



**Department of Computer Science Engineering & Application**

**Soft Computing Lab File**

**Name – Puneet Kumar**

**Section – K**

**Roll No. – 33**

**University Roll No. – 191500612**

**Submitted To –**

**Dr. Praphula Kumar Jain**

# INDEX

S.No	List of Experiments	PageNo
1	Plot Different types of activation Functions	3-4
2	Program To Create Single Layer Perceptron	5-6
3	To implement AND function using ADALINE with bipolar input and output	7-8
4	To Construct and test Auto Associate Network for input vector HEBB's rule	9-9
5	Create a multilayer Perceptron & WAP for Back - propagation Network	10-11
6	Program for fuzzy set operation and properties	12-14
7	Program to find relation using max-min composition enter the two vectors whose relation is to be found	15-15
8	Method Of Defuzzification	16-16
9	Program for complete Genetic Algorithm Cycle	17-19
10	WAP to find the minimum value of a function	20-21

## Experiment 1 – Plot different types of Activation Function.

### Linear Activation Function -

```
import numpy as np
import matplotlib.pyplot as plt
import numpy as np
def linear(x):
    ''' y = f(x) It returns the input as it is'''
    return x
x = np.linspace(-10, 10)
plt.plot(x, linear(x))
plt.axis('tight')
plt.title('Activation Function :Linear')
plt.show()
```

### Sigmoid Activation Function

```
import numpy as np
import matplotlib.pyplot as plt
import numpy as np
def sigmoid(x):
    ''' It returns  $1/(1+\exp(-x))$ . where the values lies between zero and one '''
    return 1/(1+np.exp(-x))
x = np.linspace(-10, 10)
plt.plot(x, sigmoid(x))
plt.axis('tight')
plt.title('Activation Function :Sigmoid')
plt.show()
```

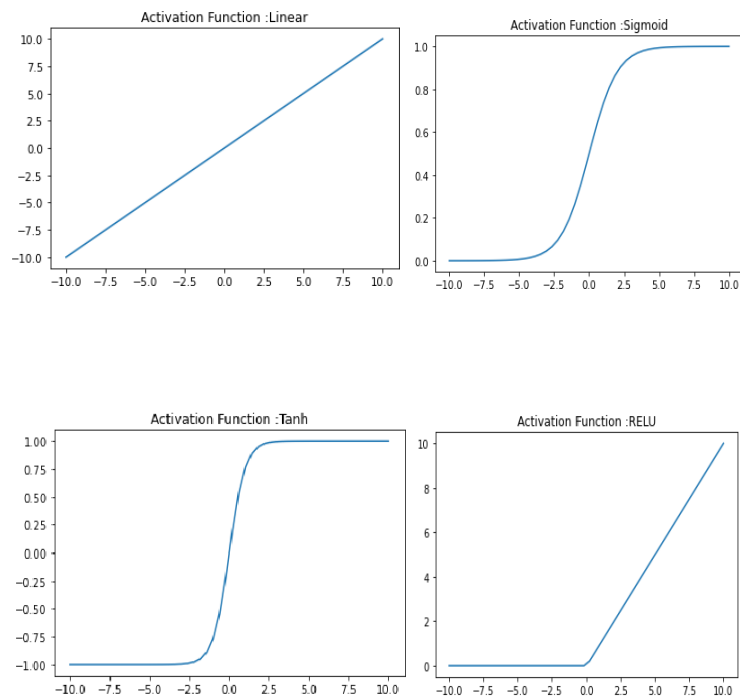
### Tanh Activation Function-

```
import numpy as np
import matplotlib.pyplot as plt
import numpy as np
def tanh(x):
    ''' It returns the value  $(1-\exp(-2x))/(1+\exp(-2x))$  and the value returned will be lies in between - 1 to 1.'''
    return np.tanh(x)
x = np.linspace(-10, 10)
plt.plot(x, tanh(x))
plt.axis('tight')
plt.title('Activation Function :Tanh')
plt.show()
```

### RELU Activation Function –

```
import numpy as np
import matplotlib.pyplot as plt
import numpy as np
def RELU(x):
    ''' It returns zero if the input is less than zero otherwise it returns the given input. '''
    x1=[]
    for i in x:
        if i<0:
            x1.append(0)
        else:
            x1.append(i)
```

```
return x1
x = np.linspace(-10, 10)
plt.plot(x, RELU(x))
plt.axis('tight')
plt.title('Activation Function :RELU')
plt.show()
```



