

If M has a negative eigen value, there exist x_1, x_2 s.t $f(x) < 0$

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Is there an M , not the semidef s.t

$$\begin{bmatrix} x_1 & x_2 & x_1 x_2 \end{bmatrix} M \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{bmatrix} \geq 0 \quad \forall x$$

\Rightarrow

$$\text{If } \exists \lambda > 0, v \neq 0 : Mv = -\lambda v$$

$$\begin{aligned} \text{Then } \forall \alpha, \quad (\alpha v)^T M (\alpha v) &= \alpha^2 v^T M v \\ &= -\alpha^2 \cdot \lambda \cdot \|v\|^2 < 0 \end{aligned}$$

$$\text{If } \{ \alpha v \mid \alpha \in \mathbb{R}, Mv = -\lambda v \} \cap \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{bmatrix} \mid x_1, x_2 \in \mathbb{R} \right\}$$

is non-empty, then we have a contradiction.

(case 1) $v_1 \neq 0$
 $v_2 \neq 0$
 $v_3 \neq 0$

$$\text{let: } Mv = -\lambda v$$

(No component of v is 0)

$$\text{with } \begin{aligned} x_1 &= \frac{v_3}{v_2} \\ x_2 &= \frac{v_3}{v_1} \end{aligned}, \quad \begin{bmatrix} x_1 & x_2 & x_1 x_2 \end{bmatrix} M \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{v_3}{v_2} & \frac{v_3}{v_1} & \frac{v_3^2}{v_1 v_2} \end{bmatrix} M \begin{bmatrix} v_3/v_2 \\ v_3/v_1 \\ v_3^2/v_1 v_2 \end{bmatrix}$$

$$= \left(\frac{v_3}{v_1 v_2} \right)^2 \begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix} M \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

$$= -\lambda \cdot \left(\frac{v_3}{v_1 v_2} \right)^2 \cdot \|v\|^2 < 0$$

Case 5] (One component of \vec{v} is 0)

$\nexists x_1, x_2:$

$$\propto \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ v_2 \\ v_3 \end{bmatrix}, \begin{bmatrix} v_1 \\ 0 \\ v_3 \end{bmatrix}, \begin{bmatrix} v_1 \\ v_2 \\ 0 \end{bmatrix}$$

(One component of \vec{v} is 0)

$$\begin{array}{l|l|l} x_1 = v_3/v_2 & x_1 = \alpha v_1 & x_1 = \alpha v_1 \\ x_2 = \alpha v_2 & x_2 = v_3/v_1 & x_2 = \alpha v_2 \\ x_1 x_2 = \alpha v_3 & x_1 x_2 = \alpha v_3 & x_1 x_2 = \alpha^2 v_1 v_2 \end{array}$$

$$\begin{array}{l|l|l} \alpha \rightarrow \infty & \alpha \rightarrow 0 & \text{Consider } \alpha \rightarrow 0 \\ \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{bmatrix} \rightarrow \begin{bmatrix} 0 \\ \alpha v_2 \\ \alpha v_3 \end{bmatrix} & \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{bmatrix} \rightarrow \begin{bmatrix} \alpha v_1 \\ 0 \\ \alpha v_3 \end{bmatrix} & \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{bmatrix} \rightarrow \begin{bmatrix} \alpha v_1 \\ \alpha v_2 \\ 0 \end{bmatrix} \end{array}$$

Case 2]

$$\begin{array}{l} v_1 \neq 0 \\ v_2 = 0 \\ v_3 = 0 \end{array}$$

\Rightarrow

$$\begin{array}{l} v_1 = x_1 \\ v_2 = x_2 = 0 \\ v_3 = x_1 x_2 = 0 \end{array}$$

✓

Case 3]

$$\begin{array}{l} v_1 = 0 \\ v_2 \neq 0 \\ v_3 = 0 \end{array}$$

\Rightarrow

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Case 4]

$$\begin{array}{l} v_1 = 0 \\ v_2 = 0 \\ v_3 \neq 0 \end{array}$$

\Rightarrow

$$m_{33} < 0 \Rightarrow \text{contradiction can't happen}$$

(Two components of \vec{v} are 0)