

# Bayesian Machine Learning

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- 1 Main Context
- 2 Reminder: Gaussian Distribution
- 3 Bayesian Probability
- 4 Curve fitting re-visited
- 5 Linear Basis Function Models
- 6 Bayesian Linear Regression

## 1 Main Context

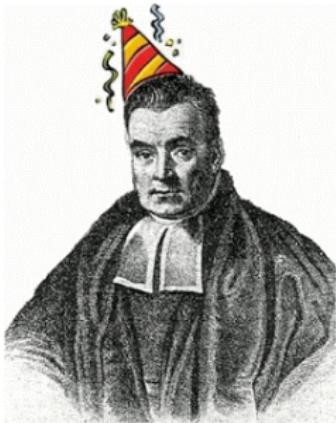
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Thomas Bayes (c. 1701 – 7 April 1761) was an English statistician, philosopher and Presbyterian minister

$$\mathbb{P}(B|A) = \frac{\mathbb{P}(A|B)\mathbb{P}(B)}{\mathbb{P}(A)}$$



**"All things being equal, the simplest solution tends to be the best one."**

**William of Ockham**

William of Ockham (c. 1287 – 1347) was an English Franciscan friar and scholastic philosopher and theologian



## OCCAM'S RAZOR

Sure there are simpler ways to catch that bird,  
but the complicated ones kick ass.

[motifake.com](http://motifake.com)

## Example: Polynomial Curve Fitting

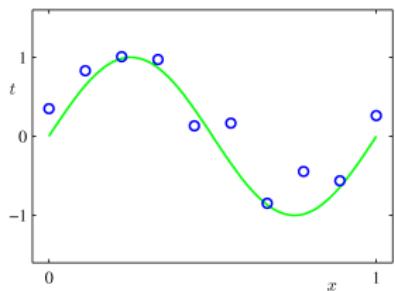


Figure – Plot of a training data

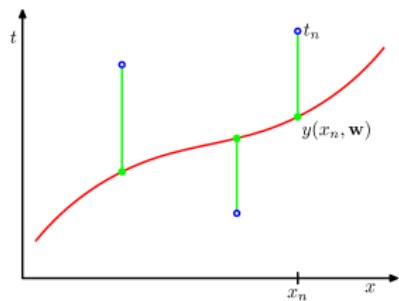


Figure – Residuals

- $\mathcal{D}_m = \{\mathbf{X}_m, \mathbf{Y}_m\} = \{(x_i, y_i)\}_{i=1}^m$ , where  $y_i = \sin(2\pi x_i) + \varepsilon_i$ ,  $\varepsilon_i$  is a Gaussian white noise

## Example: Polynomial Curve Fitting

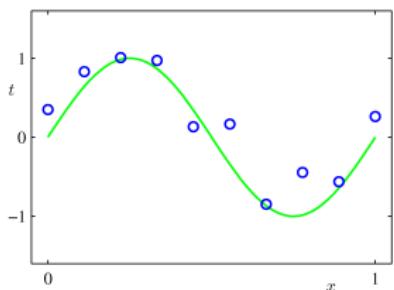


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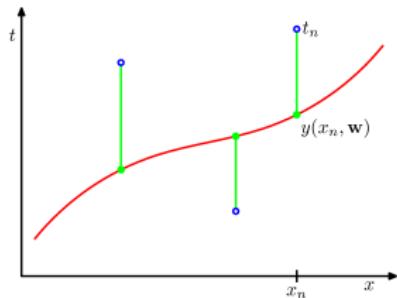


Figure – Residuals

- We fit a model

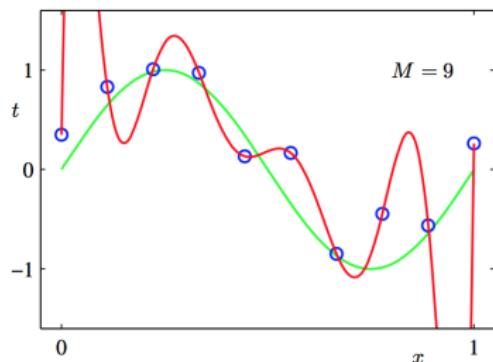
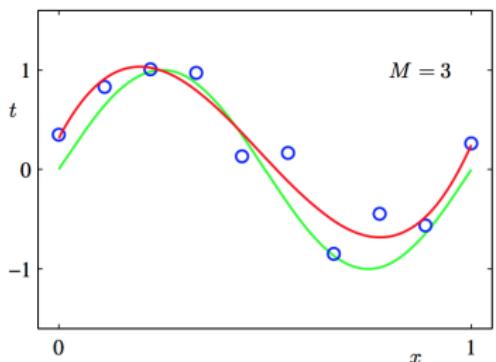
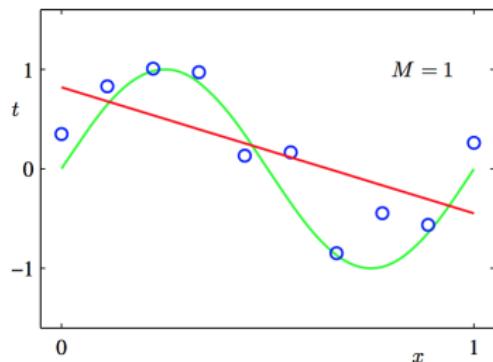
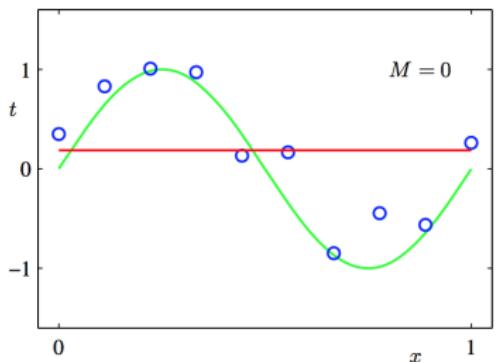
$$f(x, \mathbf{w}) = \sum_{j=0}^M w_j x^j,$$

by minimizing the error

$$E(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^m \{f(x_i, \mathbf{w}) - y_i\}^2$$

# Plots of polynomials having various orders $M$

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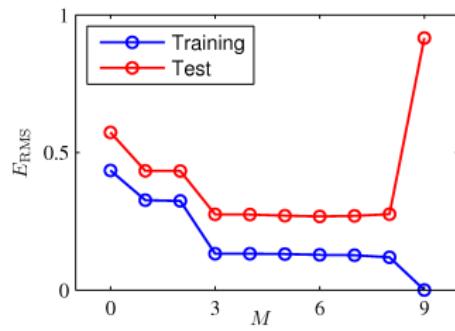


Figure –  $E_{RMS} = \sqrt{2E(\mathbf{w}^*)/n}$

	$M = 0$	$M = 1$	$M = 6$	$M = 9$
$w_0^*$	0.19	0.82	0.31	0.35
$w_1^*$		-1.27	7.99	232.37
$w_2^*$			-25.43	-5321.83
$w_3^*$				17.37
$w_4^*$				48568.31
$w_5^*$				-231639.30
$w_6^*$				640042.26
$w_7^*$				-1061800.52
$w_8^*$				1042400.18
$w_9^*$				-557682.99
				125201.43

