

# Clustering Initialization

when data points are indistinguishable  
between clusters

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ESTIMATING MIXED MULTINOMIAL CHOICE MODELS

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# ESTIMATING PREFERENCES

**DATA.** Sales data, including assortment offered and product bought



$$\mathbf{x} = \{\mathbf{A}, \mathbf{B}, \mathbf{C}\} | \mathbf{A}$$

**TASK.** Predict purchase probability for each item in each assortment

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**COMMON MODELING APPROACH. Fit a mixed MNL model**

□ **MNL MODEL.** Purchase probabilities given by  $p(i|S) = \lambda_i / \sum_{j \in S} \lambda_j$

□ **MIXED MNL.** There are K customer types, each following a MNL model.

$$p(i|S) = \sum_{k=1:K} \pi_k p^k(i|S)$$

□ **ESTIMATION.** EM algorithm

# WHY IS THIS INTERESTING?

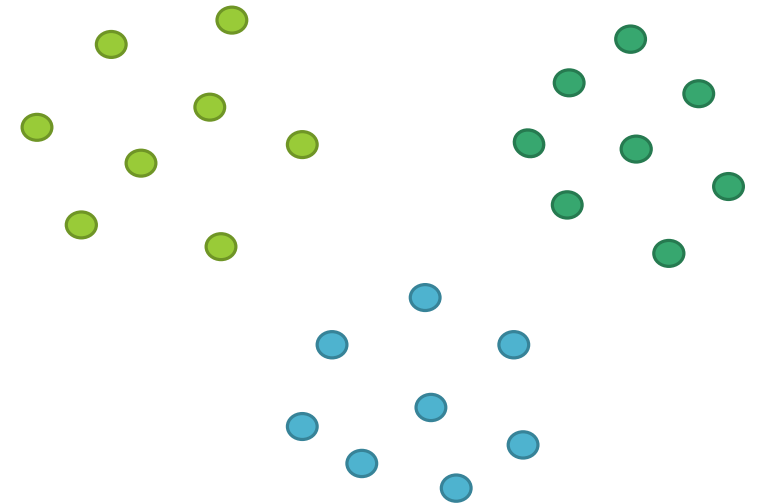
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EM PERFORMANCE NOTORIOUSLY DEPENDENT ON **INITIALIZATION**

- Convergence with common initialization for mixed MNL is slow.

**K-MEANS** ~ EM FOR MIXED GAUSSIANS,  $\sigma = 1$

- **Efficient initialization due to [Arthur, D. 2006]**



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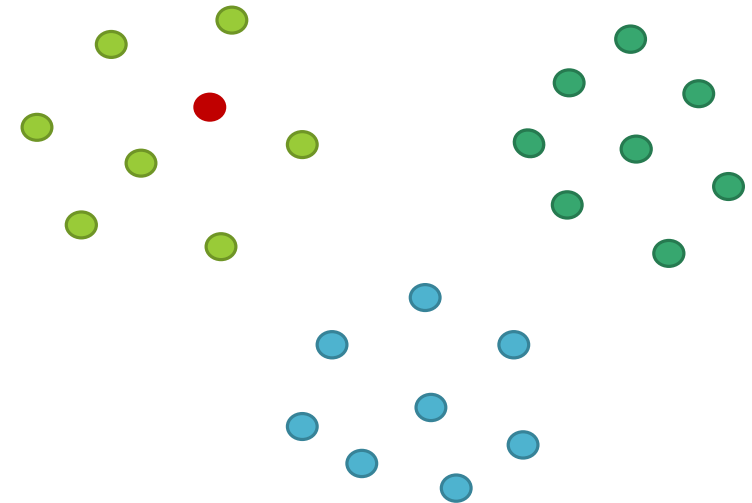
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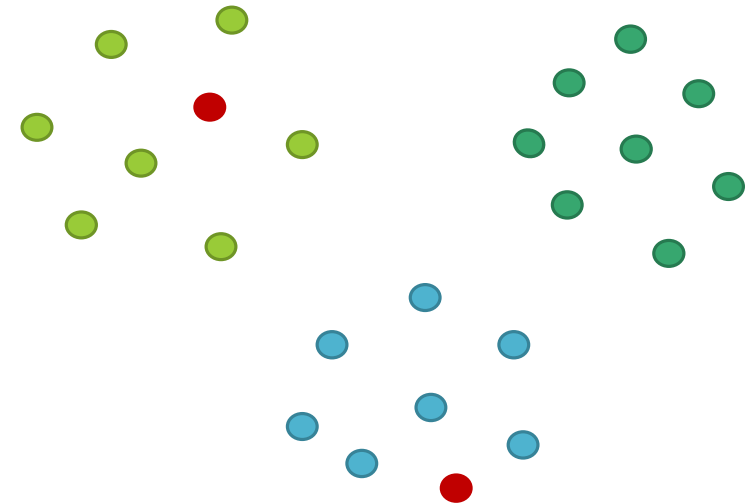
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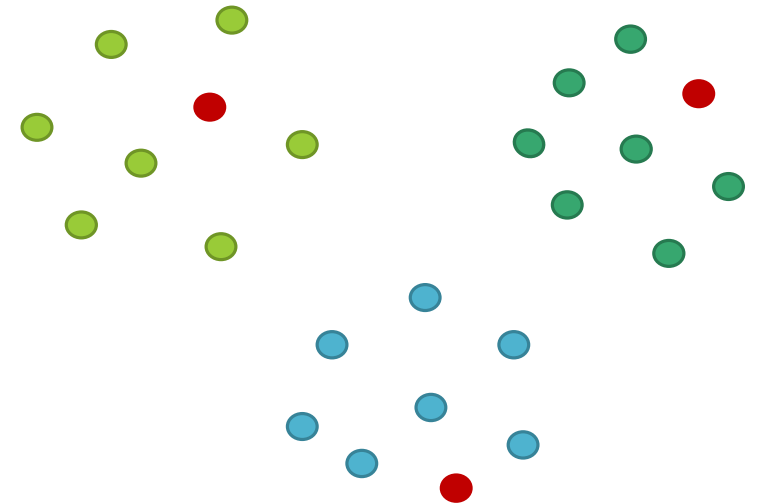
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- **Efficient initialization due to [Arthur, D. 2006]**
- Good seeding: centroids as different as possible
- What makes seeding possible?

