
Installation

1. Installing PyNN:
\$ pip install pyNN
Or follow the instructions in
http://neuralensemble.org/docs/PyNN/installation.html
2. Compile and install PyCARL
2.1 Clone the PyCARL repository to the CARLsim root.
\$ cd CARLsim4/
\$ git clone https://github.com/adarshabalaji/PyCarlsim.git
2.2 Compile and generate the pyNN -> carlsim interface file (carlsim.py)
2.2.1 Install SWIG:
\$ sudo apt update
\$ sudo apt install swig
2.2.2 Compile and link the interface file (carlsim_wrap.cxx), generated by swig, with the libcarlsim.a library.
\$ cd source
\$ source build.sh
This creates a static library _carlsim.so and a pyNN -> CARLsim interface (carlsim.py)

OPTIONAL If you want to compile and link the interface file manually, then
3. 1 Compile the carlsim.i (interface file) using SWIG
\$ cd source
\$ swig -c++ -python carlsim.i
The output of the swig build is a wrapper file (carlsim_wrap.cxx) and the pyNN -> carlsim interface file (carlsim.py).
3. 2 In the source folder, follow the steps below to compile a new pyNN interface (carlsim.i and carlsim_wrap.cxx) with the static library libcarsim.a (generated during a CARLsim build).
\$gcc -fPIC -c carlsim_wrap.cxx -I/usr/include/python <version></version> -I <carlsim4 dir="" include=""> -I/usr/local/cuda/include -I/usr/local/cuda/samples/common/inc -DNO_CUDA</carlsim4>
Update the above command with the python version of choice and the CARLsim4 installation directory.
3.1 Link the carlsim_wrap.o file to the libcarlsim.a file.
\$ g++ -shared carlsim_wrap.o -o _carlsim.so
\$ g++ -shared ~/CARL/lib/libcarlsim.a carlsim_wrap.o -o _carlsim.so
4. Copy the compiled sources and the carlsim/ folder in the pyCARL repo to pyNN.
\$ cp -r CARLsim4/pyCARL/carlsim <root installation="" of="" pynn=""></root>
4.1 Copy the generated _carlsim.so and carlsim.py file to <root installation="" of="" pynn="">/carlsim</root>
PyCARL is now integrated with pyNN.
#######################################
List of APIs implemented.

Define the cell type for all the input groups

inputCellType = sim.SpikeSourceArray("input", <numNeurons>, "EXCITATORY_NEURON", "CUBA")

create a population of <numNeurons> neurons of cellType inputCellType.

spike_source = sim.Population(<numNeurons>, inputCellType, label='input')

pyCARL only supports Izhikevich neurons

Define the inzhikevich cell type for the group

izhikevichCellType = sim.Izhikevich("EXCITATORY_NEURON", α=0.02, b=0.2, c=-65, d=8)

create a pyNN population of <numNeurons> neurons of cellType izhikevichCellType qExc = sim.Population(<numNeurons>, izhikevichCellType, label='Exc') 3. Setup Network An equivalent for this function does not exist for pyNN. Therefore the user will have to call this CARLsim function directly in pyNN. #sim.state.setupNetwork() 4. Run Network Input - rumtime in Ms sim.run(<time in Ms>) 5. STDPMechanism for a group Input - rumtime in Ms # define the properties of the STDP synapse. stdp model = sim.STDPMechanism(timing dependence=sim.SpikePairRule(tau_plus=20.0, tau_minus=20.0, A_plus=0.01, A minus=0.012), weight dependence=sim.AdditiveWeightDependence(w min=0, w max=0.0000001), weight=0.00000005, delay=delay, dendritic delay fraction=float(options.dendritic delay fraction))

connect the groups G1 and G2 using an all-to-all connector, with stdp enabled synapses.

connections = sim.Projection(G1, G2, sim.AllToAllConnector(), stdp_model)

Connect function

 $\label{thm:connector: full, "FixedProbabilityConnector": "random", "FromListConnector": "FromListConnector": "FromListConnector") \\$

PyCARL only supports 'full', 'one-to-one' and 'random' connectors

The corresponding

connectionID = sim.Projection(spike_source, neuron_group1, sim.OneToOneConnector(), synapse_type, receptor_type='excitatory')