Figure – Coefficients  $\mathbf{w}^*$

# Overfitting vs. Sample size

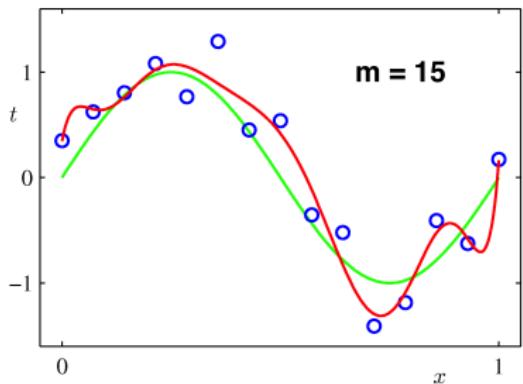


Figure –  $M = 9, m = 15$

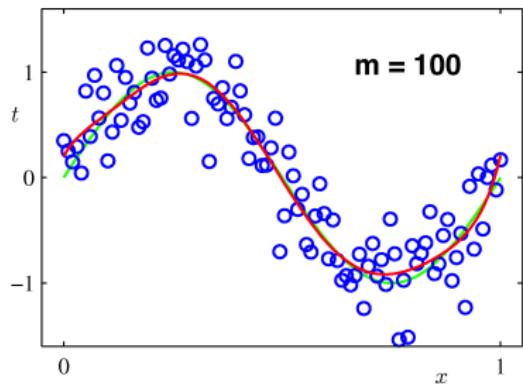


Figure –  $M = 9, m = 100$

- Limit the number of parameters  $M$  w.r.t. the size of the available training set?
- Instead choose the complexity of the model (effective model parameters) according to the complexity of the problem!

$$\tilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^m \{f(x_i, \mathbf{w}) - y_i\}^2 + \frac{\lambda}{2} \|\mathbf{w}\|^2$$

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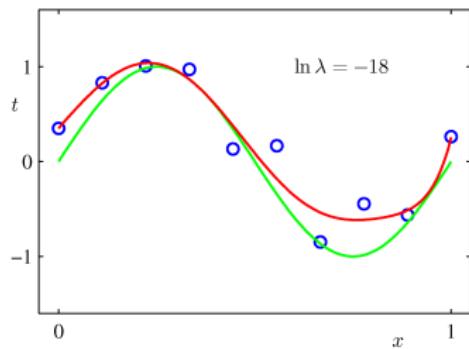


Figure –  $\lambda = e^{-18} \approx 0$

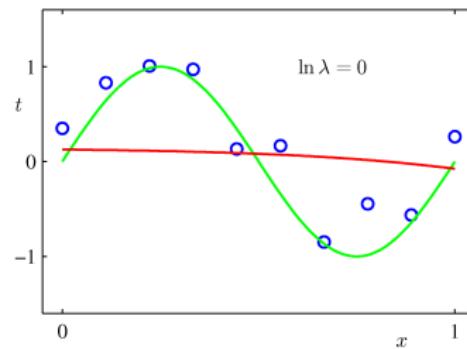


Figure –  $\lambda = 1$

# Overfitting vs. Regularization

	$\ln \lambda = -\infty$	$\ln \lambda = -18$	$\ln \lambda = 0$
$w_0^*$	0.35	0.35	0.13
$w_1^*$	232.37	4.74	-0.05
$w_2^*$	-5321.83	-0.77	-0.06
$w_3^*$	48568.31	-31.97	-0.05
$w_4^*$	-231639.30	-3.89	-0.03
$w_5^*$	640042.26	55.28	-0.02
$w_6^*$	-1061800.52	41.32	-0.01
$w_7^*$	1042400.18	-45.95	-0.00
$w_8^*$	-557682.99	-91.53	0.00
$w_9^*$	125201.43	72.68	0.01

Figure – Dependence of  $w^*$  on  $\lambda$

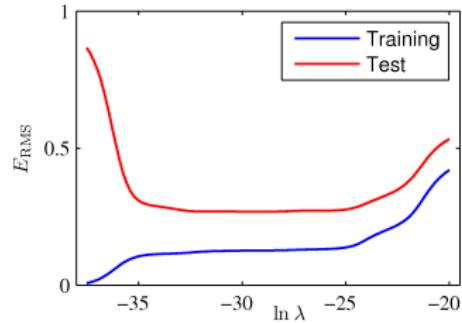


Figure – Dependence of  $E_{RMS}$  on  $\lambda$

- We would have to find a way to determine a suitable value for the model complexity!
- Hold-out set to select a model complexity (either  $M$  or  $\lambda$ )? Too wasteful  $\Rightarrow$  Bayesian Learning!

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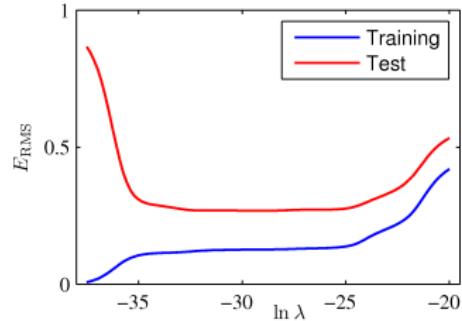


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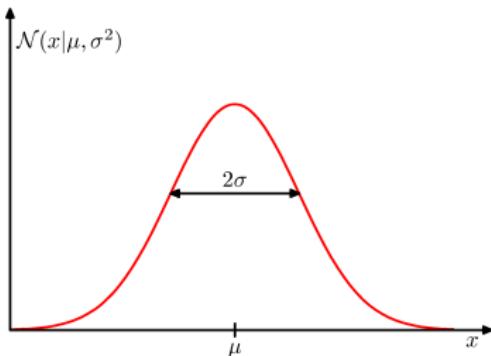
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# 1d Gaussian distribution

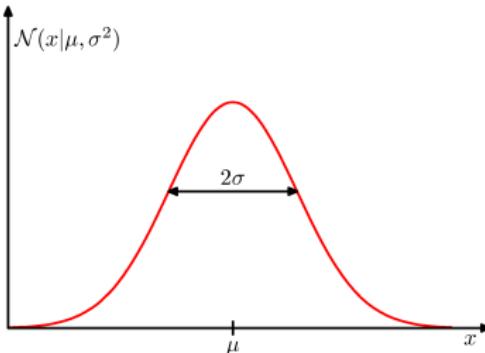


- Gaussian distribution of  $x \in \mathbb{R}^1$  with  $\mathbb{E}[x] = \mu$ ,  $\text{var}[x] = \sigma^2$

$$N(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{1}{2\sigma^2}(x - \mu)^2\right\}$$

- Multivariate Gaussian distribution of  $\mathbf{x} \in \mathbb{R}^d$  with  $\mathbb{E}[\mathbf{x}] = \boldsymbol{\mu}$ ,  $\text{cov}[\mathbf{x}] = \boldsymbol{\Sigma}$

$$N(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{d/2}} \frac{1}{|\boldsymbol{\Sigma}|^{1/2}} \exp\left\{-\frac{1}{2\sigma^2}(\mathbf{x} - \boldsymbol{\mu})^\top \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right\}$$

