

1. Metric axioms. Metric spaces. Norms. Normed linear spaces

Definition: (Metric space)

A metric space is a set X with a metric $\rho : X \times X \rightarrow [0, \infty)$ (or it can be valid notation d , in that way we can call it by 'distance') such that $\forall x, y, z \in X$, ρ satisfies the following properties:

1. Positive definite:

$$\rho(x, y) \geq 0, \quad \forall x \neq y$$

$$\rho(x, y) = 0 \iff x = y; \quad \rho(x, x) = 0.$$

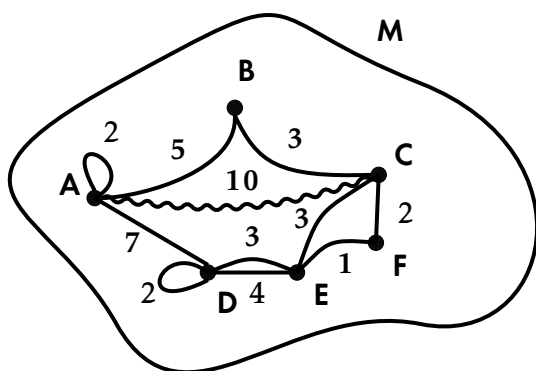
2. Symmetric:

$$\rho(x, y) = \rho(y, x).$$

3. Triangle Inequality:

$$\rho(x, z) \leq \rho(x, y) + \rho(y, z).$$

Example 1:



Let define some metric space with metric $\rho(x, y)$ is equal to the length of the shortest path. Then $\dim(M) = 10$ and, e.g.:

$$\rho(A, A) = 0;$$

$$\rho(A, D) = 7;$$

$$\rho(A, C) = 8$$

Also we can show, for example, open ball on this example (we will define it little bit later):

$$B_3(A) = \{A\}$$

$$B_9(A) = \{A, B, C, D, E\}$$

Example 2: Given a set X :

- The discrete metric ρ on X is defined by:

$$\rho(x, y) = \begin{cases} 1, & x \neq y \\ 0, & x = y. \end{cases}$$

- Metric on continuous functions:

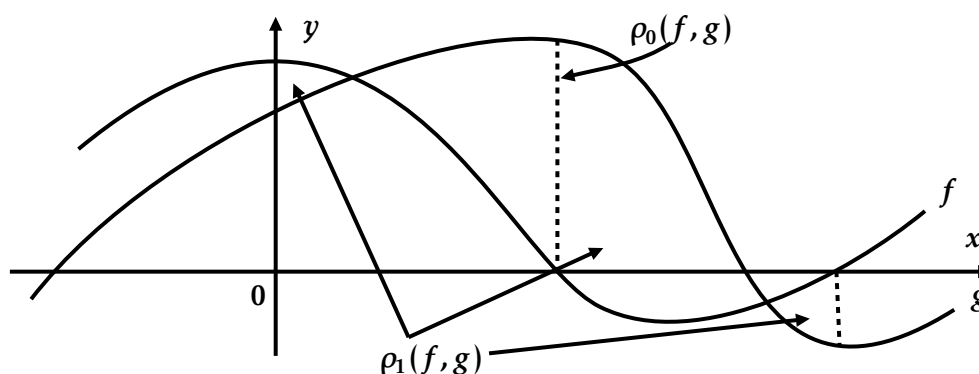
Let $X = \mathcal{C}[0, 1] = \{\text{continuous functions } f : [0, 1] \rightarrow \mathbb{R}\}$. Then we can define metrics:

$$\rho_0(f, g) = \max_{x \in [0, 1]} |f(x) - g(x)|.$$

$$\rho_1(f, g) = \int_0^1 |f(x) - g(x)| dx$$

Or:

$$\rho(f, g) = \rho_0(f, g) + |f(1) - g(1)|.$$



- Let $x = \mathbb{R}$. Possible metric:

$$\rho(x, y) = |e^x - e^y|.$$

- Another example of metric:

$$\rho(x, y) = \begin{cases} 1, & x - y \in \mathbb{Q} \\ 2, & x - y \notin \mathbb{Q} \\ 0, & x = y \end{cases}$$

