

Time Series

Stationarity (weak sense):

$$E(y_t) = \mu \quad \forall t$$

$$\text{Var}(y_t) = \sigma^2 \quad \forall t$$

$$\text{cov}(y_t, y_{t-k}) = \gamma_k \quad \forall t$$

ARIMA(p, d, q)

$$\text{ARMA: } y_t = \alpha + \beta_1 y_{t-1} + \dots + \beta_p y_{t-p} + u_t + \alpha_1 u_{t-1} + \dots + \alpha_q u_{t-q}$$

Difference stationary
 Δy_t - stationary

Trend stationary

$$y_t = \alpha + \beta t$$

L - lag operator

$$L y_t = y_{t-1} \quad L^k y_t = y_{t-k}$$

Autocorrelation:

$$\text{Cov}(\varepsilon_i, \varepsilon_j) \neq 0$$

$$y_t = \beta_0 + \beta_1 x_t + u_t \quad \begin{matrix} \varepsilon_t + \alpha_1 \varepsilon_{t-1} \\ // \end{matrix}$$

$$\text{Cov}(u_t, u_{t-1}) = \sigma_1$$

$$y_t = \beta_0 + \beta_1 x_t + \beta_2 y_{t-1} + u_t$$

$= \beta_2 (\beta_0 + \beta_1 x_{t-1} + \varepsilon_{t-1}) + \varepsilon_t$
 $\varepsilon_t + \alpha_1 \varepsilon_{t-1}$

Consequences of Autocorr.

① if y_{t-1} is in RHS
 \Rightarrow endogeneity

② else consequences
are the same as
with Heterosced.

$\Rightarrow \hat{\beta}_{OLS}$ - inefficient

$\hat{\beta}_{GLS}$ - efficient

TGM

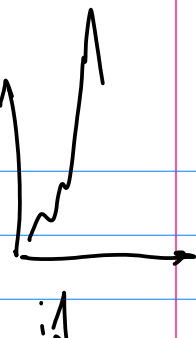
$$\sigma^2_{\epsilon} \begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$$

Heterosce.

$$\sigma^2_{\epsilon} \begin{pmatrix} x_1 & & 0 \\ & \ddots & \\ 0 & & x_n \end{pmatrix}$$

Autore. (of order 1)

$$\sigma^2_{\epsilon} \begin{pmatrix} 1 & \gamma_1 & \dots & 0 \\ \gamma_1 & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \gamma_1 \\ 0 & \dots & \gamma_1 & 1 \end{pmatrix}$$



$$[y_t = \beta_1 + \beta_2 \cdot X_t + \beta_3 (L y_t) + u_t]$$

$|\beta_3| < 1$ \uparrow w.a.

$\beta_3 > 1$

$$(1 - \beta_3 L) y_t = \beta_1 + \beta_2 X_t + u_t$$

$$y_t = \frac{\beta_1}{1 - \beta_3 L} + \frac{\beta_2 X_t}{1 - \beta_3 L} + \frac{u_t}{1 - \beta_3 L}$$

$\beta_2 X_t = b_0$
" " " "

$$y_t = \beta_1^* + \beta_2 X_t + L(\beta_2 \cdot X_t \cdot \beta_3) + \beta_2 \cdot \beta_3^2 \cdot X_{t-2} +$$

" " " "

$$b_0 + b_0 \cdot q + b_0 \cdot q^2 + \dots$$

$$= \frac{b_0}{1 - q}$$

$$\beta_2 \cdot \beta_3 \cdot X_{t-1} + \dots + u_t^*$$

$$y = \begin{pmatrix} y_1 \\ \vdots \\ y_t \end{pmatrix} \quad L y = \begin{pmatrix} 0 \\ y_1 \\ \vdots \\ y_{t-1} \end{pmatrix}$$

$$(0 \dots 1)$$

$$y_t = \beta_0 + \beta_1 x_t + \beta_2 y_{t-1} + u_t$$

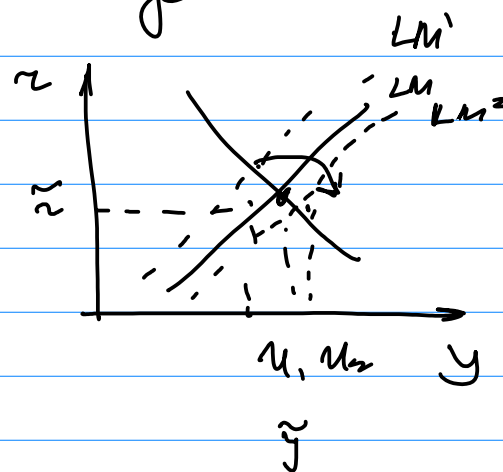
β_1 - SR effect (shows change at t)

\tilde{y}, \tilde{x} - LR equilibrium

$$t \rightarrow \infty : \tilde{y} = \beta_0 + \beta_1 \tilde{x} + \beta_2 \tilde{y}$$

$$(1 - \beta_2) \tilde{y} = \beta_0 + \beta_1 \tilde{x}$$

$$\tilde{y} = \frac{\beta_0}{1 - \beta_2} + \frac{\beta_1}{1 - \beta_2} \tilde{x}$$



$$\beta_1 + \beta_1 \beta_2 + \beta_1 \beta_2^2 + \dots = \frac{\beta_1}{1 - \beta_2} \quad \text{— LR effect } x \text{ on } y$$

\checkmark

β_1 — SR effect

ARDL (p, q) ; ADL (p, q) .

$$y_t = \beta_0 + \beta_1 x_t + \dots + \beta_q x_{t-q} + \alpha_1 y_{t-1} + \dots + \alpha_p y_{t-p} + u_t$$

