





PEN SOURCE SUMMIT

# Serverless Service Mesh Based on Istio and Virtual Kubelet

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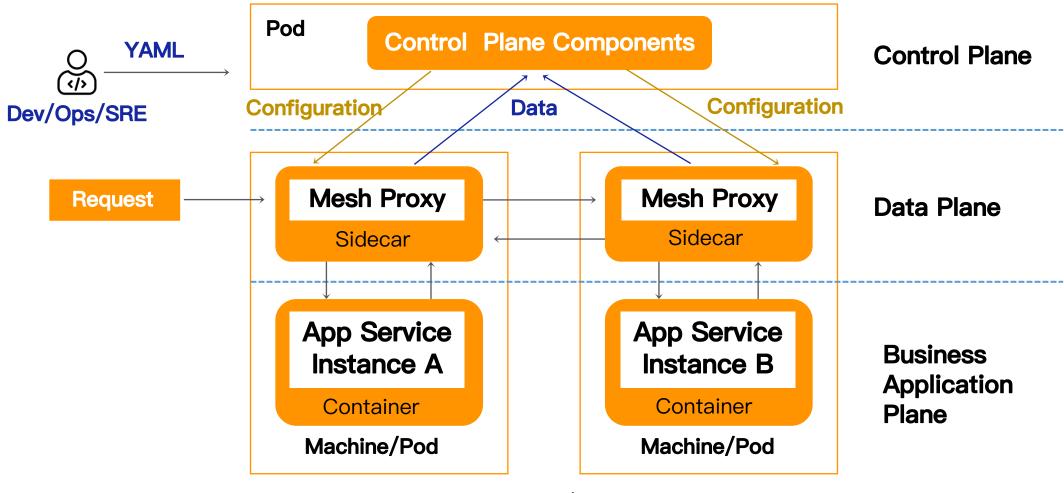




## Traditional Sidecar mode in Service Mesh S OPEN SOURCE SUMMIT



Both the control plane and data plane components run within a single K8s cluster



### Decoupling of the control plane and data plane

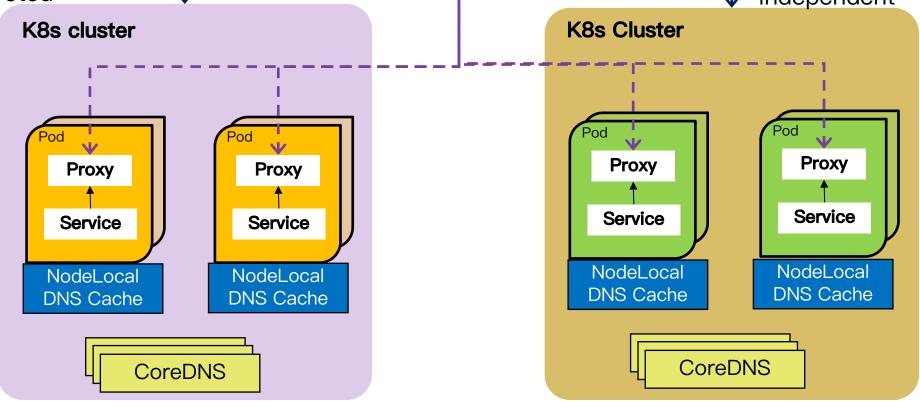


- Control Plane is running on separated cluster
- Control Plane is managed mode, e.g. all the mesh CRD objects stored within managed etcd