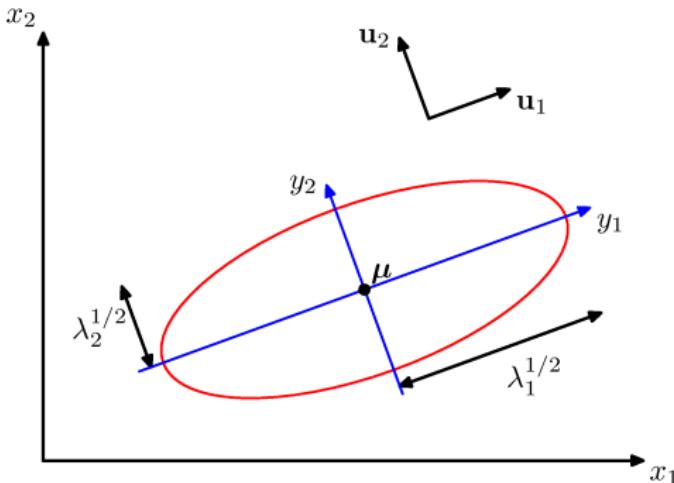


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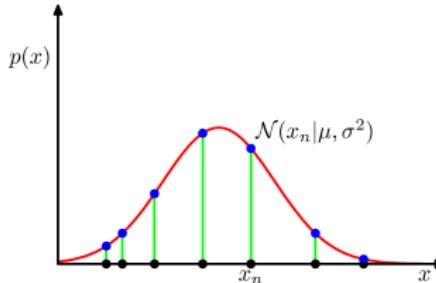
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- The red curve shows the elliptical surface of constant probability density for  $\mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma})$ ,  $d = 2$
- Curve corresponds to the density  $\exp(-1/2)$  of its value at  $\mathbf{x} = \boldsymbol{\mu}$
- The major axes of the ellipse are defined by the eigenvectors  $\mathbf{u}_i$  of the covariance matrix  $\boldsymbol{\Sigma}$ , with eigenvalues  $\lambda_i$



- Likelihood of an i.i.d. Gaussian sample  $\mathbf{X}_m = \{x_1, \dots, x_m\}$

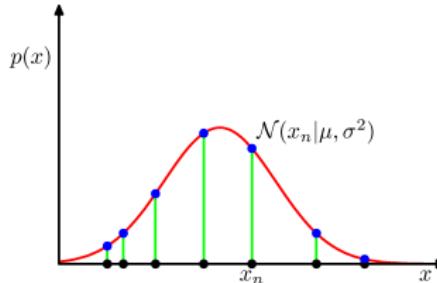
$$p(\mathbf{X}_m | \mu, \sigma^2) = \prod_{i=1}^m \mathcal{N}(x_i | \mu, \sigma^2)$$

- Log-likelihood is equal to

$$\log p(\mathbf{X}_m | \mu, \sigma^2) = -\frac{1}{2\sigma^2} \sum_{i=1}^m (x_i - \mu)^2 - \frac{m}{2} \log \sigma^2 - \frac{m}{2} \log\{2\pi\} \rightarrow \max_{\mu, \sigma^2}$$

- MLE is equal to

$$\mu_{ML} = \frac{1}{m} \sum_{i=1}^m x_i, \quad \sigma_{ML}^2 = \frac{1}{m} \sum_{i=1}^m (x_i - \mu_{ML})^2$$



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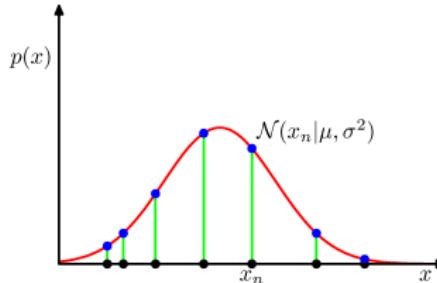
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- Repeatable events  $\Rightarrow$  classical (frequentist) interpretation of probability
- Bayesian view: probabilities provide a quantification of uncertainty
- Consider an uncertain (non-repeatable) event:
  - “whether the Arctic ice cap will have disappeared by the end of the century?”
  - we can generally have some idea how quickly we think the polar ice is melting
  - we obtain fresh data: e.g. from an Earth observation satellite we may revise our opinion on the rate of ice loss
  - we need to quantify our expression of uncertainty and make precise revisions of uncertainty in the light of new data

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- Data model:  $y = f(\mathbf{x}, \mathbf{w}) + \varepsilon$ ,  $\varepsilon$  is a noise
- Quantify uncertainty about model parameters  $\mathbf{w}$ ?
- Prior  $p(\mathbf{w})$  captures our assumptions about  $\mathbf{w}$  before observing the data!

- It is almost impossible to predict random rare events  $\Rightarrow$  their description is very long  $\Rightarrow$  complex
- $\mathbf{w}$  defines “complexity” of the model
- $p(\mathbf{w})$  quantifies this complexity, as “small probability”  $\equiv$  “complex”



Figure – Kolmogorov A.N.  
(1903-1987)

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$$p(\mathbf{w}|\mathcal{D}_m) = \frac{p(\mathcal{D}_m|\mathbf{w})p(\mathbf{w})}{p(\mathcal{D}_m)}$$

- $p(\mathcal{D}_m|\mathbf{w})$  is a likelihood function (how probable the observed data set is for different settings of the parameter vector  $\mathbf{w}$ )
- Normalization constant (evidence)

$$p(\mathcal{D}_m) = \int p(\mathcal{D}_m|\mathbf{w})p(\mathbf{w})d\mathbf{w}$$

- General form:

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- General form:

posterior  $\sim$  likelihood  $\times$  prior

log posterior  $\sim$  log likelihood + log prior

- Observed data  $\mathcal{D}_m = \{\mathbf{X}, \mathbf{y}\} = \{(\mathbf{x}_i, y_i)\}_{i=1}^m$  influences the conditional probability  $p(\mathbf{w}|\mathcal{D}_m)$ :

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— Posterior

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MAP = Maximum a posteriori

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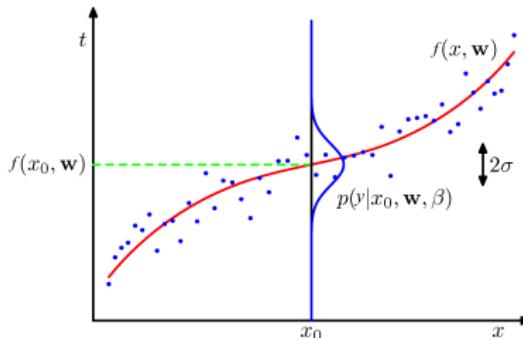
2 Reminder: Gaussian Distribution

