

# Macroeconometrics

## Lecture 21 Bayesian estimation of SV models using auxiliary mixture

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## Objectives.

- ▶ To present Gibbs sampling for Stochastic Volatility models
- ▶ To introduce auxiliary mixture technique
- ▶ To use an inverse probability transform sampling method

## Learning outcomes.

- ▶ Applying log-linearisation for feasible computations
- ▶ Transforming a non-linear model to a Gaussian state-space specification
- ▶ Applying a normal mixture approximation of a distribution for a real-valued random variable



# A simple Stochastic Volatility model

## A model with a conditional mean specification.

Let  $\mu_t(\alpha)$  denote a conditional mean of  $y_t$  that is a function of a parameter (vector)  $\alpha$ .

$$y_t = \mu_t(\alpha) + \exp\left\{\frac{1}{2}h_t\right\}\epsilon_t$$

$$y_t - \mu_t(\alpha) = \exp\left\{\frac{1}{2}h_t\right\}\epsilon_t$$

$\downarrow$

$$y_{\mu.t} = \exp\left\{\frac{1}{2}h_t\right\}\epsilon_t$$

$$h_t = h_{t-1} + \sigma_v v_t$$

$$\epsilon_t \sim \mathcal{N}(0, 1)$$

$$v_t \sim \mathcal{N}(0, 1)$$

$h_0$  – estimated parameter of the model

# Log-linearization of the measurement equation

Perform the log-linearization of the measurement equation by:

**taking the square** of both sides of the equation

**taking the logarithm** of both sides of the equation

$$y_{\mu,t} = \exp\left\{\frac{1}{2}h_t\right\}\epsilon_t$$

$$\log y_{\mu,t}^2 = h_t + \log \epsilon_t^2$$

$$\tilde{y}_t = h_t + \tilde{\epsilon}_t$$

$$\tilde{\epsilon}_t \sim \log \chi_1^2$$

# Matrix notation

## A simple Stochastic Volatility model

$$\tilde{y} = h + \tilde{\epsilon}$$

$$Hh = h_0 e_{1.T} + \sigma_v v$$

$$\tilde{\epsilon}_t \sim iid \log \chi_1^2$$

$$v \sim \mathcal{N}_T(\mathbf{0}_T, I_T)$$

Define the following  $T \times 1$  matrices

$$\tilde{y} = \begin{bmatrix} \tilde{y}_1 \\ \vdots \\ \tilde{y}_T \end{bmatrix} \quad h = \begin{bmatrix} h_1 \\ \vdots \\ h_T \end{bmatrix} \quad \tilde{\epsilon} = \begin{bmatrix} \tilde{\epsilon}_1 \\ \vdots \\ \tilde{\epsilon}_T \end{bmatrix} \quad v = \begin{bmatrix} v_1 \\ \vdots \\ v_T \end{bmatrix} \quad e_{1.T} = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

Auxiliary mixture



# Auxiliary mixture

Approximate the  $\log \chi_1^2$  distribution by a mixture of ten normal distributions given by:

$$\log \chi_1^2 \approx \sum_{m=1}^{10} Pr(s_t = m) \mathcal{N}(\mu_m, \sigma_m^2)$$