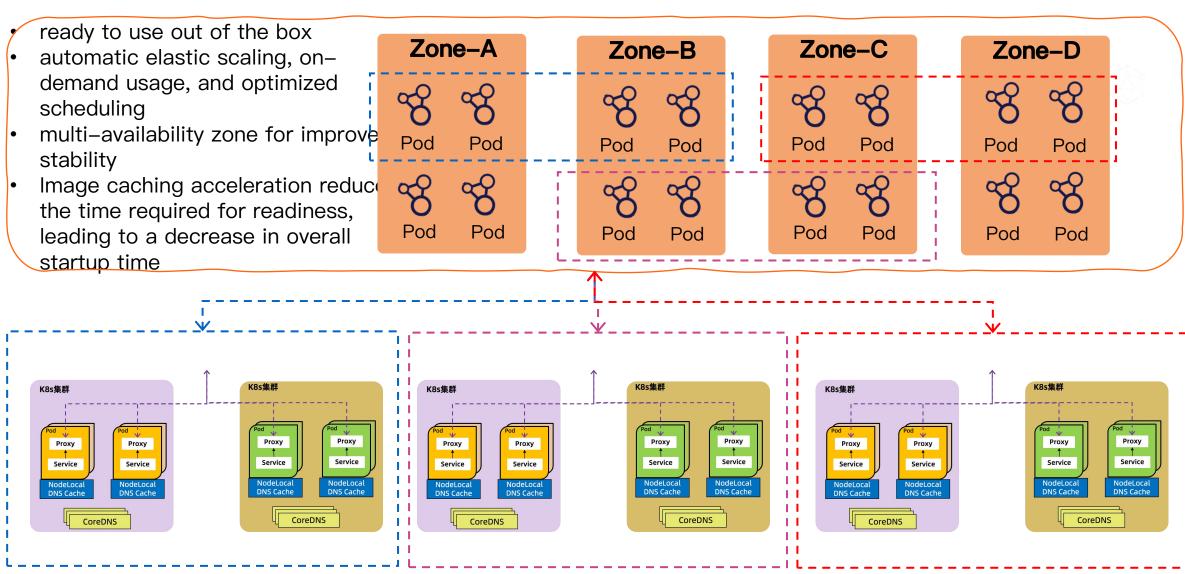
Istiod/Pilot API Server

- Easy to support for multicluster mode
- The lifecycle management of the control plane and data plane K8s clusters is independent



# Serverless of the managed control plane.





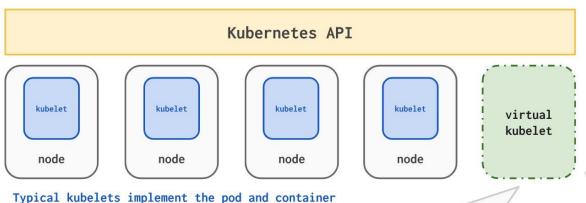


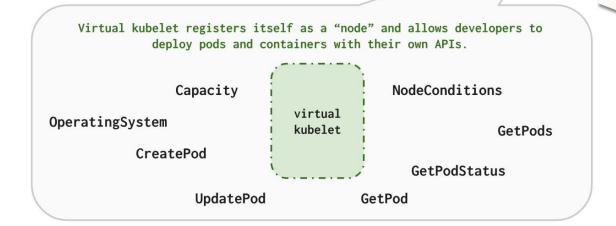


## Virtual Kubelet & Serverless Container



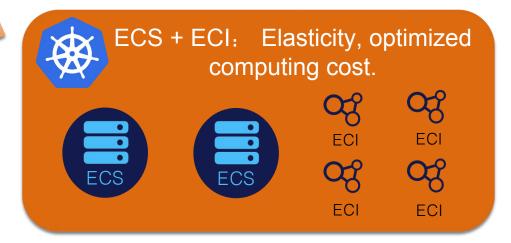
 VK: Decoupling the orchestration layer from the resource pool, fully unleashing resource elasticity.





operations for each node as usual.





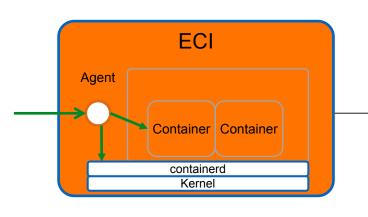
## How to make Sidecar and Gateway Pods Serverless



What are the challenges and how to address them?

1. Deployment strategy: Running on virtual nodes.

```
affinity:
 nodeAffinity:
    preferredDuringSchedulingIgnoredDuringExecution:
    - preference:
        matchExpressions:
            - key: type
            operator: In
            values:
                - virtual-kubelet
    requiredDuringSchedulingIgnoredDuringExecution:
   nodeSelectorTerms:
       - matchExpressions:
            - key: type
            operator: In
            values:
                - virtual-kubelet
tolerations:
effect: NoSchedule
    key: virtual-kubelet.io/provider
   operator: Equal
    value: alibabacloud
```



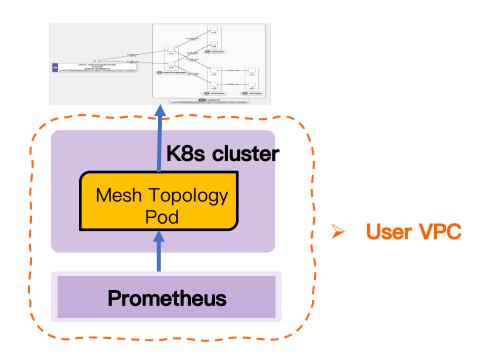
2. Security considerations:
 securityContext

```
securityContext:
    allowPrivilegeEscalation: false
    privileged: false
    capabilities:
    add:
    - NET_ADMIN
    drop:
    - ALL
```