Definition: (Continuous function)

The function is called continuous iff:

$$\lim_{x \rightarrow x_0} f(x) = y_0,$$

that is $\forall \varepsilon > 0 \exists \delta :$

$$f[B_\delta(x_0)] \subset B_\varepsilon[f(x_0)] \equiv B_\varepsilon(y_0)$$

Definition: (Open ball)

An open ball of radius $r > 0$ centered at the point $x_0 \in X$ is the set:

$$B(x_0, r) = \{x \in X \mid \rho(x, x_0) < r\}$$

Definition: (Closed ball)

A closed ball of radius $r > 0$ centered at the point $x_0 \in X$ is the set:

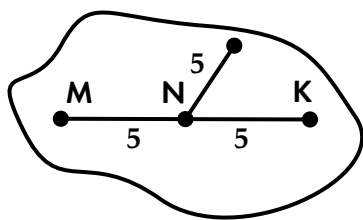
$$\overline{B}(x_0, r) = \{x \in X \mid \rho(x, x_0) \leq r\}.$$

Note

A ball centered at the point A of radius r in some metric space X

$$B_r(A) = \{x \in X \mid \rho(A, x) \leq r\}.$$

.....
Example 3: Let define space:



$$B_8(M) = \{M, N\}$$

$$B_6(N) = \{M, N, K\}$$

Definition: (Normed space)

A (complex or real) vector space V is called normed space if a function ('norm') $\nu : V \rightarrow \mathbb{R}$, denoted for $v \in V$ $\|v\|$, which satisfies the following axioms:

1. Positive definite property:

$$\nu(\vec{x}) > 0;$$

2. Homogeneity

$$\nu(\alpha \vec{x}) = |\alpha| \nu(\vec{x});$$

3. Triangle inequality $\forall x, y \in V$:

$$\nu(\vec{x} + \vec{y}) \leq \nu(\vec{x}) + \nu(\vec{y}).$$

Example 4: Euclidean norm:

$$|\vec{x}|_2 = \sqrt{\sum_{i=1}^n |x_i|^2}$$

Prop

In a normed space V , the function $\rho(\vec{x}, \vec{y}) = \nu(\vec{y} - \vec{x})$ is a metric.

Proof: For proving positive definition of function $\nu(\vec{x}, \vec{y})$ we need a lemma:

Lemma

$$\nu(\vec{0}) = 0$$

Proof: $\nu(0 \cdot \vec{0}) = 0 \cdot \nu(\vec{0}) = 0.$

□

1. Positive definition:

$$\rho(\vec{x}, \vec{y}) = \nu(\vec{y} - \vec{x}) > 0$$

$$\rho(\vec{x}, \vec{x}) = \nu(\vec{x} - \vec{x}) = \nu(\vec{0}) = 0$$

2. Symmetric:

$$\rho(\vec{x}, \vec{y}) = \nu(\vec{y} - \vec{x}) = |-1| \nu(\vec{x} - \vec{y}) = \nu(\vec{x} - \vec{y}) = \rho(\vec{y}, \vec{x})$$

3. Triangle inequality:

$$\rho(\vec{x}, \vec{y}) + \rho(\vec{y}, \vec{z}) = \nu(\vec{y} - \vec{x}) + \nu(\vec{z} - \vec{y}) \geq$$

$$\geq \nu(\vec{y} - \vec{x} + \vec{z} - \vec{y}) = \nu(\vec{z} - \vec{x}) = \rho(\vec{x}, \vec{z})$$

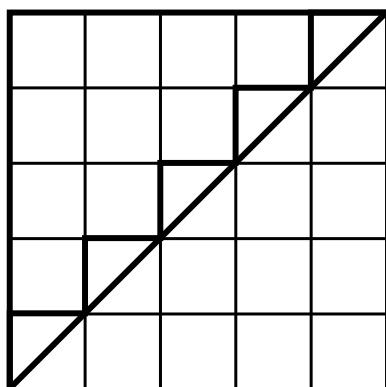


Note

Each normed space is a metric space.