## Experiment 2- Program to create Single Layer Perceptron.

```
def perceptron(X, y, lr, epochs):
    # X --> Inputs.
    # y --> labels/target.
    # lr --> learning rate.
    # epochs --> Number of iterations.
    # m--> number of training examples
    # n--> number of features
    m, n = X.shape
    # Initializing parameters(theta) to zeros.
    # +1 in n+1 for the bias term.
    theta = np.zeros((n+1,1))
    # Empty list to store how many examples were
    # misclassified at every iteration.
    n_miss_list = []
    # Training.
    for epoch in range(epochs):
        # variable to store #misclassified.
        n_miss = 0
        # looping for every example.
        for idx, x_i in enumerate(X):
            # Inserting 1 for bias, X0 = 1.
            x_i = np.insert(x_i, 0, 1).reshape(-1,1)
            # Calculating prediction/hypothesis.
            y_hat = step_func(np.dot(x_i.T, theta))
            # Updating if the example is misclassified.
            if (np.squeeze(y_hat) - y[idx]) != 0:
                theta += lr*((y[idx] - y_hat)*x_i)
            # Incrementing by 1.
            n_miss += 1
        # Appending number of misclassified examples
        # at every iteration.
        n_miss_list.append(n_miss)
    return theta, n_miss_list

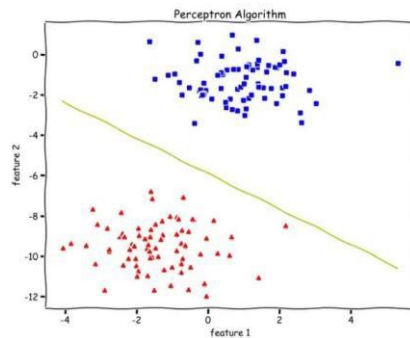
# Plotting Features
def plot_decision_boundary(X, theta):
    # X --> Inputs
    # theta --> parameters
    # The Line is y=mx+c
    # So, Equate mx+c = theta0.X0 + theta1.X1 + theta2.X2
```

```

# Solving we find m and c
x1 = [min(X[:,0]), max(X[:,0])]
m = -theta[1]/theta[2]
c = -theta[0]/theta[2]
x2 = m*x1 + c
# Plotting
fig = plt.figure(figsize=(10,8))
plt.plot(X[:, 0][y==0], X[:, 1][y==0], 'r^')
plt.plot(X[:, 0][y==1], X[:, 1][y==1], 'bs')
plt.xlabel('feature 1')
plt.ylabel('feature 2')
plt.title('Perceptron Algorithm') plt.plot(x1, x2, 'y-')
# Training & Plotting
theta, miss_l = perceptron(X, y, 0.5, 100)
plot_decision_boundary(X, theta)

```

**OUTPUT-**



### **Experiment 3 - To implement AND function using ADALINE with bipolar input and output**

#### **Algorithm:**

- 1. Initialize weight and bias to 0**
- 2. Accept learning rate, alpha and threshold, theta**
- 3. For each input calculate  $y_{in} = b + x(1)*w(1) + x(2)*w(2)$**
- 4. Apply activation function**
- 5. If calculated output  $\neq$  target output**
  - i) update weight and bias**
  - ii) Go to step 3**
- 6. Display final weight matrix and bias value**

#### **Program:**

**% Perceptron for AND function**

**clear;**

**clc;**

**x=[1 1 -1 -1; 1 -1 1 -1];**

**t=[1 -1 -1 -1];**

**w=[0 0];**

**b=0;**

**alpha=input('Enter Learning rate=');**

**theta=input('Enter Threshold Value=');**

**con = 1;**

**epoch = 0;**

**while con**

**con=0;**

**for i=1:4**

**yin=b+x(1,i)\*w(1)+x(2,i)\*w(2);**

**if yin>theta**

**y=1;**

**end**

**if yin<=theta & yin>= -theta**

**y=0;**

**end**

**if yin < -theta**

**y = -1;**

**end**

**if y-t(i)**

**con=1;**

**for j=1:2**

**w(j)=w(j)+alpha\*t(i)\*x(j,i);**

**end**

**b=b+alpha\*t(i);**

```
end
epoch=epoch+1;
end
disp('Perceptron for AND Function');
disp('Final Weight Matrix');
disp(w);
disp('Final Bias');
disp(b);
Sample Input and Output:
Enter Learning rate = 1
Enter Threshold Value =0.5
Perceptron for AND Function
Final Weight Matrix
1 1
Final Bias
-1
```



