Machine Learning-Theory and Practice

- 1. LECTURE 1: BAYESIAN LEARNING BASIC CONCEPTS
- 2. LECTURE 2: NAÏVE BAYES CLASSIFIER
- 3. LECTURE 3: BAYESIAN NETWORKS

Lecture 1:

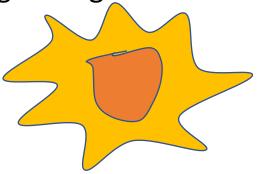
Bayesian Learning - Basic Concepts

Different Styles of Learning

- Discriminative
- Generative

Lion or Tiger? Discriminative style

Distinguishing feature: A male lion has a mane while a tiger does not have a mane



P(Male lion | Mane) >> P(Male tiger | Mane)

Distinguishing feature: A tiger has striped skin while a lion does not



Discriminative Style for learning

- Discriminative Style: Identify on the basis of distinguishing features
 - If you see an animal with mane it is mostly lion, not tiger.

 P(Lion|Mane) is high, P(Tiger|Mane) is low
 - If you see an animal with stripes, it is most probably tiger P(Tiger|Stripes) is high, P(Lion|Stripes) is low
- In general, form of P(y|X) is known, and Model fitting is carried out on historical data. Example:
 - 1. Logistic Regression assumes the form: $P(y|x) = 1/(1+e^{-w.x})$
 - 2. Estimates w-parameters by maximizing Likelihood.
 - 3. For new data the trained classifier calculates **y/X** using this relationship

Generative Style of learning – Given a Class, get general idea about its features





Generative Style of Learning

- Generally, tigers have stripes, golden yellow skin colour, are longer
- Generally, male lions have a mane, light brown skin colour, are shorted
- Probability of a set of features X, given a Class y:
 - P(stripes, golden yellow skin, long | tiger)
 - P(mane, dull brown skin, short | male lion)
- Learn P(X|y) from historical data, then find P(y|X) for new data by using Bayes Rule

Revision of basic Laws of Probability

1. Rule of Addition/Union	$P(A \cup B) = P(A) + P(B) -$
	P(A∩B)

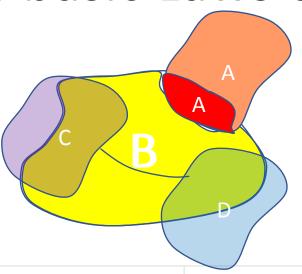
2. Rule of Product/Intersection:

Dependent Events
$$P(A \cap B) = P(A|B) P(B)$$

= $P(B|A).P(A)$

Independent Events
$$P(A \cap B) = P(A)$$
 $P(B)$

Revision of basic Laws of Probability



3. Conditional Probability:

$$P(A | B) = P(A \cap B) / P(B)$$

 $P(B|A) = P(A \cap B) / P(A)$

4. Total Probability $P(B) = \sum_{i} P(B \cap A_{i}) = \sum_{i} P(B \mid A_{i}) P(A_{i})$.

Revision of basic Laws of Probability

Bayes Formula

Consider:

A to be hypothesis or possible outcome h

B to be attributes or evidences gathered from Data D So:

$$P(h|D) = \frac{P(D|h)}{P(D)}P(h)$$

Bayesian Training: Learn Priors and Likelihood

- PRIOR PROBABILITIES P(h): These are overall probabilities of possible outcomes / hypothesis in nature:
 - $P(h|D) = \frac{P(D|h)}{P(D)} P(h)$ • P(Cancer) = .008 P(Not Cancer) = 0.992
- LIKELIHOODS P(D|h): These are conditional probabilities of evidences (Data) given an outcome / hypothesis exists:
 - P(Lab test is + | Cancer) = 0.98

 - P(Lab test is + | Not Cancer) = 0.03 $P(h|D) = \frac{P(D|h)}{P(D)}P(h)$
 - P(Lab test is -ve | Cancer) = 0.02
 - P(Lab test is –ve | Not Cancer)= 0.97
- Priors and Likelihoods are calculated from historical data

Evaluate Aposterior Probabilities

- APOSTERIORI P(h|D): Probability of hypothesis given evidence
- P(D): Total probability A normalization factor: $P(D) = \sum_{h \in H} P(h \mid D)$
- BAYESIAN LEARNING predicts the possibility of each hypothesis, given some evidence D:

$$\forall h \in H: \mathbf{P}(\mathbf{h}|\mathbf{D}) = \frac{P(D|h)}{P(D)}P(h)$$

• Posterior probability = $\frac{Likelihood}{Total\ Probability} \times Prior$

Maximum A-Posteriori MAP

 BAYESIAN LEARNING predicts the possibility of each hypothesis, given some evidence D:

$$\forall h \in H: P(h|D) = \frac{P(D|h)}{P(D)}P(h)$$

Prediction: Find Maximum APosteriori hypothesis:

$$P(h|D) = Argmax_{h \in H} \{ P(h|D) \}$$

- Note: Denominator remains same for each P(h|D)
- MAP prediction is:

$$Argmax_{h \in H} \{ P(D|h) \times P(h) \}$$

Maximum Likelihood

• If all hypotheses are equiprobable, then Priors are equal:

$$P(h_1) = P(h_2) \dots \dots$$

• Then, we predict Maximum Likelihood ML hypothesis:

$$P(h|D) = Argmax_{h \in H} \{ P(D|h) \}$$

Cancer Case:

- P(Cancer) = .008 P(Not Cancer) = 0.992
 - P(Lab test is + | Cancer) = 0.98
 - P(Lab test is + | Not Cancer) = 0.03
 - P(Lab test is –ve | Cancer) = 0.02
 - P(Lab test is –ve | Not Cancer) = 0.97
- The two hypotheses are not equiprobable. Calculate MAP.
- Given a new patient with +ve test result:
- Prediction: $Argmax\{P(+ve|Cancer\}xP(cancer), P(+ve|Not Cancer\}xP(Not cancer)\}$ = $Argmax\{0.98 \times 0.008, 0.03 \times 0.992\} = Argmax\{0.00784, 0.02976\}$

Not Cancer

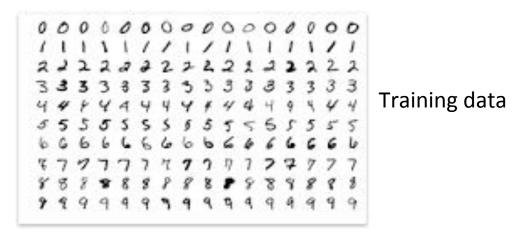
Exact Probabilities

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• { P(Cancer) = 0.98 x 0.008, P(no cancer) 0.03x0.992} = \{.0078, .0298\} Thus P(Cancer|+ve) = \frac{.0078}{.0078+.0298}
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Thus P(No Cancer|+ve) =
$$\frac{.0298}{.0078+.0298}$$

Handling Multiple Features

- So are, we considered a single evidence
- What if we have multiple features?
- Examples: Distinguish between handwritten images 1 and 7



Classify text documents into Science and Arts based on words

Handling Multiple Features

- ◆ Digit Recognition: A set of 128x128 images. Each of 4096 pixels is an individual feature.
- Document Classification: A vocabulary of 10000 words spanning all documents!
- Let $D = \{x_1, x_2, x_3, x_4 \dots \}$

Now, classifier needs to evaluate the Joint probabilities for all combination of features:

$$\forall h \in H \colon P(h|x_1, x_2, x_3, x_4 \dots) = \frac{P(\{x_1, x_2, x_3, x_4 \dots | h\})}{P(D)} P(h)$$

How many joint probabilities are needed to train?