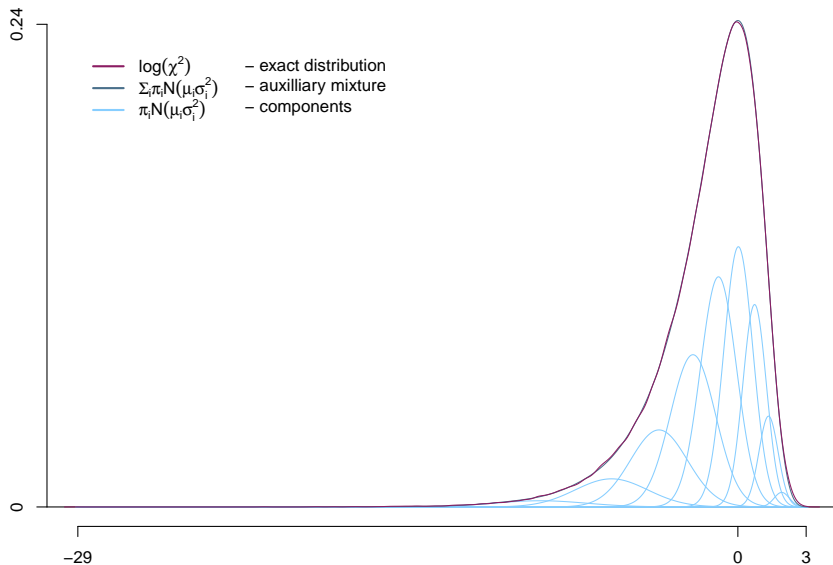
$s_t \in \{1, \dots, 10\}$  is a discrete-valued random indicator of the mixture component

$\mu_m, \sigma_m^2, Pr(s_t = m)$  are predetermined

## Auxiliary mixture

m	$Pr(s_t = m)$	$\mu_m$	$\sigma_m^2$
1	0.00609	1.92677	0.11265
2	0.04775	1.34744	0.17788
3	0.13057	0.73504	0.26768
4	0.20674	0.02266	0.40611
5	0.22715	-0.85173	0.62699
6	0.18842	-1.97278	0.98583
7	0.12047	-3.46788	1.57469
8	0.05591	-5.55246	2.54498
9	0.01575	-8.68384	4.16591
10	0.00115	-14.65000	7.33342

# Auxiliary mixture



## Auxiliary mixture

### Conditional distribution of $\tilde{\epsilon}_t$

$$\tilde{\epsilon}_t | s_t = m \sim \mathcal{N}(\mu_m, \sigma_m^2)$$

### A simple Stochastic Volatility model

$$\tilde{y} = h + \tilde{\epsilon} \tag{1}$$

$$Hh = h_0 e_{1.T} + \sigma_v v \tag{2}$$

$$\tilde{\epsilon} | s \sim \mathcal{N}_T(\mu_s, \text{diag}(\sigma_s^2)) \tag{3}$$

$$v \sim \mathcal{N}_T(\mathbf{0}_T, I_T) \tag{4}$$

$$s = [s_1 \quad \dots \quad s_T]' \quad \mu_s = [\mu_{s_1} \quad \dots \quad \mu_{s_T}]' \quad \sigma_s^2 = [\sigma_{s_1}^2 \quad \dots \quad \sigma_{s_T}^2]'$$

## Bayesian estimation of SV models

# Prior distributions

Hierarchical prior structure is given by:

$$p(h, s, h_0, \sigma_v^2) = p(h|h_0, \sigma_v^2) p(h_0) p(\sigma_v^2) p(s)$$

Eqs. (2) and (4) determine a conditional prior distribution of  $h$ :

$$\begin{aligned} p(h|h_0, \sigma_v^2) &\sim \mathcal{N}_T(h_0 H^{-1} e_{1..T}, \sigma_v^2 (H' H)^{-1}) \\ &\propto \det(\sigma_v^2 I_T)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} \frac{1}{\sigma_v^2} (Hh - h_0 e_{1..T})' (Hh - h_0 e_{1..T}) \right\} \end{aligned}$$

whereas the marginal prior distributions for  $h_0$ ,  $\sigma_v^2$ , and  $s$  are:

$$\begin{aligned} p(h_0) &= \mathcal{N}(0, \underline{\sigma}_h^2) \\ p(\sigma_v^2) &= \mathcal{IG}2(\underline{s}, \underline{\nu}) \\ p(s_t) &= \text{Multinomial}(\{m\}_{m=1}^{10}, \{Pr(s_t = m)\}_{m=1}^{10}) \end{aligned}$$

