

Neural networks' architectures

\vec{x} - input, y - output

$$f(\vec{x}) \approx y$$

Ex. 1. Regression $y \in \mathbb{R}$ $f(\vec{x}) \in \mathbb{R}$
 $(f(\vec{x}) - y)^2 \rightarrow \min$

2. Classification $y \in \{1, \dots, c\}$, $f(\vec{x}) \in \mathbb{R}^c$

$$\vec{p} = f(\vec{x}), \quad \vec{p} = [p_i]_{i=1}^c, \quad p_i \geq 0, \quad \sum p_i = 1$$

$$y = c \rightarrow \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix} = \vec{y}$$

$$-\sum y_i \log p_i \rightarrow \min \quad - \text{cross-entropy}$$

$$f(\vec{x}) \in \mathcal{F}$$

$$\mathcal{F} = \{f(\vec{x}; \vec{\Theta}) = f_{\vec{\Theta}}(\vec{x}) = f(\vec{x} | \vec{\Theta}), \vec{\Theta} \in \mathcal{H} \subseteq \mathbb{R}^P\}$$

$$f_{\vec{\Theta}_1}(\vec{x}) = \vec{\Theta}_1^T \vec{x}$$

$\vec{\Theta}_1^T \vec{x}$ is layer, $\{\vec{\Theta}_i\}_{i=1}^c$, c d parameters

$$f_{\vec{\Theta}_i}(\vec{x}) = \text{softmax}(\underbrace{\{\vec{\Theta}_i^T \vec{x}\}}_{\text{logit}}), \quad i=1 \dots c$$

$$\vec{p} = \text{softmax}(\vec{l}) = \left\{ \frac{\exp(l_i)}{\sum_{j=1}^c \exp(l_j)} \right\}$$

is layer, nonlinear layer, no parameters

$$\vec{\Theta}_1^T \vec{x} < \vec{\Theta}_2^T \vec{x} \quad 0 < (\vec{\Theta}_2 - \vec{\Theta}_1)^T \vec{x}$$

hyperplane

Multilayer (fully-connected) neural network

$$\sigma(t) = \frac{1}{1 + \exp(-t)}$$

Ex. 2 layer neural network

I layer

$$\{(\vec{\Theta}_i^1)^T \vec{x}\} \rightarrow \mathcal{H}_1 \vec{x} \rightarrow \vec{l}_1 \rightarrow \sigma(\vec{l}_1) \rightarrow \vec{z}_1$$

II layer

$$\{(\vec{\Theta}_i^2)^T \vec{z}_1\} \rightarrow \mathcal{H}_2 \vec{z}_1 \rightarrow \vec{l}_2 \rightarrow \sigma(\vec{l}_2) \rightarrow \vec{z}_2$$

\vdots

n layer

$$\{(\vec{\Theta}_i^k)^T \vec{z}_{k-1}\} \rightarrow \mathcal{H}_k \vec{z}_{k-1} \rightarrow \vec{l}_k \rightarrow \sigma(\vec{l}_k) \rightarrow \vec{z}_k$$

$$\left[\begin{array}{l} \Theta - \text{theta} \\ \eta - \text{capital theta} \end{array} \quad \begin{array}{l} t \\ T \end{array} \quad \begin{array}{l} T \\ J|| \end{array} \right]$$

$$\text{softmax}(\vec{l}_k) \rightarrow \vec{p}$$

$$L(\mathcal{H}) = \frac{1}{m} \sum_{i=1}^m CE(\vec{p}_i, y_i) \rightarrow \min_{\mathcal{H}}, \quad \mathcal{H} = \{\mathcal{H}_1, \dots, \mathcal{H}_k\}$$

$\hookrightarrow \frac{\partial L(\mathcal{H})}{\partial \mathcal{H}} \rightarrow$ apply a variant of gradient descent

Backpropagation to calculate derivatives

\mathcal{F} - big enough? - optimization - good or not?