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- Sample  $\mathcal{D}_m = \{\mathbf{X}_m, \mathbf{Y}_m\} = \{(\mathbf{x}_i, y_i)\}_{i=1}^m$ ,
$$y_i = f(\mathbf{x}_i, \mathbf{w}) + \varepsilon_i, \text{ with i.i.d. } \varepsilon_i \sim \mathcal{N}(0, \beta^{-1})$$
- Probabilistic model

$$p(y|\mathbf{x}, \mathbf{w}, \beta) = \mathcal{N}(y|f(\mathbf{x}, \mathbf{w}), \beta^{-1}),$$

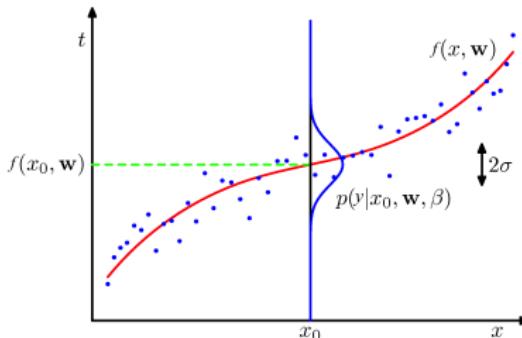
where

— the mean is given by a polynomial  $f(\mathbf{x}, \mathbf{w})$

— the noise precision is given by the parameter  $\beta^{-1} = \sigma^2$

- Likelihood

$$p(\mathbf{Y}_m | \mathbf{X}_m, \mathbf{w}, \beta) = \prod_{i=1}^m \mathcal{N}(y_i | f(\mathbf{x}_i, \mathbf{w}), \beta^{-1})$$



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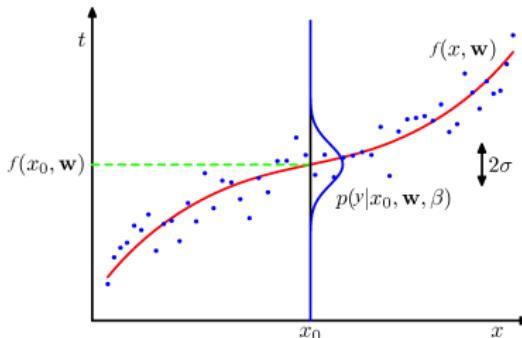
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- MLE of  $\beta$

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$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \left[ \frac{\beta}{2} \sum_{i=1}^n (f(\mathbf{x}_i, \mathbf{w}) - y_i)^2 + \frac{\alpha}{2} \mathbf{w} \cdot \mathbf{w}^\top \right]$$

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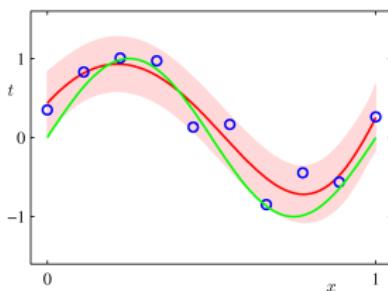


Figure – The predictive distribution for a polynomial with  $M = 9$ , parameters  $\alpha = 5 \times 10^{-3}$  and  $\beta = 11.1$  (known noise variance) are fixed

1 Main Context

2 Reminder: Gaussian Distribution

3 Bayesian Probability

4 Curve fitting re-visited

5 Linear Basis Function Models

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- Linear Basis Function Models

$$f(\mathbf{x}, \mathbf{w}) = w_0 + \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}) = \mathbf{w} \cdot \boldsymbol{\phi}(\mathbf{x})^\top$$

where  $\phi_j(\mathbf{x})$  are known basis functions

- Typical basis functions

$$\phi_j(\mathbf{x}) = x_{j_1}^{j_0}, \phi_j(\mathbf{x}) = \exp\left\{-\frac{\|\mathbf{x} - \boldsymbol{\mu}_j\|^2}{2s^2}\right\},$$

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- Optimizing log-likelihood:

$$\mathbf{w}_{ML} = (\boldsymbol{\Phi}^\top \boldsymbol{\Phi})^{-1} \boldsymbol{\Phi}^\top \mathbf{Y}_m, \quad \boldsymbol{\Phi} = \{(\phi_i(\mathbf{x}_j))_{j=0}^{M-1}\}_{i=1}^m$$

$$\frac{1}{\beta_{ML}} = \frac{1}{m} \sum_{i=1}^m \{y_i - \mathbf{w}_{ML} \cdot \phi(\mathbf{x}_i)^\top\}^2$$

- Regularized Least Squares

$$E_D(\mathbf{w}) + \lambda E_W(\mathbf{w}) \rightarrow \min_{\mathbf{w}}$$

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$$p(\mathcal{D}_m | \mathbf{w}) = \prod_{i=1}^m \mathcal{N}(y_i | \mathbf{w} \cdot \phi(\mathbf{x}_i)^\top, \beta^{-1})$$

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$$p(\mathbf{y} | \mathbf{z}) = \mathcal{N}(\mathbf{y} | \mathbf{A}\mathbf{z}, \mathbf{L}^{-1}),$$

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# Sequential Bayesian Learning

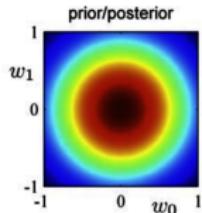
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likelihood

The Model  $f(x, \mathbf{w}) = w_0 + w_1x$

# Sequential Bayesian Learning

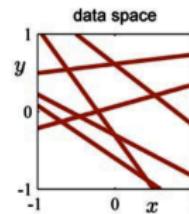
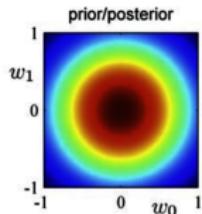
likelihood



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# Sequential Bayesian Learning

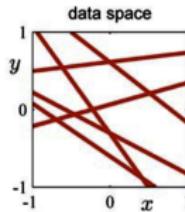
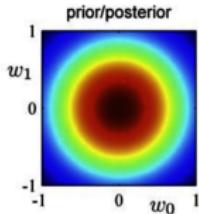
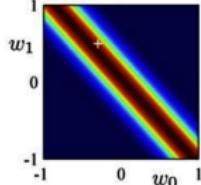
likelihood



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# Sequential Bayesian Learning

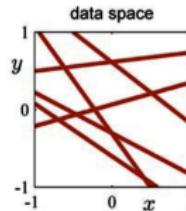
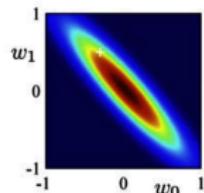
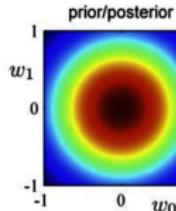
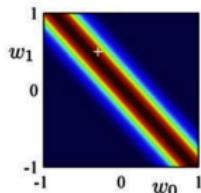
likelihood



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# Sequential Bayesian Learning

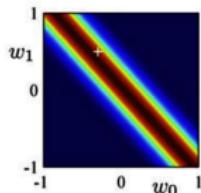
likelihood



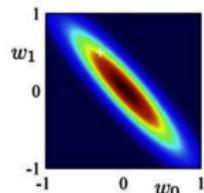
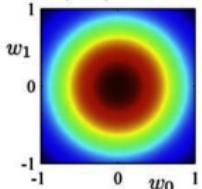
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# Sequential Bayesian Learning