## Managed mesh topology within elastic resource pool



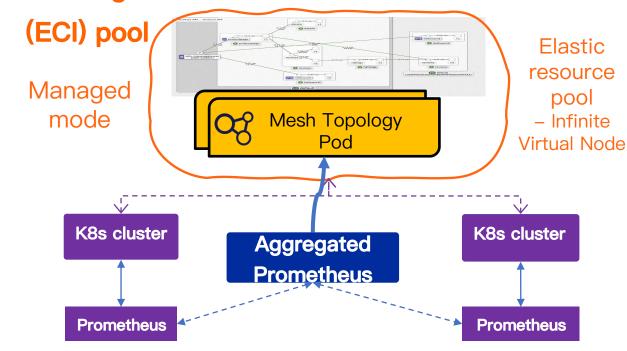
#### Running within a Kubernetes cluster



#### Deployed within a Kubernetes cluster

- The availability of services is affected by the cluster and cannot achieve the elastic capabilities
- In a multi-cluster environment, each topology can only observe the workload-related within its own cluster. Additionally, each cluster needs to be configured and deployed separately, resulting in high complexity.

#### Running within Elastic Container Instances



#### Deployed in a managed Serverless mode

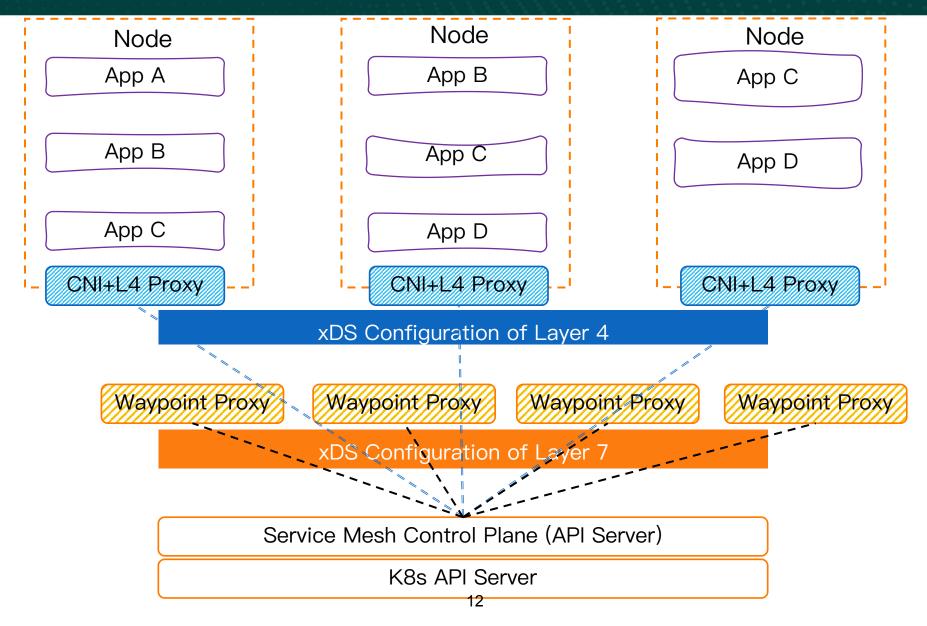
- Deployed in a managed ECI mode within an elastic resource pool, it has the ability to elastically scale and schedule across multiple availability zones. Resources are used and released on-demand.
- It provides better support for unified observation of traffic topology in a multi-cluster environment, offering centralized configuration for topology observation and a unified service access entry.