Example 5: In the vector space \mathbb{R}^n (\mathbb{C}^n) the following three norms are in common use:

- **Manhattan norm (Taxicab norm):**



This is the norm of the following kind:

$$\|x\|_1 = \sum_{i=1}^n |x_i|$$

Let's prove that this function is a norm.

1. **Positive definite property:** Let $x \in \mathbb{R}^n$ or $x \in \mathbb{C}^n$. Obviously $\|x\|_1 \geq 0$. Also $\|x\|_1 = 0$ iff $x = 0$.

2. **Homogeneity property:**

$$\forall c \in \mathbb{R} : \|c \cdot x\|_1 = \sum_{i=1}^n |c \cdot x_i| = |c| \cdot \sum_{i=1}^n |x_i| = |c| \cdot \|x\|_1.$$

3. **Triangle inequality** $\forall x, y \in \mathbb{R}^n$:

$$\begin{aligned} \|x + y\|_1 &= \sum_{i=1}^n |x_i + y_i| \leq \sum_{i=1}^n (|x_i| + |y_i|) = \\ &= \sum_{i=1}^n |x_i| + \sum_{i=1}^n |y_i| = \|x\|_1 + \|y\|_1. \end{aligned}$$

- **Maximum norm (Infinity norm):**

$$\|x\|_\infty = \max_{1 \leq i \leq n} |x_i|.$$

1. The function $\|x\|_\infty$ is positive since it is the maximum over a set of positive terms $|x_i|$.

2. **Homogeneity property:**

$$\|\alpha \cdot x\|_\infty = \max_{1 \leq i \leq n} |\alpha \cdot x_i| = \max_{1 \leq i \leq n} |\alpha| \cdot |x_i| = |\alpha| \cdot \max_{1 \leq i \leq n} |x_i| = |\alpha| \cdot \|x\|_\infty.$$

3. **Triangle inequality:**

$$\|x + y\|_\infty = \max_{1 \leq i \leq n} |x_i + y_i| \leq \max_{1 \leq i \leq n} (|x_i| + |y_i|) \leq \max_{1 \leq i \leq n} |x_i| + \max_{1 \leq i \leq n} |y_i| = \|x\|_\infty + \|y\|_\infty.$$

Example 6: For the vector $x = \begin{bmatrix} 1 \\ 2 \\ -3 \\ 5 \end{bmatrix}$ we have:

$$\|x\|_1 = 11; \|x\|_2 = \sqrt{39}; \|x\|_\infty = 5,$$

whereas for the vector $x = \begin{bmatrix} 1+i \\ 2-3i \\ 4 \end{bmatrix}$,

$$\|x\|_1 = \sqrt{2} + \sqrt{13} + 4; \|u\|_2 = \sqrt{31}; \|u\|_\infty = 4.$$

The notations $\|\cdot\|_1$, $\|\cdot\|_2$ and $\|\cdot\|_\infty$ are justified because of the fact that all these norms are special cases of the general Minkovski p -norm:

$$\|x\|_p = \sqrt[p]{\sum_{i=1}^n |x_i|^p}, \quad p \geq 1$$

Similarly, in the vector space of real-valued continuous functions $\mathcal{C}[a, b]$, the following three norms are frequently used:

$$\|f\|_1 = \int_a^b |f(x)| dx; \|f\|_2 = \sqrt{\int_a^b f^2(x) dx}; \|f\|_\infty = \max_{x \in [a, b]} |f(x)|$$

And Minkovski norm:

$$\|f\|_p = \sqrt[p]{\int_a^b |f(x)|^p dx}$$

For example, for $V = \mathcal{C}[0, 1]$:

$$\begin{aligned} \|f\|_p &= \sqrt[p]{\int_0^1 |f(x)|^p dx} \\ \|f\|_1 &= \int_0^1 |f(x)| dx \\ \|f\|_\infty &= \|f\|_0 = \max_{x \in [0, 1]} |f(x)|. \end{aligned}$$