**Datapoints in different clusters are distinguishable**  
*(in separate parts of the plane)*



# NAÏVE EM ++ INITIALIZATION FOR MIXED MNL

True models			
MNL Model / Cluster	Product weights		
	0	1	2
A ( $\pi = 0.5$ )	25	25	50
B ( $\pi = 0.5$ )	40	20	40

Data							
{0,2}	0			{0,2}	0	{0,2}	0
{0,2}	2	{0,2}	2	{0,2}	2	{0,2}	2
{0,1}	1	{0,1}	1	{0,1}	1		
{0,1}	0	{0,1}	0	{0,1}	0	{0,1}	0



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Choose centroids far apart.

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Choose centroids far apart.

Model estimated:

Product 0 is ~never bought in  $\{0,1,2\}$   
as opposed to 32.5% of time.

Data					
<div><div>{0,2}</div><div>0</div></div>			<div><div>{0,2}</div><div>0</div></div>	<div><div>{0,2}</div><div>0</div></div>	
<div><div>{0,2}</div><div>2</div></div>	<div><div>{0,2}</div><div>2</div></div>		<div><div>{0,2}</div><div>2</div></div>	<div><div>{0,2}</div><div>2</div></div>	
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# EM ++ INITIALIZATION FOR MIXED MNL

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## HOW IS EM INITIALIZED FOR MIXED MNL?

- Split observations into  $k$  groups randomly and estimate an MNL on each cluster.
- The  $k$  smaller datasets will be very similar statistically, so the  $k$  initial MNL models are very close to each other
- **Leads to slow convergence.**

# EM ++ INITIALIZATION FOR MIXED MNL

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## LEVERAGE MNL STRUCTURE TO CONSTRUCT ++ STYLE SEEDING

$$\text{MNL Signature:}$$
$$r(S) = \left[ \frac{p(i|S)}{p(\text{no item bought} \mid S)} \right]_{i \in S}$$

- MNL:  $r(S)$  constant in all assortments
- MNL: fully specified by  $r(S)$  (on  $S$ )
- Mixed MNL:  $r(S)$  linear combinations of  $r^k(S)$

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- Mixed MNL:  $r(S)$  linear combinations of  $r^k(S)$
- If  $r(S)$  is relatively stable on all assortments  $S$  observed, MNL is enough.
- If not, then every  $r^k(S)$  gives a different MNL, in the space spanned by the mixtures.

