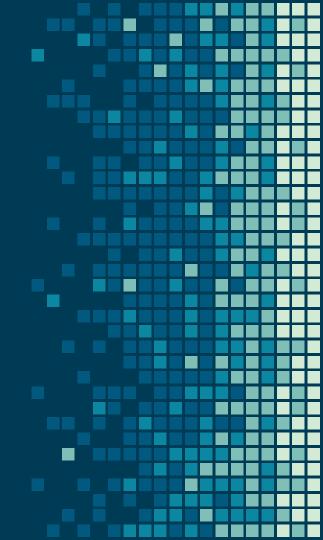
Hand Segmentation Using RefineNet

Research Paper-Analysis of Hand Segmentation in the Wild (CVPR 2018)

Adarsh Pal Singh Ishan Bansal Paawan Gupta



In a Nutshell...

The main goal of this project is to develop an egocentric hand segmentation model using RefineNet in Python.

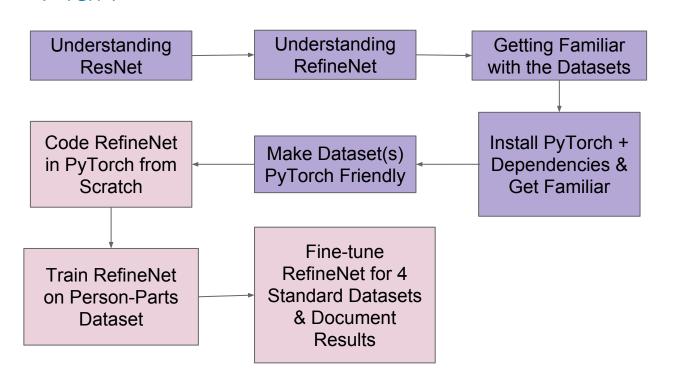




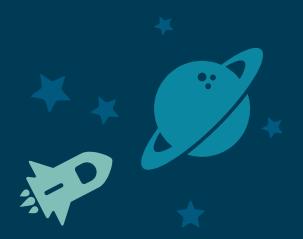
Motivation for Hand Segmentation

- 1. Hand pose and configuration tell a lot about what we plan to do or what we pay attention to.
- 2. Applications in robotics, human-machine interaction, computer vision, augmented reality, etc.
- 8. Extracting hand regions in egocentric videos is a critical step for understanding fine motor skills such as hand-object manipulation and hand-eye coordination.

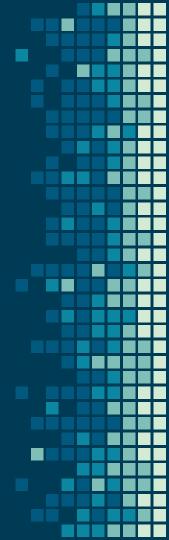
Plan





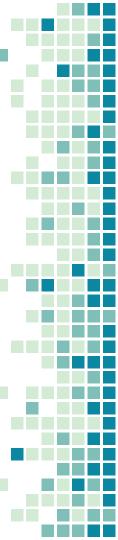


ResNet

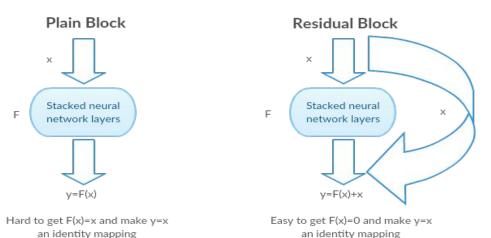


Understanding ResNet

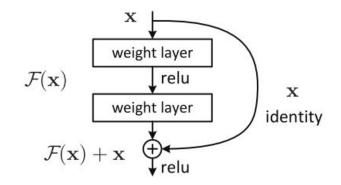
- Feedforward network with a single layer is sufficient to represent any function.
- However, the layer might be massive and the network is prone to overfitting the data.
- Common trend in research to make networks deeper!
- However, increasing network depth does not work by simply stacking layers together.
- Deep networks are hard to train because of the notorious vanishing gradient problem.



- Another Problem: Performing optimization on huge parameter space and naively adding layers leads to higher training error (Degradation Problem).
- Residual networks allow training of such deep networks by constructing the network through modules called residual model.



- The core idea of ResNet is introducing "identity shortcut connection" that skips one or more layers
- These parameterized gates control how much information is allowed to flow across the shortcut







RefineNet



Why RefineNet?

- RefineNet is a multi-path refinement network which exploits all the features at multiple levels along the down sampling path
- Authors performed off-the-shelf evaluation of leading semantic segmentation methods on the EgoHands dataset and found that RefineNet gives better results than other models.
- On EgoHands dataset, RefineNet significantly outperformed the baseline.