# Full-conditional posterior distributions

## Full-conditional posterior distribution for $h$

Equations (1) and (3) determine the conditional likelihood that is proportional to

$$\exp \left\{ -\frac{1}{2} (h - (\tilde{y} - \mu_s))' \text{diag}(\sigma_s^2)^{-1} (h - (\tilde{y} - \mu_s)) \right\}$$

which leads to:

$$\begin{aligned} h|y, s, h_0, \sigma_v^2 &\sim \mathcal{N}_T(\bar{h}, \bar{V}_h) \\ \bar{V}_h &= \left[ \text{diag}(\sigma_s^2)^{-1} + \sigma_v^{-2} H' H \right]^{-1} \\ \bar{h} &= \bar{V}_h \left[ \text{diag}(\sigma_s^2)^{-1} (\tilde{y} - \mu_s) + \sigma_v^{-2} h_0 e_{1..T} \right] \end{aligned}$$

# Full-conditional posterior distributions

## **Full-conditional posterior distribution for $s$**

is a multinomial distribution with the probabilities proportional to

$$\omega_{m.t} = Pr[s_t = m]p(\tilde{y}_t|h_t, s_t = m)$$

for  $m = 1, \dots, 10$ ,  $p(\tilde{y}_t|h_t, s_t = m)$  is based on eqs (1) & (3)

For each  $t$  and  $m$  obtain  $\omega_{m.t}$  using parallel computations and compute the probabilities of the multinomial full conditional posterior distribution by

$$Pr[s_t = m|\tilde{y}_t, h_t] = \frac{\omega_{m.t}}{\sum_{i=1}^{10} \omega_{i.t}}$$

Sampling  $s_t$  independently for each  $t$  is straightforward



# Full-conditional posterior distributions

## Full-conditional posterior distributions for $\sigma_v^2$ and $h_0$

It is straightforward to show that:

$$\sigma_v^2 | y, s, h, h_0 \sim \mathcal{IG2}(\bar{s}, \bar{\nu})$$

$$\bar{\nu} = \underline{\nu} + T$$

$$\bar{s} = \underline{s} + (Hh - h_0 e_{1..T})'(Hh - h_0 e_{1..T})$$

$$h_0 | y, s, h, \sigma_v^2 \sim \mathcal{N}(\bar{h}_0, \bar{\sigma}_h^2)$$

$$\bar{\sigma}_h^2 = (\underline{\sigma}_h^{-2} + \sigma_v^{-2})^{-1}$$

$$\bar{h}_0 = \bar{\sigma}_h^2 (\sigma_v^{-2} e' H h)$$

# Gibbs sampler

**Initialize**  $h^{(0)}$ ,  $s^{(0)}$ , and  $\sigma_v^{2(0)}$

**For**  $i = 1, \dots, S$

**Draw**  $h_0^{(i)} \sim \mathcal{N}(\bar{h}_0, \bar{\sigma}_h^2)$

**Draw**  $\sigma_v^{2(i)} \sim \mathcal{IG}2(\bar{s}, \bar{\nu})$

**Draw**  $s_t^{(i)} \sim \text{Multinomial}(\{m\}_{m=1}^{10}, \{Pr[s_t = m | \tilde{y}_t, h_t^{(i)}]\}_{m=1}^{10})$   
for  $t=1, \dots, T$  using inverse transform method