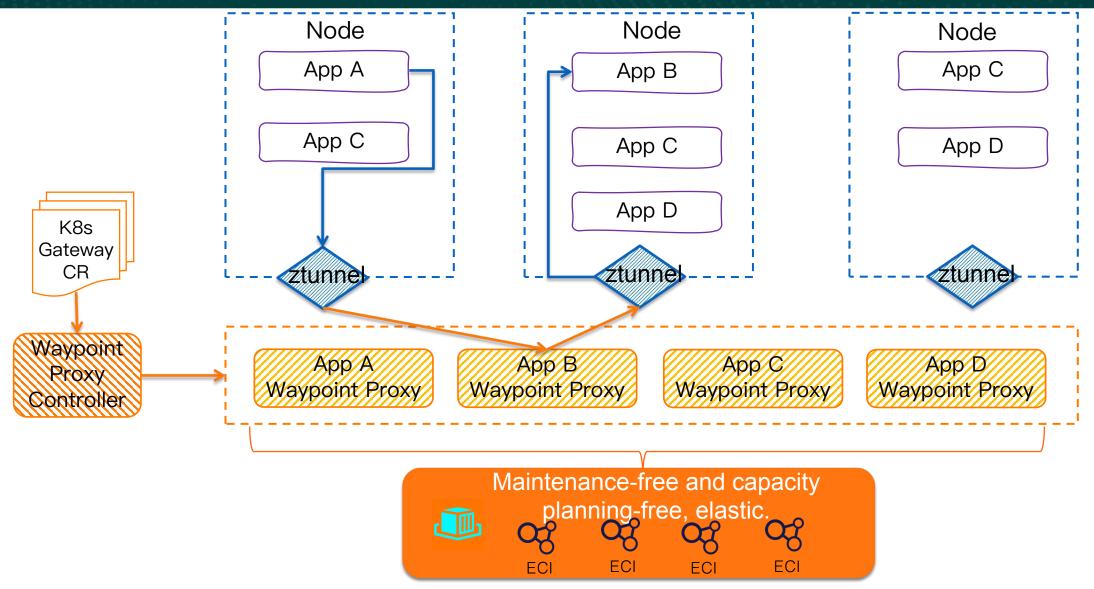
# Decoupling of L4 and L7 Proxy





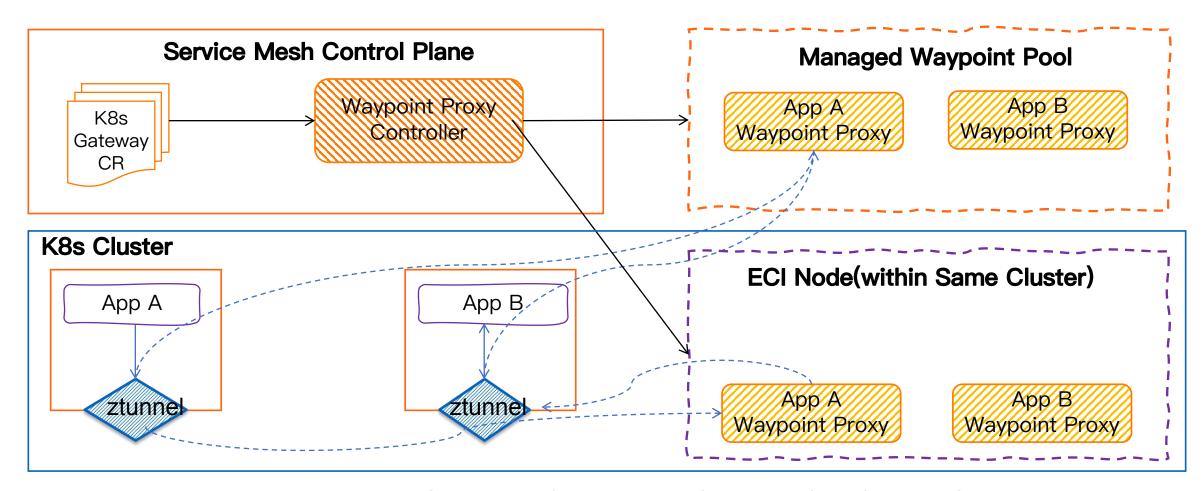
# Serverless of L7 proxy in the data plane