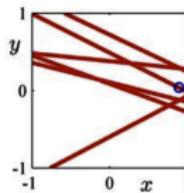
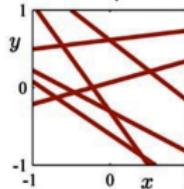
likelihood



prior/posterior



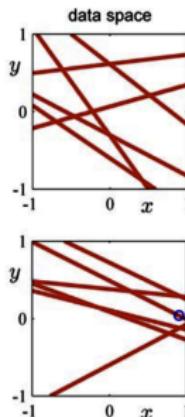
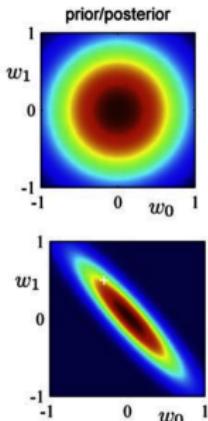
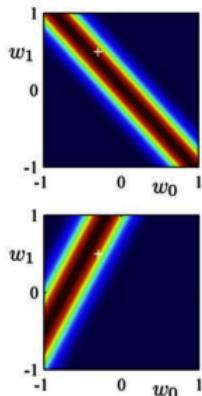
data space



The Model  $f(x, \mathbf{w}) = w_0 + w_1 x$

# Sequential Bayesian Learning

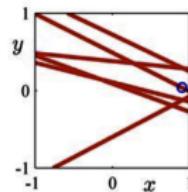
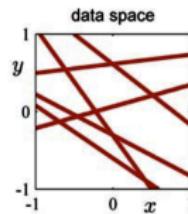
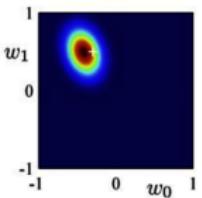
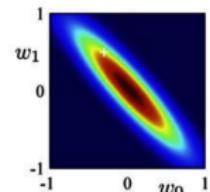
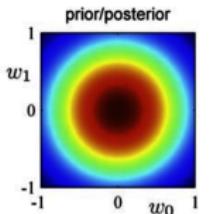
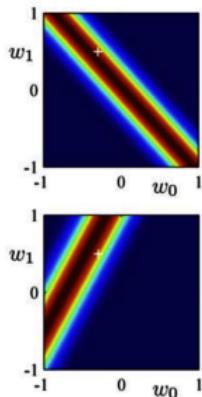
likelihood



The Model  $f(x, \mathbf{w}) = w_0 + w_1 x$

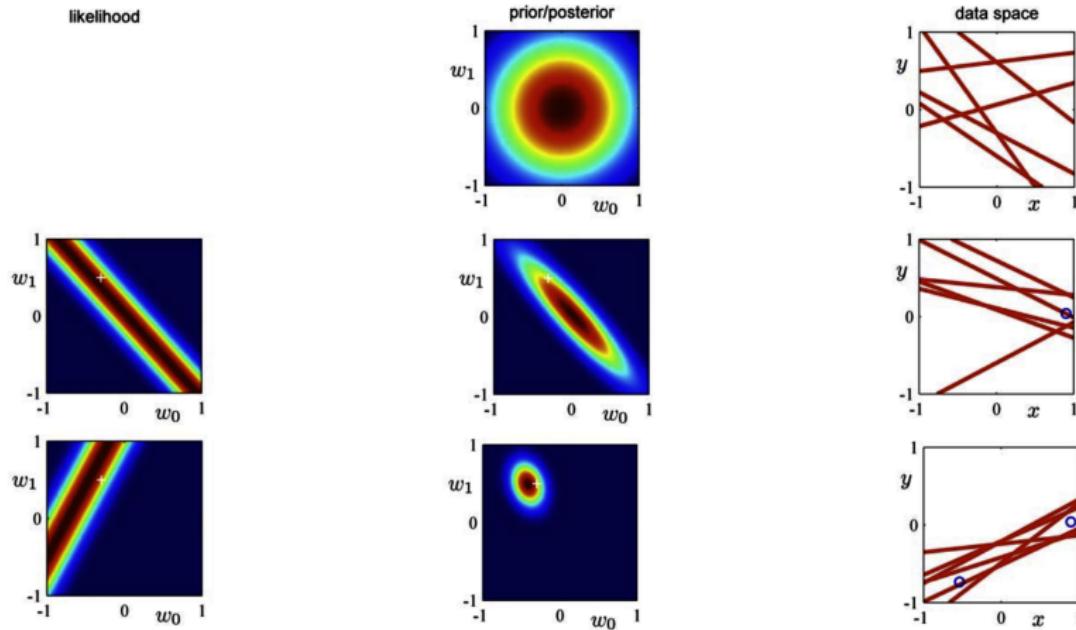
# Sequential Bayesian Learning

likelihood



The Model  $f(x, \mathbf{w}) = w_0 + w_1 x$

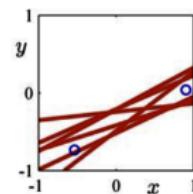
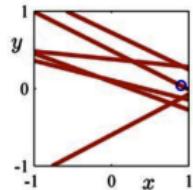
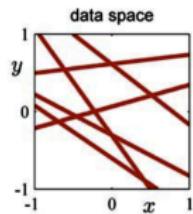
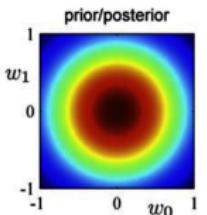
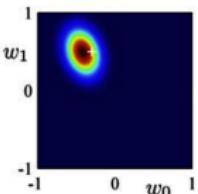
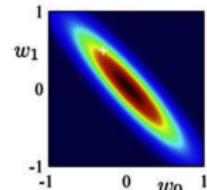
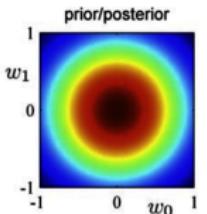
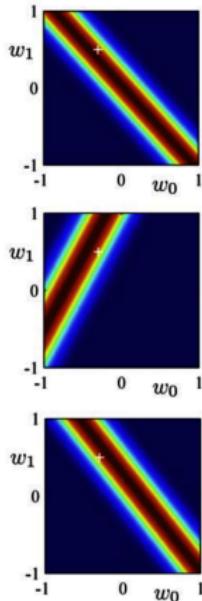
# Sequential Bayesian Learning



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# Sequential Bayesian Learning

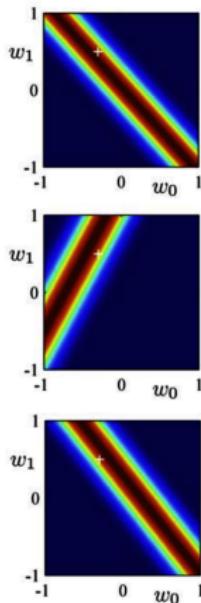
likelihood



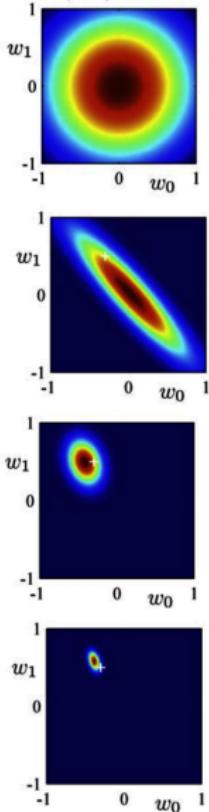
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# Sequential Bayesian Learning