**Experiment 4: To Construct and test Auto Associative Network for input vector using HEBB's Rule**

**%Autotassociative net to store the vector**

```
clc;  
  
clear;  
  
x = [1 1 -1 -1];  
  
w=zeros (4, 4);  
  
w=x'*x;  
  
yin=x*w;  
  
for i=1:4  
if yin(i)>0  
y(i)=1;  
else  
y(i) = -1;  
end  
end  
  
disp ('Weight matrix');  
  
disp (w);  
  
if x == y disp ('The vector is a Known Vector');  
  
Else  
  
disp ('The vector is a Unknown Vector');  
  
End
```

**OUTPUT:**

**Weight matrix**

**1 1 -1 -1**

**1 1 -1 -1**

**-1 -1 1 1**

**-1 -1 1 1**

**The vector is a known vector.**

## Experiment 5: Create a multilayer Perceptron & WAP for Back-propagation Network

**Import**

**numpy as np**

**# X = (hours sleeping, hours studying), y = test score of the student**

**X = np.array([[2, 9], [1, 5], [3, 6]], dtype=float)**

**y = np.array([[92], [86], [89]], dtype=float)**

**# scale units**

**X = X/np.amax(X, axis=0) #maximum of X array**

**y = y/100 # maximum test score is 100**

**class NeuralNetwork(object):**

**def \_\_init\_\_(self):**

**#parameters**

**self.inputSize = 2**

**self.outputSize = 1**

**self.hiddenSize = 3**

**#weights**

**self.W1 = np.random.randn(self.inputSize, self.hiddenSize) # (3x2) weight matrix from input to hidden layer**

**self.W2 = np.random.randn(self.hiddenSize, self.outputSize) # (3x1) weight matrix from hidden to output layer**

**def feedForward(self, X):**

**#forward propogation through the network**

**self.z = np.dot(X, self.W1) #dot product of X (input) and first set of weights (3x2)**

**self.z2 = self.sigmoid(self.z) #activation function**

**self.z3 = np.dot(self.z2, self.W2) #dot product of hidden layer (z2) and second set of weights (3x1)**

**output = self.sigmoid(self.z3)**

**return output**

**def sigmoid(self, s, deriv=False):**

```

    if (deriv == True):
        return s * (1 - s)

    return 1/(1 + np.exp(-s))

def backward(self, X, y, output):
    #backward propogate through the network
    self.output_error = y - output # error in output
    self.output_delta = self.output_error * self.sigmoid(output, deriv=True)

    self.z2_error = self.output_delta.dot(self.W2.T) #z2 error: how much our
    hidden layer weights contribute to output error

    self.z2_delta = self.z2_error * self.sigmoid(self.z2, deriv=True) #applying
    derivative of sigmoid to z2 error

    self.W1 += X.T.dot(self.z2_delta) # adjusting first set (input -> hidden)
    weights

    self.W2 += self.z2.T.dot(self.output_delta) # adjusting second set (hidden -
    > output) weights

def train(self, X, y):
    output = self.feedForward(X)
    self.backward(X, y, output)

NN = NeuralNetwork()

for i in range(1000): #trains the NN 1000 times
    if (i % 100 == 0):
        print("Loss: " + str(np.mean(np.square(y - NN.feedForward(X)))))
        NN.train(X, y)

print("Input: " + str(X))
print("Actual Output: " + str(y))
print("Loss: " + str(np.mean(np.square(y - NN.feedForward(X)))))

```

## Experiment 6 - Program for fuzzy set operation and properties

**class FzSets:**

**def \_\_init\_\_(self):**

```
    self.A = dict()
    self.B = dict()
    self.complement_A = dict()
    self.complement_B = dict()
    self.union_AB = dict()
    self.intersection_AB = dict()
    self.differenceAB = dict()
    self.differenceBA = dict()
    self.change_union = False
    self.change_intersection = False
    self.change_complement = False
```