Universal approximation theorem

$$k \geq 2 - |g(\vec{x}) - f_m(\vec{x})| < \varepsilon \quad \forall \vec{x} \in X \subset \mathbb{R}^d$$

$$d_1 = \dim(\vec{z}_1) \quad \mathcal{H}_1 \in \mathbb{R}^{d_1 \times d}$$

\vec{z}_k - a representation of an object at layer k
 $\vec{z}_0 = \vec{x}$

$$\text{softmax}(\mathcal{H}_2 \mathcal{Z}(\mathcal{H}_1, \vec{x}))$$

$$d_0 = d$$

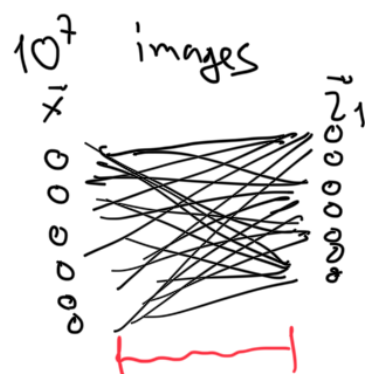
$$p = \sum_{i=1}^k d_i d_{i-1} = \underline{k \cdot d^2}, \quad m - \text{a sample size}$$

$$\vec{x} - \text{an image} \quad 32 \times 32 = 1024 = d_0$$

$$d_1 \approx d_0 \quad d_1 = d_0 \dots d_k = d_{k-1}$$

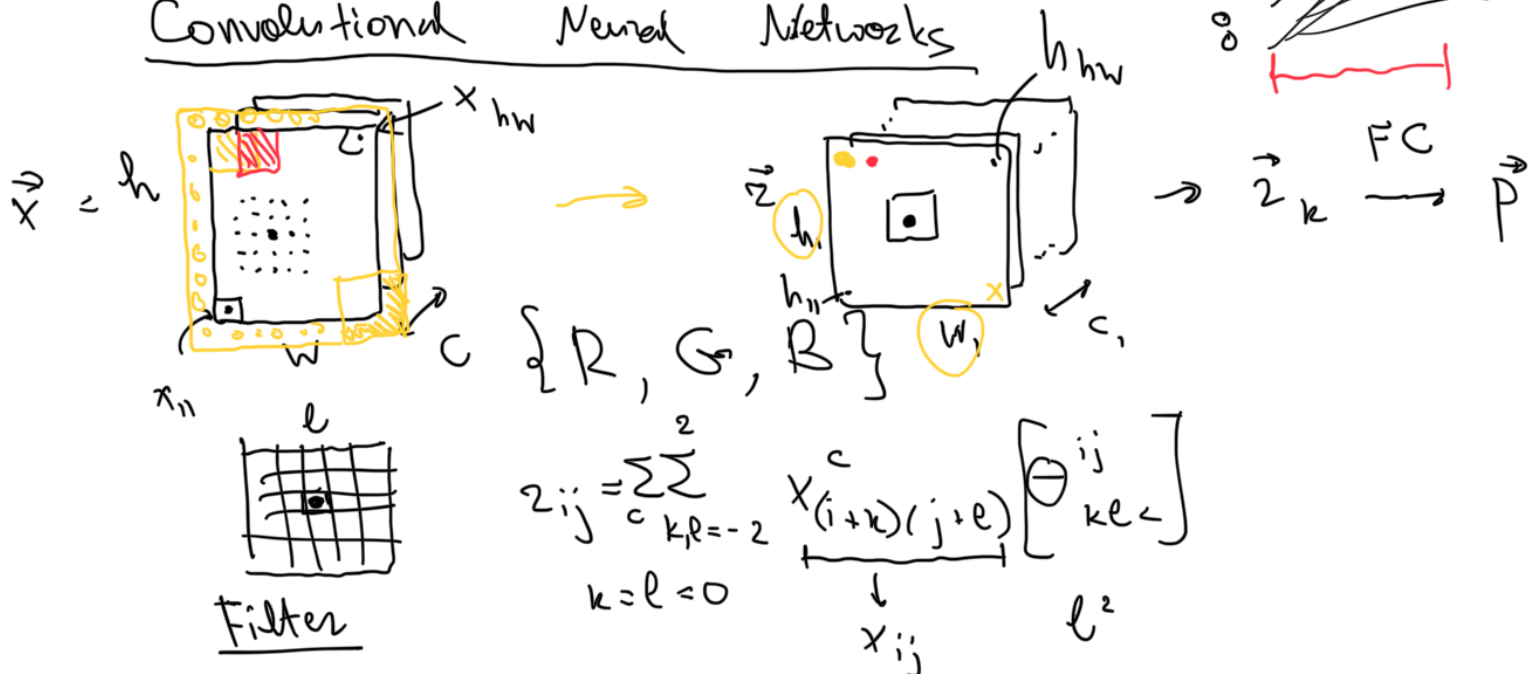
$$p \leq m$$

ImageNet



$$10 p < m$$

Convolutional Neural Networks



$$z_{ij} = \sum_{k=-2}^2 \sum_{l=0}^2 x_{(i+k)(j+l)}^c \left[\Theta_{kl}^{ij} \right]$$