**Draw**  $h^{(i)} \sim \mathcal{N}_T(\bar{h}, \bar{V}_h)$  using precision sampler

**Return** a sample drawn from the posterior distribution:

$$\{h^{(i)}, s^{(i)}, h_0^{(i)}, \sigma_v^{2(i)}\}_{i=1}^S$$

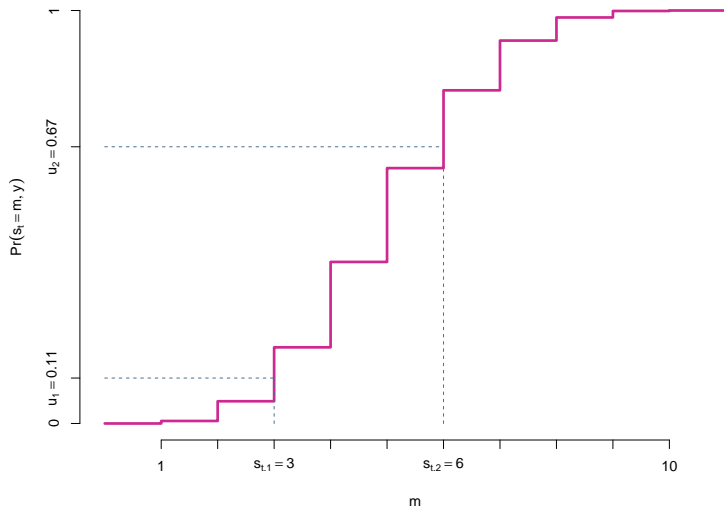
# Simulation smoother

The precision matrix of the  $T$ -variate normal full-conditional posterior distribution  $\overline{V}_h^{-1}$  is a tridiagonal matrix.

Draw random numbers from this distribution using the **simulation smoother** and computer routines for band or tridiagonal matrices.

# Sampling random draws from Multinomial distribution

## Inverse transform method



## Bayesian estimation of the SV–AR models

# Bayesian estimation of the SV–AR models

## An Autoregressive Stochastic Volatility model

$$y_t = \exp\left\{\frac{1}{2}h_t\right\}\epsilon_t$$

$$h_t = \mu_0 + \alpha h_{t-1} + \sigma_v v_t$$

$$\epsilon_t \sim \mathcal{N}(0, 1)$$

$$v_t \sim \mathcal{N}(0, 1)$$

$$|\alpha| < 1 \quad - \text{stationarity condition}$$

# Bayesian estimation of the SV–AR models

## An Autoregressive Stochastic Volatility model

$$\tilde{y} = h + \tilde{\epsilon}$$

$$H_{\alpha} h = \mu_0 I_T + \alpha h_0 e_{1..T} + \sigma_v v$$

$$h = \mu_0 I_T + \alpha h_{-1} + \sigma_v v$$

$$\tilde{\epsilon}|s \sim \mathcal{N}_T(\mu_s, \text{diag}(\sigma_s^2))$$

$$v \sim \mathcal{N}_T(\mathbf{0}_T, I_T)$$

$$h_{-1} = \begin{bmatrix} h_0 & \dots & h_{T-1} \end{bmatrix}' \quad I_T = \begin{bmatrix} 1 & \dots & 1 \end{bmatrix}' \quad H_{\alpha} = \begin{bmatrix} 1 & 0 & \dots & 0 & 0 \\ -\alpha & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \\ 0 & 0 & \dots & -\alpha & 1 \end{bmatrix}$$

# Prior distributions

Hierarchical prior structure is given by:

$$p(h, s, h_0, \mu_0, \alpha, \sigma_v^2) = p(h|\mu_0, \alpha, h_0, \sigma_v^2) p(\mu_0) p(\alpha) p(h_0) p(\sigma_v^2) p(s)$$

Conditional prior distribution of  $h$ :

$$\begin{aligned} p(h|\mu_0, \alpha, h_0, \sigma_v^2) &\sim \mathcal{N}_T(\mu_0 H_\alpha^{-1} I_T + \alpha h_0 H_\alpha^{-1} e_{1..T}, \sigma_v^2 (H'_\alpha H_\alpha)^{-1}) \\ &\propto \det(\sigma_v^2 I_T)^{-\frac{1}{2}} \exp \left\{ -\frac{1}{2} \frac{1}{\sigma_v^2} (Hh - \mu_0 I_T - h_0 e_{1..T})' (Hh - \mu_0 I_T - h_0 e_{1..T}) \right\} \end{aligned}$$