**def \_\_init\_\_(self,A,nA,B,nB):**

```
    self.A = A
    self.B = B
    self.Aname = nA
    self.Bname = nB
    self.complement_A = dict()
    self.complement_B = dict()
    self.union_AB = dict()
    self.intersection_AB = dict()
    self.differenceAB = dict()
    self.differenceBA = dict()
    self.change_union = False
    self.change_intersection = False
    self.change_complement = False
```

**def unionOp(self):**

```
    if self.change_union:
        print('Result of UNION operation :',self.union_AB)
    else:
        #unionSet = set(self.A.keys()).union(self.B.keys())
        sa = set(self.A.keys())
        sb = set(self.B.keys())
        intersectionSet = set(self.A.keys()).intersection(self.B.keys())
        for i in intersectionSet:
            self.union_AB[i] = max(self.A[i],self.B[i])
        for i in sa-intersectionSet:
            self.union_AB[i] = self.A[i]
        for i in sb-intersectionSet:
```

```

self.union_AB[i] = self.B[i]
print('Result of UNION operation :',self.union_AB)
    def intersectionOp(self):
    if self.change_intersection:
        print('Result of INTERSECTION operation :\n\t\t',self.intersection_AB)
    else:
        #unionSet = set(self.A.keys()).union(self.B.keys())
        sa = set(self.A.keys())
        sb = set(self.B.keys())
        intersectionSet = set(self.A.keys()).intersection(self.B.keys())
        for i in intersectionSet:
            self.intersection_AB[i] = min(self.A[i],self.B[i])
        for i in sa-intersectionSet:
            self.intersection_AB[i] = 0.0
        for i in sb-intersectionSet:
            self.intersection_AB[i] = 0.0
        print('Result of INTERSECTION operation :\n\t\t',self.intersection_AB)
        self.change_intersection = True
def complementOp(self):
    if self.change_complement:
        print('Result of COMPLEMENT on ',self.Aname,' operation :',self.complement_A)
        print('Result of COMPLEMENT on ',self.Bname,' operation :',self.complement_B)
    else:
        for i in self.A:
            self.complement_A[i] = 1 - A[i]
        for i in self.B:
            self.complement_B[i] = 1 - B[i]
print('Result of COMPLEMENT on ',self.Aname,' operation :',self.complement_A)
    print('Result of COMPLEMENT on ',self.Aname,' operation :',self.complement_B)
self.change_complement = True
def _oneMinustwo(self,L,R):
    minus_d = dict()
    Rcomp = dict()
    for i in R:
        Rcomp[i] = 1 - R[i]
    sa = set(L.keys())
    sb = set(R.keys())
    intersectionSet = sa.intersection(sb) # min( A , complement(B) )
    # 1 - r OR a - b
    for i in intersectionSet:
        minus_d[i] = min(L[i],Rcomp[i])

```

```

for i in sa-intersectionSet:
    minus_d[i] = 0.0
for i in sb-intersectionSet:
    minus_d[i] = 0.0
return minus_d
def AminusB(self):
    self.differenceAB = self.__oneMinustwo(self.A,self.B)
    print('Result of DIFFERENCE ',self.Aname,' | ',self.Bname,' operation
:\n\t\t',self.differenceAB)
def BminusA(self):
    self.differenceBA = self.__oneMinustwo(self.B,self.A)
    print('Result of DIFFERENCE ',self.Bname,' | ',self.Aname,' operation
:\n\t\t',self.differenceBA)
def change_Setz(self,A,B):
    self.A = A
    self.B = B
print('\nSet ',self.Aname,' : ',self.A)
    print('Set ',self.Bname,' : ',self.B,end='')
self.change_union = True
    self.change_intersection = True
    self.change_complement = True
    print('\t\t\t Cache Reset')
def displaySets(self):
    print('\nSet ',self.Aname,' : ',self.A)
    print('Set ',self.Bname,' : ',self.B)

```

**Experiment 7 - Program to find relation using max-min composition, enter the two vectors who's relation is to be find.**