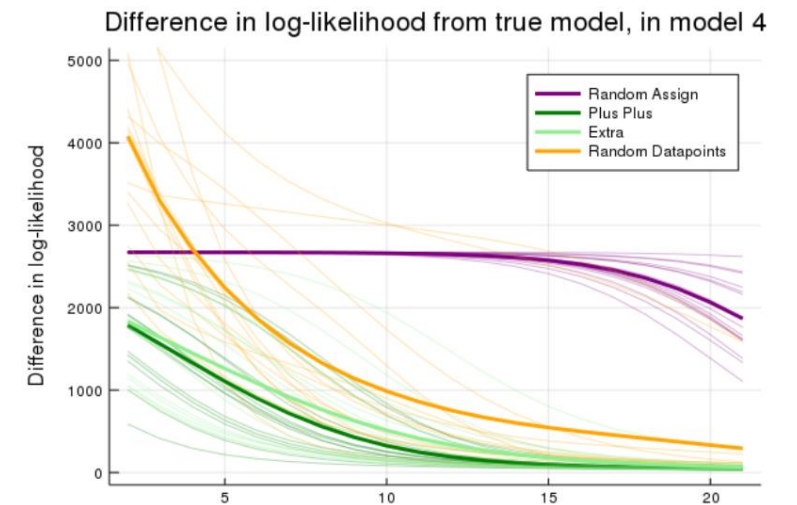
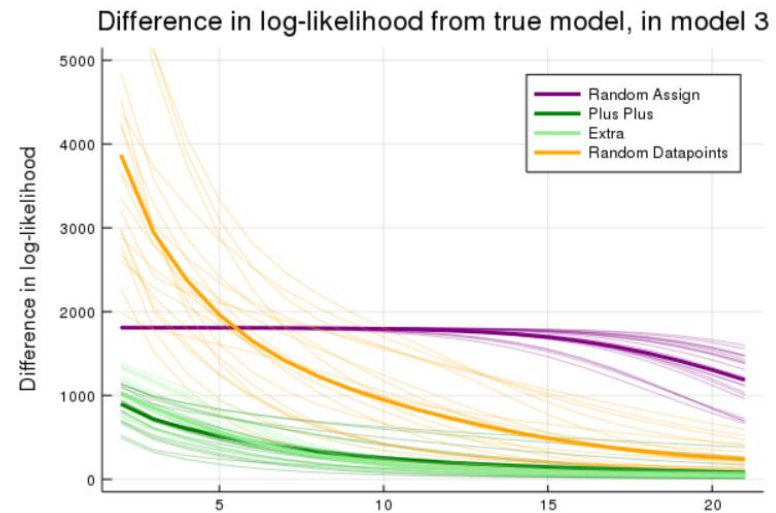
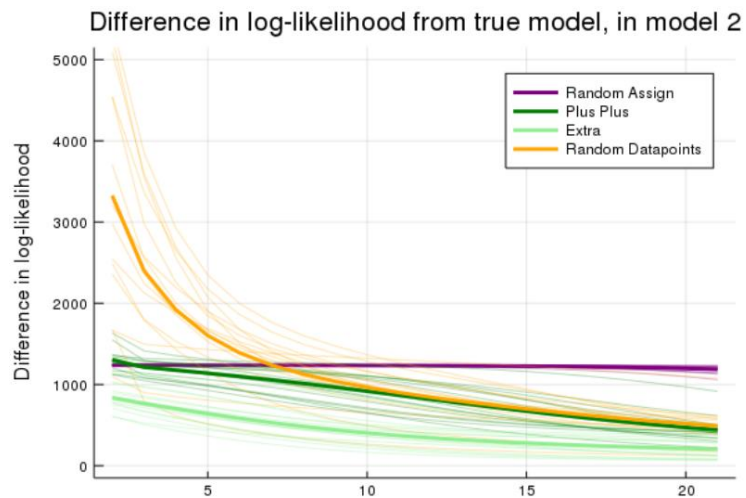
# EM ++ INITIALIZATION FOR MIXED MNL

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## FINAL SEEDING TECHNIQUE

- Compute  $r(S)$  for every assortment in the dataset.
- Technique 1: Random
  - Choose  $K$   $r(S)$  randomly and initialize EM with MNL models they specify.
- Technique 2: Plus Plus
  - Choose  $K$   $r(S)$  that are furthest apart (*how far apart the MNL models induced are*) – inspired by the original k-means ++.
- Results:
  - Both methods significantly outperform classic initialization.
  - Technique 2 is more stable.