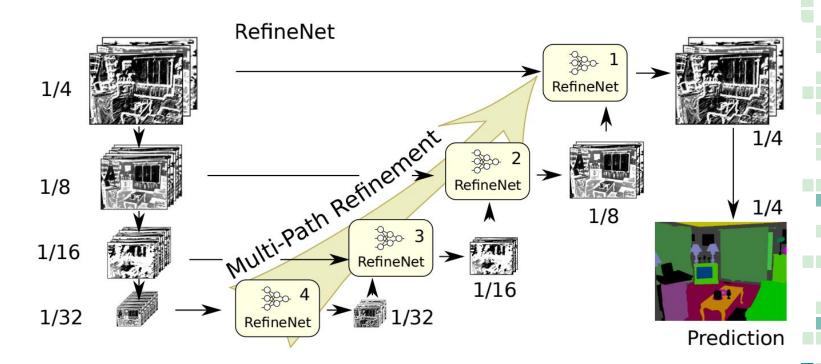
Understanding RefineNet

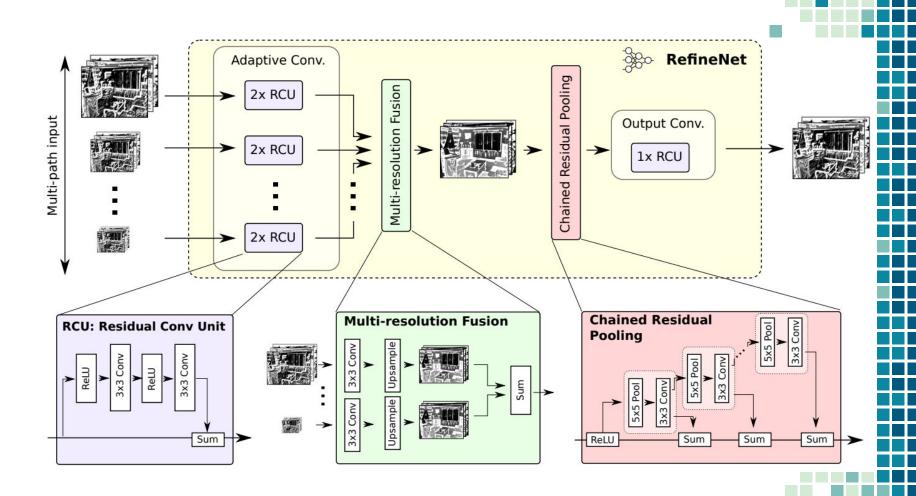
- Dilated convolutions are computationally expensive and take a lot of memory because they have to be applied on large number of high resolution feature maps.
- → This hampers the computation of high-res predictions.
- → RefineNet uses encoder-decoder architecture.
- → Encoder part is ResNet-101 blocks.
- Decoder has RefineNet blocks which concatenate/fuse high res features from encoder and low res features from previous RefineNet block.



- RefineNet provides a generic means to fuse coarse high-level semantic features with finer-grained low-level features to generate high-resolution semantic feature maps
- → It ensures that the gradient can be effortlessly propagated backwards through the network all the way to early low-level layers over long range residual connections, ensuring that the entire network can be trained end-to-end

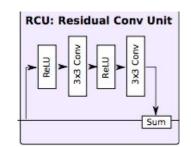






Residual Convolution Unit (RCU)

- → Adaptive Convolution set that fine tunes the pretrained ResNet weights for the task.
- → Each Input is passed sequentially through 2 RCU where Batch Normalization is removed from the original ResNet.





Multi-Resolution Fusion

- → All path inputs are then fused into a high-resolution feature map by the multi-resolution fusion block.
- First applies convolutions for input adaptation, which generates feature maps of the same feature dimension.
- Up-samples all feature maps to the largest resolution of the inputs.
- → Finally, all features maps are fused by summation.
- The input adaptation in this block also helps to re-scale the feature values appropriately along different paths.



Chain Residual Pooling

- → Aims to capture background context from a large image region.
- It is able to efficiently pool features with multiple window sizes and fuse them together using learnable weights.
- In particular, this component is built as a chain of multiple pooling blocks, each consisting of one max-pooling layer and one convolution layer.
- The current pooling block is able to re-use the result from the previous pooling operation and thus access the features from a large region without using a large pooling window.