**Program -**

**import numpy as np**

**# Max-Min Composition**

**def maxMin(x, y):**

**z = []**

**for x1 in x:**

**for y1 in y.T:**

**z.append(max(np.minimum(x1, y1)))**

**return np.array(z).reshape((x.shape[0], y.shape[1]))**

**# Max-Product Composition given by Rosenfeld**

**def maxProduct(x, y):**

**z = []**

**for x1 in x:**

**for y1 in y.T:**

**z.append(max(np.multiply(x1, y1)))**

**return np.array(z).reshape((x.shape[0], y.shape[1]))**

**# 3 arrays for the example**

**r1 = np.array([[1, 0, .7], [.3, .2, 0], [0, .5, 1]])**

**r2 = np.array([[.6, .6, 0], [0, .6, .1], [0, .1, 0]])**

**r3 = np.array([[1, 0, .7], [0, 1, 0], [.7, 0, 1]])**

**print "R1oR2 => Max-Min :\n" + str(maxMin(r1, r2)) + "\n"**

**print "R1oR2 => Max-Product :\n" + str(maxProduct(r1, r2)) + "\n\n"**

**print "R1oR3 => Max-Min :\n" + str(maxMin(r1, r3)) + "\n"**

**print "R1oR3 => Max-Product :\n" + str(maxProduct(r1, r3)) + "\n\n"**

**print "R1oR2oR3 => Max-Min :\n" + str(maxMin(r1, maxMin(r2, r3))) + "\n"**

**print "R1oR2oR3 => Max-Product :\n" + str(maxProduct(r1, maxProduct(r2, r3))) + "\n\n"**

```
R1oR2 => Max-Min :
[[ 0.6  0.6  0. ]
 [ 0.3  0.3  0.1]
 [ 0.   0.5  0.1]]

R1oR2 => Max-Product :
[[ 0.6  0.6  0. ]
 [ 0.18 0.18 0.02]
 [ 0.   0.3  0.05]]

R1oR3 => Max-Min :
[[ 1.   0.   0.7]
 [ 0.3  0.2  0.3]
 [ 0.7  0.5  1.  ]]

R1oR3 => Max-Product :
[[ 1.   0.   0.7 ]
 [ 0.3  0.2  0.21]
 [ 0.7  0.5  1.  ]]

R1oR2oR3 => Max-Min :
[[ 0.6  0.6  0.6]
 [ 0.3  0.3  0.3]
 [ 0.1  0.5  0.1]]

R1oR2oR3 => Max-Product :
[[ 0.6  0.6  0.42 ]
 [ 0.18 0.18 0.126]
 [ 0.035 0.3  0.05  ]]
```

## Experiment 8 - Method Of Defuzzification

Program -

pip install -U scikit-fuzzy

```
import numpy as np
```

```
import matplotlib.pyplot as plt
```

```
import skfuzzy as fuzz
```

```
# Generate trapezoidal membership function on range [0, 1]
```

```
x = np.arange(0, 5.05, 0.1)
```

```
mfx = fuzz.trapmf(x, [2, 2.5, 3, 4.5])
```

```
# Defuzzify this membership function five ways
```

```
defuzz_centroid = fuzz.defuzz(x, mfx, 'centroid') # Same as skfuzzy.centroid
```

```
defuzz_bisector = fuzz.defuzz(x, mfx, 'bisector')
```

```
defuzz_mom = fuzz.defuzz(x, mfx, 'mom')
```

```
defuzz_som = fuzz.defuzz(x, mfx, 'som')
```

```
defuzz_lom = fuzz.defuzz(x, mfx, 'lom')
```

```
# Collect info for vertical lines
```

```
labels = ['centroid', 'bisector', 'mean of maximum', 'min of maximum',  
          'max of maximum']
```

```
xvals = [defuzz_centroid,  
          defuzz_bisector,  
          defuzz_mom,  
          defuzz_som,  
          defuzz_lom]
```

```
colors = ['r', 'b', 'g', 'c', 'm']
```

```
ymax = [fuzz.interp_membership(x, mfx, i) for i in xvals]
```

```
# Display and compare defuzzification results against membership function
```

```
plt.figure(figsize=(8, 5))
```

```
plt.plot(x, mfx, 'k')
```

```
for xv, y, label, color in zip(xvals, ymax, labels, colors):
```

```
    plt.vlines(xv, 0, y, label=label, color=color)
```

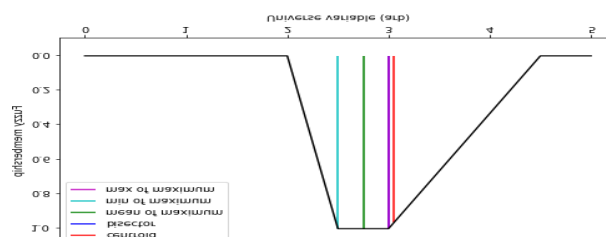
```
plt.ylabel('Fuzzy membership')
```

```
plt.xlabel('Universe variable (arb)')
```

```
plt.ylim(-0.1, 1.1)
```

```
plt.legend(loc=2)
```

```
plt.show()
```