# RESULTS ON SYNTHETIC DATA



Classic initialization (datapoints are split into K similar clusters)  
Plus Plus (Method 2)  
Described on last slide.  
Random (Method 1)

# RESULTS ON SYNTHETIC DATA

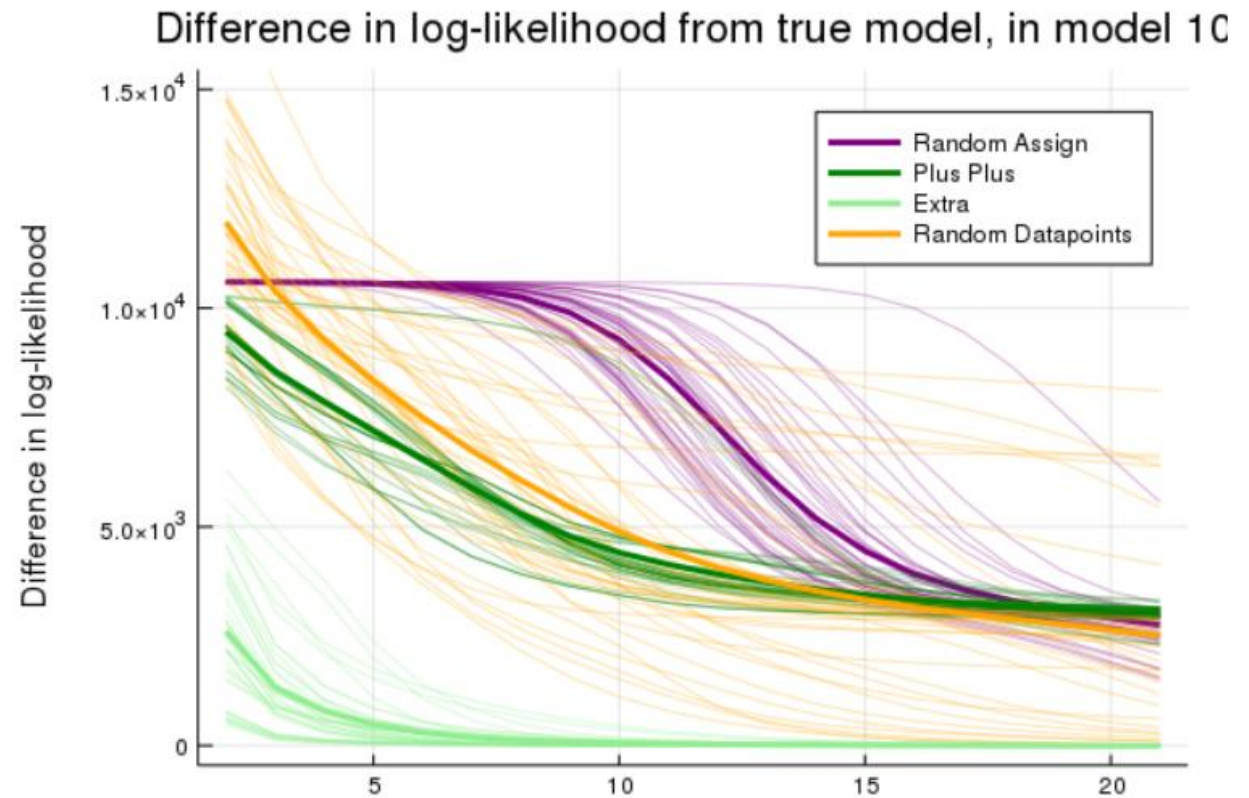
## MAIN LIMITATION OF SEEDING

Initial MNL models have information only on some products

## LIGHT GREEN METHOD

Ratios by assortment are imputed using the known linear combination and true ratios.

Then ++ seeding applied.





# Appendix

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# EM-algorithm and fuzzy k-means

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In fuzzy k-means we are minimizing through block coordinate descent on  $q, \lambda, c = (c_1, \dots, c_K)$  the function

$$\min_{q, \lambda, c_1, \dots, c_K} \sum_{i=1}^n \left( \sum_{k=1}^K q_i(k) \|y_i - c_k\|^2 + q_i(k) \log \frac{q_i(k)}{\lambda(k)} \right) \text{ subject to } \sum_{k \in [K]} q_i(k) = 1, \forall i, \quad \sum_{k \in [K]} \lambda(k) = 1$$

In EM we are minimizing through coordinate descent on  $q, \lambda, u = (u_1, \dots, u_K)$  the function

$$\min_{q, \lambda, u_1, \dots, u_K} \sum_{i=1}^n \left( \sum_{k=1}^K q_i(k) (-\log \mathbb{P}[y_i; u_k]) + q_i(k) \log \frac{q_i(k)}{\lambda_k} \right) \text{ subject to } \sum_{k \in [K]} q_i(k) = 1, \forall i, \quad \sum_{k \in [K]} \lambda_k = 1$$

The two problems are equivalent (and the same for mixed Gaussians)

- $c_1, \dots, c_K$  and  $u_1, \dots, u_K$  are the centroids of the clusters, the objects that describe the cluster properties.
- Distance is Euclidean distance in k-means and negative log likelihood in EM.
- $q$  gives the fuzzy cluster partition of data points, and it is regularized through entropy.
- $\lambda$  is the relative size of the clusters.