Output Convolutions

- → The final step of each RefineNet block is another residual convolution unit (RCU).
- This results in a sequence of three RCUs between each block. To reflect this behavior in the last RefineNet-1 block, we place two additional RCUs before the final softmax prediction step.
- The goal here is to employ non-linearity operations on the multi-path fused feature maps to generate features for further processing or for final prediction.
- The feature dimension remains the same after going through this block.

How is RefineNet used?

- → RefineNet-Res101 pre-trained on Pascal Person-Part dataset used in all experiments.
- → A new classification layer added with 2 classes: hand and no hand.
- → Fine-tuned the model on EgoHands, EYTH, GTEA, and HOF datasets.
- → RefineNet-Res101 uses feature maps from ResNet101.
- After fine tuning, performed multi-scale evaluation for scales: [0.6, 0.8, 1.0] which gives consistently better results than single scale evaluation.





Datasets

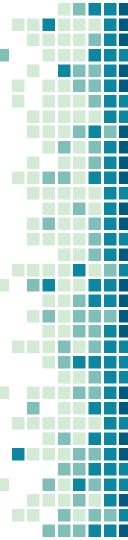


PASCAL Person-Parts Dataset

- A subset of the Parts-dataset that is present with VOC 2010 dataset.
- → 24 different human body parts annotated!
- → Mostly third person photos.
- Link: http://www.stat.ucla.edu/~xianjie.chen/pascal_part_dataset/pascal_part.html

EgoHands

- → 48 videos recorded with Google glass.
- Videos are recorded in 3 different environments: office, courtyard and living room.
- → Each video has two actors doing one of the 4 activities: playing puzzle, cards, jenga or chess.
- → Pixel-level ground truth for over 15000 hand instances.
- → Link: http://vision.soic.indiana.edu/projects/egohands/



EgoYouTubeHands (EYTH)

- → Pixel-level hand annotations in real world images and/or videos obtained from YouTube.
- Users perform different activities and are interacting with others.
- This dataset has 2600 hand instances, with approx. 1800 first-person hand instances and approx. 800 third-person hands.
- Link: https://github.com/aurooj/Hand-Segmentation-in-the-Wild

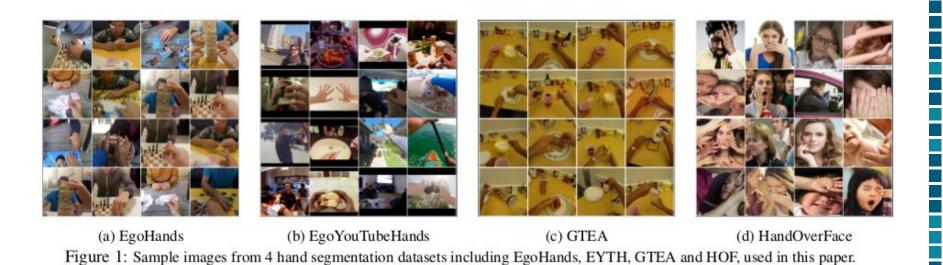
Georgia Tech Egocentric Activity (GTEA)

- → 7 daily activities performed by 4 subjects.
- → Videos are collected in the same environment for the purpose of activity recognition.
- → Does not capture social interactions and is collected under static illumination conditions annotated at 15 fps for 61 action classes.
- → 663 images with pixel-level hand annotations.
- → Link: http://www.cbi.gatech.edu/fpv/

HandOverFace (HOF)

- Contains 300 images obtained from the web in which faces are occluded by hands.
- → Useful to study how skin similarity can affect hand segmentation.
- → Has images for people from different ethnicities, age, and gender.
- → Pixel-level annotations for hands along with the hand type: left or right.
- → Link: https://github.com/aurooj/Hand-Segmentation-in-the-Wild







Results

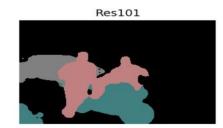


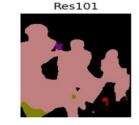
Initial Testing with RefineNet

An example code written to test and get familiar with RefineNet in PyTorch. Pre-trained VOC weight file directly used.



Original Image





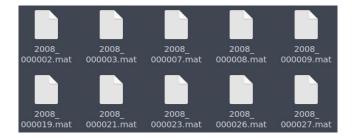
Codes

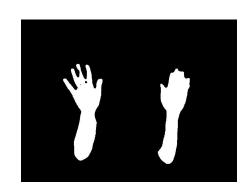
Problem: Pre-trained weight for VOC-parts dataset incompatible with PyTorch! Moreover, the parts dataset has .mat files for image labels which PyTorch's RefineNet can't use natively.

