view frames Result Recorded at time: 1761617671.065679 world Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 map Broadcaster: default authority Average rate: 5.556 Buffer length: 1.8 Most recent transform: 4389.2 Oldest transform: 4387.4 odom Broadcaster: default authority Average rate: 50.521 Buffer length: 1.92 Most recent transform: 4388.32 Oldest transform: 4386.4 base footprint Broadcaster: default authority Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: 20.505 Average rate: 20.505 Average rate: 10000.0 Buffer length: 1.902 Buffer length: 1.902 Buffer length: 0.0 Most recent transform: 4388.295 Most recent transform: 4388.295 Most recent transform: 0.0 Oldest transform: 4386.393 Oldest transform: 4386.393 Oldest transform: 0.0 right_wheel chassis Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 imu_link front camera mount caster lidar lidar mount ul sensor mount Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0

ul_sensor link

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0

laser_link

left_wheel

camera link

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0