Some weighted norms:

Let $V = \mathcal{C}[0, 1]$; $\omega \geq 0$:

$$\begin{aligned} \|f\|_p^\omega &= \left(\int_0^1 |f(x)|^p \cdot \omega(x) dx \right)^{\frac{1}{p}} \\ \|f\|_\infty^\omega &= \|f\|_0^\omega = \max_{x \in [0, 1]} |f(x) \cdot \omega(x)|. \end{aligned}$$

Balls in normed space

Let V be a normed space

- All balls of the same radius R are equal geometrically: a parallel translation of $B_R(\vec{x})$ by a vector $\vec{v} = \vec{y} - \vec{x}$ makes $B_R(\vec{y})$.
- For any two balls: $B = B_r(0)$ and $B' = B_R(0)$, there is a homotety $x \mapsto \lambda \vec{x}$, which transfers B

onto B' , where $\lambda = \frac{R}{r}$. Also $B_1^p(0) = \text{unit ball for 0-norm}$.

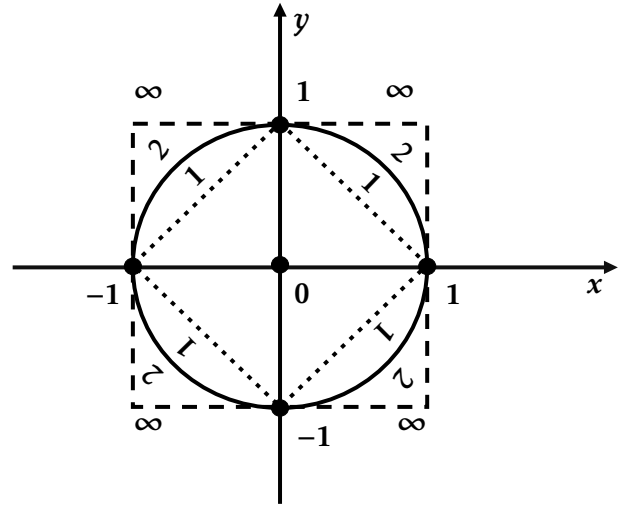
Proof:

1.

$$\begin{aligned} B_R(\vec{x}) + V &= \left\{ \vec{a} \mid \nu(\vec{a} - \vec{x}) \leq R \right\} + (\vec{y} - \vec{x}) = \\ &= \left\{ \vec{a} + \vec{y} - \vec{x} \mid \nu(\vec{a} - \vec{x}) \leq R \right\} = \left\{ \vec{b} \mid \nu(\vec{b} - \vec{y}) \leq R \right\} = \\ &= B_R(\vec{y}), \text{ where: } \vec{a} + \vec{y} - \vec{x} = \vec{b}; \vec{a} = \vec{b} - \vec{y} + \vec{x}. \end{aligned}$$

2. $\frac{R}{r} \cdot \vec{a} = \vec{b}; \vec{a} = \frac{r}{R} \cdot \vec{b}.$

$$\begin{aligned} \lambda \cdot B &= \frac{R}{r} \cdot \left\{ \vec{a} \mid \nu(\vec{a}) \leq r \right\} = \left\{ \frac{R}{r} \cdot \vec{a} \mid \nu(\vec{a}) \leq r \right\} = \\ &= \left\{ \vec{b} \mid \nu\left(\frac{r}{R} \cdot \vec{b}\right) \leq r \right\} = \left\{ \vec{b} \mid \frac{r}{R} \cdot \nu(\vec{b}) \leq r \right\} = \\ &= \left\{ \vec{b} \mid \nu(\vec{b}) \leq \frac{r \cdot R}{r} \right\} = \left\{ \vec{b} \mid \nu(\vec{b}) \leq R \right\} = B'. \end{aligned}$$



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