Dataset Cleaning: Script to process the Parts dataset. Converts .mat files to .jpg segmentations for all pictures containing "persons" => Person-parts dataset!



Codes







Training

- Train on PersonParts (for Hands).
- Fine tune for other datasets.
- 3. Learning 5e-5
- 4. Scales: [0.6, 0.8, 1.0]

```
./train val/train images/s2 cheese 0000000460.jpg']
  /train val/train images/2008 004707.jpg']
 ./train val/train images/261.jpg']
  /train val/train images/2008 005701.jpg']
 ./train val/train images/2008 003065.jpg']
 ./train val/train images/s1 pealate 0000001060.jpg'l
NFO: main : Val epoch: 7 [0/181]
                                       Mean IoU: 0.471
NFO: main : Val epoch: 7 [10/181]
                                       Mean IoU: 0.468
INFO: main : Val epoch: 7 [20/181]
                                       Mean IoU: 0.468
INFO: main : Val epoch: 7 [30/181]
                                       Mean IoU: 0.468
INFO: main : Val epoch: 7 [40/181]
                                       Mean IoU: 0.469
INFO: main : Val epoch: 7 [50/181]
                                       Mean IoU: 0.469
INFO: main : Val epoch: 7 [60/181]
                                       Mean IoU: 0.467
                                       Mean IoU: 0.468
INFO: main : Val epoch: 7 [70/181]
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                                       Mean IoU: 0.467
INFO: main : Val epoch: 7 [90/181]
                                       Mean IoU: 0.468
INFO: main : Val epoch: 7 [100/181]
                                       Mean IoU: 0.466
INFO: main : Val epoch: 7 [110/181]
                                       Mean IoU: 0.467
INFO: main : Val epoch: 7 [120/181]
                                       Mean IoU: 0.483
INFO: main : Val epoch: 7 [130/181]
                                       Mean IoU: 0.567
INFO: main : Val epoch: 7 [140/181]
                                       Mean IoU: 0.571
INFO: main : Val epoch: 7 [150/181]
                                       Mean IoU: 0.610
INFO: main : Val epoch: 7 [160/181]
                                       Mean IoU: 0.637
INFO: main : Val epoch: 7 [170/181]
                                       Mean IoU: 0.664
NFO: main : Val epoch: 7 [180/181]
                                       Mean IoU: 0.687
NFO: main : IoUs: [0.93723754 0.43736504]
NFO: main : Val epoch: 7
INFO: main : New best value 0.6873, was 0.6704
 ./train val/train images/106.jpg']
INFO: main : Train epoch: 8 [0/840] Avg. Loss: 0.502
 ./train_val/train_images/2008_004372.jpg']
 ./train val/train images/2010 000131.jpg']
 ./train val/train images/s1 pealate 0000001340.jpg']
 ./train val/train images/2010 005046.jpg']
 ./train val/train images/294.jpg']
  /train_val/train_images/2009_004309.jpg']
 ./train val/train images/s2 cofhoney 0000000060.jpg']
  /train_val/train_images/143.jpg']
  /train val/train images/207.jpg'
```

mloU

PersonParts (Hand): 0.61

EgoHands: 0.662

EYTH: 0.492

GTEA: 0.637

HOF: 0.612



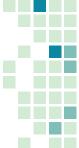
^{**} On their respective train-test splits.



