# Serverless Waypoint Proxy Architecture

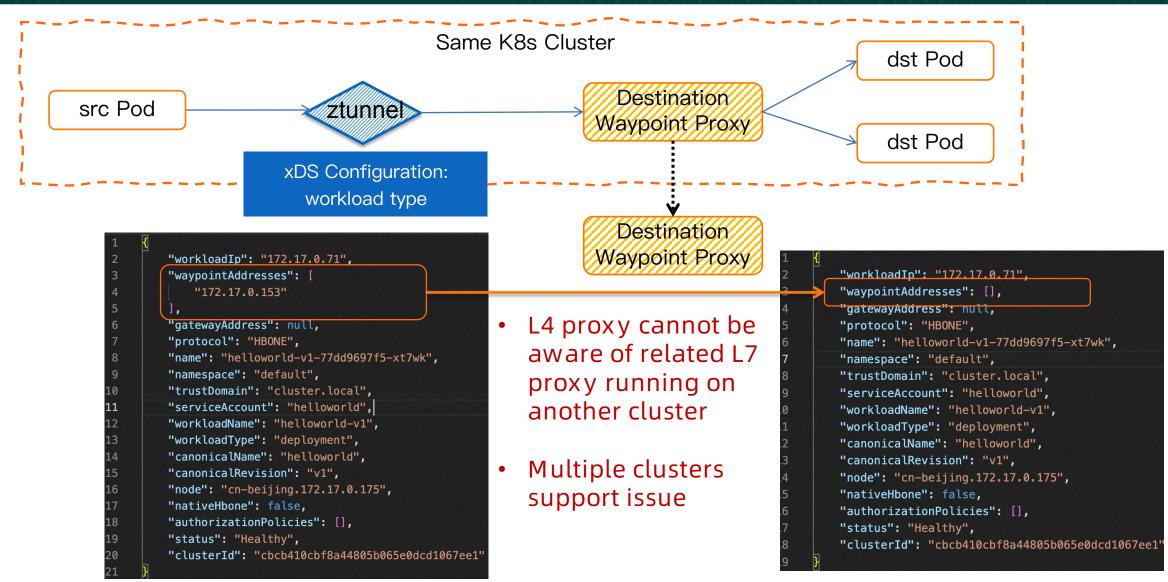




Running Waypoint Proxy within Managed Waypoint Pool or ECI Node within user cluster

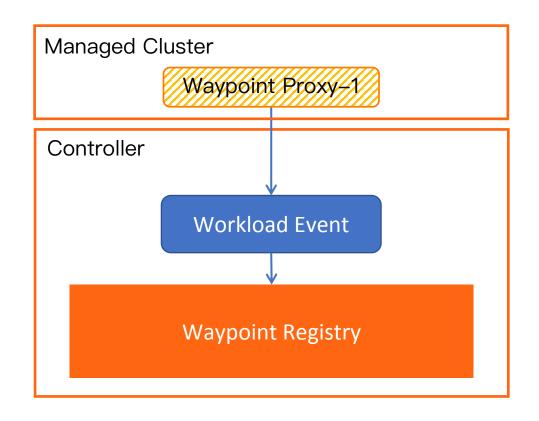
## Challenges: L4 proxy <--> L7 Proxy

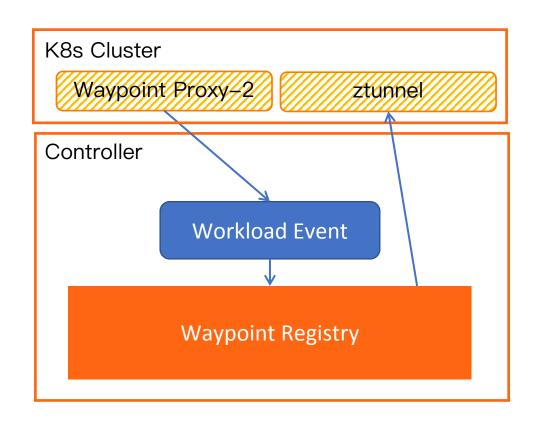




## Solution





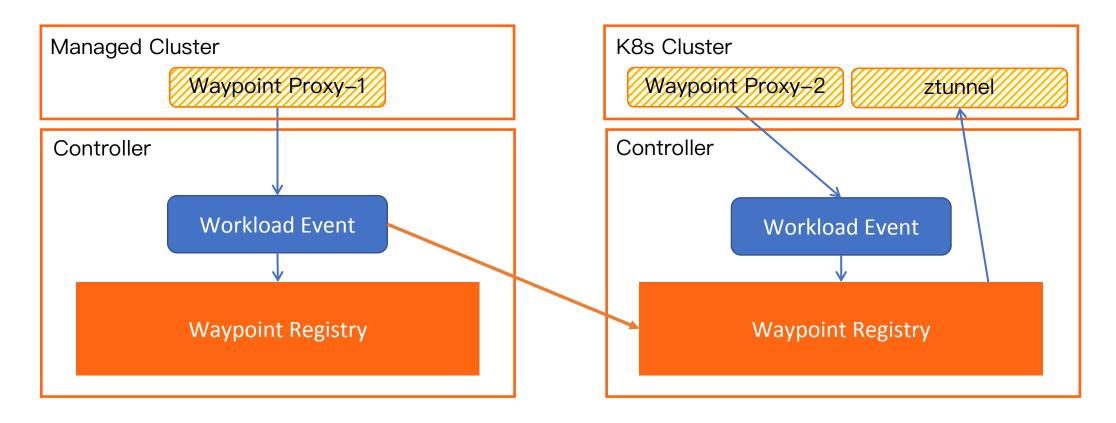


The Istio control plane runs a controller on each cluster and updates the registry when workloads are added or removed. However, the registry between different clusters is not shared.