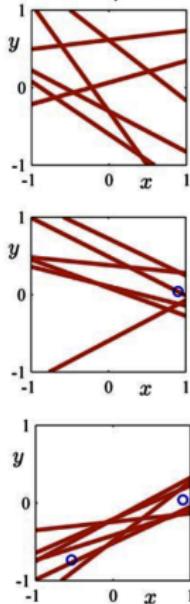
likelihood



prior/posterior



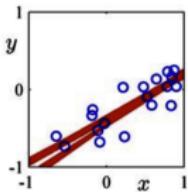
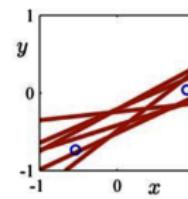
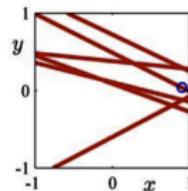
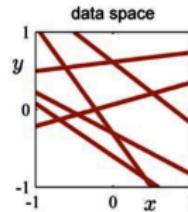
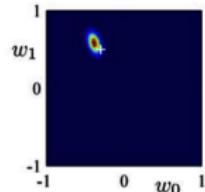
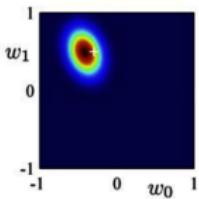
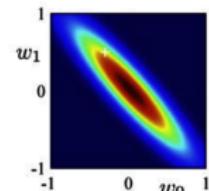
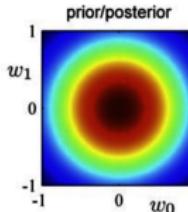
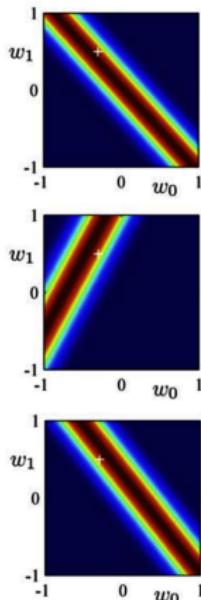
data space



The Model  $f(x, \mathbf{w}) = w_0 + w_1 x$

# Sequential Bayesian Learning

likelihood



The Model  $f(x, \mathbf{w}) = w_0 + w_1 x$

- Make prediction of  $y$  for new value of  $\mathbf{x}$ :

$$p(y|\mathbf{x}, \mathcal{D}_m, \alpha, \beta) = \int p(y|\mathbf{x}, \mathbf{w}, \beta)p(\mathbf{w}|\mathcal{D}_m, \alpha, \beta)d\mathbf{w}$$

- Actually, posterior of  $\mathbf{w}$  is  $p(\mathbf{w}|\mathcal{D}_m) = \mathcal{N}(\mathbf{w}|\boldsymbol{\omega}_m, \mathbf{S}_m)$  with
  - $\mathbf{S}_m = (\alpha^{-1}\mathbf{I} + \beta\boldsymbol{\Phi}^\top\boldsymbol{\Phi})^{-1}$  — posterior covariance of  $\mathbf{w}$
  - $\boldsymbol{\omega}_m = \beta\mathbf{S}_m\boldsymbol{\Phi}^\top\mathbf{Y}_m$  — posterior mean of  $\mathbf{w}$
- Since  $p(y|\mathbf{x}, \mathbf{w}, \beta) = \mathcal{N}(y|f(\mathbf{x}, \mathbf{w}), \beta^{-1})$  and the posterior  $p(\mathbf{w}|\mathcal{D}_m, \alpha, \beta)$  is Gaussian, then

$$p(y|\mathbf{x}, \mathcal{D}_m, \alpha, \beta) = \mathcal{N}(y|\boldsymbol{\omega}_m \cdot \phi(\mathbf{x})^\top, \sigma_m^2(\mathbf{x}))$$

Here

- We can use posterior mean for point prediction

$$\hat{f}(\mathbf{x}, \mathbf{w}) = \boldsymbol{\omega}_m \cdot \phi(\mathbf{x})^\top$$

and posterior variance  $\sigma_m^2(\mathbf{x})$  for its uncertainty estimate

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Here

- We can use posterior mean for point prediction

$$\hat{f}(\mathbf{x}, \mathbf{w}) = \boldsymbol{\omega}_m \cdot \phi(\mathbf{x})^\top$$

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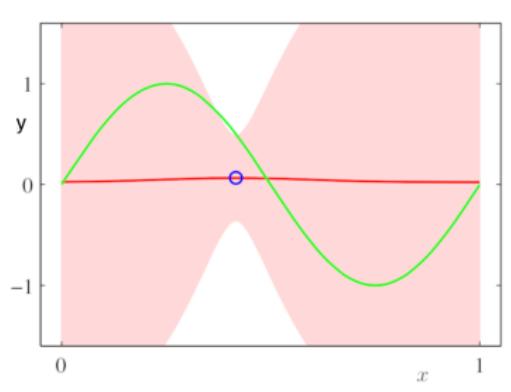
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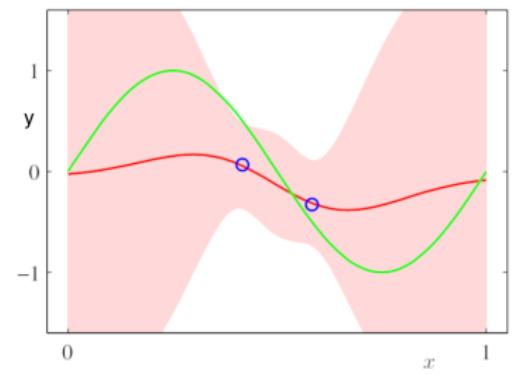
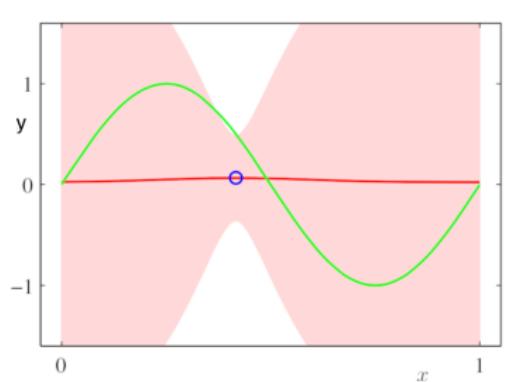
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# Predictive Distribution