## Experiment 9: Program for complete Genetic Algorithm Cycle

```
from random import randint
import random as rn

class Sample:
    def __init__(self,s,score):
        self.s = s
        self.score = score

class GeneticEvolution:
    def __init__(self,s):
        self.s = s
        #97 122
        self.population = []
        self.mutation_rate = 0.1
        for i in range(100):
            sample = ''
            for i in range(len(s)):
                sample+= chr(int(randint(97,122)))
            self.population.append(Sample(sample,self.fitness(sample)))
        def fitness(self,sample):
            score=0
            for i,j in zip(list(sample),list(self.s)):
                if i==j:
                    score+=1
            return score
        def selection(self):
            new_population = []
            self.population.sort(key = lambda x: x.score,reverse=True)
            new_population = self.population[:40]
            r_sample = rn.sample(self.population[40:],10)
            for i in r_sample:
                new_population.append(i)
            self.population = new_population
        def crossover(self):
            for i in range(100-len(self.population)):
```

```

        parents = rn.sample(self.population,2)
child = ''
for i,j in zip(list(parents[0].s),list(parents[1].s)):
    if rn.random()<0.5:
        child+=i
    else:
        child+=j
self.population.append(Sample(child,self.fitness(child)))
def mutation(self):
    new_population = []
for sample in self.population:
    mutated = ''
    for i in sample.s:
        if rn.random()<self.mutation_rate:
            mutated += chr(int(randint(97,122)))
        else:
            mutated += i
    new_population.append(Sample(mutated,self.fitness(mutated)))
self.population = new_population
def evolution(self):
    generation = 0
    while True:
        generation+=1
        print(generation)
        self.selection()
        #condition
        if self.population[0].score==self.fitness(self.s):
            print(self.population[0].s,self.population[0].score)
            return self.population[0]
        self.crossover()
        self.mutation()
        if generation>1000:
            return None
g = GeneticEvolution('hel')

```

```
g.evolution()
def brute_force(s):
    count = 0
    while True:
        e = ""
        for i in range(len(s)):
            e+=chr(int(randint(97,122)))
        if e==s:
            return count
        print(e)
        if count>10000:
            return -1
        count+=1
```

**OUTPUT:**

1  
2  
3  
4

**Experiment 10 - Write a program in MATLAB to implement De-Morgan's Law.**

**De-Morgan's Law  $c(i(u,v)) = \max(c(u),c(v))$**

**$c(u(u,v)) = \min(c(u),c(v))$**

**%Enter Data**

**u=input('Enter First Matrix');**

**v=input('Enter Second Matrix');**

**%To Perform Operations**

**w=max(u,v);**

**p=min(u,v);**

**q1=1-u;**

**q2=1-v;**

**x1=1-w;**

**x2=min(q1,q2);**

**y1=1-p;**

**y2=max(q1,q2);**

**%Display Output**

**display('Union Of Two Matrices');**

**display(w);**

**display('Intersection Of Two Matrices');**

**display(p);**

**display('Complement Of First Matrix');**

**display(q1);**

**display('Complement Of Second Matrix');**

**display(q2);**

**display('De-Morgans Law');**

**display('LHS');**

**display(x1);**

**display('RHS');**

**display(x2);**

**display('LHS1');**

**display(y1);**

**display('RHS1');**

**display(y2);**

**Output:-**

**Enter First Matrix [0.3 0.4]**

**Enter Second Matrix [0.2 0.5]**

**Union Of Two Matrices**

**w =0.3000 0.5000**

**Intersection Of Two Matrices**

**p =0.2000 0.4000**

**Complement Of First Matrix**

**q1 =0.7000 0.6000**

**Complement Of Second Matrix**

**q2 =0.8000 0.5000**

**De-Morgans Law**

**LHS**

**x1 = 0.7000 0.5000**

**RHS**

**x2 = 0.7000 0.5000**

**LHS1**

**y1 =0.8000 0.6000**

**RHS1**

**y2 = 0.8000 0.6000**