Marginal prior distributions for  $\mu + 0, \alpha, h_0, \sigma_v^2$ , and  $s$ :

$$p(\mu_0) = \mathcal{N}(\underline{\mu}_0, \underline{\sigma}_\mu^2)$$

$$p(\alpha) = \mathcal{N}(\underline{\alpha}, \underline{\sigma}_\alpha^2) \mathcal{I}(|\alpha| < 1)$$

$$p(h_0) = \mathcal{N}(0, \underline{\sigma}_h^2)$$

$$p(\sigma_v^2) = \mathcal{IG}2(\underline{s}, \underline{\nu})$$

$$p(s_t) = \text{Multinomial}(\{m\}_{m=1}^{10}, \{Pr(s_t = m)\}_{m=1}^{10})$$



# Full-conditional posterior distributions

## Full-conditional posterior distribution for $h$

Equations (1) and (3) determine the conditional likelihood that combined with the conditional prior distribution gives:

$$h|y, s, \mu_0, \alpha, h_0, \sigma_v^2 \sim \mathcal{N}_T(\bar{h}, \bar{V}_h)$$

$$\bar{V}_h = \left[ \text{diag}(\sigma_s^2)^{-1} + \sigma_v^{-2} H'_\alpha H_\alpha \right]^{-1}$$

$$\bar{h} = \bar{V}_h \left[ \text{diag}(\sigma_s^2)^{-1} (\tilde{y} - \mu_s) + \sigma_v^{-2} H'_\alpha (\mu_0 \mathbf{1}_T + \alpha h_0 \mathbf{e}_{1..T}) \right]$$

## Full-conditional posterior distribution for $s$

Neither the form of the measurement equation or the multinomial prior distribution changes, therefore, the sampler stays the same.

# Full-conditional posterior distributions

## Full-conditional posterior distribution for $\mu_0$

$$\begin{aligned}\mu_0|y, h, \alpha, h_0, \sigma_v^2 &\sim \mathcal{N}(\bar{\mu}_0, \bar{\sigma}_\mu^2) \\ \bar{\sigma}_\mu^2 &= [\underline{\sigma}_\mu^{-2} + T\sigma_v^{-2}]^{-1} \\ \bar{\mu}_0 &= \bar{\sigma}_\mu^2 [\underline{\mu}_0 \underline{\sigma}_\mu^{-2} + \sigma_v^{-2} (H_\alpha h - \alpha h_0 e_{1..T})' \mathbf{1}_T]\end{aligned}$$

## Full-conditional posterior distribution for $\alpha$

$$\begin{aligned}\alpha|y, h, \mu_0, h_0, \sigma_v^2 &\sim \mathcal{N}(\bar{\alpha}, \bar{\sigma}_\alpha^2) \mathcal{I}(|\alpha| < 1) \\ \bar{\sigma}_\alpha^2 &= [\underline{\sigma}_\alpha^{-2} + \sigma_v^{-2} h'_{-1} h_{-1}]^{-1} \\ \bar{\alpha} &= \bar{\sigma}_\alpha^2 [\underline{\alpha} \underline{\sigma}_\alpha^{-2} + \sigma_v^{-2} h'_{-1} (h - \mu_0 \mathbf{1}_T)]\end{aligned}$$

# Full-conditional posterior distributions

## Full-conditional posterior distribution for $h_0$

$$\begin{aligned}h_0|y, h, \alpha, \mu_0, \sigma_v^2 &\sim \mathcal{N}(\bar{h}_0, \bar{\sigma}_h^2) \\ \bar{\sigma}_h^2 &= [\underline{\sigma}_h^{-2} + \alpha^2 \sigma_v^{-2}]^{-1} \\ \bar{h}_0 &= \bar{\sigma}_h^2 [\underline{h}_0 \underline{\sigma}_h^{-2} + \alpha h_1 \sigma_v^{-2}]\end{aligned}$$