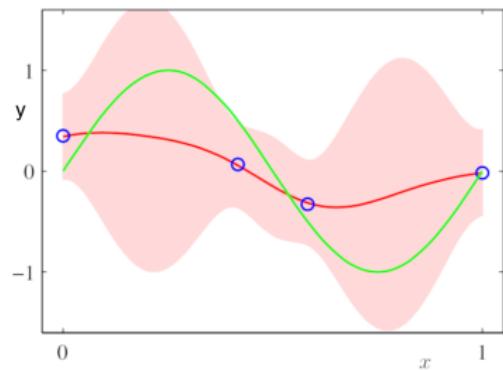
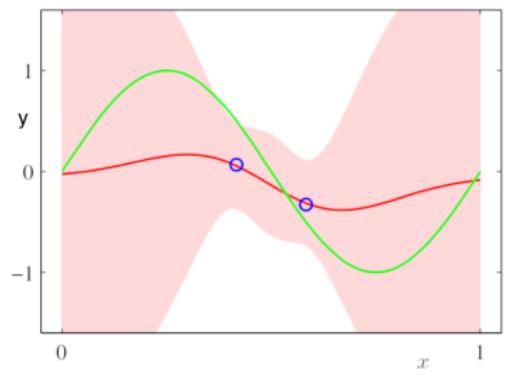
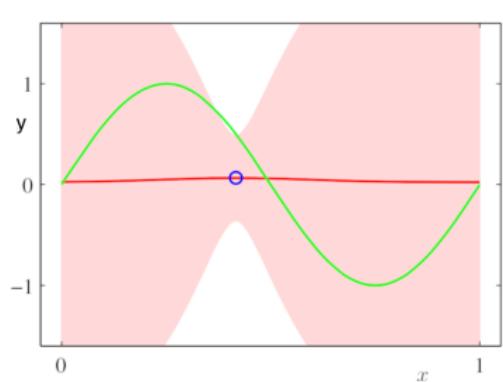
$M = 9$  Gaussian basis functions were used as  $\phi(\mathbf{x})$

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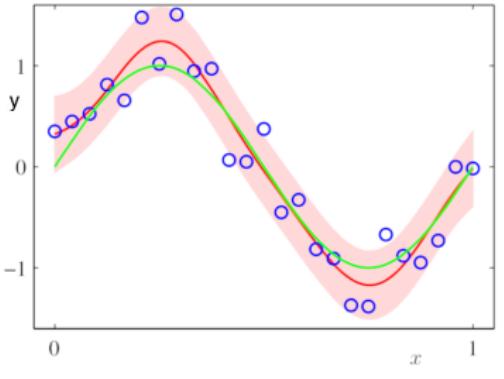
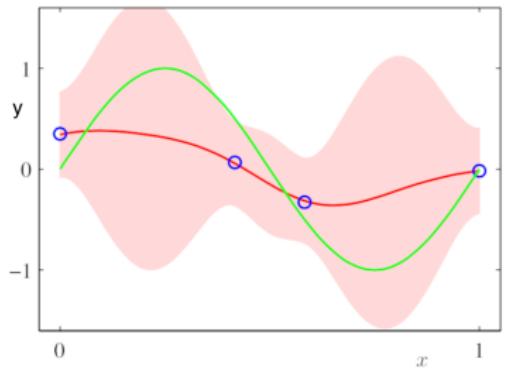
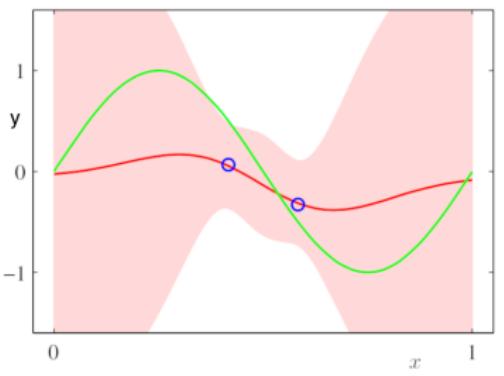
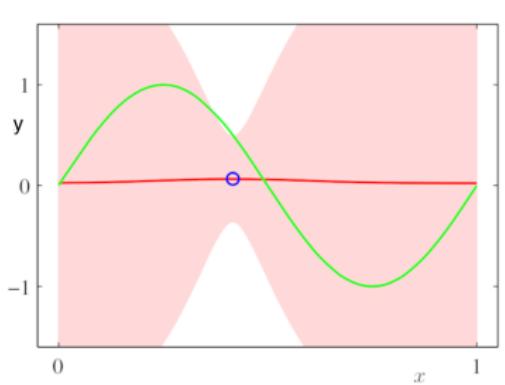
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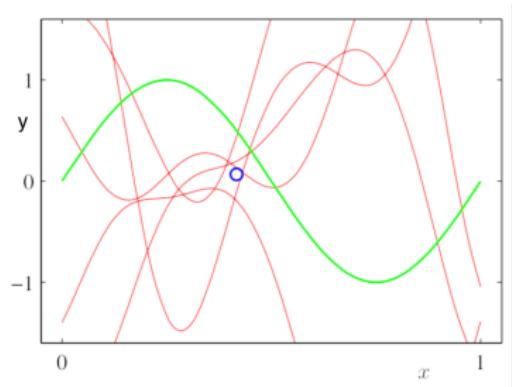
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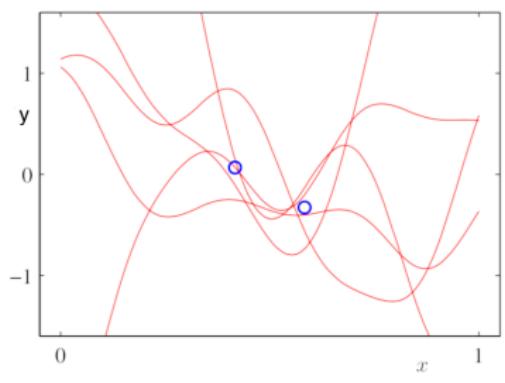
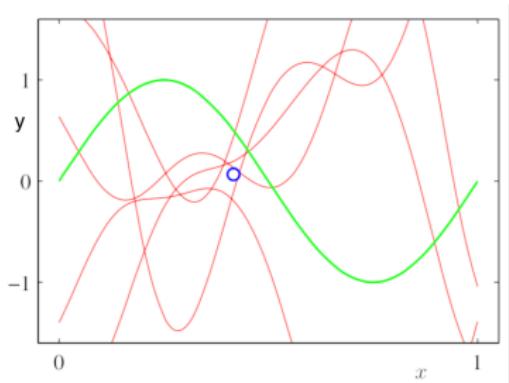
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## Samples from the Predictive Distribution