\downarrow
 x_{ij}^c l^2

$$\underbrace{l^2 \cdot hw}_{l^2 \cdot d} < d^2$$

$$l^2$$

$$z_{ij} = \sum x_{(i+k)(j+l)}^c \cdot \underline{\Theta_{kl}^{ij}}$$

$$- k \cdot l^2$$

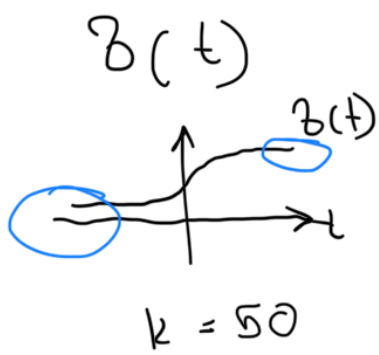
Ex.

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$z_{ij} = x_{ij}$$

$$\begin{bmatrix} 1/9 & 1/3 & \dots \\ \dots & 1/9 & \dots \end{bmatrix}$$

$$z_{ij} = \sum x_{(i+k)(j+l)} \cdot \frac{1}{9}$$



$$\vec{z}_1 = \text{ReLU}(F(\vec{x}))$$

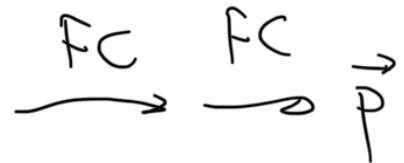
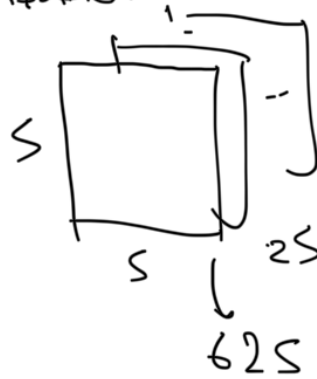
2014
Alex Net 8-10
50

2) Pooling layers

~~dropout~~

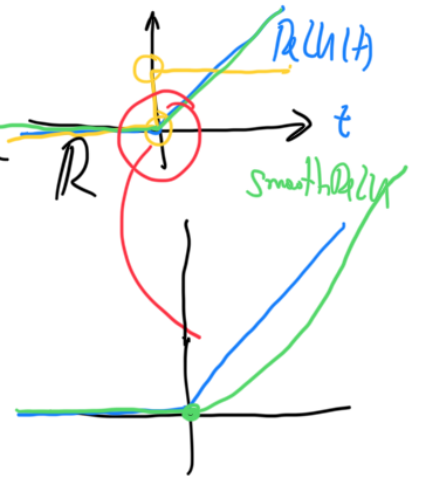


Dimension
reorganization

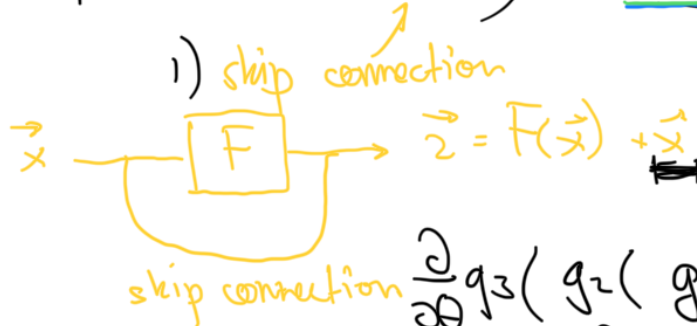


ReLU(t) - rectified linear unit

$$\text{ReLU}(t) = \begin{cases} t, & t \geq 0 \\ 0, & \text{otherwise} \end{cases}$$



$$\vec{z}_1 = \text{ReLU}(F(\vec{x}) + \vec{x})$$



$$\frac{\partial}{\partial \theta} g_3(g_2(g_1(\vec{x}, \theta))) = \frac{\partial g_3}{\partial g_2} \cdot \frac{\partial g_2}{\partial g_1} \cdot \frac{\partial g_1}{\partial \theta}$$