## Full-conditional posterior distribution for $\sigma_v^2$

$$\begin{aligned}\sigma_v^2|y, h, \mu_0, \alpha, h_0 &\sim \mathcal{IG2}(\bar{s}, \bar{\nu}) \\ \bar{s} &= \underline{s} + (H_\alpha h - \mu_0 I_T - \alpha h_0 e_{1..t})' (H_\alpha h - \mu_0 I_T - \alpha h_0 e_{1..t}) \\ \bar{\nu} &= \bar{\nu} + T\end{aligned}$$

# Gibbs sampler

**Initialize**  $h^{(0)}$ ,  $s^{(0)}$ ,  $\mu_0^{(0)}$ ,  $\alpha^{(0)}$ , and  $\sigma_v^{2(0)}$

**For**  $i = 1, \dots, S$

**Draw**  $h_0^{(i)} \sim \mathcal{N}(\bar{h}_0, \bar{\sigma}_h^2)$

**Draw**  $\sigma_v^{2(i)} \sim \mathcal{IG2}(\bar{s}, \bar{\nu})$

**Draw**  $\mu_0^{(i)} \sim \mathcal{N}(\bar{\mu}_0, \bar{\sigma}_\mu^2)$

**Draw**  $\alpha^{(i)} \sim \mathcal{N}(\bar{\alpha}, \bar{\sigma}_\alpha^2)$

**Draw**  $s_t^{(i)} \sim \text{Multinomial}(\{m\}_{m=1}^{10}, \{Pr[s_t = m | \tilde{y}_t, h_t^{(i)}]\}_{m=1}^{10})$   
for  $t = 1, \dots, T$  using inverse transform method

**Draw**  $h^{(i)} \sim \mathcal{N}_T(\bar{h}, \bar{V}_h)$  using precision sampler

**Return** a sample drawn from the posterior distribution:

$$\{h^{(i)}, s^{(i)}, \mu_0^{(i)}, \alpha^{(i)}, h_0^{(i)}, \sigma_v^{2(i)}\}_{i=1}^S$$

## Introduction to heteroskedastic models

# Introduction to heteroskedastic models

## A linear regression with Stochastic Volatility

$$Y = X\beta + E$$

$$E \mid X \sim \mathcal{N}_T(\mathbf{0}_T, \text{diag}(\sigma^2))$$

$$\sigma^2 = (\exp\{h_1\}, \dots, \exp\{h_T\})$$

$h_t$  – follows a Stochastic Volatility process

$$\beta \sim \mathcal{N}(\underline{\beta}, \underline{V}_\beta)$$

## A model with conditional heteroskedasticity

- ▶ Improves the precision of the estimation of  $\beta$
- ▶ Improves the in-sample fit of the model
- ▶ Greatly improves the forecasting performance of the model

# Introduction to heteroskedastic models

## Full conditional posterior distribution of $\beta$

$$\beta \mid Y, X, h \sim \mathcal{N}(\bar{\beta}, \bar{V}_{\beta})$$

$$\begin{aligned}\bar{V}_{\beta} &= \left[ \underline{V}_{\beta}^{-1} + X' \text{diag}(\sigma^2)^{-1} X \right]^{-1} \\ \bar{\beta} &= \bar{V}_{\beta} \left[ \underline{V}_{\beta}^{-1} \underline{\beta} + X' \text{diag}(\sigma^2)^{-1} Y \right]\end{aligned}$$

Conditionally on  $h$  the remaining model parameters can be sampled from their respective full conditional posterior distributions that take into account the conditional variances of the error term

# Bayesian estimation of SV models

**An efficient and computationally fast** method of estimating SV models is Bayesian Gibbs sampler

**Dedicated computational techniques** include

- auxiliary mixture
- simulation smoother
- operations on tridiagonal matrices
- inverse transform method

**The algorithm** presented in this lecture is applicable to

- univariate models** with SV conditional heteroskedasticity
- multivariate models** with independent SV processes

**Adapt** your Gibbs sampler to use function `SV.Gibbs.iteration` from file `00 SV codes.R`