This means that ztunnel cannot detect Waypoint proxies that are not in the same cluster as itself.

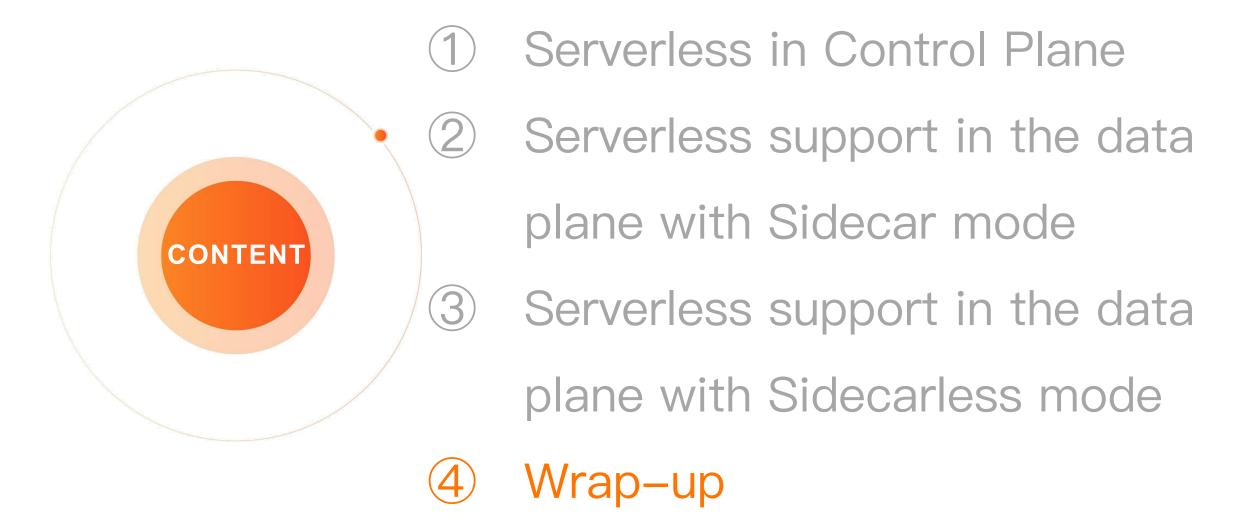
## Solution





When the waypoint of the managed cluster starts, update the Registry in all cluster Controllers and execute the XDS Push





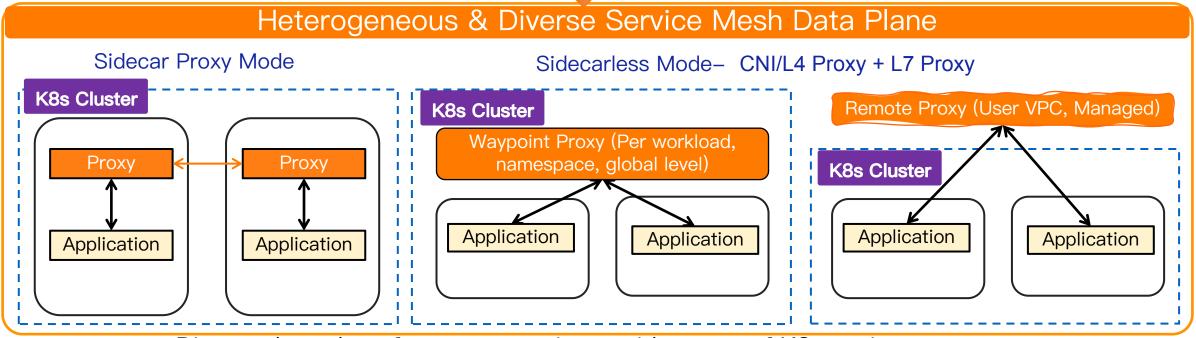
## The evolution of Serverless Service Mesh



The fusion of Sidecar Proxy and Sidecarless modes

#### Unified Service Mesh Control Plane

Unified API b/w control plane & data plane



Diverse data plane forms, supporting a wide range of K8s environments: (K8s version x form x ECS specifications x OS version)



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