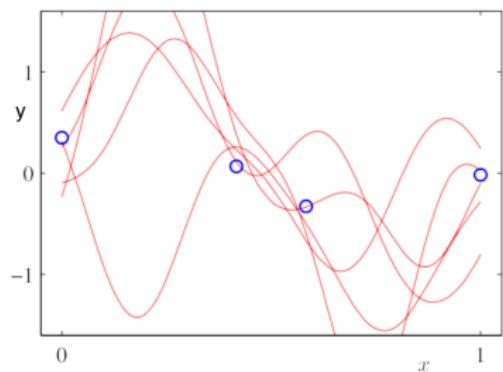
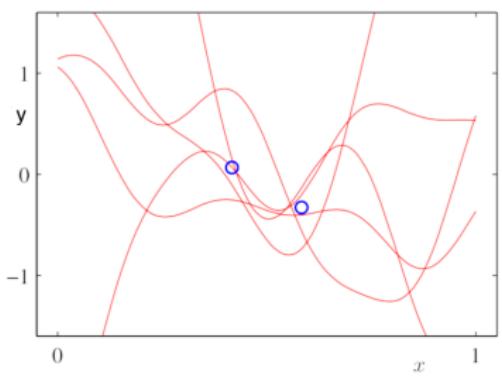
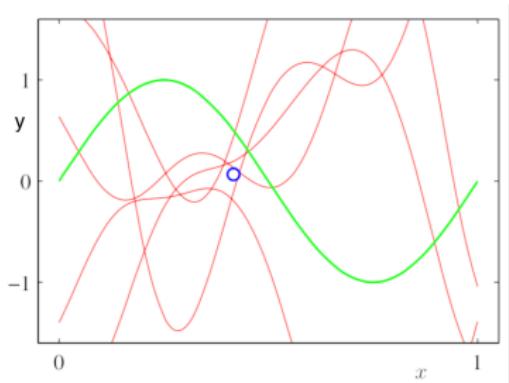
Plots of  $f(x, w)$  using samples from the posterior distributions over  $w \sim p(w|\mathcal{D}_m, \alpha, \beta)$  for some  $\alpha$  and  $\beta$

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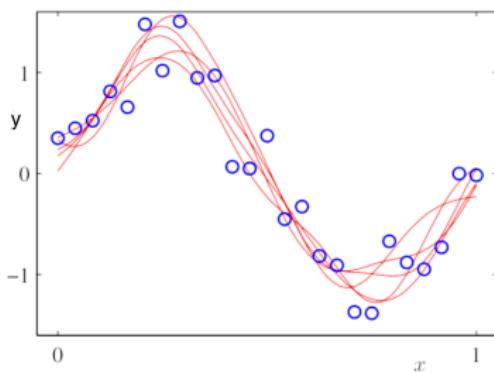
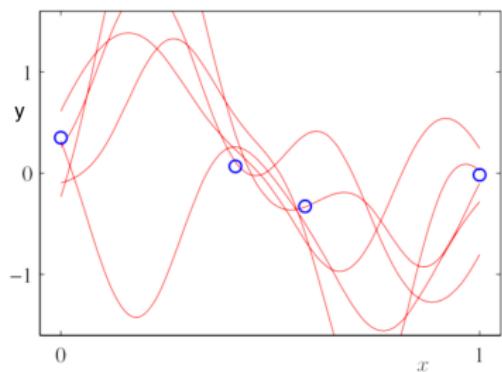
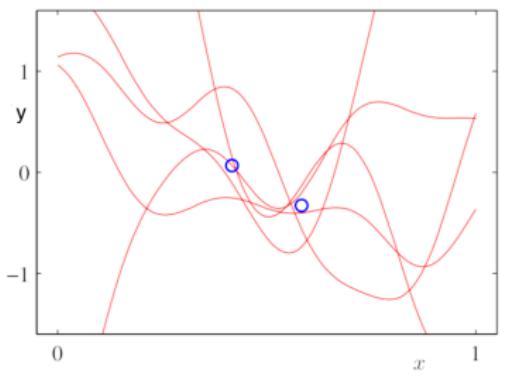
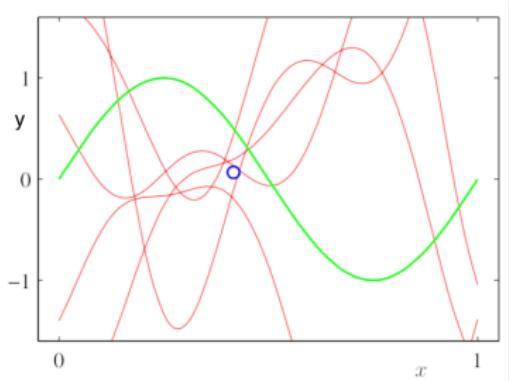
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- We assume that the posterior distribution  $p(\alpha, \beta|\mathcal{D}_m)$  is sharply peaked around values  $\hat{\alpha}$  and  $\hat{\beta}$
- Then we simply marginalize over  $\mathbf{w}$ , where  $\alpha$  and  $\beta$  are fixed to the values  $\hat{\alpha}$  and  $\hat{\beta}$ , so that

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$$p(\alpha, \beta | \mathcal{D}_m) \sim p(\mathcal{D}_m | \alpha, \beta) \cdot p(\alpha, \beta)$$

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$$(\hat{\alpha}, \hat{\beta}) = \arg \max_{\alpha, \beta} p(\mathcal{D}_m | \alpha, \beta)$$

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- Let us denote by  $E(\mathbf{w})$  the sum of the fit and the regularization on coefficients  $\mathbf{w}$

$$E(\mathbf{w}) = \beta E_D(\beta) + \alpha E_W(\mathbf{w}) = \frac{\beta}{2} \|\mathbf{Y}_m - \Phi \cdot \mathbf{w}^\top\|^2 + \frac{\alpha}{2} \mathbf{w} \cdot \mathbf{w}^\top$$

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$$p(\mathcal{D}_m | \alpha, \beta) = \left( \frac{\beta}{2\pi} \right)^{m/2} \left( \frac{\alpha}{2\pi} \right)^{M/2} \int \exp\{-E(\mathbf{w})\} d\mathbf{w}$$

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- So

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and we can get that

$$\begin{aligned} \log p(\mathcal{D}_m | \alpha, \beta) &= \frac{M}{2} \log \alpha + \frac{m}{2} \log \beta \\ &\quad - E(\boldsymbol{\omega}_N) - \frac{1}{2} \log |\mathbf{A}| - \frac{m}{2} \log(2\pi), \end{aligned}$$

where

$$\mathbf{A} = \mathbf{S}_m^{-1} = \alpha^{-1} \mathbf{I} + \beta \boldsymbol{\Phi}^\top \boldsymbol{\Phi} \in \mathbb{R}^{M \times M},$$

$$\boldsymbol{\omega}_m = \beta \mathbf{S}_m \boldsymbol{\Phi}^\top \mathbf{Y}_m$$

- **Bayesian ML course:** derivations of all formulas and an approach to optimize  $\log p(\mathcal{D}_m | \alpha, \beta)$  w.r.t.  $(\alpha, \beta)$

- So

$$p(\mathcal{D}_m | \alpha, \beta) = \left( \frac{\beta}{2\pi} \right)^{m/2} \left( \frac{\alpha}{2\pi} \right)^{M/2} \int \exp\{-E(\mathbf{w})\} d\mathbf{w}$$

and we can get that

$$\begin{aligned} \log p(\mathcal{D}_m | \alpha, \beta) &= \frac{M}{2} \log \alpha + \frac{m}{2} \log \beta \\ &\quad - E(\boldsymbol{\omega}_N) - \frac{1}{2} \log |\mathbf{A}| - \frac{m}{2} \log(2\pi), \end{aligned}$$

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