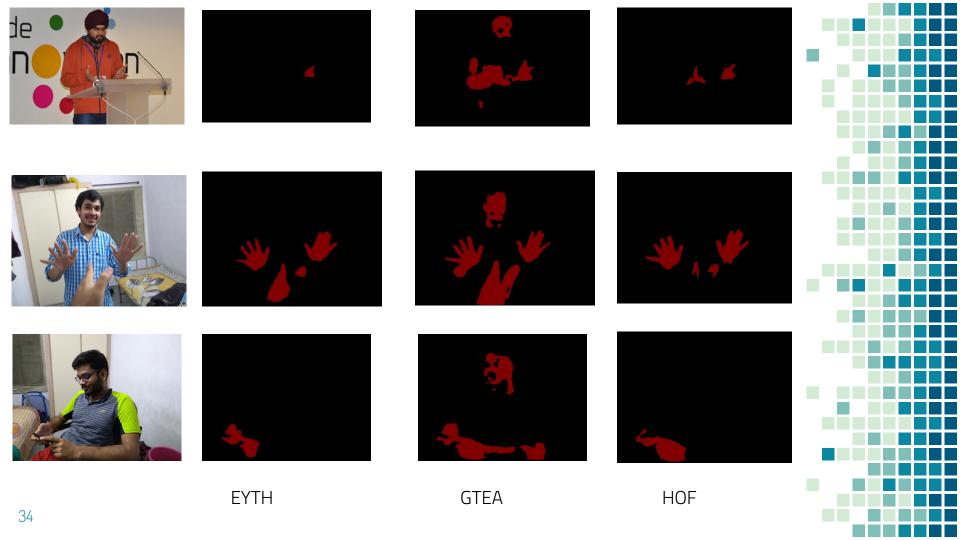
Person Parts

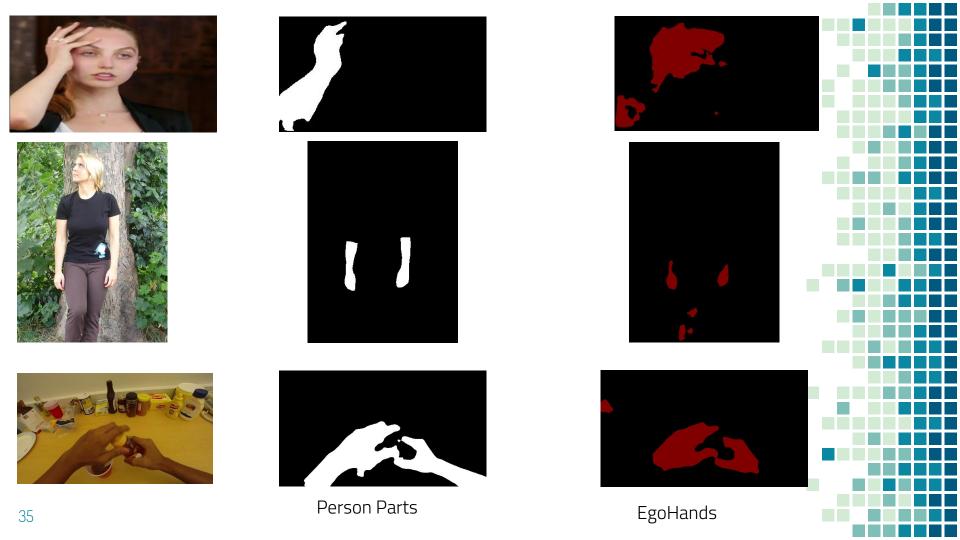


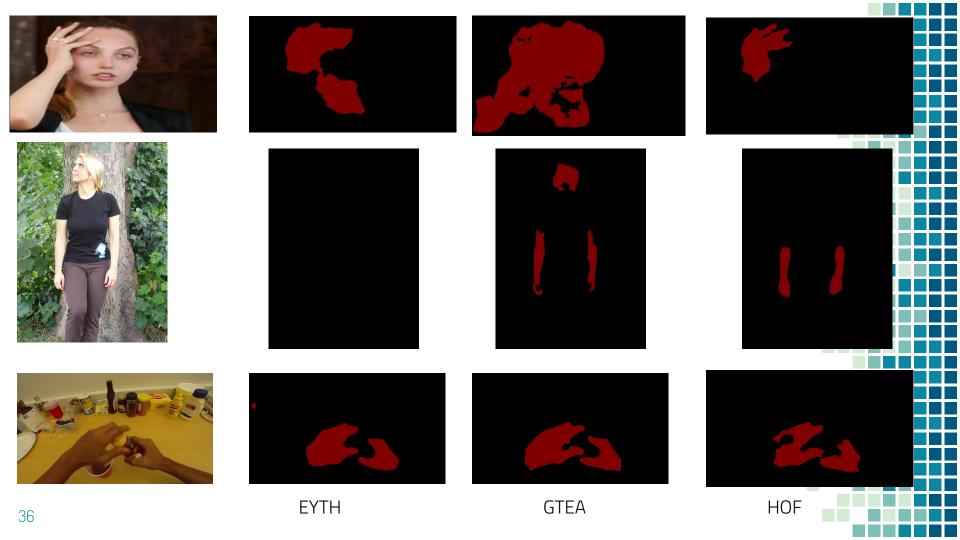
EgoHands



33









Conclusion

- We got different results for fined tuned models on different datasets.
- Best result was from PersonParts & EgoHands based model
- HoF based model is useful to study similar appearance occlusions like hand-to-skin occlusions
- Cross-dataset testing revealed segmentation faults with other body parts like in the case of GTEA.



Failure Cases

Motion Blur





- Occlusion
- Similar Appearance Occlusion
- Small Hands
- Lightning Conditions

THANKS!

Any questions?

