

Group Research Meeting

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5th Sept, 2019

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- ▶ Item 1
- ▶ Item 2

Blank Slide 2

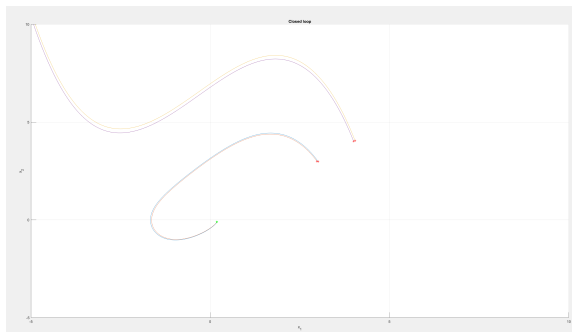


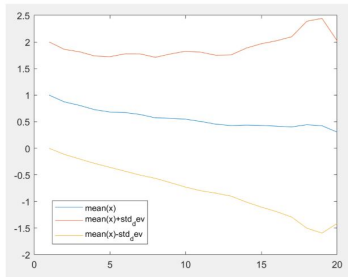
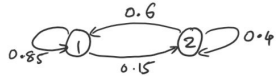
Figure 1: Trajectories

- ▶ Item 1
- ▶ Item 2

Back to the Dynamical System : Example 1

$$x(k+1) = a_{\theta(k)} x_k, \quad a_{\theta(k)} \in \{1.15, 0.1\} \quad x(0) = 1$$

$$T = \begin{bmatrix} 0.85 & 0.6 \\ 0.15 & 0.4 \end{bmatrix}, \quad p(0) = \begin{bmatrix} 0.7 \\ 0.3 \end{bmatrix}$$



Thank you