi-layer Perceptron Learning: one Epoch

Below is a snapshot of a neural network during training. There are two input units, two hidden layer perceptrons, and a single output unit. Input  $I_1$  has a value of 0; input  $I_2$  has a value of 1; all bias have value 1. Edges are labeled with their corresponding weights. Learning factor  $\eta = 0.5$ . Target value is 1.



## Step 1: Feed the inputs forward

Use the formula, output =  $\frac{1}{1+e^{-\sigma}}$  where  $\sigma = \sum_{i} w_i x_i + bias$ 

$$\begin{aligned} &h_1 = (1 \bullet 0) + (0.5 \bullet 1) + (1 \bullet 1) = 1.5 \Rightarrow 1/(1 + e^{-1.5}) = 0.818 \\ &h_2 = (-1 \bullet 0) + (2 \bullet 1) + (1 \bullet 1) = 3 \Rightarrow 1/(1 + e^{-3}) = 0.953 \\ &y = (1.5 \bullet 0.818) + (-1 \bullet 0.953) + (1 \bullet 1) = 1.274 \Rightarrow 1/(1 + e^{-1.274}) = 0.781 \end{aligned}$$

Calculate total error in network,  $E = \frac{1}{2}(t - y)^2$ 

$$E = \frac{1}{2} (1 - 0.781)^2 = 0.024$$

### Step 2: Backpropagate the errors

a) Calculate the error for the output unit y, Use the formula,  $E_y = y(1-y)(t-y)$ 

$$E_y = (0.781)(1 - 0.781)(1 - 0.781) = 0.037$$

b) Calculate the error for each hidden unit  $h_i$ Use the formula,  $E_{h_i} = h_i (1 - h_i) (w_{h_i, y} \cdot E_y)$ 

$$E_{h1} = (0.818)(1 - 0.818)(1.5 \cdot 0.037) = 0.008$$

$$E_{h2} = (0.953)(1 - 0.953)(-1 \cdot 0.037) = -0.002$$

c) Update network weights proportionately
Use the formula,  $w_{i,j} = w_{i,j} + \eta E_i z_i$  where  $z_i$  is value of i

$$W_{h1,y} = 1.5 + (0.5)(0.037)(0.818) = 1.515$$

$$W_{h2,y} = -1 + (0.5)(0.037)(0.953) = -0.982$$

$$W_{b1,y} = 1 + (0.5)(0.037)(1) = 1.019$$

$$W_{11, h1} = 1 + (0.5)(0.008)(0) = 1$$

$$W_{12, h1} = 0.5 + (0.5)(0.008)(1) = 0.504$$

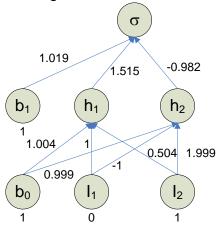
$$W_{b0, h1} = 1 + (0.5)(0.008)(1) = 1.004$$

$$W_{11, h2} = -1 + (0.5)(-0.002)(0) = -1$$

$$W_{12, h2} = 2 + (0.5)(-0.002)(1) = 1.999$$

$$W_{b0, h2} = 1 + (0.5)(-0.002)(1) = 0.999$$

Label network with updated weights:



Repeat for all training samples ⇒ one epoch.